

# Is Deeper Better only when Shallow is Good?

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# Depth Efficiency

- Basic question: on which distributions deeper networks are much better than shallow ones?

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- Several recent results show

## Depth Separation

There exist functions which can be expressed by a small deep network but must have an exponential width in order to be expressed by a shallow network

E.g. Telgarsky 2015, Safran and Shamir 2016, Cohen et al 2016, Daniely 2017, Poggio et al 2017

## Main Claim

Strong depth separation  $\Rightarrow$  Gradient based Algorithms fail

- 1 Case study: Fractal Distributions
- 2 Depth Separation
- 3 Approximation Curve and Strong Depth Separation
- 4 Success of SGD depends on the Approximation Curve

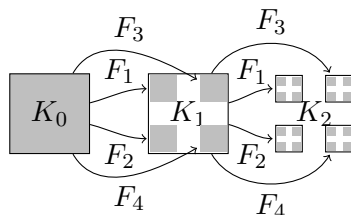
# Fractals

- Iterated Function System:

$$K_0 = [-1, 1]^d$$

$$K_n = F_1(K_{n-1}) \cup \dots \cup F_r(K_{n-1})$$

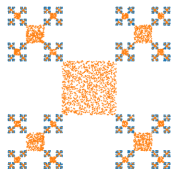
- We assume  $F_i$  are affine, invertible, contractive, and for  $i \neq j$ , the images of  $F_i$  and  $F_j$  are disjoint.
- The “depth” of the fractal is  $n$
- Example:  $F_i(x) = c_i + \frac{1}{4}(x - c_i)$  for  $c_i \in \{\pm 1\}^2$



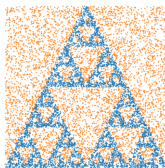
# Fractal Distributions

- A “fractal distribution” is a distribution in which positive examples are sampled from the set  $K_n$  and negative examples are sampled from its complement
- Examples:

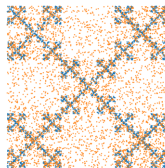
Cantor



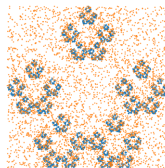
Sierpinsky



Vicsek



Pentaflake



## Theorem

*Consider an IFS over  $[-1, 1]^d$  with  $r$  generating functions and depth  $n$ . For any fractal distribution  $D_n$  there exists a ReLU feed forward network of depth  $2n + 1$  and width  $5dr$  which realizes  $D_n$ .*

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## Proof by induction:

- Basis: a shallow ReLU network can approximate  $I_0(x) = 1_{x \in K_0}$
- Suppose we have a deep network expressing:  $I_{n-1}(x) = 1_{x \in K_{n-1}}$
- Recall:  $K_n = F_1(K_{n-1}) \cup \dots \cup F_r(K_{n-1})$  and  $F_i$  are affine, invertible, and have disjoint images
- Take  $x \in K_n$ , then there's  $z \in K_{n-1}$  and  $i$  s.t.  $x = F_i(z)$ , or equivalently,  $z = F_i^{-1}(x)$
- Therefore,  $[\sum_i I_{n-1}(F_i^{-1}(x))]_+ - [\sum_i I_{n-1}(F_i^{-1}(x)) - 1]_+ = 1_{x \in K_n}$



## Theorem

*If  $D_n$  has non-zero probability in any area of  $K_n$ , then a network of depth  $t$  must have a width of at least  $\frac{d}{e} r^{\frac{n}{td}}$  to realize  $D_n$ .*

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## Proof idea:

- A network of width  $k$  and depth  $t$  has at most  $(ek/d)^{td}$  linear regions
- To realize the fractal distribution, we need  $r^n$  linear regions

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# Approximation Curve

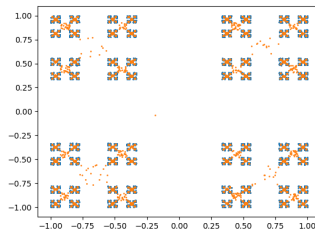
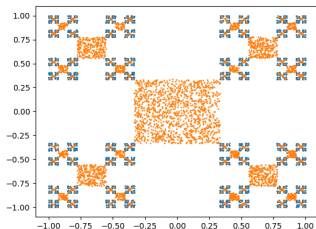
- We saw: a network of depth  $O(n)$  can express a depth  $n$  fractal, but a shallower network requires exponential width to fully realize the distribution
- **Approximation curve:** How much of the negative examples are on the fine details of the fractal:

$$P(j) := 1 - L_{D_n}(1_{x \in K_j}) := 1 - \mathbb{P}_{(x,y) \sim D_n} [x \in K_j \wedge y = -1]$$

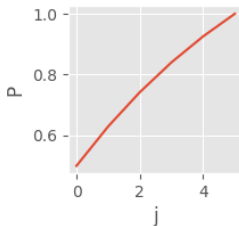
- Note:  $P(0) = 1/2$ ,  $P(n) = 1$ , and  $P$  is monotonically increasing

# Approximation Curve: coarse vs. fine

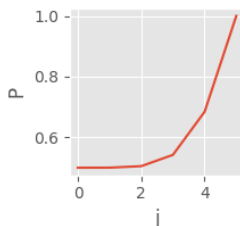
$$P(j) = 1 - L_{D_n}(1_{x \in K_j})$$



curve#1



curve#4



# Approximation Curve and Strong Depth Separation

The following theorem shows that with reasonable width, the error of a depth  $\Theta(j)$  network is roughly  $1 - P(j)$

## Theorem

*Fix a depth  $n$  distribution with approximation curve  $P$ . Then, for every  $j$*

- ① *For a depth  $t = 2j + 2$  and width  $k = 5dr$  network we have*

$$L_{D_n}(H_{t,k}) \leq (1 - P(j))$$

- ② *For every  $s$ , if  $k < r^s$  and  $t < j/s$  then*

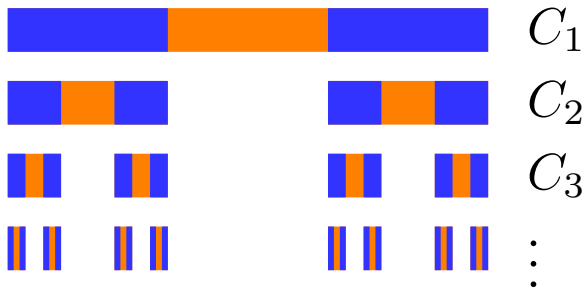
$$(1 - r^{st-j})(1 - P(j)) \leq L_{D_n}(H_{t,k})$$

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# One dimensional Cantor Fractal with “Fine” Distribution



- $C_0 = [0, 1]$  and  $C_n = F_1(C_{n-1}) \cup F_2(C_{n-1})$ , where  $F_1(x) = \frac{1}{3} - \frac{1}{3}x$  and  $F_2(x) = \frac{2}{3} + \frac{1}{3}x$
- “Fine” cantor distributions of growing depth. Negative areas in orange, positive in blue.

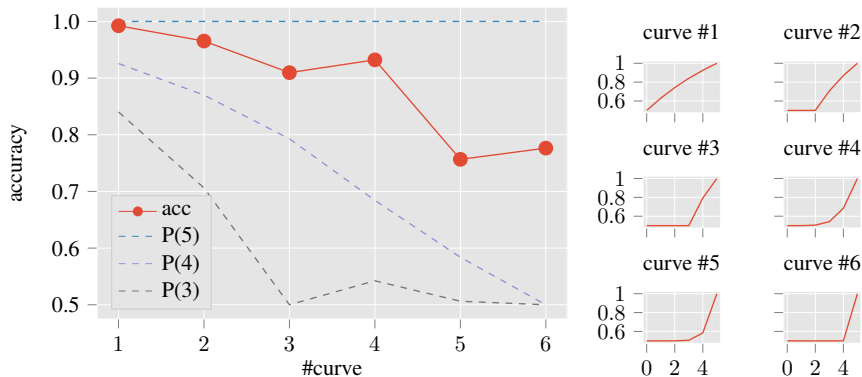


## Theorem

*Consider a depth  $t$ , width  $k$ , network, and suppose the weights,  $W$ , are initialized randomly in the “normal” way. Consider a depth  $n$ , one-dimensional Cantor fractal, and let  $j = \lceil \log(tk^2/\delta) \rceil$ . Then, with probability  $> 1 - \delta$ , all elements of the gradient at  $W$  are of magnitude  $< 5(P(j) - \frac{1}{2})$ .*

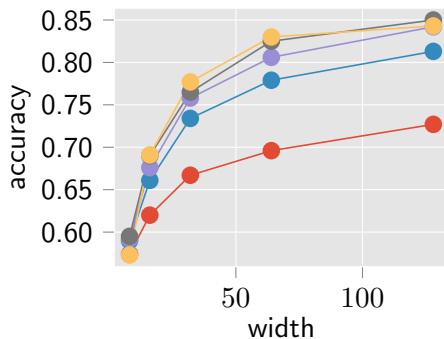
- Corollary: gradient descent is likely to fail on every cantor distribution with strong depth separation, even though the deep network is expressive enough

# Success of SGD depends on the Approximation Curve



Learning depth 5 network on 2D cantor set of depth 5, with different approximation curves.

# Is Deep Good only When Shallow is Also Good ?



- The effect of depth on learning CIFAR-10.
- We train CNNs with Adam for 60K steps. All layers are 5x5 Convolutions with ReLU activation, except the readout layer
- Line colors correspond to different network depth

- Fractal distributions are natural for studying depth efficiency of deep learning
- The “approximation curve” is correlated with how much going deeper really helps
- Strong depth separation: shallow networks perform like random guess while deeper networks realize the distribution
- **Conjecture:** gradient based algorithms fail when there is strong depth separation. In other words,  
**deep is better only when shallow is also good**

# A more concrete formalism of the conjecture

## Conjecture:

- Let  $\mathcal{H}$  be all functions which cannot be approximated by a shallow network. Then:
  - 1 For each  $f \in \mathcal{H}$  there exists a distribution  $D_f$  on  $\mathcal{X} \times \{\pm 1\}$  for which  $f$  achieves zero loss while the best shallow network achieves a loss  $> 1/2 - \epsilon$ .
  - 2 For every such  $D_f$ , gradient-descent fails to learn a deep network.