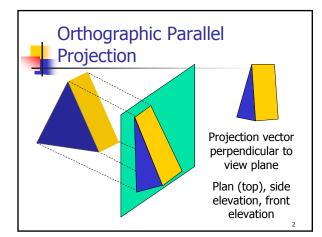
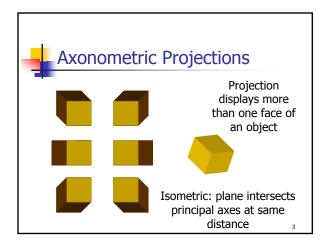


## **Projections**

- Mapping 3-D to 2-D
- Parallel projection
  - Preserves relative proportions
  - Unrealistic appearance
- Perspective projection
  - Realistic view
  - Does not preserve proportions

.







## Orthographic Transform

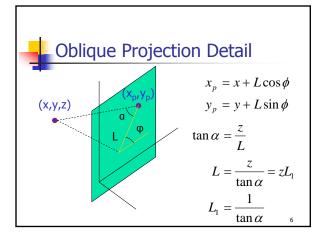
- Transform world to view coordinates
  - So direction vector aligned to +z
- Keep x and y coordinates
- Flatten z coordinate
  - Set to zero?
  - Use for depth cueing?

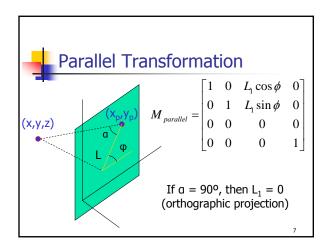
.

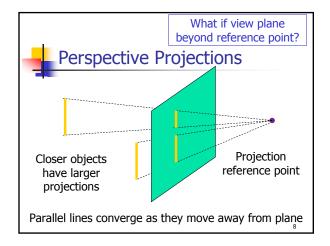
Oblique Parallel Projection

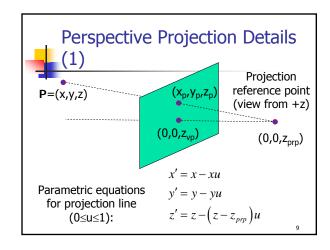
Projection vector not perpendicular to view plane

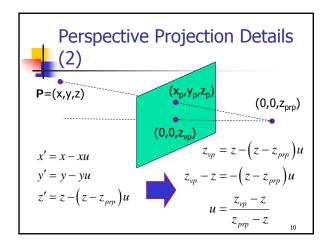
"Looking out of the corner of your eye"

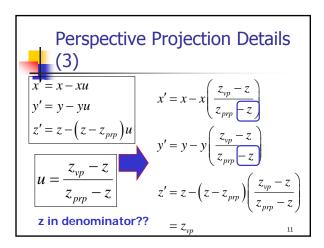








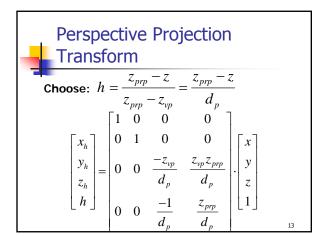


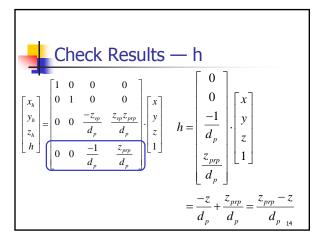


## Homogeneous Coords. Revisited • Homogeneous point

- $P_h = (x_h, y_h, z_h, h)$
- Actual point
  - P =  $(x_h/h, y_h/h, z_h/h)$
- So far we've ignored h
  - Set h=1, so  $x_h = x$ , etc.
  - But h is in denominator! Use it?

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Check Results — x, y
$\begin{bmatrix} x_h \\ y_h \\ z_h \\ h \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{-z_{vp}}{d_p} & \frac{z_{vp}z_{prp}}{d_p} \\ 0 & 0 & \frac{-1}{d_p} & \frac{z_{prp}}{d_p} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \qquad x_h = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = x$
$x = xd_p \qquad x\left(z_{prp} - z_{vp}\right)$
$x = \frac{1}{h} = \frac{1}{\left(z_{prp} - z\right)/d_p} = \frac{1}{z_{prp} - z} = \frac{1}{z_{prp} - z}$ $= \frac{x\left(z_{prp} - z\right) - x\left(z_{vp} - z\right)}{z_{prp} - z} = x - xu$ Same for y

Check Results — z (1)
$$\begin{bmatrix} x_h \\ y_h \\ z_h \\ h \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{-z_{vp}}{d_p} & \frac{z_{vp}z_{pp}}{d_p} \\ 0 & 0 & \frac{-1}{d_p} & \frac{z_{pp}}{d_p} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \qquad z_h = \begin{bmatrix} 0 \\ 0 \\ \frac{-z_{vp}}{d_p} \\ \frac{z_{vp}z_{pp}}{d_p} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

$$= \frac{-z_{vp}z}{d_p} + \frac{z_{vp}z_{pp}}{d_p} = \frac{z_{v$$

