

ADD VISION TO YOUR PI

Hasan Ijaz

September 13, 2015



EmbeddedLance

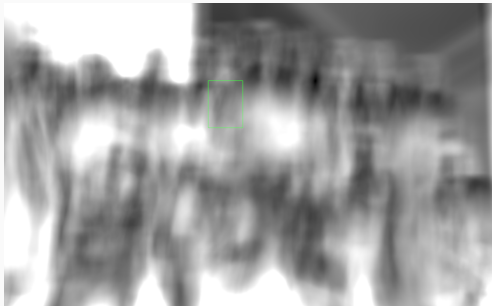
TEMPLATE MATCHING



Primary Components

- Source Image(I), Template Image(T), Metric







cvMatchTemplate

- source Image
- template Image
- result Image
- Metric
 - CV_TM_SQDIFF, CV_TM_SQDIFF_NORMED, CV_TM_CCORR, CV_TM_CCORR_NORMED, CV_TM_CCOEFF and CV_TM_CCOEFF_NORMED



CV_TM_SQDIFF

$$R(x, y) = \sum_{x', y'} (T(x', y') - I(x + x', y + y'))^2$$

CV_TM_SQDIFF_NORMED

$$R(x, y) = \frac{\sum_{x', y'} (T(x', y') - I(x + x', y + y'))^2}{\sqrt{\sum_{x', y'} T(x', y')^2 \cdot \sum_{x', y'} I(x + x', y + y')^2}}$$



CV_TM_CCORR

$$R(x, y) = \sum_{x', y'} (T(x', y') \cdot I(x + x', y + y'))$$

CV_TM_CCORR_NORMED

$$R(x, y) = \frac{\sum_{x', y'} (T(x', y') \cdot I(x + x', y + y'))}{\sqrt{\sum_{x', y'} T(x', y')^2 \cdot \sum_{x', y'} I(x + x', y + y')^2}}$$



CV_TM_CCOEFF

$$R(x, y) = \sum_{x', y'} (T'(x', y') \cdot I'(x + x', y + y'))$$

where

$$\begin{aligned} T'(x', y') &= T(x', y') - 1/(w \cdot h) \cdot \sum_{x'', y''} T(x'', y'') \\ I'(x + x', y + y') &= I(x + x', y + y') - 1/(w \cdot h) \cdot \sum_{x'', y''} I(x + x'', y + y'') \end{aligned}$$

CV_TM_CCOEFF_NORMED

$$R(x, y) = \frac{\sum_{x', y'} (T'(x', y') \cdot I'(x + x', y + y'))}{\sqrt{\sum_{x', y'} T'(x', y')^2 \cdot \sum_{x', y'} I'(x + x', y + y')^2}}$$

YOU CAN NOW PERFORM TEMPLATE MATCHING WITH
OPENFRAMEWORKS :)