

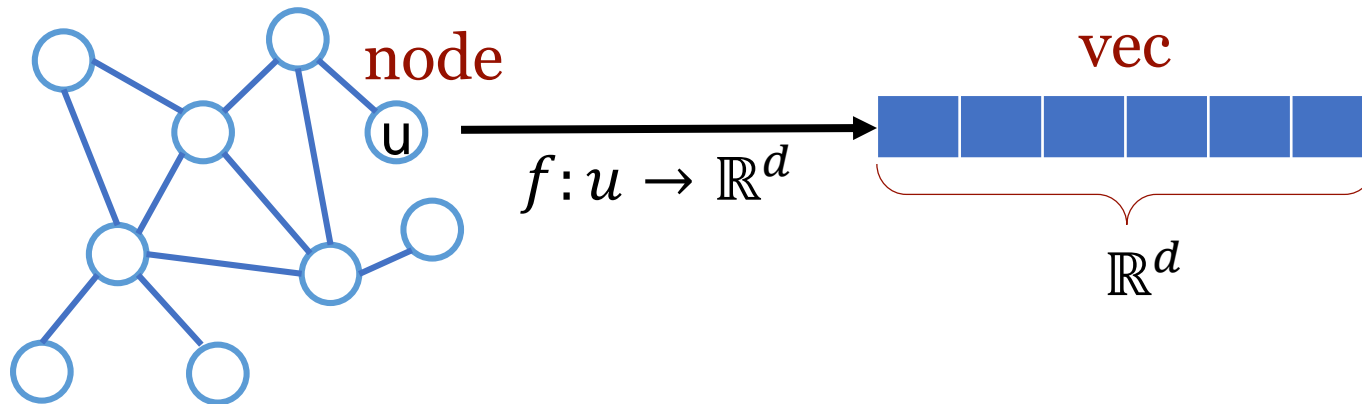
# 课程安排

- 1. GNN基础
- 2. 基于random walk的图嵌入算法
- 3. GCN
- 4. 研究方向说明
- 5. 语言模型GraphSAGE
- 6. Attention机制与GAT
- 7. 实例讲解：HGNN
- 8. 异质图算法
- 9. VGAE和graph GAN
- 10. 实例讲解：DSTG
- 11. GNN模型的解释性
- 12. How to write
- 13. beyondGNN
- 14. 论文选会以及如何让你的论文更容易发表

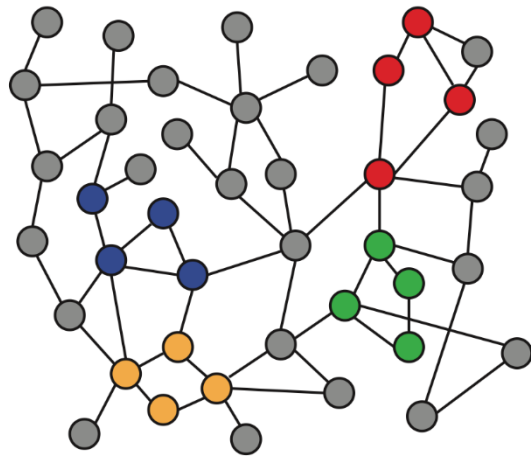
# Node Embedding

# Feature Learning in Graphs

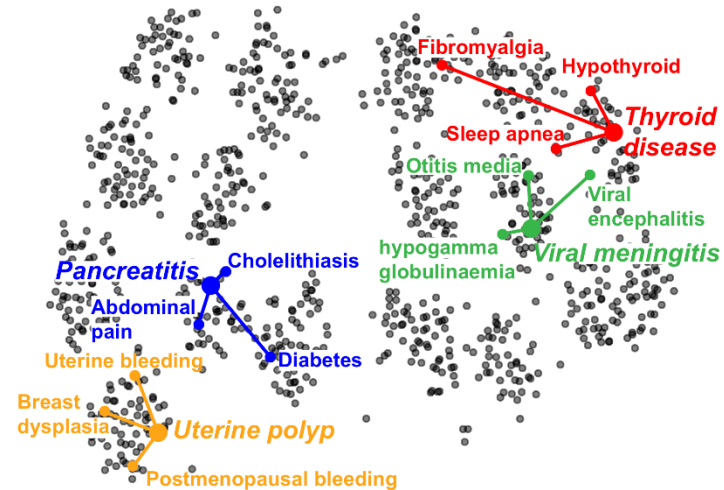
**Goal:** Efficient **task-independent** feature learning for machine learning in networks!



# Embedding Nodes



**Input**



**Output**

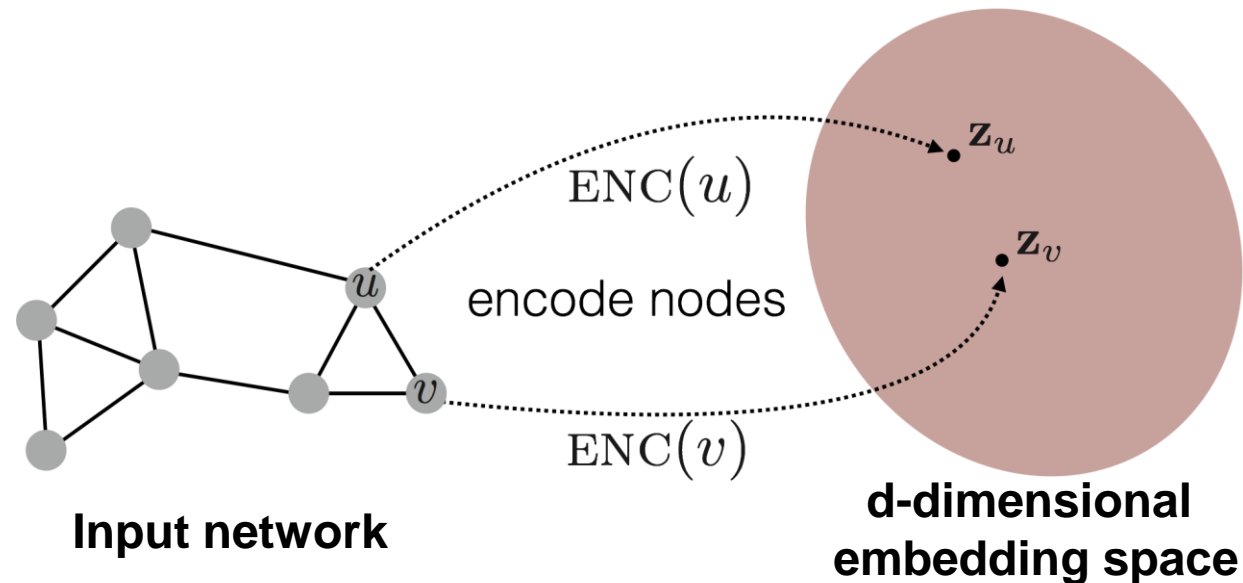
**Intuition:** Map nodes to  $d$ -dimensional embeddings such that similar nodes in the graph are embedded close together

# Feature Learning in Graphs

Assume we have a graph  $G$ :

- $V$  is the vertex set
- $A$  is the adjacency matrix (assume binary)
- **No node features or extra information is used!**

**Goal:** Map nodes so that **similarity in the embedding space (e.g., dot product)** approximates **similarity in the network**

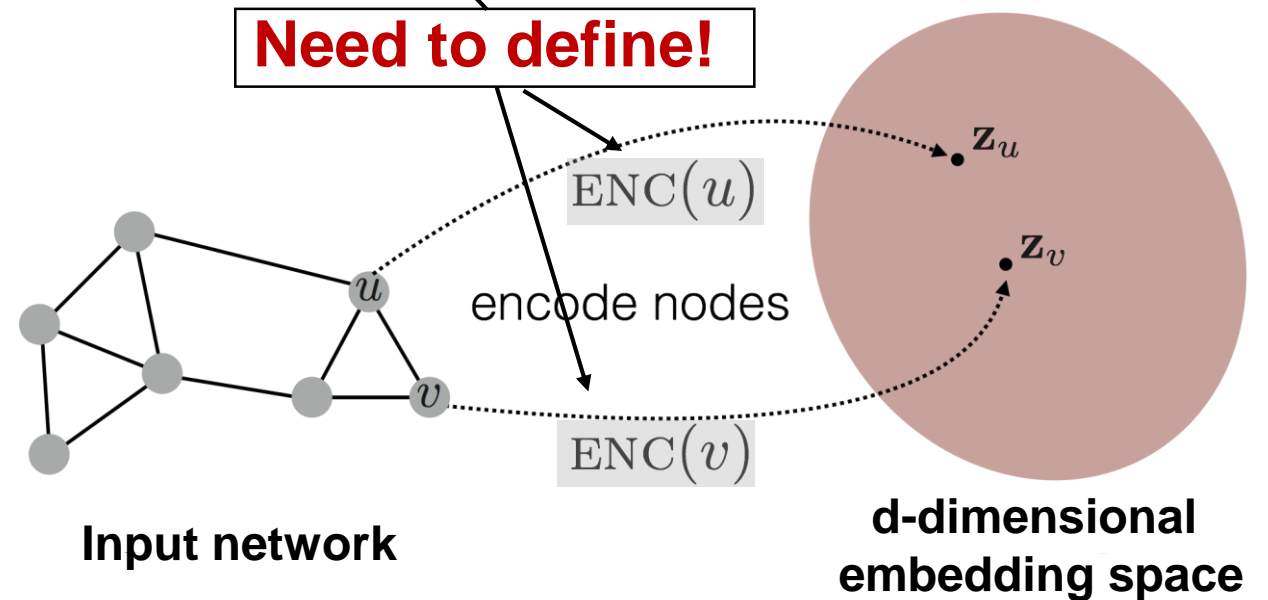


# Embedding Nodes

1. **Define an encoder** (a function ENC that maps node  $u$  to embedding  $\mathbf{z}_u$ )
2. **Define a node similarity function** (a measure of similarity in the input network)
3. **Optimize parameters of the encoder so that:**

$$\text{similarity}(u, v) \approx \mathbf{z}_v^\top \mathbf{z}_u$$

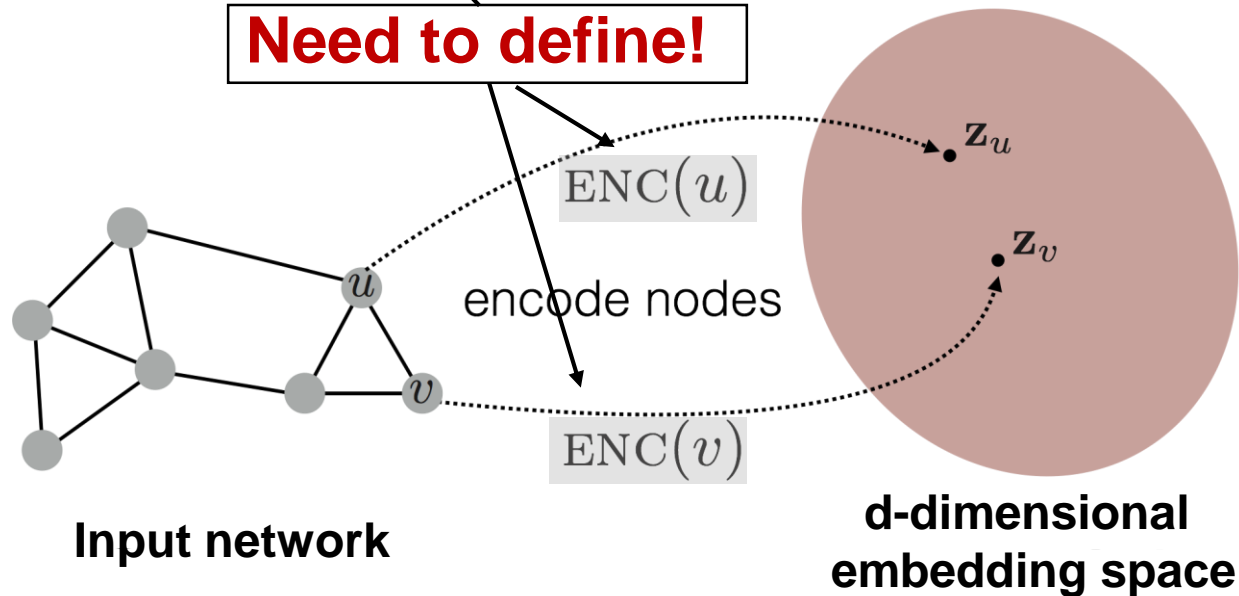
**Goal:**  $\text{similarity}(u, v) \approx \mathbf{z}_v^\top \mathbf{z}_u$



# Embedding Nodes

**Goal:**  $\text{similarity}(u, v) \approx \mathbf{z}_v^\top \mathbf{z}_u$

**Need to define!**



1. **Encoder** maps a node to a d-dimensional vector:

$$\text{ENC}(v) = \mathbf{z}_v$$

node in the input graph d-dimensional embedding

2. **Similarity function** defines how relationships in the input network map to relationships in the embedding space:

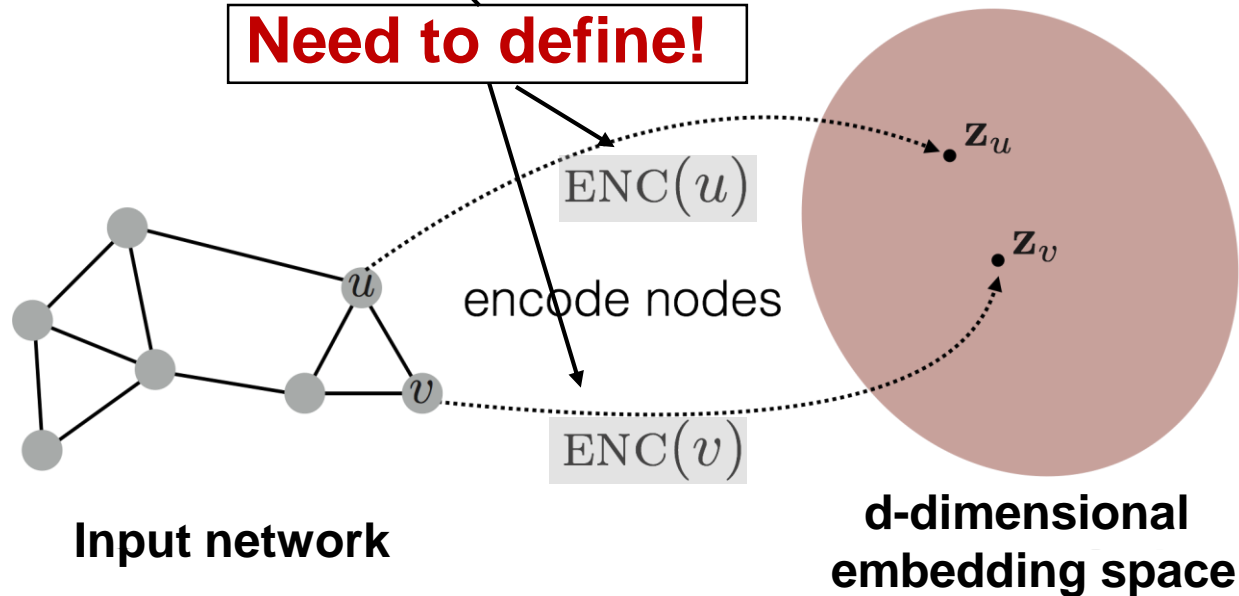
$$\text{similarity}(u, v) \approx \mathbf{z}_v^\top \mathbf{z}_u$$

Similarity of  $u$  and  $v$  in the network dot product between node embeddings

# Embedding Nodes

**Goal:**  $\text{similarity}(u, v) \approx \mathbf{z}_v^\top \mathbf{z}_u$

**Need to define!**



- Many methods use similar encoders:
  - **node2vec**, **DeepWalk**, LINE, struc2vec
- These methods use different notions of node similarity:
  - they are connected?
  - they share many neighbors?
  - they have similar local network structure?
  - etc.



# Adjacency-based Similarity

- **Similarity function** is the edge weight between  $u$  and  $v$  in the network
- **Intuition:** Dot products between node embeddings approximate edge existence

$$\mathcal{L} = \sum_{(u,v) \in V \times V} \| \mathbf{z}_u^\top \mathbf{z}_v - \mathbf{A}_{u,v} \|^2$$

loss (what we want to minimize)

sum over all node pairs

embedding similarity

(weighted) adjacency matrix for the graph

# Adjacency-based Similarity

$$\mathcal{L} = \sum_{(u,v) \in V \times V} \|\mathbf{z}_u^\top \mathbf{z}_v - \mathbf{A}_{u,v}\|^2$$

- Find embedding matrix  $\mathbf{Z} \in \mathbb{R}^{d \times |V|}$  that minimizes the loss  $\mathcal{L}$ :
  - **Option 1: Stochastic gradient descent (SGD)**
    - Highly scalable, general approach
  - **Option 2: Solve matrix decomposition solvers**
    - e.g., SVD or QR decompositions
    - Need to derive specialized solvers

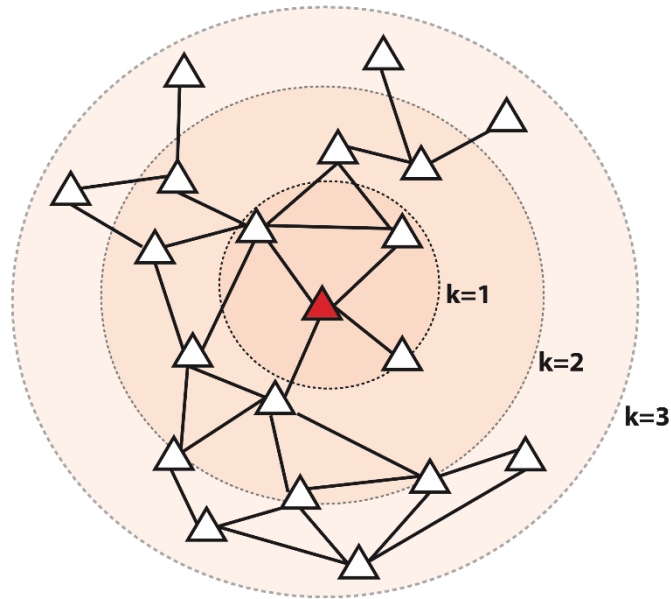
# Random Walk

Material based on:

- Perozzi et al. 2014. [DeepWalk: Online Learning of Social Representations](#). *KDD*.
- Grover et al. 2016. [node2vec: Scalable Feature Learning for Networks](#). *KDD*.
- Ribeiro et al. 2017. [struc2vec: Learning Node Representations from Structural Identity](#). *KDD*.

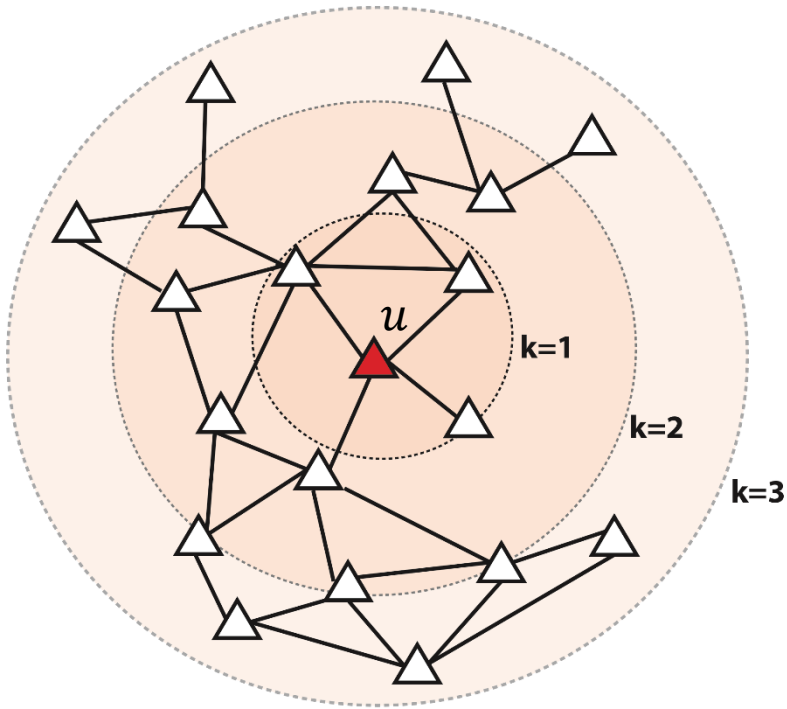
# Multi-Hop Similarity

**Idea:** Define node similarity function based on higher-order neighborhoods



- **Red:** Target node
  - **k=1:** 1-hop neighbors
    - $A$  (i.e., adjacency matrix)
  - **k=2:** 2-hop neighbors
  - **k=3:** 3-hop neighbors
- How to stochastically define these higher-order neighborhoods?**

# Unsupervised Feature Learning

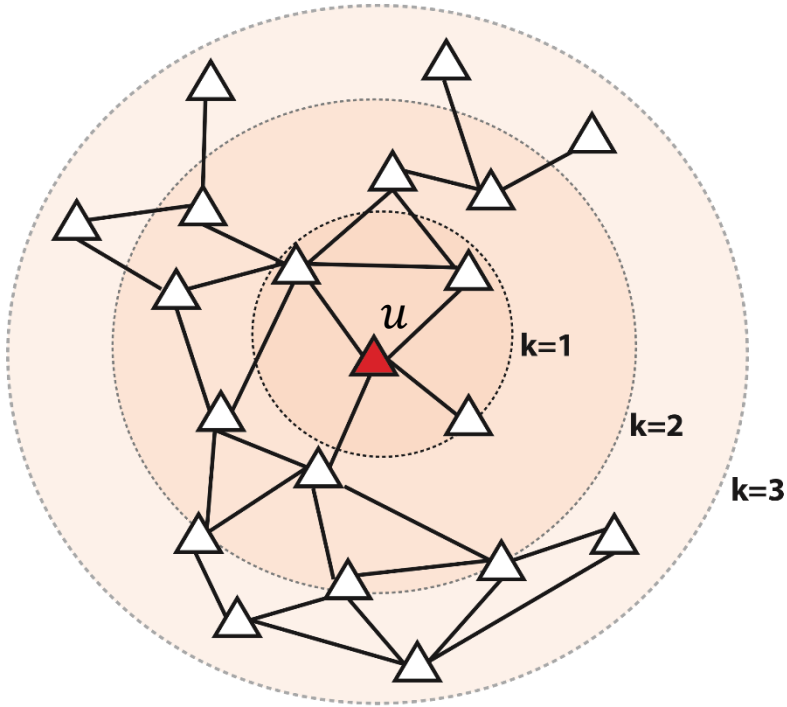


- **Intuition:** Find embedding of nodes to  $d$ -dimensions that preserves similarity
- **Idea:** Learn node embedding such that **nearby** nodes are close together
- **Given a node  $u$ , how do we define nearby nodes?**
  - $N_R(u)$  ... neighbourhood of  $u$  obtained by some strategy  $R$

Randomwalk:

- 节点 $u$ 开始形成100个路径
- 每个路径跳3次

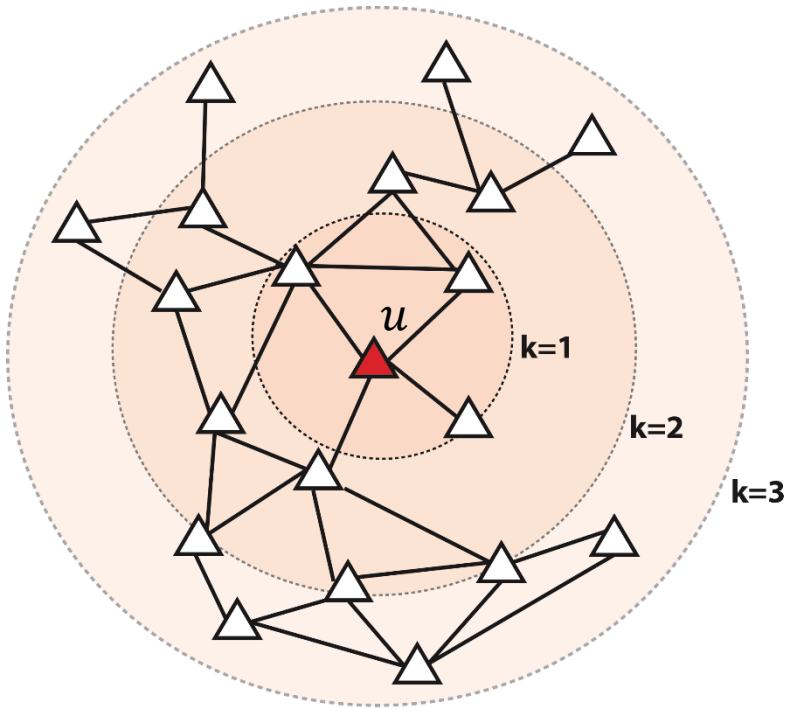
# Unsupervised Feature Learning



- Given  $G = (V, E)$
- Goal is to learn  $f: u \rightarrow \mathbb{R}^d$ 
  - where  $f$  is a table lookup
    - We directly “learn” coordinates  $\mathbf{z}_u = f(u)$  of  $u$
- Given node  $u$ , we want to learn feature representation  $f(u)$  that is predictive of nodes in  $u$ ’s neighborhood  $N_R(u)$

$$\max_f \sum_{u \in V} \log \Pr(N_R(u) | \mathbf{z}_u)$$

# Unsupervised Feature Learning



**Goal:** Find embedding  $\mathbf{z}_u$  that predicts nearby nodes  $N_R(u)$ :

$$\sum_{v \in V} \log(P(N_R(u) | \mathbf{z}_u))$$

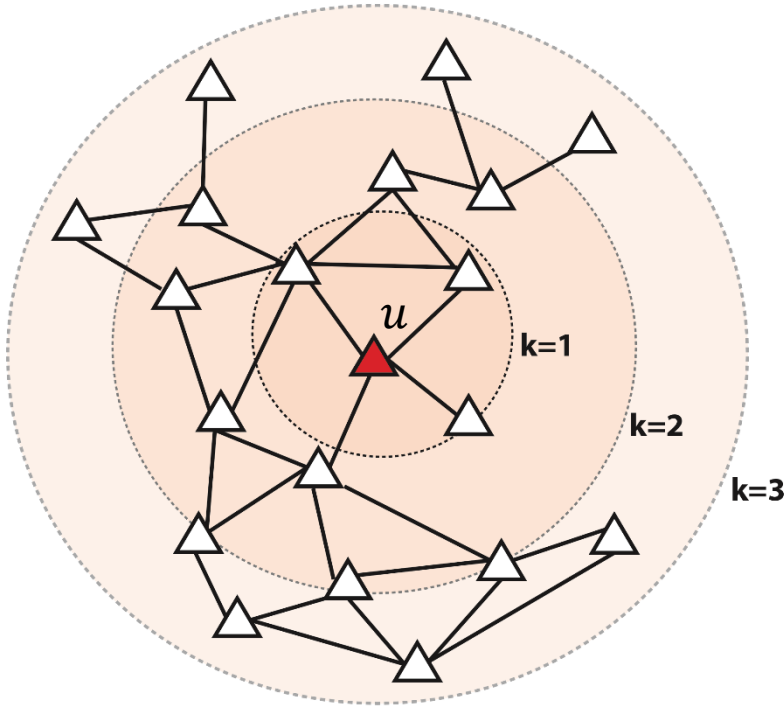
Assume conditional likelihood factorizes:

$$P(N_R(u) | \mathbf{z}_u) = \prod_{n_i \in N_R(u)} P(n_i | \mathbf{z}_u)$$

Random-walk Embeddings  $\mathbf{z}_u^\top \mathbf{z}_v \approx$

Probability that  $u$  and  $v$  co-occur in a random walk over the network

# Random Walk



1. Simulate many short random walks starting from each node using a strategy  $R$
2. For each node  $u$ , get  $N_R(u)$  as a sequence of nodes visited by random walks starting at  $u$
3. For each node  $u$ , learn its embedding by predicting which nodes are in  $N_R(u)$ :

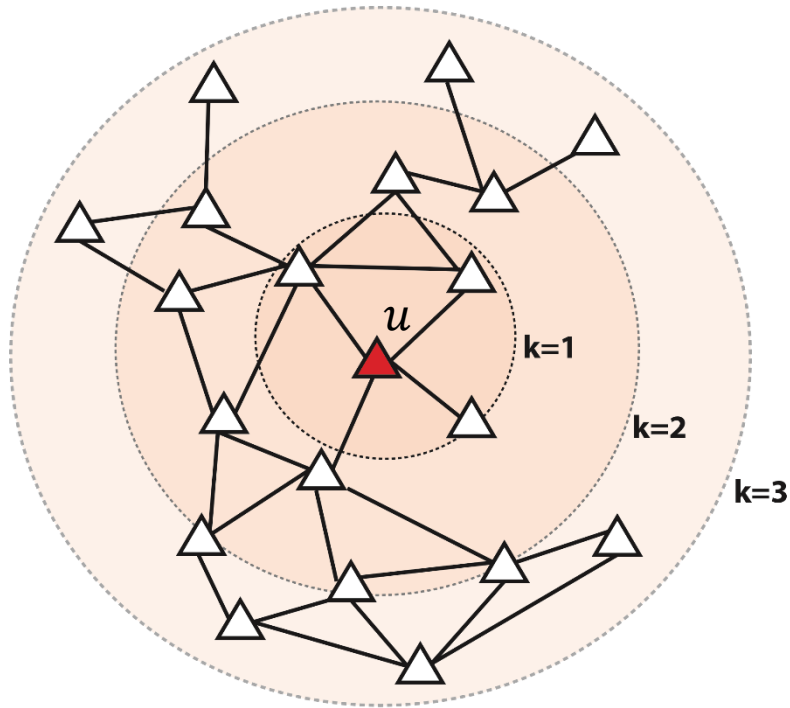
$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} -\log(P(v|\mathbf{z}_u))$$

Random-walk Embeddings  $\mathbf{z}_u^\top \mathbf{z}_v \approx$

Probability that  $u$  and  $v$  co-occur in a random walk over the network



# Random Walk



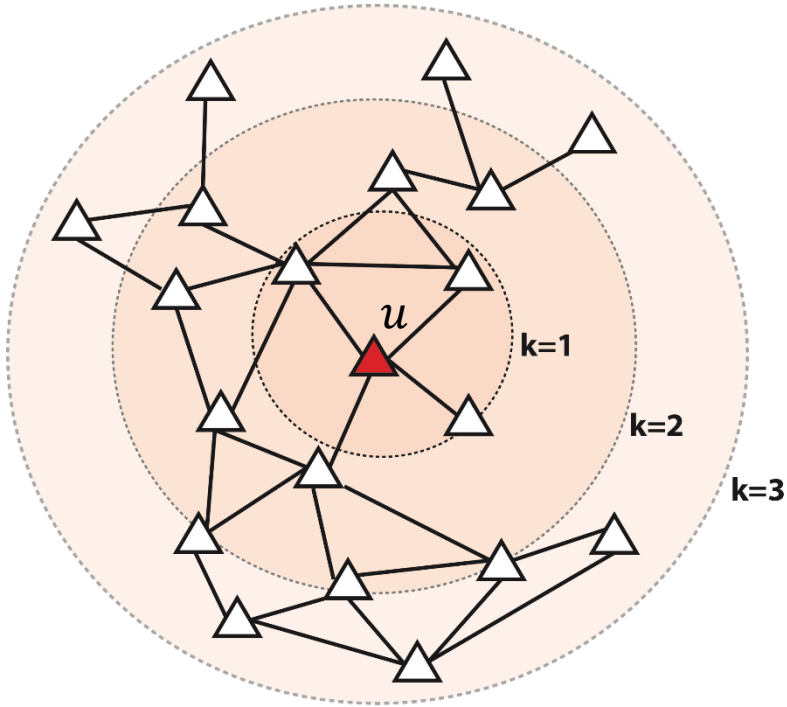
$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} -\log \left( \frac{\exp(\mathbf{z}_u^\top \mathbf{z}_v)}{\sum_{n \in V} \exp(\mathbf{z}_u^\top \mathbf{z}_n)} \right)$$

Annotations for the equation:

- sum over all nodes  $u$  (green arrow pointing to  $\sum_{u \in V}$ )
- sum over nodes  $v$  seen on random walks starting from  $u$  (grey arrow pointing to  $\sum_{v \in N_R(u)}$ )
- predicted probability of  $u$  and  $v$  co-occurring on random walk, i.e., use softmax to parameterize  $P(v|\mathbf{z}_u)$  (blue arrow pointing to the fraction)

**Random walk embeddings =  $\mathbf{z}_u$  minimizing  $\mathcal{L}$**

# Random Walk



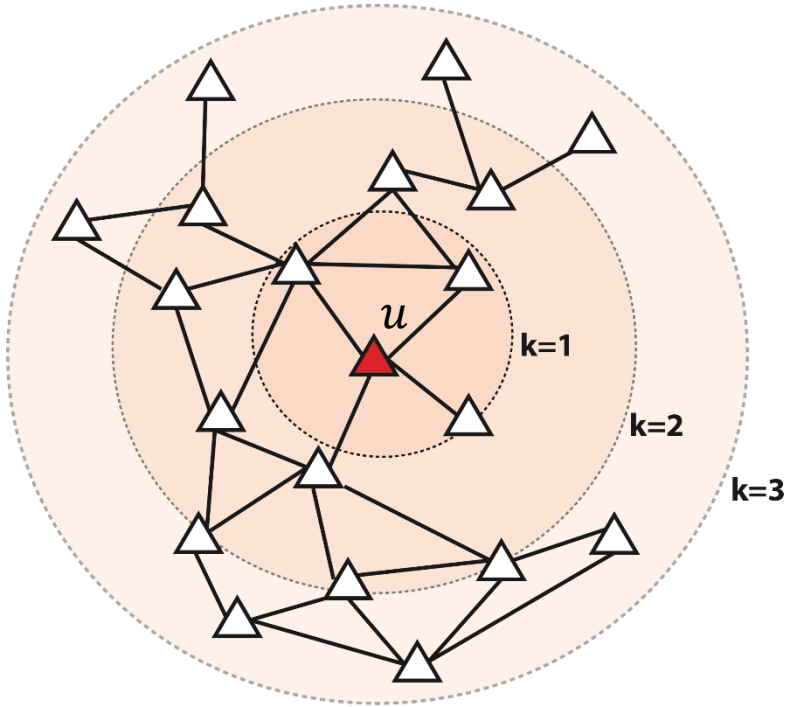
**But doing this naively is too expensive!**

$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} -\log \left( \frac{\exp(\mathbf{z}_u^\top \mathbf{z}_v)}{\sum_{n \in V} \exp(\mathbf{z}_u^\top \mathbf{z}_n)} \right)$$

Nested sum over nodes gives  $O(|V|^2)$  complexity!

The problem is normalization term in the softmax function?

# Random Walk



**Solution:** Negative sampling ([Mikolov et al., 2013](#))

$$\log \left( \frac{\exp(\mathbf{z}_u^\top \mathbf{z}_v)}{\sum_{n \in V} \exp(\mathbf{z}_u^\top \mathbf{z}_n)} \right)$$

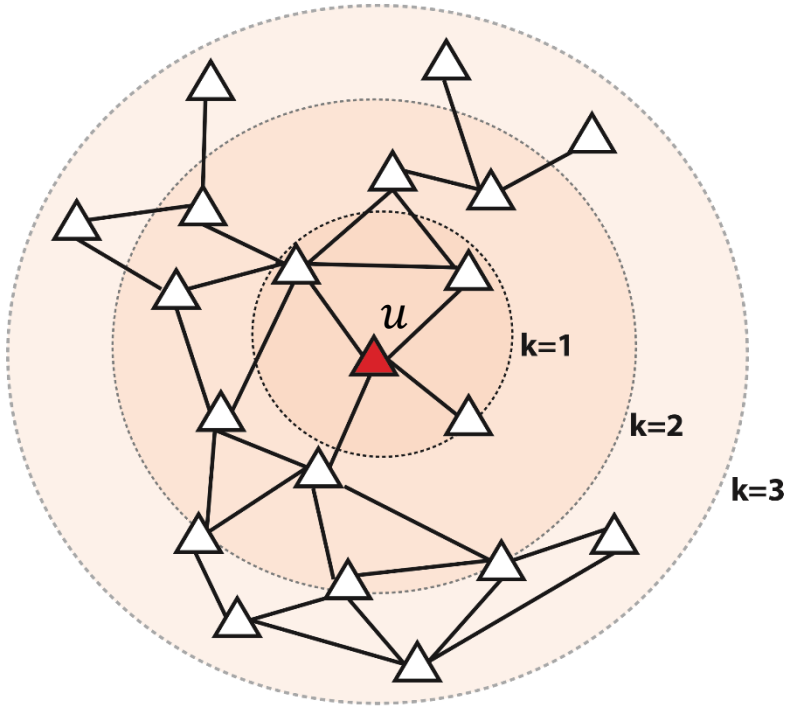
$$\approx \log(\sigma(\mathbf{z}_u^\top \mathbf{z}_v)) - \sum_{i=1}^k \log(\sigma(\mathbf{z}_u^\top \mathbf{z}_{n_i})), n_i \sim P_V$$

sigmoid function

random distribution  
over all nodes

i.e., instead of normalizing w.r.t. all nodes, just normalize against  $k$  random **negative samples**

# Random Walk

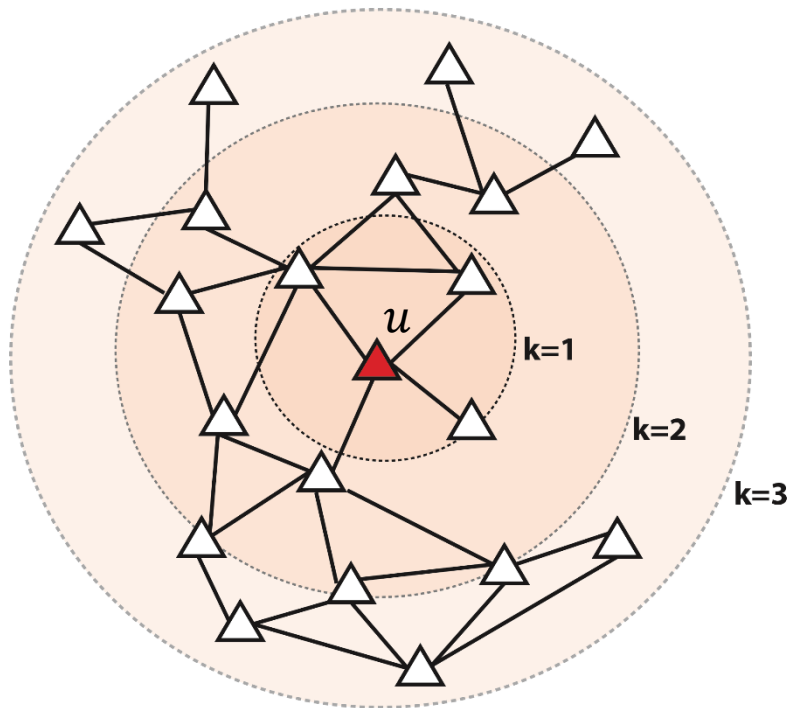


1. Simulate many short random walks starting from each node using a strategy  $R$
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3. For each node  $u$ , learn its embedding by predicting which nodes are in  $N_R(u)$ :

$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} -\log(P(v|\mathbf{z}_u))$$

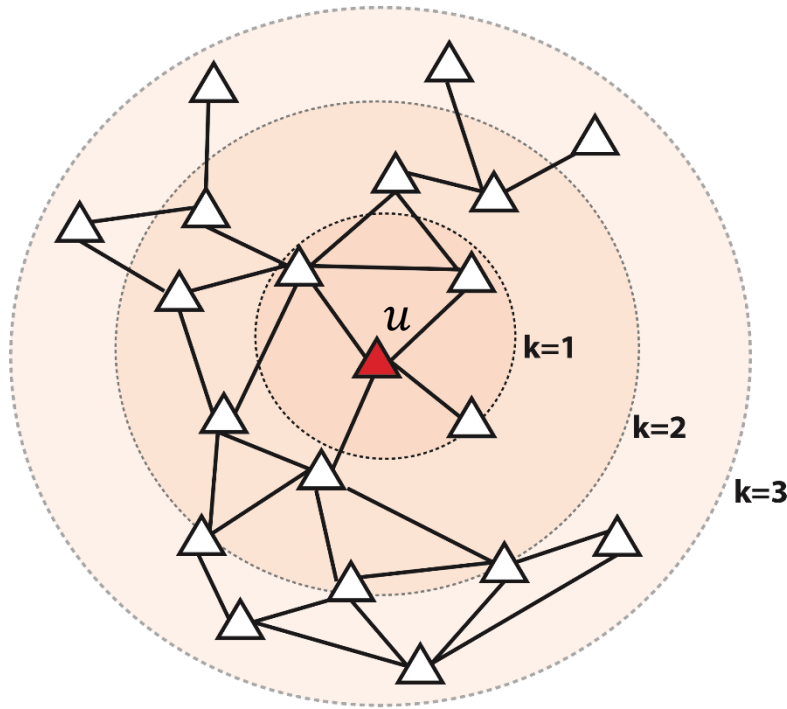
Can efficiently approximate using negative sampling

# Random Walk (针对有权图如何修改)

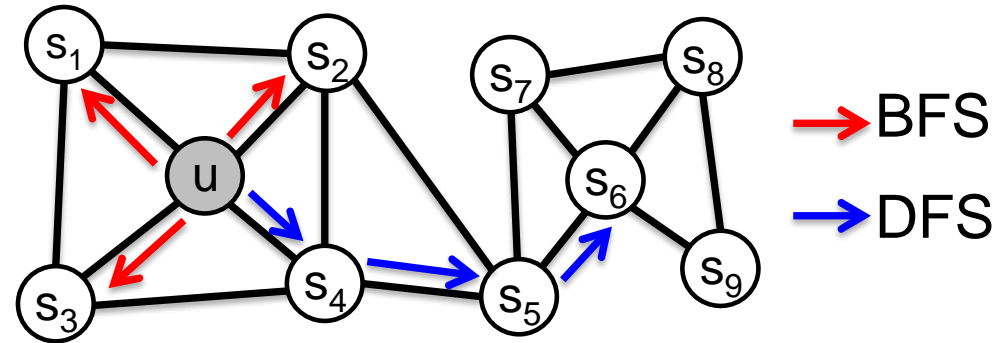


- **What strategies can we use to obtain these random walks?**
  - Simplest idea:
    - Fixed-length, unbiased random walks starting from each node (i.e., [DeepWalk from Perozzi et al., 2013](#))
  - **Can we do better?**
    - [Grover et al., 2016](#); [Ribeiro et al., 2017](#); [Abu-El-Haija et al., 2017](#) and many others

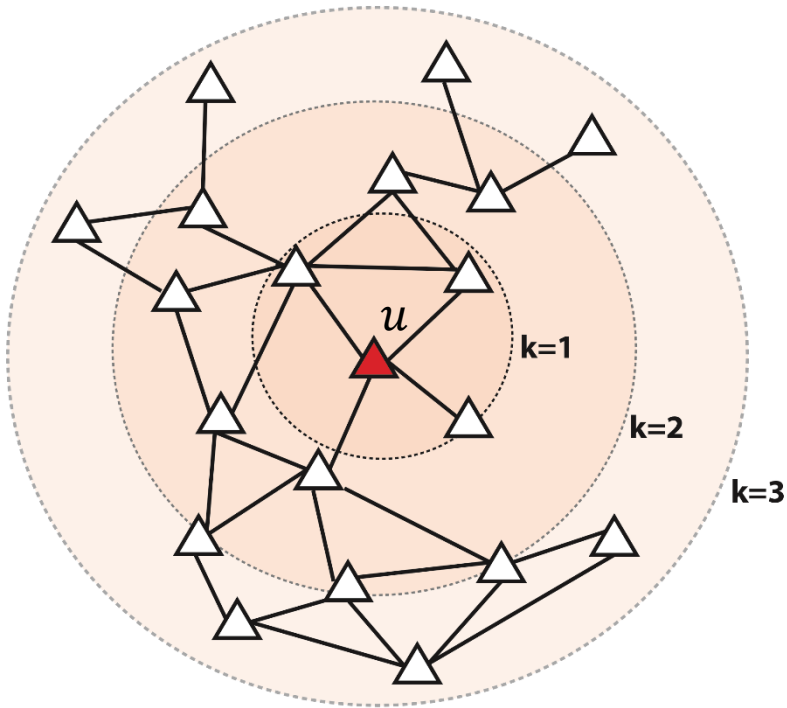
# node2vec: Biased Walks



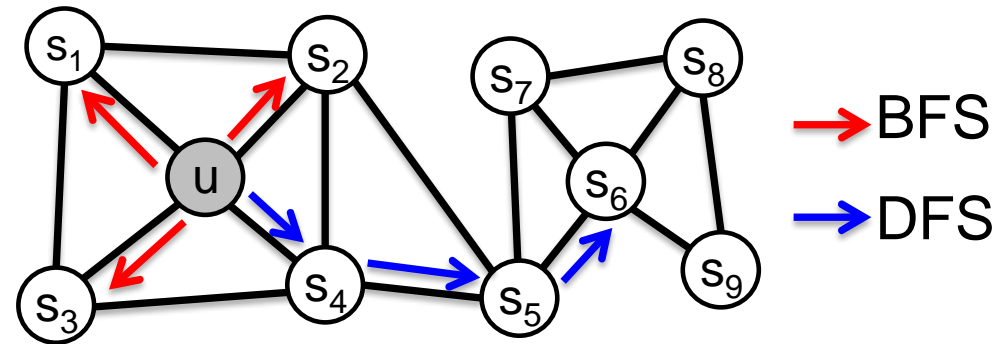
**Idea:** Use flexible, biased random walks that can trade off between **local** and **global** views of the network ([Grover and Leskovec, 2016](#))



# node2vec: Biased Walks



Two classic strategies to define a neighborhood  $N_R(u)$  of a given node  $u$ :



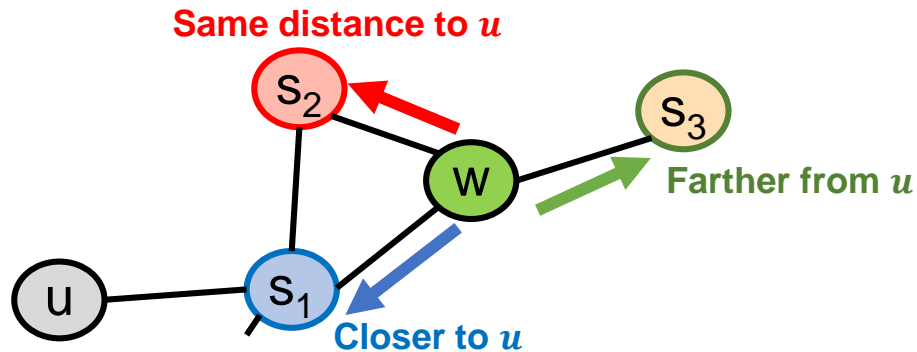
$$N_{BFS}(u) = \{s_1, s_2, s_3\}$$

**Local** microscopic view

$$N_{DFS}(u) = \{s_4, s_5, s_6\}$$

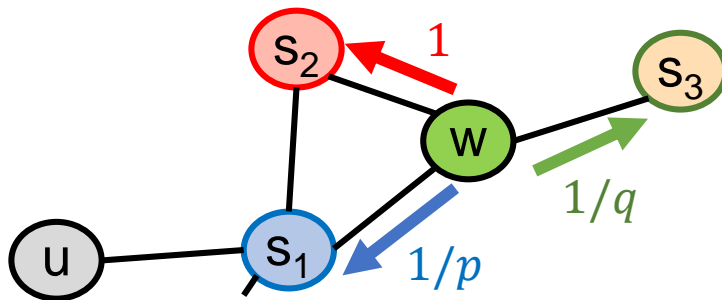
**Global** macroscopic view

# node2vec: Biased Walks



Biased random walk  $R$  that given a node  $u$  generates neighborhood  $N_R(u)$

- Two parameters:
  - Return parameter  $p$ :
    - return parameter
    - Return back to the previous node
  - In-out parameter  $q$ :
    - walk away parameter
    - Moving outwards (DFS) vs. inwards (BFS)

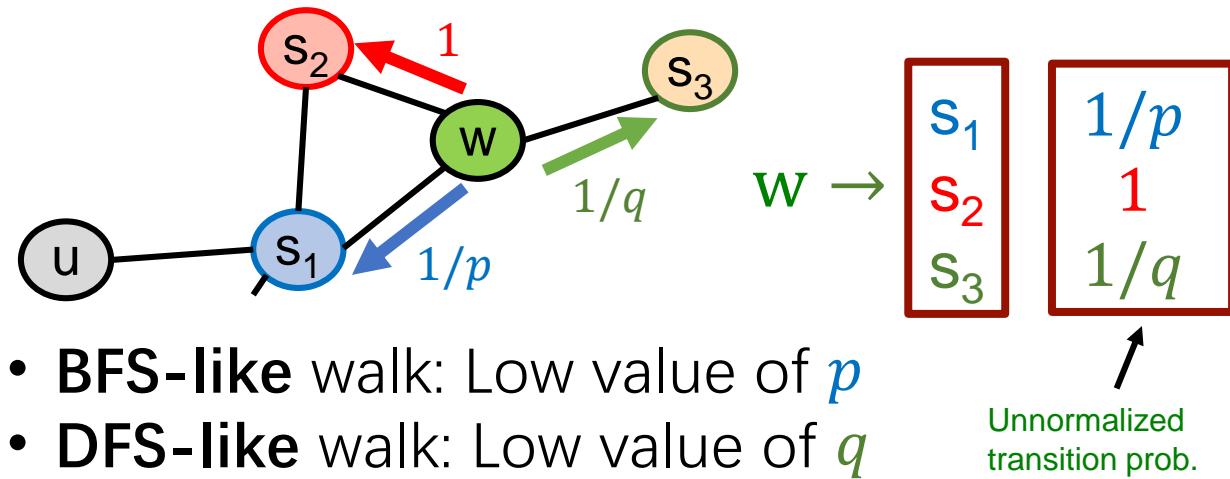


$1/p, 1/q, 1$  are  
unnormalized  
probabilities



# node2vec: Biased Walks

- Walker is at  $w$ . Where to go next?



$N_s(u)$  are the nodes visited by the walker

# Karate Club

- 该图描述了一个空手道俱乐部会员的社交关系，以34名会员作为节点，如果两位会员在俱乐部之外仍保持社交关系，则在节点间增加一条边。
- 每个节点具有一个34维的特征向量，一共有78条边。
- 在收集数据的过程中，管理人员 John A 和 教练 Mr. Hi（化名）之间产生了冲突，会员们选择了站队，一半会员跟随 Mr. Hi 成立了新俱乐部，剩下一半会员找了新教练或退出了俱乐部。

