# Tracker EDM analysis note: A measurement of the longitudinal magnetic field in Run-1

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#### Abstract

This document briefly outlines the methodology of the longitudinal magnetic field,  $B_z$ , measurement using the tracker data in Run-1. The final results for the systematic uncertainty on  $\omega_a$  due to  $B_z$  are presented, and are found to be: 0 ppm  $<\frac{\Delta\omega_a}{\omega_a}<4$  ppm.

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## 1 Introduction

A presence of a longitudinal field,  $B_z$ , tilts the precession plane of the muon, as shown in Figure 1, and modifies [1] the observed precession frequency according to

$$\omega_a = a_\mu \frac{e}{m_\mu} B \to \frac{e}{m_\mu} \sqrt{(a_\mu B_y)^2 + \left(\frac{(1 + a_\mu) B_z}{\gamma}\right)^2}.$$
 (1)

It is therefore imperative to estimate this systematic effect on  $\omega_a$ .

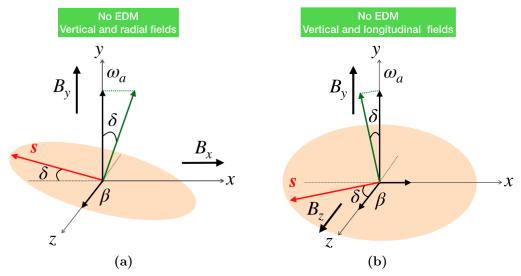


Figure 1: The tilt in the precession plane due to field components: a) radial  $(B_x)$  b) longitudinal  $(B_z)$ . The momentum vector  $(\beta)$  is along the z-axis. The tilt due to the radial field - towards the centre of the ring - is analogous to an effect due to an EDM. The longitudinal field, however, would produce a tilt towards the direction of the stored beam, by an angle  $\delta$ .

This tilt due to  $B_z$  can be used in the measurement of the average vertical angle of muon decay as a function of time: an up-down oscillation in-phase with  $\omega_a$  would be indicative of a longitudinal field.

#### 2 Methodology

In this study, the measurement of the vertical angle,  $\theta_y$ , is coming from the tracking detector, where for each track a corresponding measurement of track time in a fill is available. This time is used to modulate data by the g-2 period,  $T_{g-2}$ , to remove any systematic effects that are not periodic with  $T_{g-2}$  (e.g. VBO). This is analogous to the method used in the BNL EDM analysis by M. Sossong [2]. The remaining analysis steps also follow the Sossong's methodology closely, and are presented in detail in DocDB:22201 [3]. These steps include fitting data for the number oscillation

$$N(t) = Ne^{-t/\tau} [1 + A\cos(\omega_a t + \phi)], \tag{2}$$

using a constant value of 1.439311 MHz for  $\omega_a$ , as measured at the BNL g-2 [4]. This is shown in Figure 2a. The value of  $\phi$  from Equation (2) is then used in the fit to the vertical angle oscillation

$$\theta(t) = A_{\rm B_z} \cos(\omega_a t + \phi) + A_{\rm EDM} \sin(\omega_a t + \phi) + c, \tag{3}$$

where  $A_{\rm B_z}$  is the amplitude due to the longitudinal magnetic field,  $A_{\rm EDM}$  is the EDM amplitude, and c is the overall offset. This is shown in Figure 2b.  $A_{\rm EDM}$  is blinded with data, as discussed in DocDB:22201 [3].

Parameter stability scans with fit start time, fit end time, momentum cuts, bin width, and a choice of  $T_{g-2}$  (i.e.  $\omega_a$ ) and  $\phi$  are also presented in DocDB:22201 [3], and are found to be stable.

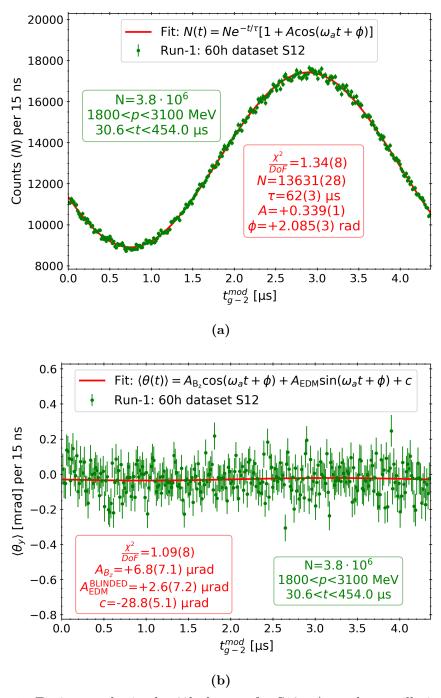


Figure 2: Fitting results in the 60h dataset for S12: a) number oscillation, and b) average vertical angle oscillation.

# 3 Results

The observed (i.e. fitted) amplitudes of the vertical angle oscillation due to  $B_z$  (i.e.  $A_{\rm B_z}$ ) from all the four Run-1 datasets are presented in Figure 3.

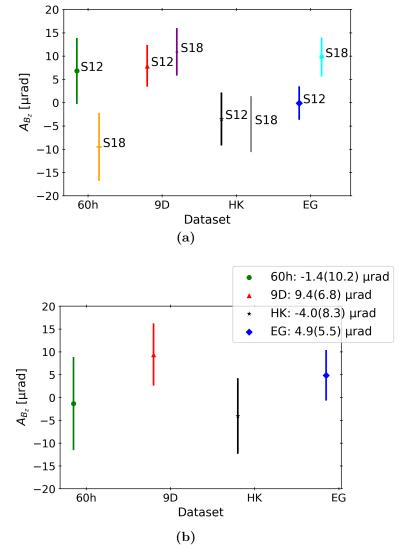


Figure 3: Fitting results in all Run-1 datasets: a) S12 and S18 separately, and b) mean of the two stations. The individual fit results are summarised in DocDB:22201 [3].

Joe has posted a great and comprehensive note [5], which deals with a conversion from an observed amplitude to an estimated value of  $B_z$ . The conversion steps are as follows. Asymmetry term, A = 0.1, is connecting the observed amplitude  $(A_{B_z})$  with the actual precession plane tilt in the lab frame  $(\delta')$ 

$$A_{B_z} = 0.1\delta'. (4)$$

Asymmetry is accounting for the fact that not all positrons are emitted in the direction of polarisation vector [5]. Given that the muon motion is along z (c.f. Figure 1), there is no Lorentz boost in this direction. Therefore, the estimate of  $B_z$  is directly available from the measured angle in the lab frame, after the asymmetry term is taken into account. Hence,

$$\delta' = \tan(\frac{B_z}{B_y}) \approx \frac{B_z}{B_y}. (5)$$

Finally, the corresponding systematic uncertainty on  $\omega_a$  can be estimated using the formula in Bill's note [1]

$$\frac{\Delta\omega_a}{\omega_a} = \frac{1}{2} \left( \frac{(1+a_\mu)}{a_\mu \gamma} \frac{B_z}{B_y} \right)^2. \tag{6}$$

The final results of the application of Equations (5) and (6) to Run-1 vertical angle oscillation is given in Figure 4.

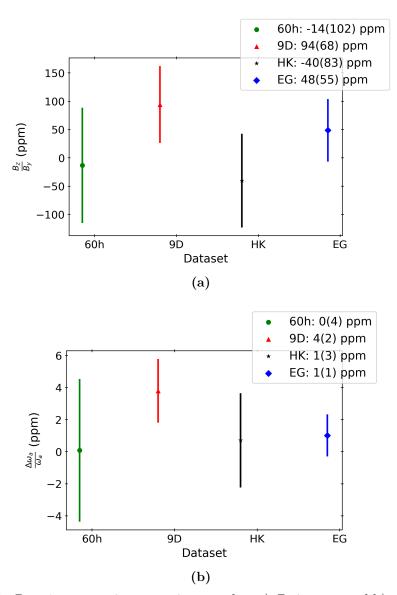


Figure 4: Run-1 systematic uncertainty results: a)  $B_z$  in ppm and b)  $\omega_a$  in ppm.

Given the range of values in Figure 4b, the uncertainty spread on  $\omega_a$  can be summarised as

$$0 \text{ ppm} < \frac{\Delta \omega_a}{\omega_a} < 4 \text{ ppm}. \tag{7}$$

## References

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