Askesis: Granular Cells

Eric Purdy

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1 Golgi cells perform non-maximal suppression of the granular cells

Non-maximal suppression is a special case of a phenomenon called "explaining away". When there are two possible causes of a particular event, knowing that one of the causes did take place lowers the probability that the other possible cause took place. The classic example is an alarm that goes off in response to a robbery, but which can also be set off by an earthquake. Both robbery and earthquake are very rare events, so their initial probability is low. If all we know is that the alarm went off, both possible causes become more likely. If we then learn that an earthquake did indeed take place, then the probability of a robbery goes back down to something like its initial probability - the earthquake has "explained away" the evidence provided by the alarm.

Consider now the example of signal coming from muscle spindles, which fire fastest when their muscle is at a particular length. However, they also fire more quickly than normal when the muscle is close to the correct length. Consider two neurons, A, which fires most quickly when a particular muscle is 12 inches long, and B, which fires most quickly when the muscle is 13 inches long. If we then learn that both A and B are firing quickly, but that B is firing more quickly, then our interpretation should be that the muscle is thirteen inches long. The firing of A is explained away - it comes from the muscle being close to the correct length.

We can apply this logic whenever we have two similar events that are unlikely to hold simultaneously.

In order for the non-maximal suppression performed by the Golgi cell to make sense, we need to know that the granular cells suppressed by a particular Golgi cell are similar to one another. Some amount of similarity is given just by the somatotopic mapping encoded by the mossy fibers - mossy fibers that are close to one another tend to respond to stimuli from regions of the body that are close to one another.

We thus postulate that the granular cells under a particular Golgi cell function somewhat like a flock of birds: at each time step, each granular cell updates its parameters to be more correlated with the Golgi cell, which can be thought of as the center of the flock. The overall effect is thus to create an ensemble of granular cells to which non-maximal suppression can be meaningfully applied.

Golgi cells have two kinds of dendrites, basal dendrites which receive excitatory input from mossy fibers, and apical dendrites which receive excitatory input from parallel fibers. It has been said ¹ that the two sets of dendrites are too far apart for the Golgi cell to perform summation, so we should think of the Golgi cell as firing when either 1) several nearby mossy fibers are firing, or 2) many of its parallel fiber inputs are firing.

The Golgi cell also acts to suppress a granular cell that has been firing for more than a certain amount of time. The granular cell is active only if it has only recently started firing. Thus its firing encodes the fact that we have very recently arrived at a very particular state. The recentness is known because the granular cell wasn't firing long enough ago to trigger the Golgi cell to suppress it. The particularity is known because the granular cell is suppressing all granular cells which are too similar to it but which are not firing as quickly.

Let $G_i(t)$ be the percentage of the time that the *i*-th granular cell was firing for a small window of time ending at time t. (So, $G_i(t) = 1$ would imply that the *i*-th granular cell is firing at its maximum rate.) Let \mathcal{G}_i be the set of granular cells (excluding the *i*-th granular cell itself) which receive inhibitory input from the same Golgi cell as the *i*-th granular cell. We then have

$$G_i^{nms}(t) = \begin{cases} 1 & G_i(t-1) < \theta \text{ and } \forall j \in \mathcal{G}_i, G_j(t) < G_i(t) \\ 0 & \text{otherwise} \end{cases},$$

for some threshold θ .

2 Maximizing the Variance

Let the *i*-th granular cell's output be defined by

$$G_i(x) = \sigma \left(\sum_j w_{ji} x_j - \theta_i \right).$$

For a fixed mean,

$$Var(G_i) = \mathbb{E}_x[(G_i(x) - \overline{G_i})^2]$$

$$= \sum_x p(x)(G_i(x) - \overline{G_i})^2$$

$$\frac{\partial Var(G_i)}{\partial w_{ji}} = \sum_x p(x)2(G_i(x) - \overline{G_i})\frac{\partial G_i(x)}{\partial w_{ji}}$$

$$= \sum_x 2p(x)(G_i(x) - \overline{G_i})G_i(x)(1 - G_i(x))x_j$$

¹Eccles et al.?

This leads to the update rule

$$\Delta w_{ii} = \eta G_i(x) (1 - G_i(x)) (G_i(x) - \overline{G_i}) x_i,$$

which yields the BCM rule.

If we allow the mean to vary

$$Var(G_i) = \mathbb{E}_x [(G_i(x) - \overline{G_i})^2]$$

$$= \sum_x p(x)(G_i(x) - \overline{G_i})^2$$

$$\frac{\partial Var(G_i)}{\partial w_{ji}} = \sum_x p(x)2(G_i(x) - \overline{G_i}) \left[\frac{\partial G_i(x)}{\partial w_{ji}} - \frac{\partial \overline{G_i}}{\partial w_{ji}} \right]$$

$$= \sum_x p(x)2(G_i(x) - \overline{G_i}) \left[G_i(x)(1 - G_i(x))x_j - \sum_y p(y)G_i(y)(1 - G_i(y))y_j \right]$$

$$= \sum_x p(x)2(G_i(x) - \overline{G_i})G_i(x)(1 - G_i(x))x_j$$

$$- \sum_x p(x)2(G_i(x) - \overline{G_i})\sum_y p(y)G_i(y)(1 - G_i(y))y_j$$

$$= \sum_x p(x)2(G_i(x) - \overline{G_i})G_i(x)(1 - G_i(x))x_j$$

$$- 2\left(\sum_x p(x)G_i(x) - \sum_x p(x)\overline{G_i}\right) \cdot \left(\sum_y p(y)G_i(y)(1 - G_i(y))y_j\right)$$

and this last term vanishes because $\sum_{x} p(x)G_i(x) = \overline{G_i} = \sum_{x} p(x)\overline{G_i}$. So we end up with the same partial derivative, and thus the same update rule.

3 Maximizing the Covariance

We wish to derive a learning rule for the mossy fiber-granular cell synapse that maximizes the covariance between the granular cell and the Golgi cell which receives and sends feedback to it. This will create the flocking behavior of the previous section. We actually modify this desire slightly: we want to maximize the covariance between the Golgi cell's activity and what the granular cell's activity would have been if it received no input from the Golgi cell². The inhibitory input from the Golgi cell will make the granular cell less correlated with it.

²Actually, having done the calculation both ways (with and without input from the Golgi cell), it doesn't make much difference. We omit the more complicated case (with the Golgi cell input), as it doesn't add much insight.

Recall the logistic function

$$\sigma(x) = \frac{1}{1 + e^{-x}}.$$

Recall that its derivative is

$$\frac{d}{dx}\sigma(x) = \frac{e^{-x}}{(1 + e^{-x})^2} = \sigma(x)(1 - \sigma(x)).$$

Consider the situation where we have a number of granular cells which all excite the same Golgi cell, and which receive inhibitory signals from that Golgi cell

Let x_i be a binary variable (either 0 or 1) that encodes whether the *i*-th mossy fiber fired at a particular time step. Let x be the vector of all the mossy fiber activations, so that x_i is 1 exactly when the *i*-th mossy fiber fires, and 0 otherwise. Let p(x) be the probability of observing the value x. We will assume that we receive a sample from this distribution at every time step. In this section, we will assume that each sample is independent of the others.

Let the *i*-th granular cell's output be defined by

$$G_i(x) = \sigma \left(\sum_j w_{ji} x_j - \theta_i \right).$$

Let the Golgi cell's output be defined by

$$Z(x) = \sigma \left(\alpha \sum_{i} G_i(x) - \varphi \right).$$

Note that we are assuming that the Golgi cell weights all of its inputs evenly. As discussed above, we wish to maximize the covariance between G_i and Z.

$$Cov(G_i, Z) = \mathbb{E}_x[G_i(x)Z(x)] - \mathbb{E}_x[G_i(x)]\mathbb{E}_y[Z(y)]$$

$$= \sum_x p(x)G_i(x)Z(x) - \sum_x p(x)G_i(x)\sum_y p(y)Z(y)$$

$$\frac{\partial Cov(G_i, Z)}{\partial w_{ji}} = \sum_x p(x) \left[\frac{\partial G_i(x)}{\partial w_{ji}}Z(x) + G_i(x)\frac{\partial Z(x)}{\partial w_{ji}} \right]$$

$$- \sum_x p(x)G_i(x)\sum_y p(y)\frac{\partial Z(y)}{\partial w_{ji}} - \sum_x p(x)\frac{\partial G_i(x)}{\partial w_{ji}}\sum_y p(y)Z(y)$$

Letting $\overline{Z} = \sum_y p(y)Z(y)$ and $\overline{G_i} = \sum_x p(x)G_i(x)$, we have

$$\begin{split} &= \sum_{x} p(x) \left[\frac{\partial G_{i}(x)}{\partial w_{ji}} Z(x) + G_{i}(x) \frac{\partial Z(x)}{\partial w_{ji}} \right] \\ &- \overline{G_{i}} \sum_{x} p(x) \frac{\partial Z(x)}{\partial w_{ji}} - \overline{Z} \sum_{x} p(x) \frac{\partial G_{i}(x)}{\partial w_{ji}} \\ &= \sum_{x} p(x) \left(Z(x) - \overline{Z} \right) \frac{\partial G_{i}(x)}{\partial w_{ji}} + \sum_{x} p(x) \left(G_{i}(x) - \overline{G_{i}} \right) \frac{\partial Z(x)}{\partial w_{ji}} \end{split}$$

Now, by the chain rule

$$\frac{\partial G_i(x)}{\partial w_{ji}} = \sigma' \left(\sum_k w_{ki} x_k - \theta_i \right) \cdot \frac{\partial}{\partial w_{ji}} \left(\sum_k w_{ki} x_k - \theta_i \right)$$
$$= G_i(x) (1 - G_i(x)) x_j$$

and similarly

$$\frac{\partial Z}{\partial w_{ji}}(x) = Z(x)(1 - Z(x))\frac{\partial}{\partial w_{ji}} \left(\sum_{k} \alpha G_k(x) - \phi\right)$$
$$= Z(x)(1 - Z(x))\alpha \frac{\partial G_i(x)}{\partial w_{ji}}$$
$$= \alpha Z(x)(1 - Z(x))G_i(x)(1 - G_i(x))x_j$$

Substituting this into the above, we arrive at

$$\begin{split} \frac{\partial Cov(G_i,Z)}{\partial w_{ji}} &= \sum_x p(x)(Z(x) - \overline{Z})G_i(x)(1 - G_i(x))x_j \\ &+ \sum_x p(x)(G_i(x) - \overline{G_i})\alpha Z(x)(1 - Z(x))G_i(x)(1 - G_i(x))x_j \\ &= \sum_x p(x)x_jG_i(x)(1 - G_i(x))\left[Z(x) - \overline{Z} + \alpha(G_i(x) - \overline{G_i})Z(x)(1 - Z(x))\right] \\ &= \alpha \sum_x p(x)x_jG_i(x)(1 - G_i(x))Z(x)(1 - Z(x))\left[G_i(x) - \overline{G_i} + \frac{Z(x) - \overline{Z}}{\alpha Z(x)(1 - Z(x))}\right] \end{split}$$

We can use stochastic gradient descent to maximize the covariance, yielding the update rule

$$\Delta w_{ji} = \eta \alpha x_j G_i(x) (1 - G_i(x)) Z(x) (1 - Z(x)) \left[G_i(x) - \overline{G_i} + F_{\alpha}(Z) \right],$$
 where $F_{\alpha}(Z) = \frac{Z - \overline{Z}}{\alpha Z(1 - Z)}$.

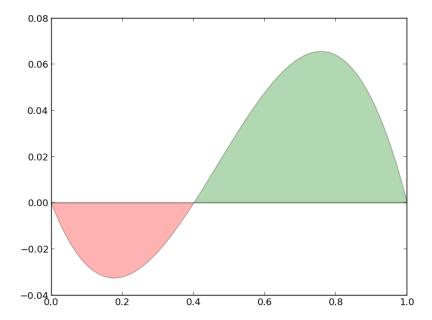


Figure 1: Δw_{ji} as a function of G_i , with $(\overline{G_i} - A) = 0.4$.

For a fixed Z, we then have (letting $A = F_{\alpha}(Z)$)

$$\Delta w_{ii} \propto x_i G_i(x) (1 - G_i(x)) (G_i(x) - (\overline{G_i} - A)),$$

which yields the BCM rule, with zeros at $G_i = 0, G_i = 1$, and $G_i = \overline{G_i} - A$. Note that the middle threshold, where Δw_{ji} switches from negative to positive, varies as a function of Z. Changing Z will thus switch the sign of Δw_{ii} for values of G close to the middle threshold.

4 Transition between Update Regimes

Recall that our update rule was

$$\Delta w_{ji} = \eta \alpha x_j G_i(x) (1 - G_i(x)) Z(x) (1 - Z(x)) \left[G_i(x) - \overline{G_i} + F_{\alpha}(Z) \right],$$

where
$$F_{\alpha}(Z)=\frac{Z-\overline{Z}}{\alpha Z(1-Z)}.$$
 There are thus three different regimes:

1. When Z is sufficiently high, then $(\overline{G_i} - F_{\alpha}(Z))$ is zero or less, and the term $\left[G_i(x) - \left(\overline{G_i} - F_{\alpha}(Z)\right)\right]$ is always positive, so our update is always positive.

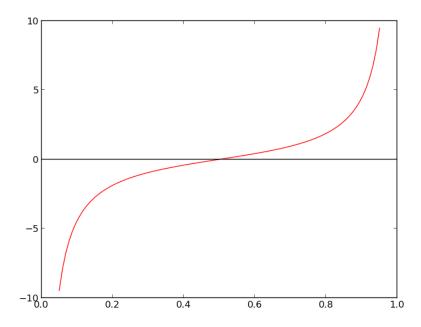


Figure 2: $F_{\alpha}(Z) = \frac{Z - \overline{Z}}{\alpha Z(1 - Z)}$, with $\overline{Z} = 0.5$ and $\alpha = 1$

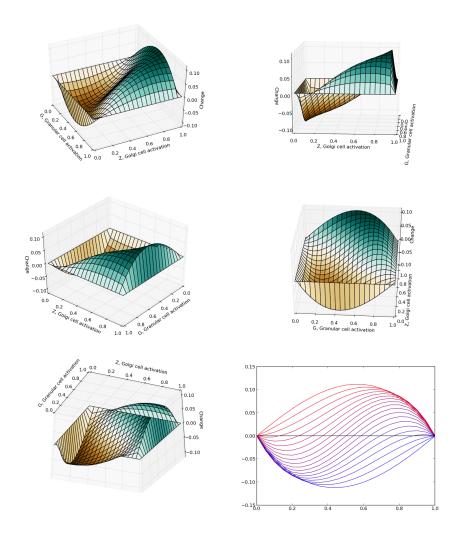


Figure 3: Change in mossy fiber-granular cell synapse weight as a function of Granular cell firing rate (G) and Golgi cell firing weight (Z). The bottom right shows the change as a function of G; each curve corresponds to one value of Z, redder indicating higher Z, bluer indicating lower Z. We are using the parameters $\overline{G} = 0.5, \overline{Z} = 0.5, \alpha = 5$.

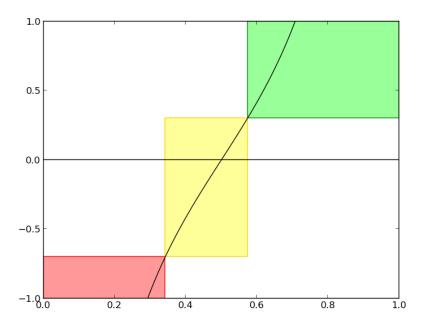


Figure 4: The three different regimes: the red box is when Z is low and the update is always negative. The green box is when Z is high and the update is always positive. The yellow box is when Z is in between and the update follows the BCM rule. With $\overline{Z}=0.5, \overline{G_i}=0.3,$ and $\alpha=1.$

- 2. When Z is sufficiently low, then $(\overline{G_i} F_{\alpha}(Z))$ is more than 1, and the term $[G_i(x) (\overline{G_i} F_{\alpha}(Z))]$ is always negative, so our update is always negative.
- 3. When Z is in between, and $(\overline{G_i} F_{\alpha}(Z))$ is between 0 and 1, we have the BCM rule.

The positive regime starts with Z satisfying

$$\overline{G_i} - F(Z) = 0$$

The negative regime starts with Z satisfying

$$\overline{G_i} - F(Z) = 1$$

Both of these equations can be solved with the quadratic formula, but we omit the solutions, since they don't shed much light.

5 Excitability of Granular Cells

We can also calculate $\frac{\partial Cov(G_i,Z)}{\partial \theta_i}$ to get an update rule for the excitability of the granular cell. We omit the calculation, as it is analogous to the one above, but the resulting update rule is:

$$\Delta\theta_i = -\eta G_i(x)(1 - G_i(x))Z(x)(1 - Z(x)) \left[G_i(x) - \overline{G_i} + F_\alpha(Z) \right].$$

Increasing θ_i makes it harder for the granular cell to fire. We should expect that low activation of the granular cell leads to higher θ_i , which leads to less excitability. High activation of the granular cell should lead to lower θ_i , which leads to higher excitability. ³

Looking at the three regimes:

- 1. When Z is high, $G_i F_{\alpha}(Z)$ is always zero or less, so $\Delta \theta_i$ is always negative, so the granular cell becomes more excitable.
- 2. When Z is low, the granular cell becomes less excitable.
- 3. When Z is in-between, the sign of the update depends on G_i .

6 Flocking Experiment

We conducted some flocking experiments using 15 random functions of the form

$$G_i = \sigma(ax + by + c).$$

 $^{^3}$ This seems like a poor choice.

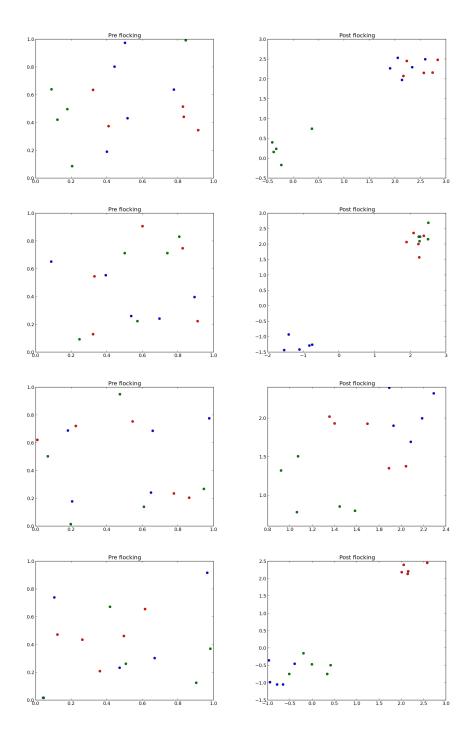


Figure 5: Results of performing flocking on functions of the form $G_i = \sigma(ax + by + c)$. Each function is plotted at point (a, b) for its specific weights a and b. The left column shows the functions before flocking, the right column the corresponding trial after flocking.

We grouped the points into three groups (red, green, and blue), and applied the flocking update rule on random input for 10,000 iterations. The results are shown in Figure ??. Note the randomness of the input and the similarity of the output. Also note that we often wind up with overlapping clusters; this is less likely in higher dimensions.

7 Predictions

Prediction 7.1. Mossy fiber - granular cell synapse should follow a learning rule like that given above in Section 3.

Prediction 7.2. The Purkinje cells that a particular basket or stellate cell innervates should suppress the same deep nuclear cell. Or, more weakly, they should suppress deep nuclear cells with similar firing patterns. This is necessary for the basket/stellate cell to make sense as the site for negative weights of the corresponding Purkinje cell.

Prediction 7.3. Each Golgi cell should inhibit roughly the same set of granular cells which excite it. These granular cells should also be excited by the same set of mossy fibers that excite the Golgi cell. (I think this is already known to be true, but I'm not sure.) This is necessary for the granular cells under a particular Golgi cell to make sense as a flock.

Prediction 7.4. If you prevent a Golgi cell from firing, the granular cells it outputs to should be somewhat correlated in their firing patterns. If you then allow the Golgi cell to fire, the granular cells should become more correlated. (This only holds true if the granular cells are being fed a stream of mossy fiber activations from the same distribution as the one they learned from.)

Prediction 7.5. Two mossy fiber inputs to a Golgi cell should be more correlated than two mossy fibers which are the same distance apart but which do not synapse on the same Golgi cell. This would be the result of following the flocking rule.

Prediction 7.6. Either the inferior olive receives a copy of the signal from some command mossy fibers, or the negative pathway does not suppress state transitions. In the latter case, there should be no active synapses between Purkinje cells and state cells.

Prediction 7.7. Each inferior olive cell should send a collateral to the same deep nuclear cell that its Purkinje cell(s) projects to. If this is not the case, then the two deep nuclear cells (the one receiving the collateral and the one receiving the output of the Purkinje cell) should exhibit similar firing patterns. This is necessary for the inferior olive cell to have a single coherent meaning: that it fires when we desire to see more firing from the relevant deep nuclear cell.

Prediction 7.8. The mossy fibers of state cells, context cells, and command cells should be intermingled when they reach the granular cell, so that each

granular cell can potentially form synapses with mossy fibers of all three types. This increases the representational ability of the system.