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FUNDAMENTALS OF OPTIMIZATION

Constrained convex optimization

CONTENT

- Lagrange dual function
- Lagrange dual problem
- KKT condition

Lagrange dual function

- Optimization problem in the standard form

$$\begin{aligned} (P) \quad & \text{minimize } f(x) \\ \text{s.t.} \quad & g_i(x) \leq 0, \quad i = 1, 2, \dots, m \\ & h_i(x) = 0, \quad i = 1, 2, \dots, p \\ & x \in X \subseteq \mathbb{R}^n \end{aligned}$$

with $x \in \mathbb{R}^n$, and assume $D = (\cap_{i=1}^m \text{dom } g_i) \cap (\cap_{i=1}^p \text{dom } h_i)$ is not empty.

- Denote f^* the optimal value of $f(x)$
- If f, g_i ($i = 1, 2, \dots, m$) are convex functions, h_i ($i = 1, \dots, p$) are linear \rightarrow **convex program**

Lagrange dual function

- Define Lagrangian function $L: R^n \times R^m \times R^p \rightarrow R$

$$L(x, \lambda, \mu) = f(x) + \sum_{i=1}^m \lambda_i g_i(x) + \sum_{i=1}^p \mu_i h_i(x)$$

- Lagrange dual function (or dual function)

$$q(\lambda, \mu) = \inf_{x \in D} L(x, \lambda, \mu)$$

- Lagrange dual problem

$$(D) \text{ maximize } q(\lambda, \mu)$$

$$\lambda, \mu \geq 0$$

Lagrange dual function

- **Weak duality theorem** if x^* is an optimal solution to the primal problem and (λ^*, μ^*) is an optimal solution to the dual problem, then $f(x^*) \geq q(\lambda^*, \mu^*)$
- **Corollary** If there exist x^* and (λ^*, μ^*) such that $f(x^*) = q(\lambda^*, \mu^*)$, then x^* and (λ^*, μ^*) are respectively optimal solutions to the primal and dual problems

KKT Conditions

- **Theorem** (Fritz John necessary conditions) Let x^* be a feasible solution of (P) . If x^* is a local minimum of (P) , then there exists (u, λ, μ) such that:
 - $u \nabla f(x^*) + \sum_{i=1}^m \lambda_i \nabla g_i(x^*) + \sum_{i=1}^p \mu_i \nabla h_i(x^*) = 0$
 - $u, \lambda \geq 0, (u, \lambda, \mu) \neq 0$
 - $\lambda_i g_i(x^*) = 0, i = 1, \dots, m$

KKT Conditions

- **Theorem** (Karush-Kuhn-Tucker (KKT) necessary conditions) Let x^* be a feasible solution of (P) and $I = \{j: g_j(x^*) = 0\}$. Further, suppose that $\nabla h_i(x^*)$ for $i = 1, \dots, p$ and $g_i(x^*)$ for $i \in I$ are linearly independent. If x^* is a local minimum of (P) , then there exists (λ, μ) such that:
 - $\nabla f(x^*) + \sum_{i=1}^m \lambda_i \nabla g_i(x^*) + \sum_{i=1}^p \mu_i \nabla h_i(x^*) = 0$
 - $\lambda \geq 0$,
 - $\lambda_i g_i(x^*) = 0, i = 1, \dots, m$

KKT Conditions

- **Theorem** (KKT sufficient conditions) Let x^* be a feasible solution of (P) which is convex program (f, g_i are convex functions, h_i are linear functions). If there exists (λ, μ) such that:
 - $\nabla f(x^*) + \sum_{i=1}^m \lambda_i \nabla g_i(x^*) + \sum_{i=1}^p \mu_i \nabla h_i(x^*) = 0$
 - $\lambda \geq 0,$
 - $\lambda_i g_i(x^*) = 0, i = 1, \dots, m$

then x^* is a global optimal solution of (P)

Example

$$\begin{aligned} &\text{minimize } f(x,y) = 2x - y \\ &\text{s.t. } g_1(x,y) = x^2 + y^2 - 2 \leq 0 \\ &\quad g_2(x,y) = x - y - 1 \leq 0 \end{aligned}$$

- $\nabla f(x,y) = [2 \ 1]^T$, $\nabla g_1(x,y) = [2x \ 2y]^T$, $\nabla g_2(x,y) = [1 \ -1]^T$
- f and g_2 are linear, so they are convex
- $\nabla^2 g_1(x,y) = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$ which is positive definite, so g_1 is convex
- **Exercise** Apply KKT condition, solve the problem ?

Lagrange relaxation for Integer Programming

$$\begin{aligned} Z_{IP} = \text{minimize } f(x) &= c^T x \\ \text{s.t. } Ax &\geq b \\ Dx &\geq d \\ x &\text{ integer} \end{aligned}$$

- Let $X = \{x \text{ integer} \mid Dx \geq d\}$
- Assume optimizing over X can be solved easily, but adding constraint $Ax \geq b$ makes the problem too difficult

Lagrange relaxation for Integer Programming

$$\begin{aligned} Z(\lambda) = \min_x \quad & c^T x + \lambda^T (b - Ax) \\ \text{s.t.} \quad & Dx \geq d \\ & x \text{ integer} \end{aligned} \quad c$$

- For a fixed λ , $Z(\lambda)$ is assumed to be computed easily
- Important: compute the best lower bound

$$Z_D = \max_{\lambda \geq 0} Z(\lambda)$$

Lagrange relaxation for Integer Programming

- **Exercise** Given a constant value $\lambda = \lambda^{(k)}$, suppose $x^{(k)}$ is an optimal solution to the problem

$$\begin{aligned} Z(\lambda) = \min_x \quad & c^T x + \lambda^T (b - Ax) \\ \text{s.t.} \quad & Dx \geq d \\ & x \text{ integer} \end{aligned} \quad c$$

Explain why $s^{(k)} = b - Ax^{(k)}$ is a subgradient of function Z at $\lambda^{(k)}$?

Lagrange relaxation for Integer Programming

- Subgradient method for computing Z_D

```
Choose starting point  $\lambda^{(0)}$  (e.g.,  $\lambda^{(0)} = 0$ );  $k = 0$ 
while (STOP condition not reach) {
     $x^{(k)}$  is the solution of  $Z(\lambda^{(0)})$ 
    Compute subgradient  $s^{(k)} = b - Ax^{(k)}$  of function  $Z$  at  $\lambda^{(k)}$ 
    if  $s^{(k)} = 0$  then BREAK
     $\lambda^{(k+1)} = \max\{0, \lambda^{(k)} + \alpha^{(k)}s^{(k)}\}$  /*  $\alpha^{(k)}$  denote the step size */
     $k = k + 1$ 
}
```



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**Thank you
for your
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