

NAG Library Installation

SPK Library relies on some of the components from NAG Library such as a re-entrant optimizer, matrix multiplication routine and so on. The installation package comes as a simple compressed archive. The installer is expected to unpack the package and manually place headers and libraries in appropriate places. This tutorial explains these steps.

Table of Contents

Installation	1
Verification	2

Installation

1. As ordinary user, download the linux version of the Nag C library from whitechuck:

```
cd /tmp
scp whitechuck:/opt/download/lux06dbt.Z .
```

2. Become root,

```
su -
```

3. Unpack the archive

```
cd /tmp
tar xvzf lux06dbt.Z
```

4. Install the library and headers

```
cd cllux06db
cp libnagc* /usr/local/lib
cp include/* /usr/local/include
cd /usr/local/lib
ln -s libnagc.so.6 libnagc.so
```

5. Make sure /usr/local/flexlm/licenses/license.dat contains the following license key entries:

```
FEATURE NAG_CL NAG 9.900 01-aug-2004 0 BC5E444363B0CF819FC9 "ANY" DEMO
FEATURE NAG_FD NAG 9.900 01-aug-2004 0 CCDE34737BB5C767BCC6 "ANY" DEMO
FEATURE NAG_FL NAG 29.900 01-aug-2004 0 AC9E44335FBDCF5F94E2 "ANY" DEMO
FEATURE NAG_FN NAG 9.900 01-aug-2004 0 BC3E3473619FD15D8CE0 "ANY" DEMO
FEATURE IRIS_Explorer NAG 9.900 01-aug-2004 0 1CEE44345A79C7B1394 "ANY" DEMO
INCREMENT NAGWaref95 NAG 9.900 01-aug-2004 0 FCEE4483B7ADA5C0CA49 "ANY" DEMO
FEATURE NAGWareFtools NAG 9.900 01-aug-2004 0 ECDEB423F87A659A99EB "ANY" DEMO
```

6. Clean up

```
cd /tmp
rm lux06dbt.Z
```

```
rm -rf cllux06db
```

Verification

1. Copy and past the following code into a new file and save the file in somewhere as nag_test.cpp.

```
#include <iostream>
#include <valarray>
#include <cassert>
#include <string>

using namespace std;
static void NagDgemm(
    char transa,          // Is matrix A transpose (At) or non (An)?
    char transb,          // Is matrix B transpose (Bt) or non (Bn)?
    int m,                // (An) A->nr, (At) A->nc
    int n,                // (Bn) B->nc, (Bt) B->nr
    int k,                // (An) A->nc, (Bn) B->nr, (At) A->nr, (Bt) B->nc
    double alpha,         // scalar
    const double A[],     // column major matrix
    const double B[],     // column major matrix
    double beta,          // scalar
    double C[],           // column major matrix
    int ldc,              // leading dimension of C
    int lda,               // leading dimension of A
    int ldb,               // leading dimension of B
    int info);

static const valarray<double> multiply( const valarray<double> & A, int nColsA,
    const valarray<double>& B, int nColsB );

void printInMatrix( const valarray<double> & A, int cols );

int main()
{
    //      /      \
    //      |      |
    // A =  |  1  2  |
    //      |  3  4  |
    //      \      /
    //
    valarray<double> A(4);
    for( int i=0; i<4; i++ )
        A[i] = i+1;

    //      /      \
    //      |      |
    // B =  |  2  |
    //      |  2  |
    //      \      /
    //
    valarray<double> B(2.0, 2);

    valarray<double> C = multiply( A, 2, B, 1 );
    valarray<double> correctC( 2 );
    correctC[0] = 6.0;
    correctC[1] = 14.0;

    cout << "A = " << endl;
    printInMatrix( A, 2 );
    cout << endl;
```

```

    cout << "B = " << endl;
    printInMatrix( B, 1 );
    cout << endl;

    cout << "C = " << endl;
    printInMatrix( C, 1 );
    cout << endl;

    if( C[0] == correctC[0] && C[1] == correctC[1] )
        cout << "Test passed successfully!\n" << endl;
    else
        cout << "Test failed!\n" << endl;
    return 0;
}

void printInMatrix( const valarray<double>& A, int cols )
{
    int rows = A.size() / cols;
    assert( rows * cols * A.size() );

    for( int i=0; i<rows; i++ )
    {
        cout << "[ ";
        for( int j=0; j<cols; j++ )
        {
            cout << A[j + i * cols] << " ";
        }
        cout << "]" << endl;
    }
}

const valarray<double> multiply( const valarray<double>& A, int nColsA,
                                const valarray<double>& B, int nColsB )
{
    using namespace std;

    if( A.size() == 0 || B.size() == 0 )
        return valarray<double>(0);

    int nRowsA = A.size() / nColsA;
    assert( nRowsA * nColsA == A.size() );

    int nRowsB = B.size() / nColsB;
    assert( nRowsB * nColsB == B.size() );

    assert( nColsA == nRowsB );

    double pA[ A.size() ];
    for( int i=0; i<A.size(); i++ )
        pA[i] = A[i];
    double pB[ B.size() ];
    for( int i=0; i<B.size(); i++ )
        pB[i] = B[i];
    double pC[ nRowsA * nColsB ];

    NagDgemm('n', 'n', nRowsA, nColsB, nColsA, 1.0, pA, pB, 0.0, pC);
    return C;
};

/*****
*
*                               NagDgemm Implementation
*
* Cpp interface to Nag's dgemm (f06yac)
*
* dgemm (f06yac) performs real matrix-matrix multiplication:
*   C = (alpha * A B) + (beta * C)
*****/

```

```

*
* This function terminates the program when receives an invalid ar-
gument value.
*
*****/
# include <stdio.h>
# include <stdlib.h>

extern "C"{
# include "nag.h"
# include "nag_types.h"
# include "nag_names.h"
# include "nagf06.h"
}
static void NagDgemm(
    char transa,          // Is matrix A transpose (At) or non (An)?
    char transb,          // Is matrix B transpose (Bt) or non (Bn)?
    int m,                // (An) A->nr, (At) A->nc
    int n,                // (Bn) B->nc, (Bt) B->nr
    int k,                // (An) A->nc, (Bn) B->nr, (At) A->nr, (Bt) B-
>nc
    double alpha,         // scalar
    const double A[],      // row major matrix
    const double B[],      // row major matrix
    double beta,          // scaler
    double C[]            // row major matrix
){
    const char* errmsg =
        "\nNagDgemm received an invalid value in the %s argument (%c)...terminating pr

    MatrixTranspose transA;
    MatrixTranspose transB;

    if( transa == 'n' || transa == 'N' ){
        transA = NoTranspose;
    }
    else if( transa == 't' || transa == 'T' ){
        transA = Transpose;
    }
    else{
        fprintf(stderr, errmsg, "1st", transa);
        exit(-1);
    }

    // for matrix B
    if( transb == 'n' || transb == 'N' ){
        transB = NoTranspose;
    }
    else if( transb == 't' || transb == 'T' ){
        transB = Transpose;
    }
    else{
        fprintf(stderr, errmsg, "2nd", transb);
        exit(-1);
    }

    dgemm(
        transA,
        transB,
        (Integer) m,
        (Integer) n,
        (Integer) k,
        alpha,
        A,
        (Integer) k,

```

```

        B,
        (Integer) n,
        beta,
        C,
        (Integer) n
    );
}

```

2. Compile `nag_test.cpp` and statically link to the NAG library which requires two other libraries: `pthreadlib` and `mlib`:

```
g++ nag_test.cpp -static -lnagc -lpthread -lm -o test
```

The following warning messages will be displayed. Please ignore.

```

s09zzft.o(.text+0x479b): `sys_errlist' is deprecated; use `strerror' or `str-
error_r' instead
s09zzft.o(.text+0x4785): `sys_nerr' is deprecated; use `strerror' or `str-
error_r' instead

```

3. If the above compilation completed successfully, you should be able to run the built executable `test`:

```
./test
```

and see the following output on screen.

```
[Honda@pasta myTemp]$ ./test
```

```

A =
[ 1 2 ]
[ 3 4 ]

```

```

B =
[ 2 ]
[ 2 ]

```

```

C =
[ 6 ]
[ 14 ]

```

```
Test passed successfully!
```

