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MSc in Computer Animation and Visual Effects

evulkan

A Vulkan Library

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Abstract

Vulkan is a low-level graphics API which aims to provide users with faster draw speeds by removing overhead from the driver. The user is expected to explicitly provide the details previously generated by the driver. The resulting extra code can be difficult to understand and taxing to write for beginners, leading to the need for a helper library.

Acknowledgements

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Dedication

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Introduction

Vulkan (Khronos Group 2016b) is a cross-platform graphics and compute API. It aims to provide higher efficiency than other current cross-platform APIs, by using the full performance available in today's largely-multithreaded machines. Vulkan achieves this by allowing tasks to be generated and submitted to the GPU in parallel (multithreaded programming). In addition, the API itself is written at a lower-level than other graphics APIs, meaning that the developer is required to provide many of the details previously generated by the driver at run-time.

This project aims to alleviate this cost by providing a wrapper library for Vulkan, which allows a developer to use some of the more common features of Vulkan with much less effort than writing an application from scratch. This library is written in C++, using modern C++ features, adheres to both the official C++ Core Guidelines and Google C++ Style Guide and is fully unit tested. The library is available for download from GitHub and can be built using CMake.

The library is specifically written with beginners and casual users of Vulkan in mind. The examples included in the repository provide a demonstration of how to use the library for different purposes, including drawing a triangle, loading an OBJ with a texture and using multiple passes to render simple objects with deferred shading. A non-goal is to create a library which is as fast as writing pure Vulkan, however the library must be reasonably fast.

Previous Work

While Vulkan is a relatively new API for graphics and compute, many engines now support Vulkan, including CryEngine, Valve's Source, Unity and Unreal Engine. As a result, there are many libraries and utilities available online for Vulkan, each of which serves a different purpose.

2.1 V-EZ

AMD created the open-source V-EZ library (AMD 2018). Its main goal is to increase the adoption of Vulkan in the games industry by reducing the complexity of Vulkan. It is a lightweight C API wrapped around the basic Vulkan API. It is part of the GPU-Open initiative.

It still requires the user to have a good knowledge of Vulkan, making it difficult for beginners to adopt. For example, some rather complex components include semaphores, swapchain creation and lengthy enumerations such as

While it does remove some of the boilerplate, it is still relatively low level and, as a result, is not perfectly suited to beginners.

2.2 Anvil

The goal of Anvil is to reduce the amount of time taken to write Vulkan applications. It is ideal for rapidly prototyping Vulkan applications, but it still requires a large amount of writing. It is stated in the documentation itself that Anvil is not suitable for beginners.

Anvil is not the right choice for developers who do not have a reasonable understanding of how Vulkan works.

2.3 GLOVE

GLOVE (Think Silicon 2016) provides an intermediate layer between an OpenGL ES application and Vulkan. It is easy to build and integrate new features and has a GL interface for developing applications.

GLOVE is useful for developing Vulkan applications for embedded devices, especially for developers who already have an understanding of GL applications. However, GLOVE is not useful for learning Vulkan as it only provides a GL interface.

2.4 MoltenVK

As Apple hardware lacks native Vulkan driver support, MoltenVK (Khronos Group 2016a) provides an interface over Apple's Metal graphics framework. This provides no speedup in terms of development time, it simply allows Vulkan to be developed and run on macOS. As a result, it does not provide any extra help for beginners to Vulkan.

2.5 Personal Inquiry

This library was developed using a previous project as a starting point (Crotty 2020). The base project can be found at http://github.com/eimearc/vulkan. It provided the boilerplate to run an instance of Vulkan and it saved days of typing 1000 lines of code to simply have a starting point. All class construction, library design and testing was implemented in this masters project.

Technical Background

3.1 Useful Resources

As Vulkan is a relatively complex topic, many resources, both online and in-print, came in useful during this project and may help the reader with their Vulkan understanding.

- Vulkan Programming Guide (Sellers 2016)
- Sascha Willem's Vulkan examples (Willems 2015)
- Vulkan Tutorial (Overvoorde 2020)
- ARM Vulkan tutorial (ARM 2020)

3.2 Comparison with OpenGL

Vulkan is a low-overhead, cross-platform graphics and computing API. It was developed to allow higher performance and more balanced CPU/GPU usage in comparison to older APIs such as OpenGL.



Figure 3.1: OpenGL compared to Vulkan (Khronos Group 2016c, p.1).

While OpenGL acts as a state machine, keeping track of application state, Vulkan requires the developer to keep track of such state. OpenGL requires operations to be submitted in sequence, while Vulkan takes full advantage of modern multicore machines and allows operations to be recorded and submitted in parallel.

OpenGL handles host-device synchronization and memory management in the driver, while Vulkan requires the developer to deal with this. The idea behind this is that the developer knows best how their data will be accessed and, as a result, the developer knows the optimal way to lay out data in memory. While this does result in a more explicit, low level API and longer development times, the advantage becomes apparent in the runtime speedup. There is much less overhead in the Vulkan driver, as the developer provides most of the required detail. Less driver work generally results in faster run times.

OpenGL provides a constant level of error checking. While this is useful during the development phase, once an application is rolled out to production, error checking slows down the application. Vulkan provides a way around this with validation layers that can be registered during development and removed afterwards, further speeding up an application.

OpenGL reads shader code in GLSL and compiles it at run time. This leads to a slower run time in the best case, or run time errors in the worst case when the GLSL is not properly formed. Vulkan requires the developer to compile the shader code to byte code (SPIR-V) ahead of time and to provide as such. This has the dual advantage of ensuring the shader code is correct and speeding up the run time.

The pattern is apparent; Vulkan requires more setup, state tracking and memory management from the developer. This removes much of the required word from the driver, resulting in faster draw speeds in comparison with older APIs such as OpenGL.

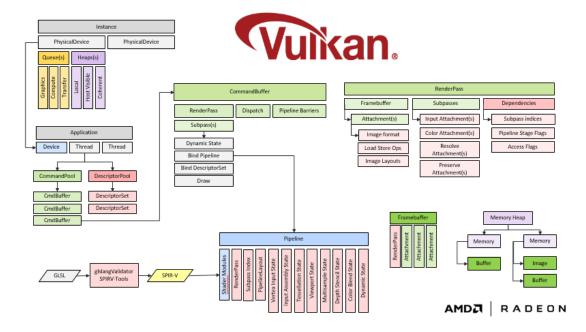


Figure 3.2: Vulkan API objects and their interactions (AMD 2018, p.1).

The evulkan Library

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```
Device
       const std::vector<const char *> &deviceExtensions.
       const uint32_t swapchainSize
       uint32 t numThreads.
       const std::vector<const char *> &deviceExtensions,
       uint32 t swapchainSize,
       const std::vector<const char*> &validationLavers
);
void createSurface(
       std::function<void()> surfaceFunc.
       uint32_t width,
uint32_t height,
       const std::vector<const char *> &windowExtensions
) noexcept:
void finalize(
Buffer &indexBuffer
      Buffer &vertexBuffer.
       std::vector<Pipeline*> &pipelines
) noexcept;
void draw() noexcept
void resizeRequired() noexcept:
```

Figure 4.1: Device class diagram.

```
Texture

Texture(
    const Device &device,
    const std::string &fileName
);
```

Figure 4.2: Texture class diagram.

```
Attachment

enum class Type{FRAMEBUFFER,COLOR,DEPTH};

Attachment(
    const Device &device,
    uint32_t index,
    const Type &type
) noexcept;

6
```

Figure 4.3: Attachment class diagram.

Nulla malesuada porttitor diam. Donec felis erat, congue non, volutpat at, tincidunt tristique,

libero. Vivamus viverra fermentum felis. Donec nonummy pellentesque ante. Phasellus adipiscing semper elit. Proin fermentum massa ac quam. Sed diam turpis, molestie vitae, placerat a, molestie nec, leo. Mae-

cenas lacinia. Nam ipsum ligula, eleifend at, accumsan nec, suscipit a, ipsum. Morbi blandit ligula feugiat magna. Nunc eleifend consequat lorem. Sed lacinia nulla vitae enim. Pellentesque tincidunt purus vel magna. Integer non enim. Praesent euismod nunc eu purus. Donec bibendum quam in tellus. Nullam cursus pulvinar lectus. Donec et mi. Nam vulputate metus eu enim. Vestibulum pellentesque felis eu massa.

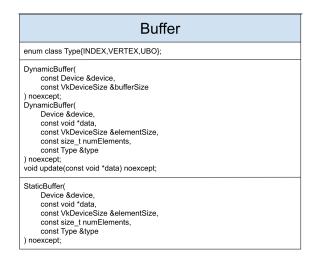


Figure 4.4: Buffer class diagram.

```
Descriptor
Descriptor(
     const Device &device,
     const size_t swapchainSize
) noexcept;
void addInputAttachment(
     const uint32 t binding.
     Attachment &attachment,
     const Shader::Stage shaderStage
) noexcept;
void addTextureSampler(
     const uint32_t binding,
     const Texture &texture,
     const Shader::Stage shaderStage
) noexcept;
void addUniformBuffer(
     const uint32_t binding,
     const Buffer &buffer,
     const Shader::Stage shaderStage
) noexcept;
```

Figure 4.5: Descriptor class diagram.

Subpass typedef uint32_t Dependency; Subpass(const uint32_t index, const std::vector<Dependency> &dependencies, const std::vector<Attachment*> &colorAttachments, const std::vector<Attachment*> &depthAttachments, const std::vector<Attachment*> &inputAttachments) noexcept;

Figure 4.6: Subpass class diagram.

Renderpass Renderpass(const Device &device, std::vector<Subpass*> &subpasses) noexcept;

Figure 4.7: Renderpass class diagram.

```
Pipeline

Pipeline(
    Device &device,
    Subpass &subpass,
    Descriptor &descriptor,
    const VertexInput &vertexInput,
    Renderpass &renderpass,
    const std::vector<Shader*> &shaders
) noexcept;

Pipeline(
    Device &device,
    Subpass &subpass,
    const VertexInput &vertexInput,
    Renderpass &renderpass,
    const std::vector<Shader*> &shaders
) noexcept;
```

Figure 4.8: Pipeline class diagram.

```
Shader

enum class Stage{VERTEX,FRAGMENT};
Shader(
const Device &device,
const std::string &fileName,
const Stage &stage
);
```

Figure 4.9: Shader class diagram.

```
VertexInput

VertexInput(uint32_t stride) noexcept;
void setVertexAttributeVec2(
    uint32_t location, uint32_t offset
) noexcept;
void setVertexAttributeVec3(
    uint32_t location, uint32_t offset
) noexcept;
```

Figure 4.10: VertexInput class diagram.

Conclusion

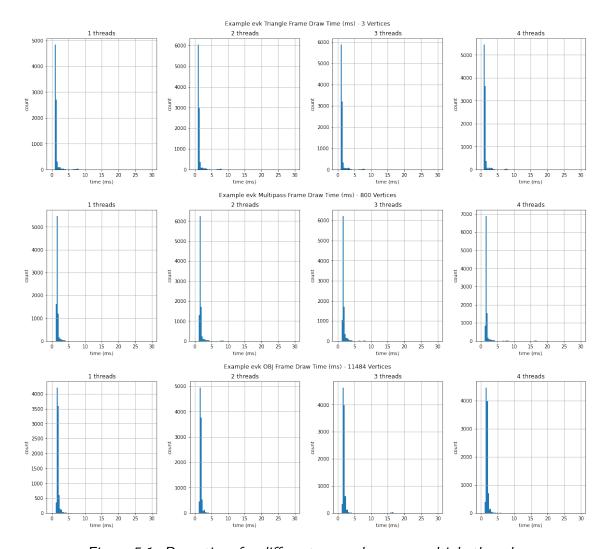


Figure 5.1: Draw time for different examples over multiple threads.

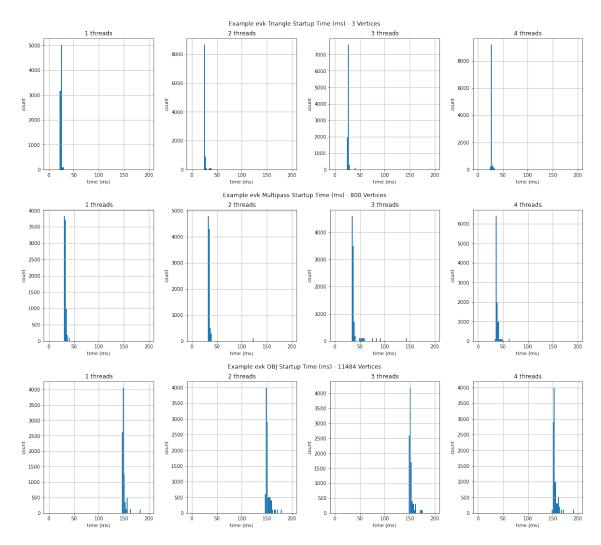


Figure 5.2: Setup time for different examples over multiple threads.

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Appendices