

```
from google.colab import files
uploaded = files.upload()
```



选择文件 2 个文件

- **arr\_big\_data.csv**(application/vnd.ms-excel) - 141518235 bytes, last modified: 2020/4/30 - 100% done
  - **dep\_big\_data.csv**(application/vnd.ms-excel) - 139548527 bytes, last modified: 2020/4/30 - 100% done
- Saving arr\_big\_data.csv to arr\_big\_data.csv  
Saving dep\_big\_data.csv to dep\_big\_data.csv

```
import pandas as pd
data = pd.read_csv('arr_big_data.csv')
pd.DataFrame.from_records(data)
# del data['Unnamed: 0']
# data
```



on_pressure	visibilty	wind_speed	precip	fog	rain_drizzle	snow_ice_pellets	hail	thunder	t
1010.5	10.0	8.6	0.62	0	0	0	0	0	
1018.3	6.9	3.9	0.00	1	0	0	0	0	
938.9	10.0	6.2	0.00	0	0	0	0	0	
982.4	10.0	5.7	0.00	0	0	0	0	0	
1023.6	10.0	6.1	0.00	0	0	0	0	0	
...	...	...	...	...	...	...	...	...	...
989.3	10.0	5.3	0.00	0	0	0	0	0	
977.0	5.2	11.0	0.66	1	0	1	0	0	
0.0	10.0	10.7	0.00	0	0	0	0	0	
15.9	9.9	12.7	0.08	0	1	0	0	0	
994.7	10.0	13.0	0.00	0	0	0	0	0	

## ▼ Predictions for Arrival Delay

```
import pandas as pd
from sklearn.model_selection import train_test_split
import xgboost as xgb
from sklearn.metrics import mean_squared_error
import numpy as np

# data.dropna(axis=0, subset=['total_arr_delay'], inplace=True)

y = data.total_arr_delay
X = data.drop(['total_arr_delay'], axis=1).select_dtypes(exclude=['object'])

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=888)
```

## ▼ Mean Absolute Error results

```

data_dmatrix = xgb.DMatrix(data=X, label=y)
# dtrain = xgb.DMatrix(X_train, label=y_train)
# dtest = xgb.DMatrix(X_test, label=y_test)

xg_reg = xgb.XGBRegressor(objective='reg:linear', colsample_bytree = 0.3, learning_rate = 0.1,
                           max_depth = 5, alpha = 10, n_estimators = 10)

xg_reg.fit(X_train, y_train)

preds = xg_reg.predict(X_test)

rmse = np.sqrt(mean_squared_error(y_test, preds))
print("RMSE: %f" % (rmse))

↪ RMSE: 23.745028

```

## ▼ Using k-fold Cross Validation for model tuning

```

# params = {"objective": "reg:linear", 'colsample_bytree': 0.3, 'learning_rate': 0.1,
#           'max_depth': 5, 'alpha': 10}

# cv_results = xgb.cv(dtrain=data_dmatrix, params=params, nfold=3,
#                     num_boost_round=50, early_stopping_rounds=10, metrics="rmse", as_pandas=True)

params = {"objective": 'reg:squarederror', 'colsample_bytree': 0.3, 'learning_rate': 0.35,
          'max_depth': 7, 'alpha': 10, 'subsample': 0.7, 'gamma': 0.1}
cv_results_g1 = xgb.cv(dtrain=data_dmatrix, params=params, nfold=5,
                      num_boost_round=200, early_stopping_rounds=10, metrics="rmse", as_pandas=True)

cv_results_g1.head()

```

```

↪

```

	train-rmse-mean	train-rmse-std	test-rmse-mean	test-rmse-std
<b>0</b>	29.512923	0.038624	29.551592	0.161476
<b>1</b>	23.782266	2.543996	23.860410	2.448174
<b>2</b>	22.744114	3.272639	22.890786	3.134779
<b>3</b>	21.819126	3.650699	22.018433	3.552576
<b>4</b>	21.699805	3.681405	21.923173	3.580048

## ▼ Better RMSE

```

print((cv_results_g1["test-rmse-mean"]).tail(1))

↪ 199    13.856875
   Name: test-rmse-mean, dtype: float64

xg_reg = xgb.train(params=params, dtrain=data_dmatrix, num_boost_round=10)

```

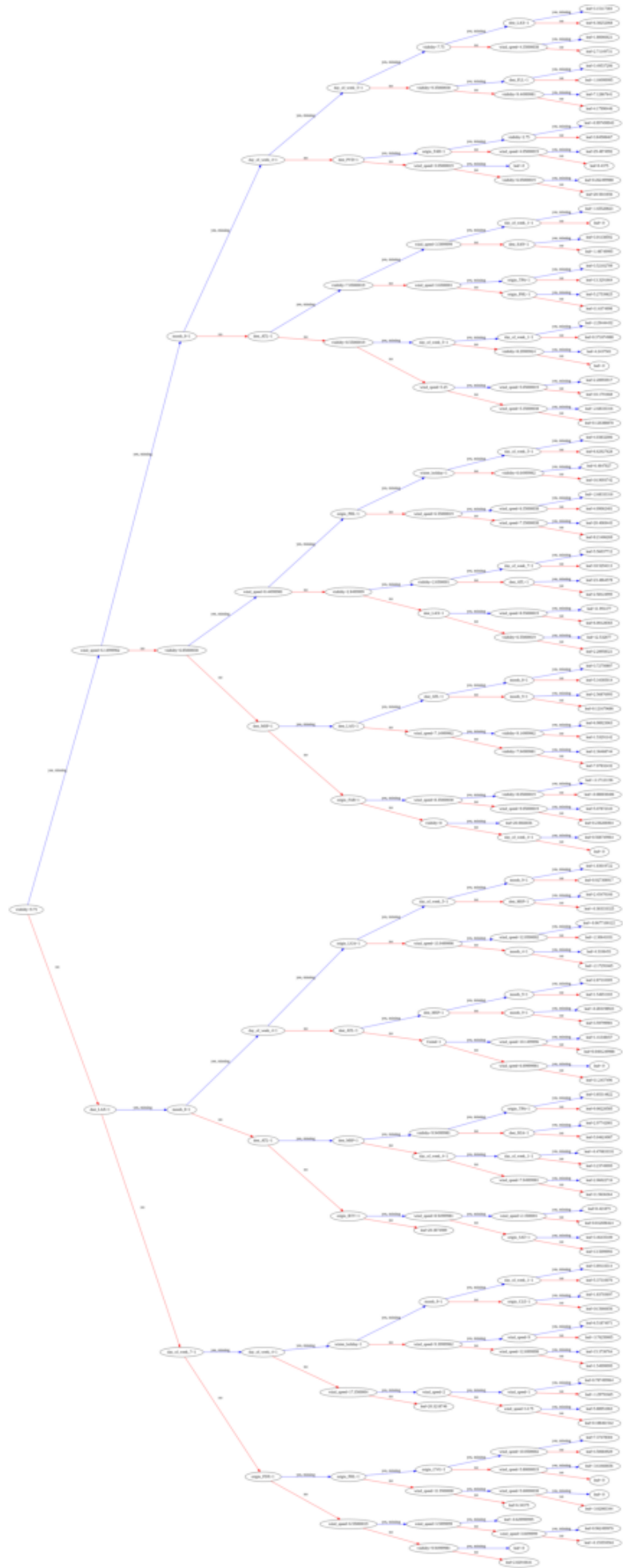
## ▼ Visualize Boosting Trees and Feature Importance

```
from numpy import loadtxt
from xgboost import XGBClassifier
from xgboost import plot_tree
import matplotlib.pyplot as plt

plt.rcParams["figure.figsize"] = 20,20
plot_tree(xg_reg, num_trees=0, rankdir='LR')
# xgb.plot_tree(xg_reg,num_trees=0)
# xgb.plot_tree(xg_reg, num_trees=0, rankdir='LR')
# plt.show()
```



<matplotlib.axes.\_subplots.AxesSubplot at 0x7f1bb7c230b8>



## ▼ Top Features

```
xgb.plot_importance(xg_reg)
plt.rcParams["figure.figsize"] = 20,20
plt.show()
```





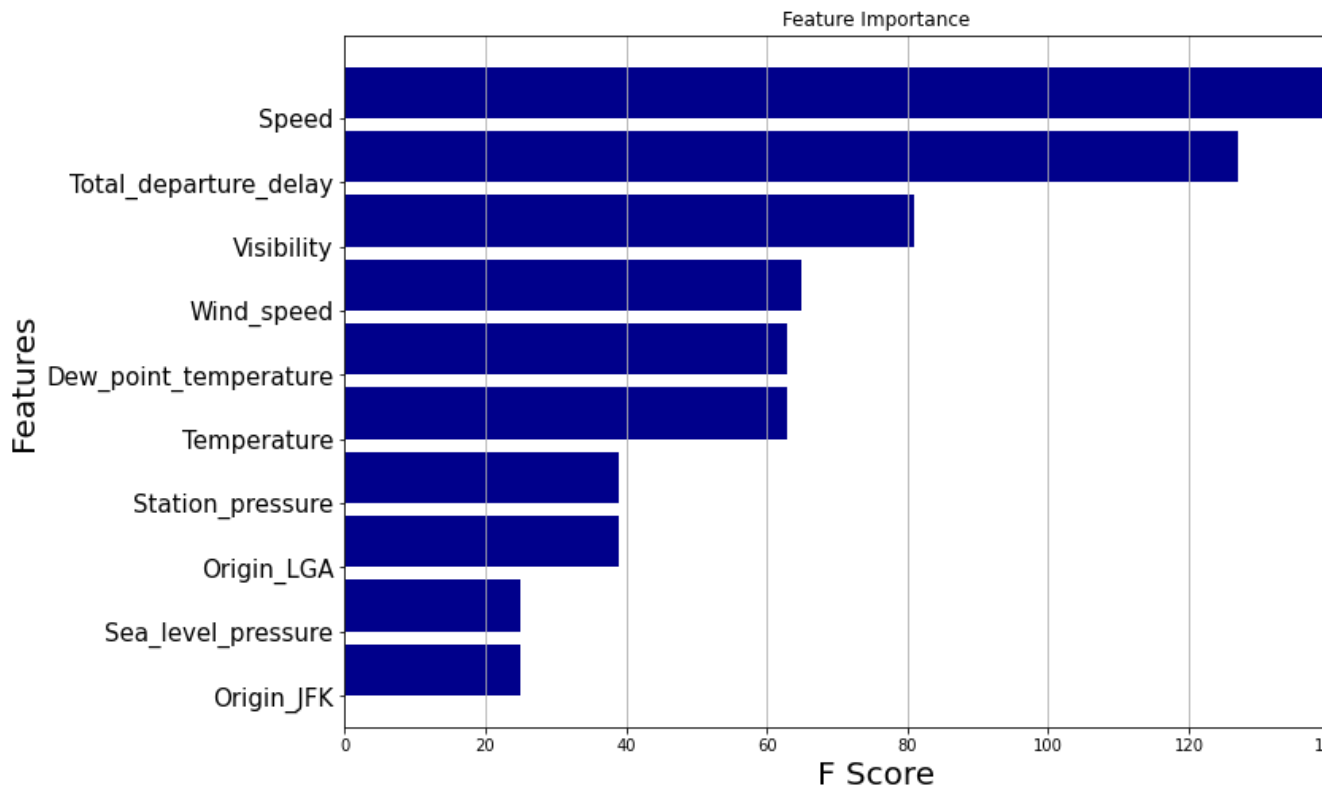
```
plt.figure(figsize=[12,8])

import matplotlib.pyplot as plt
from matplotlib import cm
import numpy as np

label = ['Speed','Total_departure_delay','Visibility','Wind_speed','Dew_point_temperature','Temperature','Sta
x = [144,127,81,65,63,39,39,25,25]

idx = np.arange(len(x))
# color = cm.jet(np.array(x)/max(x))
plt.barh(idx, x, color='darkblue')
plt.yticks(idx+0.4,label,fontsize=15)
plt.grid(axis='x')
plt.xlabel('F Score',fontsize=20)
plt.ylabel('Features',fontsize=20)
plt.title('Feature Importance')
plt.gca().invert_yaxis()

plt.show()
```



## ▼ Predictions for Departure Delay

```
import pandas as pd
data = pd.read_csv('dep_big_data.csv')
pd.DataFrame.from_records(data)
```



tation_pressure	visibilty	wind_speed	prcp	fog	rain_drizzle	snow_ice_pellets	hail	thunde
1010.5	10.0	8.6	0.62	0	0	0	0	
1018.3	6.9	3.9	0.00	1	0	0	0	
938.9	10.0	6.2	0.00	0	0	0	0	
982.4	10.0	5.7	0.00	0	0	0	0	
1023.6	10.0	6.1	0.00	0	0	0	0	
...	...	...	...	...	...	...	...	...
989.3	10.0	5.3	0.00	0	0	0	0	
977.0	5.2	11.0	0.66	1	0	1	0	
0.0	10.0	10.7	0.00	0	0	0	0	
15.9	9.9	12.7	0.08	0	1	0	0	
994.7	10.0	13.0	0.00	0	0	0	0	

```

import pandas as pd
from sklearn.model_selection import train_test_split
import xgboost as xgb
from sklearn.metrics import mean_squared_error
import numpy as np

# data.dropna(axis=0, subset=['total_dep_delay'], inplace=True)

y = data.total_dep_delay
X = data.drop(['total_dep_delay'], axis=1).select_dtypes(exclude=['object'])

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=123)

```

## ▼ Mean Absolute Error results

```

data_dmatrix = xgb.DMatrix(data=X, label=y)

xg_reg = xgb.XGBRegressor(objective='reg:linear', colsample_bytree=0.3, learning_rate=0.1,
                           max_depth=5, alpha=10, n_estimators=10)

xg_reg.fit(X_train, y_train)

preds = xg_reg.predict(X_test)

rmse = np.sqrt(mean_squared_error(y_test, preds))
print("RMSE: %f" % (rmse))

```

➞ RMSE: 27.676985



## ▼ Using k-fold Cross Validation for model tuning

```
# params = {"objective": "reg:linear", 'colsample_bytree': 0.3, 'learning_rate': 0.1,
#           'max_depth': 5, 'alpha': 10}

# cv_results = xgb.cv(dtrain=data_dmatrix, params=params, nfold=3,
#                     num_boost_round=50, early_stopping_rounds=10, metrics="rmse", as_pandas=True)

params = {"objective": 'reg:squarederror', 'colsample_bytree': 0.3, 'learning_rate': 0.1,
          'max_depth': 7, 'alpha': 10, 'subsample': 0.7, 'gamma': 0.1}
cv_results_g1 = xgb.cv(dtrain=data_dmatrix, params=params, nfold=5,
                      num_boost_round=200, early_stopping_rounds=10, metrics="rmse", as_pandas=True)

cv_results_g1.head()
```

```
↗
```

	train-rmse-mean	train-rmse-std	test-rmse-mean	test-rmse-std
<b>0</b>	33.669781	0.044570	33.679391	0.188015
<b>1</b>	32.377024	0.045918	32.402808	0.187011
<b>2</b>	31.299827	0.045561	31.335240	0.183580
<b>3</b>	30.384858	0.045082	30.436723	0.186172
<b>4</b>	29.630687	0.047559	29.693999	0.186524

## ▼ Better RMSE

```
print((cv_results_g1["test-rmse-mean"]).tail(1))
```

```
↗ 199    25.592875
   Name: test-rmse-mean, dtype: float64
```

```
xg_reg = xgb.train(params=params, dtrain=data_dmatrix, num_boost_round=10)
```

## ▼ Visualize Boosting Trees and Feature Importance

```
from numpy import loadtxt
from xgboost import XGBClassifier
from xgboost import plot_tree
import matplotlib.pyplot as plt

plt.rcParams["figure.figsize"] = 20, 20
plot_tree(xg_reg, num_trees=0, rankdir='LR')
# xgb.plot_tree(xg_reg, num_trees=0)
# xgb.plot_tree(xg_reg, num_trees=0, rankdir='LR')
# plt.show()
```

```
↗
```

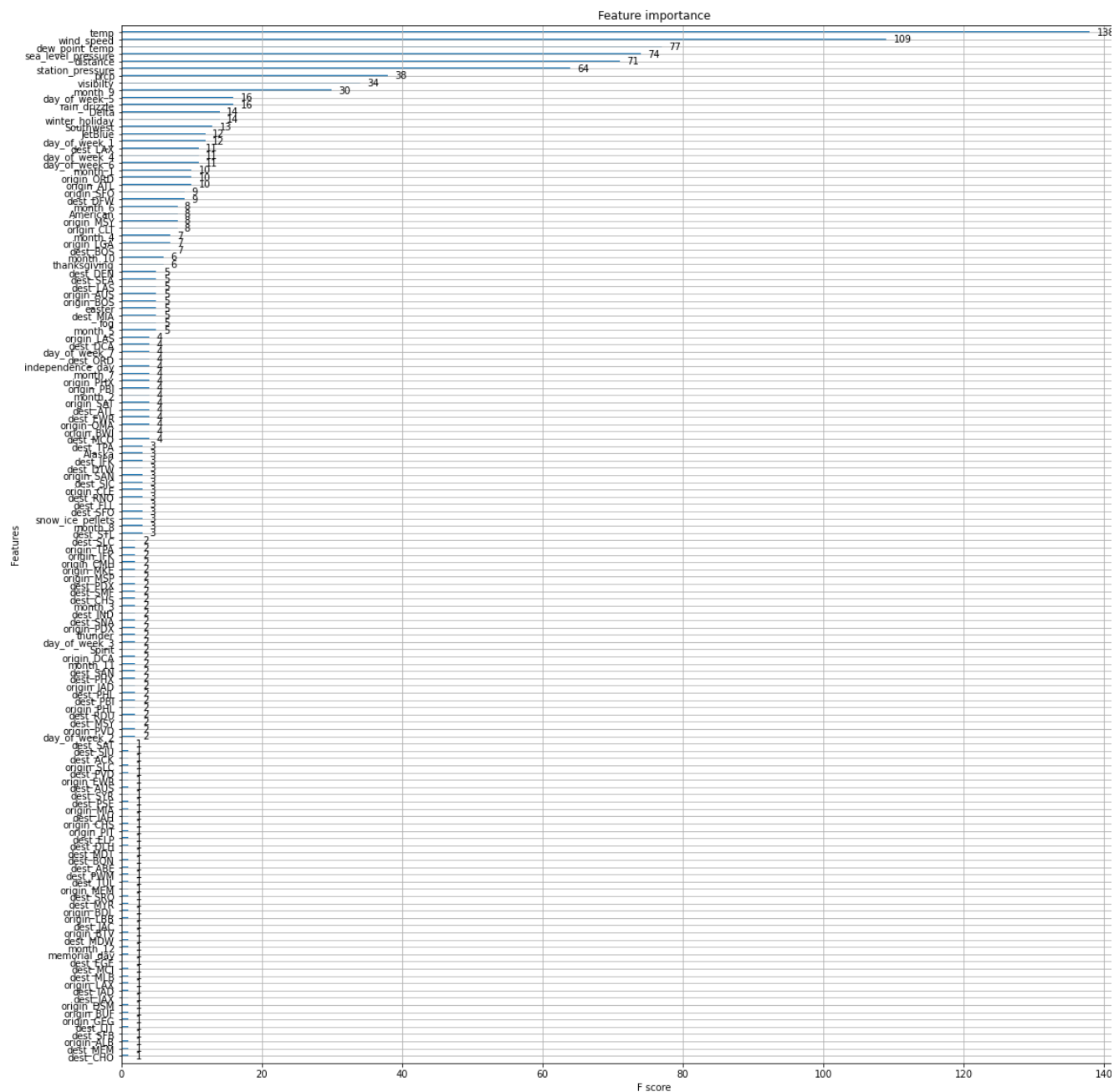
```
<matplotlib.axes._subplots.AxesSubplot at 0x7f1bb5dec588>
```



## ▼ Top Features

```
xgb.plot_importance(xg_reg)
plt.rcParams['figure.figsize'] = [5, 5]
plt.show()
```





```

plt.figure(figsize=[12,8])

import matplotlib.pyplot as plt
from matplotlib import cm
import numpy as np

label = ['Temperature','Wind_speed','Dew_point_temperature','Sea_level_pressure','Distance','Station_pressure','Precipitation','Visibility','Month_9','Day_of_week_5','Rain_drizzle']
x = [138, 109, 77, 74, 71, 64, 38, 34, 30, 16, 16]

idx = np.arange(len(x))
# color = cm.jet(np.array(x)/max(x))
plt.barh(idx, x, color='darkblue')
plt.yticks(idx+0.4, label, fontsize=15)
plt.grid(axis='x')
plt.xlabel('F Score', fontsize=20)
plt.ylabel('Features', fontsize=20)
plt.title('Feature Importance')
plt.gca().invert_yaxis()
plt.show()

```

