MNS Project 2: Learning of Grid Cells

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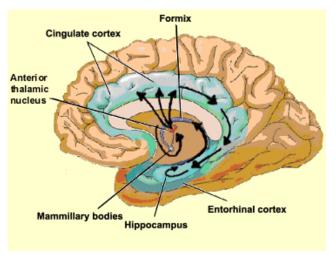
BCCN

February 9^{th} 2016

Structure

- Introduction
- Modelling details
- Results

Introduction



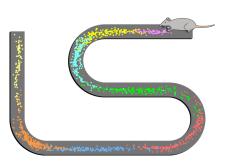
In Hippocampus and the medial enthorhinal cortex (mEC) various types of neurons have been found that encode an animals spacial location.

Cells encoding spacial location

- Place cells
- Grid cells
- Head-direction cells
- Head-Grid-Conjunctive cells

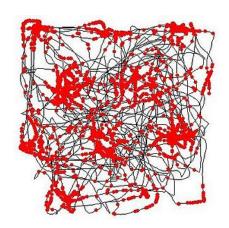
Properties of place cells

Located in hippocampus. Activated when the animal enters a specific region of the environment - the *place field*.



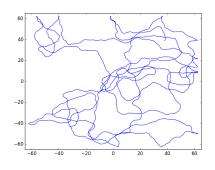
Properties of grid cells

- Located in medial enthorhinal cortex (mEC). Activated at several spacial positions. The firing map shows an equally spaced hexagonal pattern.
- Mostly independent of visual stimulus
- Different grid cells show different spacing, orientation and size of their patterns.
- Spacing from 25cm to 3m.



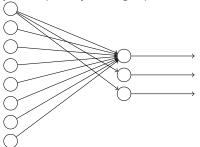
Rat trajectory

- Square environment of size 125×125 cm.
- Speed: v = 0.4 m/s
- Initialization with random position
- Every 10ms: chose new direction from a gaussian distribution with
 - \bullet $\mu=$ previous direction
 - $\sigma = 0.2$



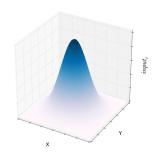
Model: Overview

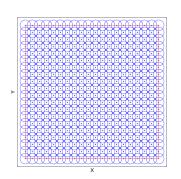
input layer output layer magic processing output



Model: Input Layer



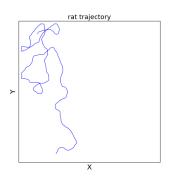


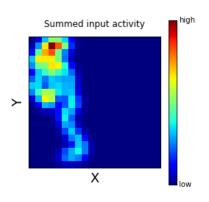


$$input_i = \exp\left(-\frac{||rat_pos-center_i||^2}{50}\right)$$

Model: Input Layer







Model: Output Layer



$$h_j = \sum_i w_{ij} \cdot input_i$$

Model: Output Layer

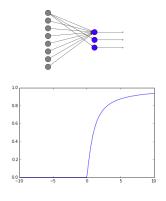


$$h_j(t) = \sum_i w_{ij} \cdot input_i(t)$$

ightarrow adaptation dynamics:

$$\tau^{+} \frac{d}{dt} r_{j}^{+} = h_{j}(t) - r_{j}^{+}(t) - r_{j}^{-}(t)$$
$$\tau^{-} \frac{d}{dt} r_{j}^{-}(t) = r_{j}^{-}(t)$$

Model: Output Layer



$$h_j(t) = \sum_i w_{ij} \cdot input_i(t)$$

ightarrow adaptation dynamics:

$$\tau^{+} \frac{d}{dt} r_{j}^{+} = h_{j}(t) - r_{j}^{+}(t) - r_{j}^{-}(t)$$
$$\tau^{-} \frac{d}{dt} r_{j}^{-}(t) = r_{j}^{-}(t)$$
$$\rightarrow \text{output:}$$

$$\begin{aligned} output_j(t) &= \\ \frac{2}{\pi} \arctan(g \cdot (r_j^+(t) - \mu)) \cdot \theta(r_j^+(t) - \mu) \\ q - \text{gain}, \ \mu - \text{threshold} \end{aligned}$$

Model: Weight Updates

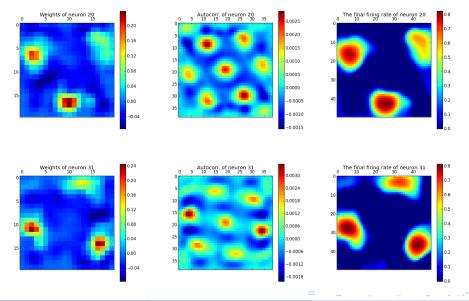


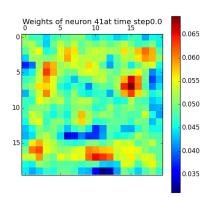
$$h_j = \sum_i w_{ij} \cdot input_i$$

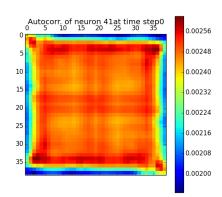
- ightarrow How to determine the weights w_{ij} ?
- $\rightarrow \mbox{ Hebbian learning dynamics}$

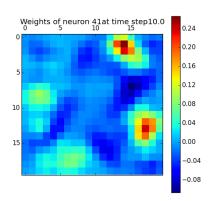
$$w_{ij}(t + \Delta) = w_{ij}(t) + \epsilon (input_i(t) \cdot output_j - \sum_s input_i(s) \cdot \sum_s output_j(s))$$

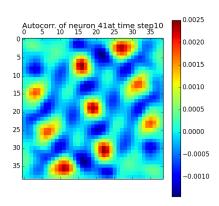
Cherrypicked final weights

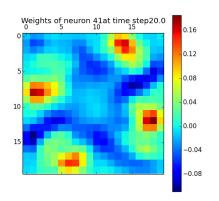


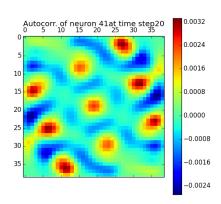


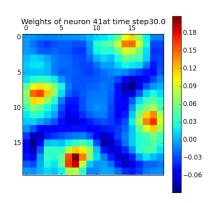


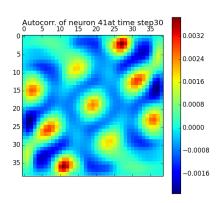


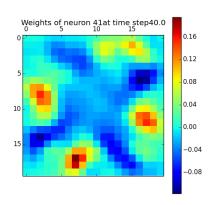


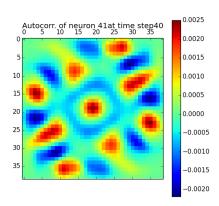


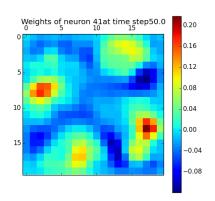


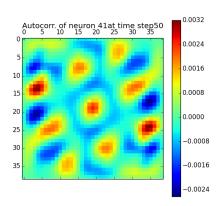


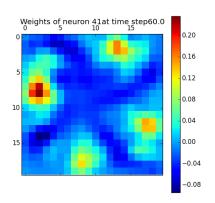


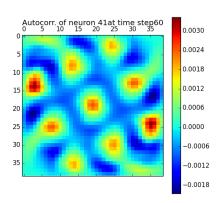


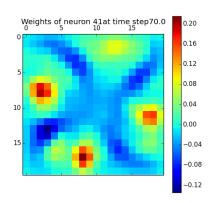


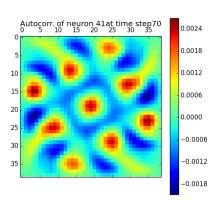


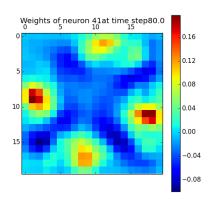


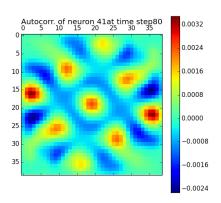


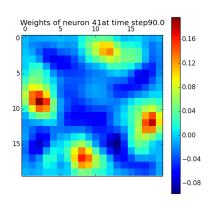


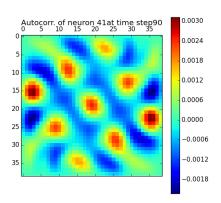


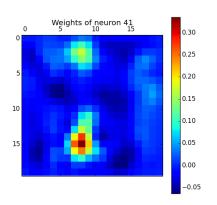


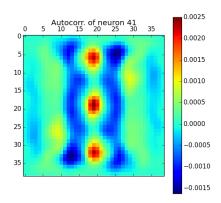












Thanks. Questions?