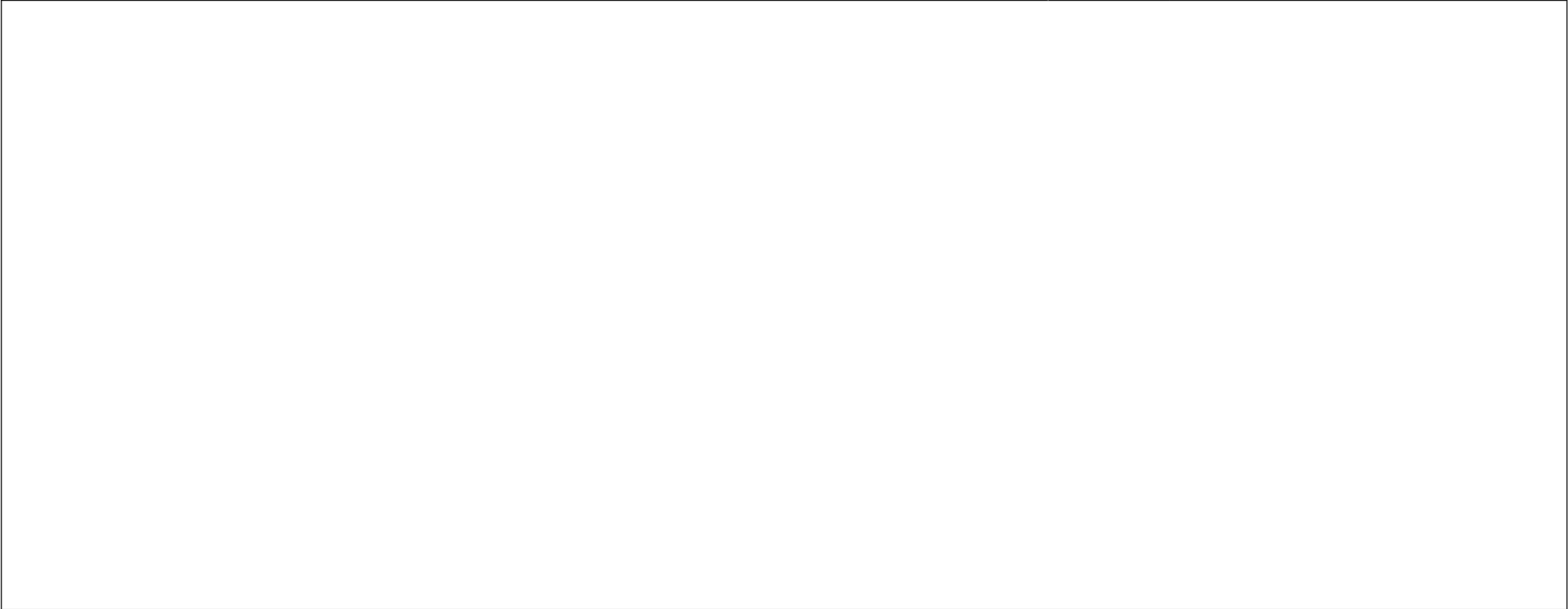


ID	Task Name	Duration	Feb 5, '12						Feb
			M	F	T	S	W	S	
5	Order inverter and related cabling	5 days							
1	CAD Alan's Drive Base	5 days							
6	Get Kinect (Do we have one?)	7 days							
19	Figure out what the deal is with HS network comms to IRC5	1 day							
28	Find Out About Alan's HDD Contents from Tony	7 days							
31	Have Wyatt Contact ABB About HS Network Comms (?)	10 days							
4	Order computer	5 days							
2	CAD/find models of all components	1 day							
8	Finalize sensor package	1 day							
3	Figure out component mounting and weight distribution	5 days							
7	Fabricate all mechanical parts (frame rails, mounting brackets)	5 days							
24	Set Up Laptop for ROS Dev	1 day							
22	Disassemble Alan	1 day							
16	Create ROS representation of IRB-120 (Joint/Link model, tied to 3D model for visualization)	2 days							
32	Assemble Alan's Computer	1 day							
9	Rebuild Alan's Frame	1 day							
11	Set Up Alan's new computer	1 day							
10	Rewire Allen	5 days							
13	Calibrate Allen's systems	2 days							
12	Run rebuilt Alan's Mobile Base/Localization	3 days							
17	Create ROS representation of full robot, incorporating existing drive base model and IRB-120 model	5 days							
25	Test ROS Setup by Bringing Jinx Online and Driving	1 day							
26	Test Alan by Bringing Online and Driving	2 days							
27	Test Alan LIDAR Localization	1 day							
29	Set up Solidworks Workstation (Alan PC)	1 day							
23	Test IRB-120 Jogging Ability	1 day							

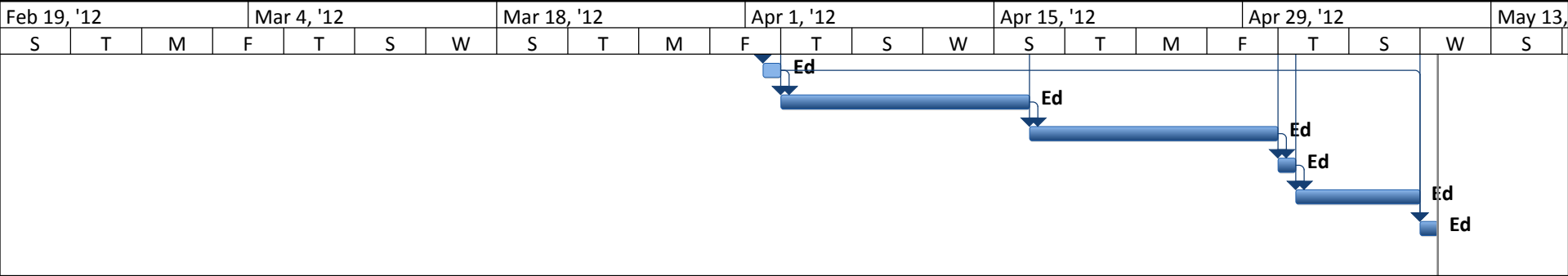
Project: project.mpp Date: Sun 2/5/12	Task		External Milestone		Manual Summary Rollup	
	Split		Inactive Task		Manual Summary	
	Milestone		Inactive Milestone		Start-only	
	Summary		Inactive Summary		Finish-only	
	Project Summary		Manual Task		Deadline	
	External Tasks		Duration-only		Progress	

ID	Task Name	Duration	Feb 5, '12					Feb
			M	F	T	S	W	S
20	Test IRB-120 with ABB software (prove it moves, run a small RAPID program)	1 day						
15	Set up IRB-120 to respond to control from network	10 days						
14	Create ROS Position Control Package for IRB-120	10 days						
30	Test Fully Assembled Robot under Teleop Control	1 day						
18	Demonstrate working playback of robot model from recorded data	5 days						
21	Test IRB-120 on Inverter Power	1 day						
33	Integrate Arm and DT Control (Path Planning)							



Project: project.mpp Date: Sun 2/5/12	Task		External Milestone		Manual Summary Rollup	
	Split		Inactive Task		Manual Summary	
	Milestone		Inactive Milestone		Start-only	
	Summary		Inactive Summary		Finish-only	
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	External Tasks		Duration-only		Progress	





Project: project.mpp Date: Sun 2/5/12	Task		External Milestone		Manual Summary Rollup	
	Split		Inactive Task		Manual Summary	
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