

# **Creating Chaos and Hard Faults**

...because you can

**Elecia** White

# Agenda

1 Smash the stack!

4 Creating hard faults

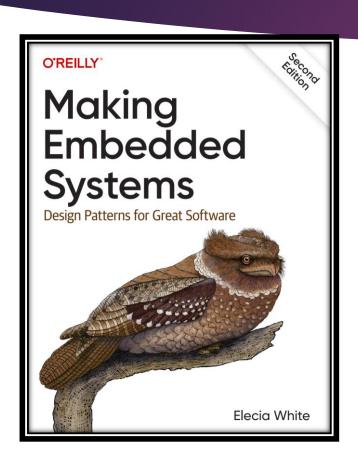
Wait, what is the stack?

5 Debugging hard faults

3 Debugging

6 Debugging impossible bugs

# Speaker: **Elecia** White





Goal: Build interesting gadgets that make the world a better place

If you like this talk, check out my book and podcast:

- Making Embedded Systems: Design Patterns for Great Software, 2nd edition, 2024.
- **Embedded.fm**, a show about engineering and engineers, wherever you get your podcasts from.

# 1 Smash the stack!

One of the best and most effective ways to cause chaos on your embedded system.

## Stack Chaos!

#### Overflow a buffer

This type of error allows anyone to run code on your processor.

```
#define MAX_NAME_LENGTH 10
     // enter more than 10 characters to cause problems
11
     void unbounded fill from input(char* name)
15
         int i = 0;
16
         char ch;
         ch = getchar();
18
         while (ch != '\n') { // wait for new line
19
             name[i] = ch; i++;
20
              ch = getchar();
21
22
         name[i] = NULL; // NULL terminate string
25
     void trash_the_stack(void)
26
         char name[MAX NAME LENGTH];
         printf("Hello! Tell me your name: ");
28
         unbounded_fill_from_input(name);
29
          printf("Hello %s\r\n", name);
30
```

Wait, what is the stack?

Chaos is more fun when you understand what you are doing.

# Memory Map

embedded.fm/blog/mapfiles



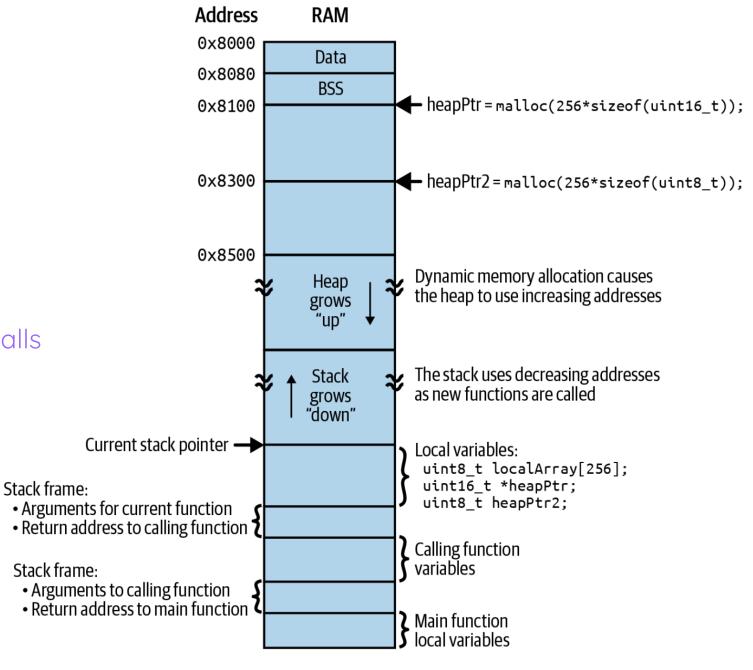
# Memory Map: RAM

**Data**: global variables you initialize

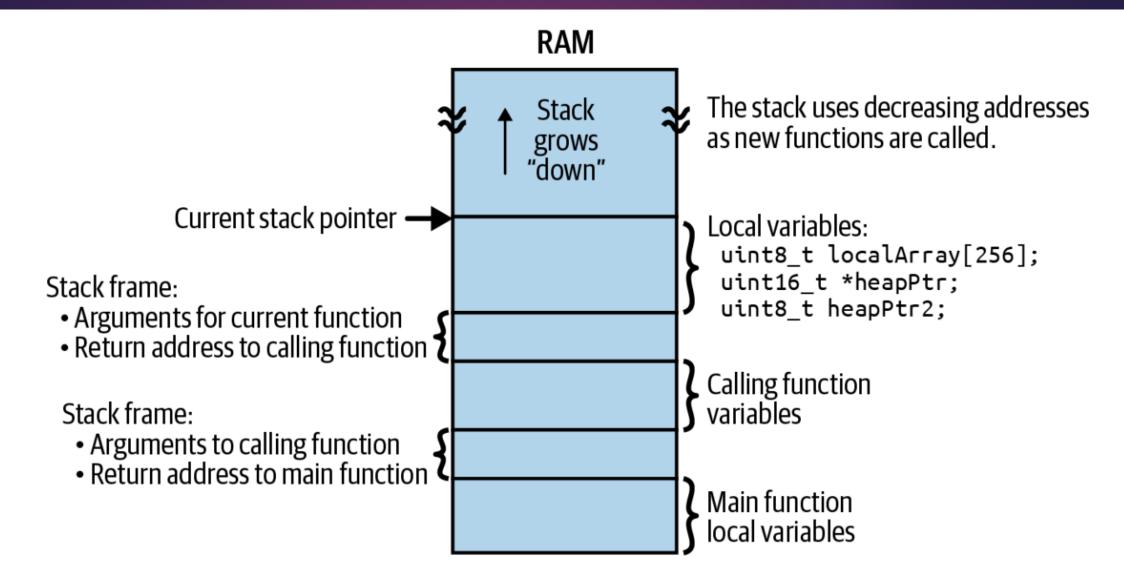
**BSS**: global variables auto-init to zero

**Heap**: malloc space

**Stack**: working memory for function calls



# Looking More Closely at the Stack



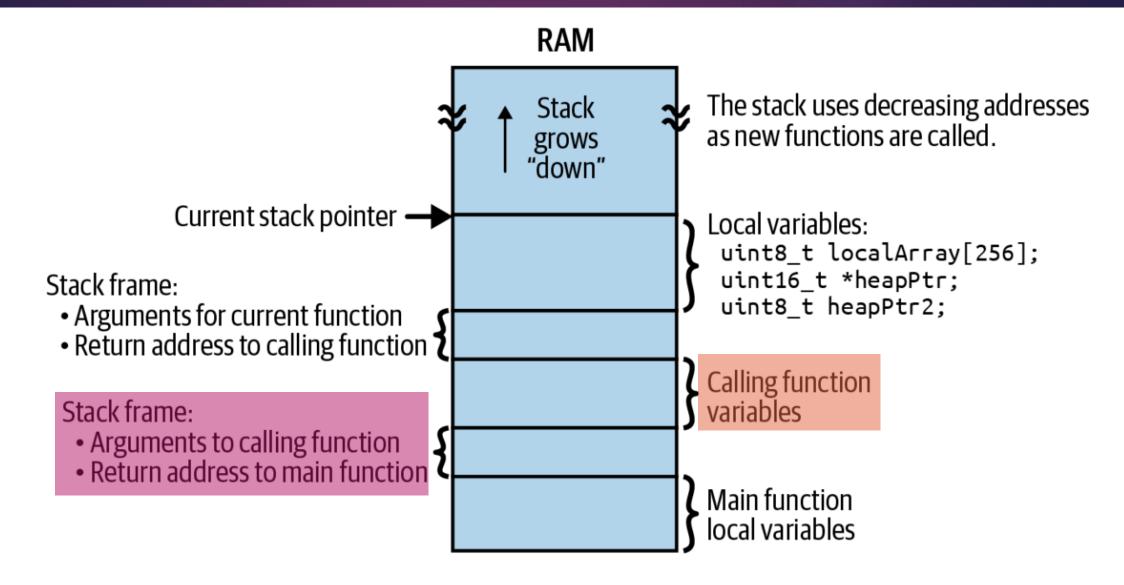
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# 3 Debugging

Let's start with normal debugging.

# Six Stages of Debugging

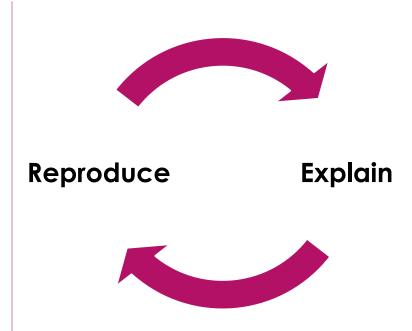
- That can't happen.
- That doesn't happen on my machine.
- That shouldn't happen.
- ? Why does that happen?
- e Oh! I see...
- How did that ever work?

# Debugging

### Reproduce the bug | Explain the bug

Make it happen on command with a minimal code set.

Rubber duck debugging is amazing.



4

# **Creating hard faults**

Intentionally causing crashes is way more fun than when it happens in real life.

## Hard faults

- Divide by zero
- Incorrect memory access (unaligned)
- Talking to things that aren't there
- Weird return code from interrupt/RTOS
- Running from non-code memory (undefined instruction, invalid)
- Stack error
- Data access disallowed memory
- Instruction access disallowed memory
- Debug breakpoint (asserts in production code?)
- Invalid address in exception



I WROTE SOME TERRIBLE CODE FOR YOU.
I HOPE YOU APPRECIATE IT.

You can find the code at <a href="https://github.com/eleciawhite/making-embedded-systems/blob/main/Ch09\_Debugging">https://github.com/eleciawhite/making-embedded-systems/blob/main/Ch09\_Debugging</a>

FAULT 1: DIVIDE BY ZERO

```
int divide_by_zero(void)

int a = 1;

int c = 0;

int b = a/c;

return b; // forces compiler to actually run this
}
```

FAULT 1: DIVIDE BY ZERO

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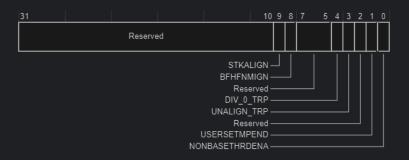
### Configuration and Control Register

The CCR controls entry to Thread mode and enables:

- the handlers for NMI, hard fault and faults escalated by FAULTMASK to ignore BusFaults
- trapping of divide by zero and unaligned accesses
- access to the STIR by unprivileged software, see *Software Trigger Interrupt Register*.

See the register summary in Table 4.12 for the CCR attributes.

The bit assignments are:



Divide by zero causes a hard fault

```
only if DIV_0_TRP is set in SCB->CCR
System Control Block ->
Configuration and Control Register
```

Cortex-M3 Devices Generic User Guide describes these procesor registers

#### FAULT 2: WRITE TO NULL

Works fine.

But should it?

```
// uninitalized global ends up initialized to 0
     int* global_ptr_to_null = NULL;
41
     int* global_ptr_unitialized;
42
     int write to null(void) {
      int* ptr to null = NULL;
      int* ptr_unitialized;
      *global_ptr_to_null = 10; /* tries to write to address zero */
       *global_ptr_unitialized = 10; /* tries to write to address zero */
       *ptr_to_null = 10; /* tries to write to address zero */
       *ptr_unitialized = 10; /* tries to write ?? somewhere ?? */
52
       return *global_ptr_to_null + *global_ptr_unitialized +
           *ptr_to_null + *ptr_unitialized;
```

FAULT 3: NOT EVERY SET OF BYTES IS A VALID INSTRUCTION

Touch your nose to your elbow!

```
// Assuming 0xE0000000 is a bad instruction
int illegal_instruction_execution(void) {
  int instruction = 0xE0000000;
  int (*bad_instruction)(void) = (int(*)())(&instruction);
  return bad_instruction();
}
```

#### HARD FAULT HANDLER 1

Finally, something fails!

```
void HardFault_Handler(void)
          asm volatile
180
          " movs r0,#4
                          n"
          " movs r1, lr \n"
181
          " tst r0, r1
                         \n"
          " beq MSP
183
                        \n"
          " mrs r0, psp \n"
184
          " b HALT
                      \n"
          " MSP:
                      \n"
186
            mrs r0, msp \n"
187
188
          " HALT:
                      \n"
          " ldr r1,[r0,#20] \n"
189
             b hard fault handler c \n"
          " bkpt #0 \n"
191
          );
```

```
194
      void hard_fault_handler_c(unsigned long *hardfault_args){
        volatile unsigned long stacked_r0 ;
195
196
        volatile unsigned long stacked_r1 ;
        volatile unsigned long _BFAR ;
        volatile unsigned long _MMAR ;
        stacked_r0 = ((unsigned long)hardfault_args[0]) ;
210
        stacked_r1 = ((unsigned long)hardfault_args[1]) ;
237
        // Read the Fault Address Registers. These may not contain
238
        // valid values.
        // Check BFARVALID/MMARVALID to see if they are valid values
        // MemManage Fault Address Register
        _MMAR = (*((volatile unsigned long *)(0xE000ED34)));
241
        // Bus Fault Address Register
        _BFAR = (*((volatile unsigned long *)(0xE000ED38)));
        __asm("BKPT #0\n") ; // Break into the debugger
  Vector table calls
          HardFault Handler
  which sets up registers then calls
          hard fault handler c
  which makes things more readable then
  breakpoints for debugging
```

HARD FAULT HANDLER 2

Stash it in RAM... Check it on boot

```
typedef struct __attribute__((packed)) ContextStateFrame {
    uint32_t r0;
    uint32_t r1;
    uint32_t r2;
    uint32_t r3;
    uint32_t r12;
    uint32_t r12;
    uint32_t lr;
    uint32_t return_address;
    uint32_t xpsr;
} sContextStateFrame;
```

```
uint32 t r3;
      uint32 t returnAddress;
      uint32 t stackPointer;
      } attribute ((section(".CoreDump"))) coreDump;
298
      void my fault handler c(sContextStateFrame *frame)
301
          coreDump.key = COREDUMP_KEY;
          coreDump.r0 = frame->r0;
          coreDump.r1 = frame->r1;
          coreDump.r2 = frame->r2;
          coreDump.r3 = frame->r3;
          coreDump.return address = frame->return address;
          coreDump.stackPointer = frame->xpsr;
```

```
168
     . user heap stack :
169
170
        \cdot = ALIGN(8);
171
       PROVIDE (end = .);
172
       PROVIDE (end = .);
173
        . = . + Min Heap Size;
174
        . = . + Min Stack Size;
175
        . = ALIGN(8);
176
     } >RAM
177
178
      .CoreDump :
179
       > RAM2
180
```

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# **Debugging hard faults**

Wizardry at its finest.

## Hard faults

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## Don't create hard faults

#### Don't do bad things

- ✓ Buffer overflows (and offby-one errors)
- ✓ Stack corruption (returning memory from a function)
- ✓ Stack overflows (recursion)
- ✓ Uninitialized variables

#### Don't do useful things

- Avoid heaps
- > Avoid recursion
- Avoid pointers of all kinds
- Avoid function pointers most of all
- Avoid interrupts and RTOSs
- Avoid compiler and linker optimizations

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When they inevitably happen use Interrupt Blog's **How to Debug a Hard Fault on an ARM Cortex-M MCU** and:

- Reproduce the problem
- Explain the problem
- Create a core dump
- □ Fix compiler warnings

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# Debugging impossible bugs

To fight the unbeatable foe

To bear with unbearable sorrow

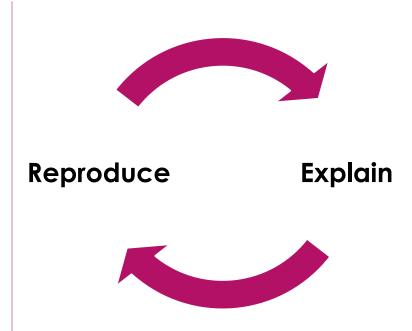
To run where the brave dare not go

# Debugging

### Reproduce the bug | Explain the bug

Make it happen on command with a minimal code set.

Rubber duck debugging is amazing.



# Debugging: Reproduce the bug

- 1. Reproduce the bug.
- 2. Add instrumentation.
- 3. Reproduce the bug with the minimal amount of code.
- 4. Go back to the last working version.
- 5. Reproduce the bug on command (or on boot) so you don't have to do ten steps to reproduce it. Remove steps if possible.
- 6. After making exploratory tweaks, are you sure you are running the code you think you are?



# Debugging: Explain the bug

- 1. Describe the bug's symptoms.
- 2. Explain how the bug could possibly do what it does. List all possible causes (without using ground loops).
- 3. Determine how to eliminate each cause, starting with the simplest.
- 4. Explain the bug and what you've tried to a duck. If you realize you forgot to try something, note it down.
- 5. Take notes on what changes have what effect. You will not remember after the third tweak.
- 6. Get a code review.



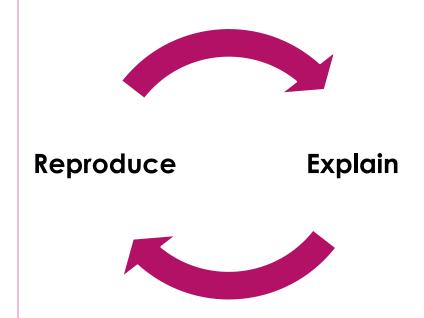
## Debugging

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# Explain the bug

#### Code

- Memory
- Timing
- Resource collision
- Operating system
- Too much time in critical sections
- Too long in an interrupt
- Unhandled interrupt
- Hard fault

#### Hardware

- Jumper wires
- Cables and connectors
- Crosstalk
- Brownouts
- Boot order
- Temperature dependence
- Clock weirdness
- Percussive maintenance
- Try a simulator

The goal is to figure out all the places the bug might be.

This is not a complete list. You should make your own version.



#### Reproduce

**Explain** 



# Reproduce the bug

- 1. Reproduce the bug.
- 2. Add instrumentation.
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Debugging Impossible Bugs

- 4. Go back to the last working version.
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#### **Explain the bug**

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### Resources

- Introduction to Hard Faults:
  - Debugging Hard Faults on ARM Cortex-M | MCU on Eclipse
  - STM32 Hard Fault debugging
- First handler shown from FreeRTOS: <u>Debugging</u> and diagnosing hard faults on ARM Cortex-M <u>CPUs</u>
- Second handler shown from Memfault: How to debug a HardFault on an ARM Cortex-M MCU

  Interrupt (this is the most in-depth resource)
  - Code used in the demo:

    <a href="https://github.com/eleciawhite/making-embedded-systems/blob/main/Ch09\_Debugging/">https://github.com/eleciawhite/making-embedded-systems/blob/main/Ch09\_Debugging/</a>

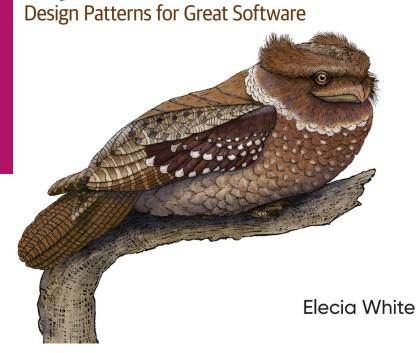
- Arm Documentation: <u>Configurable Fault</u>
   <u>Status Register Cortex-M3</u> and <u>Cortex M4</u>
   Devices Generic User Guide
- Adding NULL identification: <u>Setting up the</u>
   <u>Cortex-M3/4 (ARMv7-M) Memory Protection</u>
   <u>Unit (MPU) Sticky Bits</u>
- \$ Smashing the Stack for Fun and Profit describes how to manipulate the stack
  - Buried Treasure and Map Files (and Linker Files) talk and map:
    - https://embedded.fm/blog/mapfiles

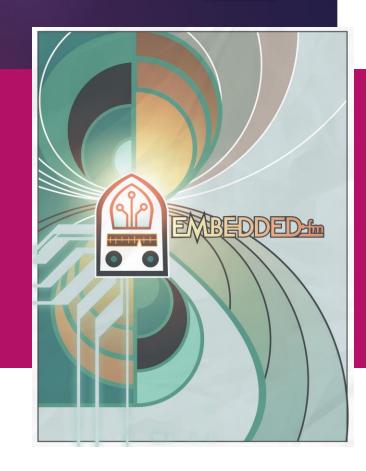
## Thank you!

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# Making Embedded Systems





# **THANK YOU**

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