## 11 Neural Network

## 11.1 Feedforward neural networks

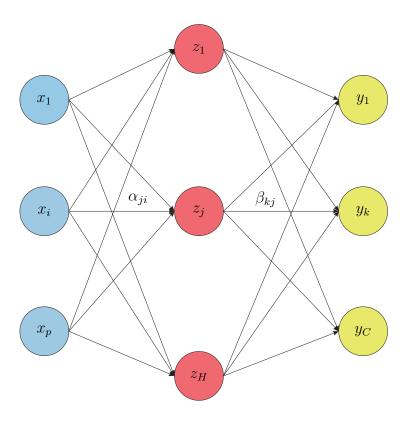


Figure 1: Neural Network with single hidden layer

We denote the complete set of weights by  $\boldsymbol{\theta}$ , which consists of

$$oldsymbol{ heta} = \left\{egin{array}{c} oldsymbol{lpha} \ oldsymbol{eta} \end{array}
ight.$$

Each of the  $\alpha_j$  and  $\beta_k$  is a subset vector of  $\boldsymbol{\alpha}$  and  $\boldsymbol{\beta}$ ,

$$oldsymbol{lpha} = egin{pmatrix} oldsymbol{lpha}_1 & oldsymbol{lpha}_2 & \cdots & oldsymbol{lpha}_H \ oldsymbol{lpha} = oldsymbol{eta}_1 & oldsymbol{lpha}_{21} & \cdots & oldsymbol{lpha}_{H1} \ oldsymbol{lpha}_{12} & oldsymbol{lpha}_{22} & \cdots & oldsymbol{lpha}_{H2} \ dots & dots & \ddots & dots \ oldsymbol{lpha}_{1D} & oldsymbol{lpha}_{2D} & \cdots & oldsymbol{lpha}_{HD} \end{pmatrix}$$

$$\boldsymbol{\alpha}^{T} = j \begin{pmatrix} \alpha_{11} & \alpha_{12} & \cdots & \alpha_{1D} \\ \alpha_{21} & \alpha_{22} & \cdots & \alpha_{2D} \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_{H1} & \alpha_{H2} & \cdots & \alpha_{HD} \end{pmatrix}$$

$$\boldsymbol{\beta} = \begin{pmatrix} \boldsymbol{\beta}_1 & \boldsymbol{\beta}_2 & \cdots & \boldsymbol{\beta}_C \\ \boldsymbol{\beta}_1 & \boldsymbol{\beta}_2 & \cdots & \boldsymbol{\beta}_C \\ \end{pmatrix} = \begin{pmatrix} \beta_{11} & \beta_{21} & \cdots & \beta_{C1} \\ \beta_{12} & \beta_{22} & \cdots & \beta_{C2} \\ \vdots & \vdots & \ddots & \vdots \\ \beta_{1H} & \beta_{2H} & \cdots & \beta_{CH} \end{pmatrix}$$

$$\boldsymbol{\beta}^{T} = k \begin{pmatrix} \beta_{11} & \beta_{12} & \cdots & \beta_{1H} \\ \beta_{21} & \beta_{22} & \cdots & \beta_{2H} \\ \vdots & \vdots & \ddots & \vdots \\ \beta_{K1} & \beta_{K2} & \cdots & \beta_{CH} \end{pmatrix}$$

We can write the overall model as follows:

$$x_n \xrightarrow{\alpha} \mathbf{a}_n \xrightarrow{g} \mathbf{z}_n \xrightarrow{\beta} \mathbf{b}_n \xrightarrow{h} \hat{\mathbf{y}}_n$$

 $x_n$  is a vector of length D containing D variables for the nth observation. That is,

$$x_n = \begin{pmatrix} x_{n1} \\ x_{n2} \\ \vdots \\ x_{nD} \end{pmatrix} \tag{11.1}$$

In general, we have the following models extract from the overall model,

$$a_{nj} = \boldsymbol{\alpha}_{j}^{T} x_{n}, \ j = 1, \dots, H$$

$$z_{nj} = g(a_{nj}), \ j = 1, \dots, H$$

$$b_{nk} = \boldsymbol{\beta}_{k}^{T} \mathbf{z}_{n}, \ k = 1, \dots, C$$

$$\hat{y}_{nk} = h(b_{nk}), \ k = 1, \dots, C$$

From the above equations, it's not hard to see that  $\hat{y}_{nk}$  consisted from a bunch of other functions, this can be interpreted as,

$$\hat{\mathbf{y}}_n = h(\mathbf{b}_n) = h(\boldsymbol{\beta}^T \mathbf{z}_n) = h(\boldsymbol{\beta}^T g(\mathbf{a}_n)) = h(\boldsymbol{\beta}^T g(\boldsymbol{\alpha}^T x_n))$$
(11.2)

Summarize the points above,  $x_n$  is the nth observation,  $\mathbf{a}_n = \boldsymbol{\alpha}^T x_n$  be the pre-synaptic hidden layer, and  $\mathbf{z}_n = g(\mathbf{a}_n)$  be the post-synaptic hidden layer, where g is some transfer function. We typically use g(a) = sigm(a), but we may also use g(a) = tanh(a). We now convert this hidden layer to the output layer. Let  $\mathbf{b}_n = \boldsymbol{\beta}^T \mathbf{z}_n$  be the pre-synaptic output layer, and  $\hat{\mathbf{y}}_n = h(\mathbf{b}_n)$  be the post-synaptic output layer, where h is another non-linearity. For a regression model, we use  $h(\mathbf{b}) = \mathbf{b}$ ; for binary classification, we use  $h(\mathbf{b}) = [sigm(b_1), \dots, sigm(b_c)]$ ; for multi-class classification, we use  $h(\mathbf{b}) = \mathcal{S}(\mathbf{b})$ .

## 11.2 Backpropagation neural networks

We now discuss how to cimpute the gradient vector of the NLL(negative log likelihood) by applying the chain rule of calculus. The resulting algorithm is known as backpropagation.

In the regression case, with C outputs, the NLL is given by the by the squared error:

$$J(\boldsymbol{\theta}) = -\sum_{n} \sum_{k} (\hat{y}_{nk}(\boldsymbol{\theta}) - y_{nk})^{2}$$
(11.3)

In the classification case, with C classes, the NLL is given by the cross entropy,

$$J(\boldsymbol{\theta}) = -\sum_{n} \sum_{k} y_{nk} \log \hat{y}_{nk}(\boldsymbol{\theta})$$
 (11.4)

Our task is to compute  $\frac{d}{d\theta}J$ . The overall gradient is obtained by summing over n, we will derive this for each n separately or we will perform mini-batch and summing the batch size. Let us start by considering the output layer weights. We have

$$\nabla_{\beta_k} J_n = \frac{\partial J_n}{\partial b_{nk}} \nabla_{\beta_k} b_{nk} = \frac{\partial J_n}{\partial b_{nk}} \mathbf{z}_n \tag{11.5}$$

Assuming h is canonical link function for the output GLM, then

$$\frac{\partial J_n}{\partial b_{nk}} = \delta_{nk}^{\beta} = (\hat{y}_{nk} - y_{nk}) \tag{11.6}$$

So the overall gradient is

$$\nabla_{\beta_k} J_n = \delta_{nk}^{\beta} \mathbf{z}_n \tag{11.7}$$

which is the pre-synaptic input to the output layer, namely  $\mathbf{z}_n$ , times the error signal, namely  $\delta_{nk}^{\beta}$ .

For the input layer weights, we have

$$\nabla_{\alpha_j} J_n = \frac{\partial J_n}{\partial a_{nj}} \nabla_{\alpha_j} a_{nj} = \delta_{nj}^{\alpha} x_n \tag{11.8}$$

The first level error signal  $\delta_{nj}^{\alpha}$ ,

$$\delta_{nj}^{\alpha} = \frac{\partial J_n}{\partial a_{nj}} = \sum_{k} \frac{\partial J_n}{\partial b_{nk}} \frac{\partial b_{nk}}{\partial a_{nj}}$$
(11.9)

where,

$$\frac{\partial b_{nk}}{\partial a_{nj}} = \frac{\partial b_{nk}}{\partial z_{nj}} \frac{\partial z_{nj}}{\partial a_{nj}} = \beta_{kj} g'(a_{nj})$$
(11.10)

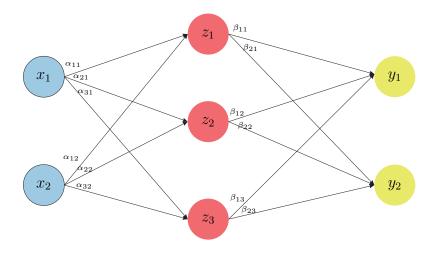
So, the first level error signal  $\delta_{nj}^{\alpha}$  is,

$$\delta_{nj}^{\alpha} = \frac{\partial J_n}{\partial a_{nj}} = \sum_k \delta_{nk}^{\beta} \beta_{kj} g'(a_{nj})$$
(11.11)

In the end, the input layer weights looks like

$$\nabla_{\alpha_j} J_n = \delta_{nj}^{\alpha} x_n = \sum_k \delta_{nk}^{\beta} \beta_{kj} g'(a_{nj}) x_n$$
 (11.12)

## 11.2.1 Example 1



$$\boldsymbol{\alpha} = \begin{pmatrix} \boldsymbol{\alpha}_1 & \boldsymbol{\alpha}_2 & \boldsymbol{\alpha}_3 \end{pmatrix} \tag{11.13}$$

$$\boldsymbol{\alpha}^T = \begin{pmatrix} \alpha_{11} & \alpha_{12} \\ \alpha_{21} & \alpha_{22} \\ \alpha_{31} & \alpha_{32} \end{pmatrix} \tag{11.14}$$

$$\boldsymbol{\beta} = \begin{pmatrix} \boldsymbol{\beta}_1 & \boldsymbol{\beta}_2 \end{pmatrix} \tag{11.15}$$

$$\boldsymbol{\beta}^{T} = \begin{pmatrix} \beta_{11} & \beta_{12} & \beta_{13} \\ \beta_{21} & \beta_{22} & \beta_{23} \end{pmatrix}$$
 (11.16)

The first output layer,

$$a_1 = \boldsymbol{\alpha}_1^T x = \sum_{i=1}^2 \alpha_{1i} x_i$$
$$a_2 = \boldsymbol{\alpha}_2^T x = \sum_{i=1}^2 \alpha_{2i} x_i$$
$$a_3 = \boldsymbol{\alpha}_3^T x = \sum_{i=1}^2 \alpha_{3i} x_i$$

So,

$$\mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \tag{11.17}$$

The post-synaptic hidden layer

$$\mathbf{z} = \begin{pmatrix} z_1 \\ z_2 \\ z_3 \end{pmatrix} = \begin{pmatrix} g(a_1) \\ g(a_2) \\ g(a_3) \end{pmatrix} \tag{11.18}$$

The second output layer,

$$b_1 = \boldsymbol{\beta}_1^T \mathbf{z} = \sum_{j=1}^3 \beta_{1j} z_j$$
$$b_2 = \boldsymbol{\beta}_2^T \mathbf{z} = \sum_{j=1}^3 \beta_{2j} z_j$$

The estimated response,

$$\hat{\mathbf{y}} = \begin{pmatrix} h(b_1) \\ h(b_2) \end{pmatrix} = \begin{pmatrix} \hat{y}_1 \\ \hat{y}_2 \end{pmatrix}$$