

Lecture Notes on Treatment Effects

(or *Completely Innocuous Econometrics*)

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This Version: 2019-11-28 23:10:05

Abstract

These are lecture notes to accompany weeks 7 and 8 of the second-year MPhil topics course *Advanced Econometrics 1* at Oxford. Depending on time constraints, the lectures may not cover all of the material included in these notes. If in doubt, feel free to ask me which material you are responsible for. If you spot any typos, I would be very grateful if you could point them out. My email address is: francis.ditraglia@economics.ox.ac.uk.

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Chapter 1

Introduction

In this chapter we set the stage for the material to come, introducing the fundamental problem of causal inference, developing notation for later use, and reviewing some important facts concerning random variables.

1.1 What are these notes about?

Will earning an MPhil in Economics from Oxford increase your lifetime earnings? Does eating bacon sandwiches cause cancer? Does watching Fox News cause people to vote Republican? Will owning a dog increase your lifespan? Each of these questions concerns the **causal effect** of a **treatment** D on an **outcome** Y . The terminology “treatment” evokes a medical trial, but we will use the term much more broadly to refer to any variable D whose causal effect we hope to learn. For us, a treatment could be earning an MPhil, eating bacon sandwiches, watching Fox news, or owning a dog. These notes will focus on the case in which D is *binary*: either zero or one. If you have $D = 1$ we say that you are **treated**; if $D = 0$ we say that you are **untreated**. We will be particularly interested in methods for learning causal effects when the treatment variable is not randomly assigned, as would be the case in an **observational** rather than experimental study. So far as I know, no experiment has yet been carried out in which subjects are randomly compelled to be dog owners or forced to watch Fox News. Nonetheless papers have been written and published that attempt to estimate the causal effects of both of these treatments. We will study methods and assumptions under which observational data can be used to recover causal effects. We will also consider experiments in which subjects may fail to *comply* with their assigned treatments. In this case, the treatments that subjects actually receive are no longer randomly assigned, even if the treatments that they have been offered actually were.

1.2 The Fundamental Problem of Causal Inference

The fundamental problem of causal inference is that we can never observe a person’s **counterfactual** outcome. In other words, we can never know what her outcome *would have been* if her treatment *had been different*. After finishing her undergraduate degree, Alice earned an MPhil in Economics at Oxford. She now makes £75,000 per year. Would she still have earned as much if she had gone straight to work after finishing her undergraduate degree? Barry was a vegetarian so he never ate bacon sandwiches. He lived to the ripe old age of 90 and died in a hang-gliding accident, never having developed cancer. If he had eaten bacon sandwiches every day, would he have died of cancer at the age of 60 instead? Donald watches Fox News 10 hours a day and always votes for the Republican candidate. If he hadn’t watched Fox News, would he instead vote for the Democrats?

A counterfactual is a **within person** comparison: it asks how a given person’s outcome would have been different if her treatment had been different. Because we can never observe the same person in two different treatment states, we can never actually make this comparison. You may be wondering about a before-and-after comparison. For example, what if we looked at Alice’s wage immediately before she earned the MPhil and then immediately afterwards. Tracking the same person over time can be an extremely helpful way to untangle cause-and-effect, as you may have gathered from your exposure to panel data methods. It cannot, however, solve the fundamental problem of causal inference: comparing Alice’s wages at two *different* points in time is not the same as comparing her wage at the *same* point in time across two “parallel universes,” one in which she went straight to work and another in which she went to Oxford. Most people’s income increases as they gain additional experience, for example. Comparing Alice’s income before and after might confuse the effect of more experience in the labor force with the effect of earning an MPhil in Economics. Or perhaps Alice started the MPhil during an economic boom and finished during a severe downturn. If so, the fact that her income fell after the MPhil would tell us little of value: perhaps it would have fallen by *more* without the degree. Because the idealized within person comparison is impossible, we will need to develop methods and assumptions that allow us to substitute a **between-person** comparison.

1.3 The Potential Outcomes Framework

In order to study causal effects we need a framework that allows us to formally define them and manipulate them mathematically. Following the bulk of the treatment effects literature, we will adopt the **potential outcomes framework**, also known as the Rubin Causal Model (RCM). With each person i we associate a pair of **potential outcomes** (y_{i0}, y_{i1}) . These are precisely the counterfactual outcomes that I discussed in the pre-

ceding section. Suppose, for example, that Alice is person i . Then y_{i0} is her wage if she doesn't earn the MPhil and y_{i1} is her wage if she does. Even though we can never observe both y_{i0} and y_{i1} for the same person, we can still *imagine* that there is a fact of the matter regarding what Alice's wage would have been in a parallel universe where her treatment had been different. Using this notation, $(y_{i1} - y_{i0})$ is the causal effect *for Alice* of earning the Oxford MPhil. This need not be the same as the causal effect for Bob of earning an Oxford MPhil, or indeed the same as the causal effect of anyone else. In other words, we will allow for the possibility that treatment effects are **heterogeneous**.

While we never observe both y_{i0} and y_{i1} , we always observe one of them. If Alice is treated then we observe y_{i1} ; otherwise we observe y_{i0} . We can express this as follows

$$y_i = (1 - d_i)y_{i0} + d_iy_{i1} = y_{i0} + d_i(y_{i1} - y_{i0}) \quad (1.1)$$

where y_i is person i 's **observed outcome** and d_i is an indicator that equals one if she was treated and zero otherwise. Implicit in this equation and the potential outcomes notation that we have adopted is a very important assumption that we will maintain throughout these notes: the **stable unit treatment value assumption** (SUTVA). This requires that Alice's outcome depends only on her own treatment and not the treatments of anyone else. SUTVA is a strong assumption and it is easy to think of settings where it doesn't hold. For example, if Alice gets a flu vaccine this makes Bob less likely to get the flu regardless of whether he was vaccinated. Finding ways to relax the SUTVA assumption constitutes a very active area of research in the treatment effects literature.

1.4 Populations, Observables, and Random Variables

The first step of any causal analysis is to specify the **population of interest**. Suppose that we hope to learn the causal effect of watching Fox News on voting behavior. Whose voting behavior are we interested in? All US voters? Swing voters? Often the choice of population is dictated by circumstance. Perhaps we have access to a fantastic dataset on Pennsylvania voters but no information about voters from other states. If so, the causal claims we can make will necessarily be limited to Pennsylvania: the effect of Fox News could be markedly different, say, in Florida.

These notes assume that we have already specified a population of interest and observed a random sample from it. If our population is Pennsylvania voters, this assumes that we have observed a representative sample of n voters from the state. But what, precisely, do we observe? As discussed in the previous section, we can only observe *one* of a person's potential outcomes (y_{i0}, y_{i1}) , namely the one that corresponds to her treatment d_i , as shown in (1.1). At a bare minimum, we will always assume that both y_i and d_i are observed for each person i in our sample. Most of the methods we describe below will

in fact rely on observing some *additional* information \mathbf{w}_i . For this reason, I will refer to (y_i, d_i, \mathbf{w}_i) as the **observables** for person i .

Throughout this section and the preceding one I have used lowercase letters: y_i rather than Y_i and d_i rather than D_i , for example. I did this to emphasize that we are talking about specific values for a particular person. There is, in principle, nothing random about Alice’s treatment, her observed outcome, or her potential outcomes. Randomness enters only when we view her as merely one member of a *population* from which we will draw a random sample. From this point onwards, we will stop thinking about the values for a particular person and instead think about random variables that represent the notion of *randomly drawing someone* from the population of interest.

The idea is as follows. Suppose that 35% of voters in Pennsylvania watch Fox News ($d_i = 1$). Then if I randomly sample a single voter, there is a 35% chance that she watches Fox News. We can represent this as a *random variable* D with a Bernoulli(0.35) distribution. Similarly, if we knew the values of y_i and \mathbf{w}_i for every voter in Pennsylvania, we could construct random variables Y and \mathbf{W} that represent the idea of randomly selecting a voter and observing her values of y_i and \mathbf{w}_i . Using this abstraction, we will view the observables (y_i, d_i, \mathbf{w}_i) for any given person a *realization* from the joint distribution of a collection of random variables (Y, D, \mathbf{W}) . The thought experiment is that we reach into the state of Pennsylvania, pull out a voter at random, and observe (y_i, d_i, \mathbf{w}_i) . Viewed in this way, knowing the values of (y_i, d_i, \mathbf{w}_i) for everyone in the population is the same thing as knowing the joint distribution of (Y, D, \mathbf{W}) .

Although we can never actually observe the pair (y_{i0}, y_{i1}) for the same person, we can still *imagine* reaching into the state of Pennsylvania and learning $(y_{i0}, y_{i1}, d_i, \mathbf{w}_i)$ for a particular person. As above, we can represent this idea using a collection of random variables: $(Y_0, Y_1, D, \mathbf{W})$. Knowing $(y_{i0}, y_{i1}, d_i, \mathbf{w}_i)$ for everyone in the population would be equivalent to knowing the joint distribution of $(Y_0, Y_1, D, \mathbf{W})$. Because these random variables are constructed from the values for each individual in the population, the relationship from (1.1) continues to apply, that is

$$Y = (1 - D)Y_0 + DY_1 = Y_0 + D(Y_1 - Y_0). \quad (1.2)$$

Equation 1.2 shows that knowledge of the joint distribution of distribution $(Y_0, Y_1, D, \mathbf{W})$ implies knowledge of the joint distribution of (Y, D, \mathbf{W}) , because Y is a function of (Y_0, Y_1, D) . The converse, however, is false: knowledge of a person’s observed outcome and her treatment does now allow use to reconstruct both of her potential outcomes.

1.5 Identification Versus Estimation

These notes mainly focus on the problem of **identifying** causal effects rather than that of estimating them. Suppose that we know the joint distribution of (Y, D, \mathbf{W}) and hope to learn the value of some quantity θ in our population of interest. As explained in the preceding section, knowing the distribution of (Y, D, \mathbf{W}) is the same as knowing the values of (y_i, d_i, \mathbf{w}_i) for everyone in the population. If this knowledge would be sufficient to uniquely pin down θ , then we say that θ is **identified**; otherwise we say that it is **unidentified**.¹ The challenge of identifying causal effects is that we observe not the joint distribution of potential outcomes (Y_0, Y_1) but only that of (Y, D, \mathbf{W}) . Our identification question is whether this observed information, combined with appropriate assumptions, will allow us determine whether D causes Y .

Identification is about populations rather than samples. Estimation, on the other hand, asks how we can use a sample of observed data to produce a “best guess” of some quantity of interest θ . In the simplest case, we assume that the researcher observes a collection of n iid draws (Y_i, D_i, \mathbf{W}_i) from the population and ask how this information can be used to construct an estimator $\hat{\theta}$ of θ with desirable properties. These notes mainly focus on identification because estimation is meaningless without it: if there is no way to learn the causal effect of D on Y from knowledge of (y_i, d_i, \mathbf{w}_i) for *everyone* in the population, there is no way to estimate it using a random sample from this population.

1.6 Our goal: identify the Average Treatment Effect

When treatment effects are heterogeneous, every person in the population could have her own, unique causal effect: $(y_{i1} - y_{i0})$. Collecting the individual treatment effects for each person in our population of interest gives rise to a *distribution* of causal effects. Using the random variables defined above, we can represent this distribution using the random variable $(Y_1 - Y_0)$. If $(Y_1 - Y_0)$ were simply a constant, i.e. if treatment effects were **homogeneous**, asking whether D causes Y would be the same thing as asking if $(Y_1 - Y_0) = 0$. The sign and magnitude of $(Y_1 - Y_0)$ would then tell us the direction and importance of the effect. When treatment effects are heterogeneous, however, the yes-or-no question “does D cause Y ?” no longer makes sense. Watching Fox News will not make Bernie Sanders vote Republican, but it might still affect the average swing voter in western Pennsylvania, for example. Faced with effects that vary across people, the natural question is “how do they vary?” In other words, what can we say about the *distribution* of $(Y_1 - Y_0)$? If we could learn the distribution of $(Y_1 - Y_0)$ across the population, we

¹Notice the use of the word *sufficient* in the definition of identification. Saying that θ is identified doesn’t mean that knowing the joint distribution of (Y, D, \mathbf{W}) is *necessary* to uniquely pin down θ . For example, uniquely determining the vector of slope coefficients from a regression of Y on (D, \mathbf{W}) would only require us to know the means, covariances, and variances of these random variables.

could answer a variety of interesting questions. For example: “what fraction of people benefit from this treatment?” or “what is the variance of treatment effects?”

Unfortunately it is impossible to learn the distribution of treatment effects. As we discussed above, the fundamental problem of causal inference is that we can never observe both y_{i1} and y_{i0} for the same person. For this reason, there is no way to identify the joint distribution of (Y_0, Y_1) . If we want to determine the correlation between height and weight, we need observations of both variables for *the same people*. So too, identifying the joint distribution between (Y_0, Y_1) would require observations of both potential outcomes for the same people. Because we observe Y_0 for a subset of the population and Y_1 for another subset, there is at least the possibility that we could learn the *marginal* distributions of Y_0 and Y_1 . What we can never learn is the *dependence* between them.

This problem severely limits our ability to characterize the distribution of $(Y_1 - Y_0)$. Suppose, for example, that we wanted to determine $\text{Var}(Y_1 - Y_0)$. By the formula for the variance of a difference,

$$\text{Var}(Y_1 - Y_0) = \text{Var}(Y_0) + \text{Var}(Y_1) - 2\text{Cov}(Y_0, Y_1).$$

Because it depends on a feature of the joint distribution of (Y_0, Y_1) —namely the covariance—the variance of the distribution of treatment effects cannot be identified. If we were willing to assume that Y_0 and Y_1 are uncorrelated, then we could indeed identify $\text{Var}(Y_1 - Y_0)$ based on knowledge of $\text{Var}(Y_0)$ and $\text{Var}(Y_1)$. In most examples, however, this assumption is untenable. Consider the problem of identifying the returns to an Oxford MPhil in Economics. More than likely, people who would earn a higher than average wage without the MPhil (high Y_0) would *also* earn a higher than average wage *with* an MPhil (high Y_1), implying a positive correlation between Y_0 and Y_1 .

It seems as though we have reached an impasse. How can we say anything useful about $(Y_1 - Y_0)$ without knowledge of the joint distribution of (Y_0, Y_1) ? Recall a fundamental property of expectation: *linearity*. The expectation of a sum equals the sum of the expectations, and the expectation of a difference equals the difference of expectations. Thus, taking expectations of both sides

$$\mathbb{E}[Y_1 - Y_0] = \mathbb{E}[Y_1] - \mathbb{E}[Y_0].$$

We call $\mathbb{E}[Y_1 - Y_0]$ the **average treatment effect** and abbreviate it ATE. The ATE measures how large the individual treatment effects ($y_{i1} - y_{i0}$) are *on average* across everyone in the population. If the ATE is positive, then the treatment is beneficial on average; if it is negative, then the treatment is harmful on average. If the ATE is zero, then the treatment has no effect on average. The primary goal of the treatment effects literature is to identify the ATE or, failing that, at least an average treatment for some

subset of the population. Undeniably the ATE is a valuable summary of $(Y_1 - Y_0)$, but it sweeps many important questions under the rug. What fraction of people would be *harmed* by the treatment? Is the treatment effect highly variable, or very similar for nearly everyone? We would love to be able to answer these questions, but unfortunately we cannot. The ATE thus represents not an ideal measure of the effect of D on Y , but the *best we can manage* given the fundamental problem of causal inference.

1.7 Quantile Treatment Effects

If you have studied quantile regression, you may have encountered the term *quantile treatment effect*. Don't let the name fool you: the fact that this quantity is called a treatment effect does not mean that it has a genuine causal interpretation. Let Q_0 be the quantile function of Y_0 and Q_1 be the quantile function of Y_1 . Then $Q_0(0.5)$ is the median of Y_0 while $Q_1(0.5)$ is the median of Y_1 . Both of these quantities are identified from the marginal distributions of the potential outcomes. Indeed, for any quantile τ , both $Q_0(\tau)$ and $Q_1(\tau)$ are identified from these marginal distributions. The difference $\delta(\tau) \equiv Q_1(\tau) - Q_0(\tau)$ is typically called the **quantile treatment effect** of D on Y . Suppose that Alice's potential outcome without treatment y_{i0} falls at the τ th quantile of the distribution of Y_0 . In other words suppose that $\tau \times 100\%$ of people have a lower value of Y_0 than Alice, and $(1 - \tau) \times 100\%$ have a higher value of Y_0 . Then $\delta(\tau)$ tells us how much higher Alice's value of y_{i1} would *need to be* in order for her to fall at the τ th quantile of the distribution of Y_1 as well. Without further assumptions, $\delta(\tau)$ lacks a causal interpretation. Giving it one requires the so-called **rank invariance** assumption. This condition requires that if Alice occupies the τ th quantile of the Y_0 distribution, then she also occupies the τ th quantile of the Y_1 distribution. Under rank invariance, $\delta(\tau)$ is the causal effect of D on Y for a person who *would have fallen* at the τ th quantile of Y_0 had she not been treated. It is difficult to think of real-world examples in which rank invariance is likely to hold. For this reason we focus on identifying the ATE in the remainder of these notes.

1.8 The problem to overcome: selection bias

We know from above that $Y = (1 - D)Y_0 + DY_1$. For a person who is treated we observe Y_1 and for a person who is not we observe Y_0 . So to estimate $ATE \equiv \mathbb{E}[Y_1] - \mathbb{E}[Y_0]$, why not simply compare the average value of Y among those with $D = 1$ to the average value of Y among those with $D = 0$? Because D is binary, this idea is *precisely* equivalent to regressing Y on D . To see this we use the following lemma.²

²For a proof, see the appendix to this chapter.

Lemma 1.1. *Let W be a binary random variable with $\mathbb{P}(W = 1) = p$. Then for any random variable X , we have $\text{Cov}(X, W) = p(1 - p) [\mathbb{E}(X|W = 1) - \mathbb{E}(X|W = 0)]$ provided that the requisite expectations exist.*

Since D is binary, $\text{Var}(D) = \mathbb{P}(D = 1) [1 - \mathbb{P}(D = 1)]$. Thus, applying [Lemma 1.1](#),

$$\beta_{OLS} \equiv \frac{\text{Cov}(D, Y)}{\text{Var}(D)} = \mathbb{E}(Y|D = 1) - \mathbb{E}(Y|D = 0). \quad (1.3)$$

Does β_{OLS} equal the ATE? To find out, we substitute [\(1.2\)](#) into [\(1.3\)](#) yielding

$$\begin{aligned} \beta_{OLS} &= \mathbb{E}(Y|D = 1) - \mathbb{E}(Y|D = 0) \\ &= \mathbb{E}[(1 - D)Y_0 + DY_1|D = 1] - \mathbb{E}[(1 - D)Y_0 + DY_1|D = 0] \\ &= \mathbb{E}[Y_1|D = 1] - \mathbb{E}[Y_0|D = 0]. \end{aligned}$$

These manipulations show that β_{OLS} *may not* equal the ATE. The unconditional mean $\mathbb{E}(Y_1)$ need not equal the conditional mean $\mathbb{E}(Y_1|D = 1)$, and similarly $\mathbb{E}(Y_0)$ need not equal $\mathbb{E}(Y_0|D = 0)$, because D may be *related* to the potential outcomes. This problem is called **selection bias**. To better understand it, consider the following example: let $D = 1$ if you graduated from university and let Y be your income at age 30. Adding and subtracting $\mathbb{E}(Y_0|D = 1)$ from the expression for β_{OLS} , we have

$$\beta_{OLS} = \underbrace{\mathbb{E}(Y_1 - Y_0|D = 1)}_{\text{TOT}} + \underbrace{[\mathbb{E}(Y_0|D = 1) - \mathbb{E}(Y_0|D = 0)]}_{\text{Difference in Outside Options}}. \quad (1.4)$$

The first term in [\(1.4\)](#) is the average causal effect of the **treatment on the treated** abbreviated TOT. This measures causal effect of graduating from university on income averaged over all the people in the population who *chose* to graduate from university. When treatment effects are heterogeneous the TOT need not equal the ATE. Mark Zuckerberg famously dropped out of Harvard University in his sophomore year ($D = 0$) but is currently one of the highest earning people on the planet. Presumably his decision to leave university was motivated by a belief that his personal treatment effect $y_{i1} - y_{i0}$ was *negative*: the time he would have spent studying could be put to more lucrative use developing Facebook. If people have some knowledge of their personal treatment effects and are to some extent free to choose their treatment, then we would expect $\mathbb{E}(Y_1 - Y_0|D = 1)$ to be *higher* than the ATE and $\mathbb{E}(Y_1 - Y_0|D = 0)$ to be *lower*.³

The second term in [\(1.4\)](#) measures the difference in average values of Y_0 between the treated and the untreated. In the university and income example, this measures the average **difference in outside options** between those who ultimately chose to attend

³By the Law of Iterated Expectations ([Lemma 1.2](#)), the ATE $\mathbb{E}(Y_1 - Y_0)$ is a convex combination of $\mathbb{E}(Y_1 - Y_0|D = 1)$ and $\mathbb{E}(Y_1 - Y_0|D = 0)$, so it necessarily lies *between* them.

university and those who did not.⁴ If higher ability people are more likely to graduate from university ($D = 1$) and also have a higher-paying outside option Y_0 , say because ability has a direct effect on income, the second term in (1.4) will be *positive*. Thus, even if the TOT is equal to the ATE, β_{OLS} will not in general identify the average causal effect of D on Y when individuals can choose their treatment status.

Once you start looking for it, you will find examples of selection bias *everywhere*. People who are admitted to hospitals are more likely to die in the next year than people who are not. This isn't because hospitals kill people: it's because sick people are more likely to go to hospitals. Dog owners are less likely to die over a five year horizon, but this may simply reflect the fact that healthy people are more likely to get a dog than sick people: taking care of an animal is a lot of work! Watching Fox News may cause you to vote Republican, or perhaps voting Republican causes you to watch Fox News.

1.9 Appendix: Proofs and Probability Review

The mathematical level of these notes is fairly modest. I assume throughout, however, that you are familiar with basic properties of random variables, expectation, variance, and covariance. In case you need to refresh your memory, this section lists some important properties that are used throughout the document.

Proof of Lemma 1.1. Let $p = \mathbb{P}(W = 1) = \mathbb{E}(W)$ and define $m_0 = \mathbb{E}(X|W = 0)$ and $m_1 = \mathbb{E}(X|W = 1)$. By the shortcut formula and iterated expectations,

$$\begin{aligned}\text{Cov}(X, W) &= \mathbb{E}(XW) - \mathbb{E}(X)\mathbb{E}(W) = \mathbb{E}[W\mathbb{E}(X|W)] - \mathbb{E}(X)p \\ &= \mathbb{E}(X|W = 1)p - \mathbb{E}(X)p = pm_1 - p\mathbb{E}(X)\end{aligned}$$

Applying iterated expectations a second time,

$$\mathbb{E}(X) = \mathbb{E}[\mathbb{E}(X|W)] = m_0(1 - p) + pm_1$$

and substituting this equation into the expression for $\text{Cov}(X, W)$,

$$\begin{aligned}\text{Cov}(X, W) &= pm_1 - p[m_0(1 - p) + pm_1] = (p + p^2)m_1 - p(1 - p)m_0 \\ &= p(1 - p)(m_1 - m_0) = p(1 - p)[\mathbb{E}(X|W = 1) - \mathbb{E}(X|W = 0)]\end{aligned}$$

□

⁴Some authors call the second term in (1.4) the “selection bias.” In contrast I reserve this phrase for the *overall* difference between β_{OLS} and the ATE that arises when people are free to choose their treatments.

Lemma 1.2 (The Law of Iterated Expectations).

$$\mathbb{E}[Y] = \mathbb{E}_X [\mathbb{E}(Y|X)], \quad \mathbb{E}[Y|Z] = \mathbb{E}_{X|Z} [\mathbb{E}(Y|X, Z)]$$

Lemma 1.3 (Taking out what is known). *If f is a measurable function, then*

$$\mathbb{E}[f(X)Y|X] = f(X)\mathbb{E}[Y|X]$$

Lemma 1.4 (The Law of Total Probability). *For discrete random variables X and Y*

$$\mathbb{P}(Y = y) = \sum_{all\ x} \mathbb{P}(Y = y|X = x)\mathbb{P}(X = x)$$

Lemma 1.5 (Linearity of Expectation). *For RVs X, Y, Z and constants a, b, c*

$$\mathbb{E}[aX + bY + c] = a\mathbb{E}[X] + b\mathbb{E}[Y] + c, \quad \mathbb{E}[aX + bY + c|Z] = a\mathbb{E}[X|Z] + b\mathbb{E}[Y|Z] + c$$

Lemma 1.6 (Bayes' Theorem).

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(B|A)\mathbb{P}(A)}{\mathbb{P}(B)}, \quad \mathbb{P}(A|B, C) = \frac{\mathbb{P}(B|A, C)\mathbb{P}(A|C)}{\mathbb{P}(B|C)}$$

Definition 1.1 (Variance and Conditional Variance).

$$\text{Var}(X) \equiv \mathbb{E} [(X - \mathbb{E} \{X\})^2], \quad \text{Var}(X|Z) \equiv \mathbb{E} [(X - \mathbb{E} \{X|Z\})^2 | Z]$$

Definition 1.2 (Covariance and Conditional Covariance).

$$\begin{aligned} \text{Cov}(X, Y) &\equiv \mathbb{E} [(X - \mathbb{E} \{X\})(Y - \mathbb{E} \{Y\})] \\ \text{Cov}(X, Y|Z) &\equiv \mathbb{E} [(X - \mathbb{E} \{X|Z\})(Y - \mathbb{E} \{Y|Z\}) | Z] \end{aligned}$$

Lemma 1.7 (Shortcut Rule for Variance and Covariance).

$$\begin{aligned} \text{Var}(X) &= \mathbb{E}[X^2] - \mathbb{E}[X]^2 \\ \text{Var}(X|Z) &= \mathbb{E}[X^2|Z] - \mathbb{E}[X|Z]^2 \\ \text{Cov}(X, Y) &= \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y] \\ \text{Cov}(X, Y|Z) &= \mathbb{E}[XY|Z] - \mathbb{E}[X|Z]\mathbb{E}[Y|Z] \end{aligned}$$

Lemma 1.8 (Properties of Variance and Covariance).

- (i) $\text{Cov}(X, X) = \text{Var}(X)$
- (ii) $\text{Var}(aX + c) = a^2 \text{Var}(X)$

$$(iii) \quad \text{Var}(aX + bY + c) = a^2 \text{Var}(X) + b^2 \text{Var}(Y) + 2ab \text{Cov}(X, Y)$$

$$(iv) \quad \text{Cov}(aX + bY, Z) = a \text{Cov}(X, Z) + b \text{Cov}(Y, Z)$$

Lemma 1.9 (Properties of Conditional Variance and Covariance).

$$(i) \quad \text{Var}(X|X) = 0$$

$$(ii) \quad \text{Cov}(X, Y|X) = 0$$

$$(iii) \quad \text{Cov}(X, X|Z) = \text{Var}(X|Z)$$

$$(iv) \quad \text{Var}(aX + c|Z) = a^2 \text{Var}(X|Z)$$

$$(v) \quad \text{Var}(aX + bY + c) = a^2 \text{Var}(X) + b^2 \text{Var}(Y) + 2ab \text{Cov}(X, Y)$$

$$(vi) \quad \text{Cov}(aX + bY, Z|W) = a \text{Cov}(X, Z|W) + b \text{Cov}(Y, Z|W)$$

Lemma 1.10 (The Law of Total Variance).

$$\text{Var}(Y) = \mathbb{E} [\text{Var}(Y|X)] + \text{Var}(\mathbb{E}[Y|X])$$

Lemma 1.11 (The Law of Total Covariance).

$$\text{Cov}(X, Y) = \mathbb{E} [\text{Cov}(X, Y|Z)] + \text{Cov}[\mathbb{E}(X|Z), \mathbb{E}(Y|Z)]$$

Chapter 2

Conditional Independence

To understand the literature on treatment effects, you will need to develop some familiarity with the notion of **conditional independence** and its properties. This chapter provides an overview. We begin by defining independence and the closely related idea of conditional independence, and go on to explain the consequences that these notions have for *expectations*. This allows us to propose our first solution to the problem of selection bias: randomly assigning individuals to treatment.

The remainder of the chapter discusses a set of *axioms* that allow us to manipulate conditional independence relationships. Defining conditional independence and deriving its axioms for *all possible* kinds of random variables requires some measure theory. If have the appropriate background, I recommend reading the technical appendix, [section 2.6](#), alongside the rest of the chapter. If you are not familiar with measure theory, don't worry: you will be able to understand everything except the technical appendix. There are only two terms from measure theory that I use in the body of the chapter. The first is that of a **measurable function**. If you haven't encountered this term before, it is just a particular way of saying that a function is “well-behaved.” Any continuous function is measurable, as is any discontinuous function with a finite or countable number of discontinuities. The second is the terminology “ W is Y -measurable.” In words, this simply means that if we know the realization of the random variable Y then we also know the realization of the random variable W .

2.1 Intuition and Notation

Two continuous random variables X and Y are **independent** if and only if their joint density equals the product of their marginal densities: $f(x, y) = f(x)f(y)$ for all x, y in the support sets of X and Y .¹ By the definition of a conditional density, $f(y|x) = f(x, y)/f(x)$ so an *equivalent* definition of statistical independence is $f(y|x) = f(y)$ for

¹For discrete RVs, replace densities with mass functions throughout, e.g. $p(x, y) = p(x)p(y)$.

all x, y in the support sets of X and Y . In other words, X and Y are independent if and only if knowing X provides *no additional information* about Y : the conditional density of Y given X is the same as the marginal density of Y . Of course we could just have easily reversed the roles of X and Y : an additional equivalent definition of conditional independence is $f(x|y) = f(x)$.

A closely related property is **conditional independence**. Two continuous random variables X and Y are conditionally independent given a third random variable Z if and only if $f(x, y|z) = f(x|z)f(y|z)$ for all x, y, z in the support sets of X, Y, Z . Using the definition of a conditional density, $f(y|x, z) = f(x, y|z)/f(x|z)$, this is equivalent to $f(y|x, z) = f(y|z)$. Reversing the roles of y and x , it is *also* equivalent to $f(x|y, z) = f(x|z)$.² If X and Y are conditionally independent given Z , this means that any dependence between X and Y comes solely from the fact that both are dependent on Z . In words: if we already know Z , then knowing X tells us nothing additional about Y , and vice-versa. We define conditional independence for continuous random *vectors* analogously: \mathbf{X} and \mathbf{Y} are conditionally independent given \mathbf{Z} if $f(\mathbf{x}, \mathbf{y}|\mathbf{z}) = f(\mathbf{x}|\mathbf{z})f(\mathbf{y}|\mathbf{z})$, or equivalently if $f(\mathbf{y}|\mathbf{x}, \mathbf{z}) = f(\mathbf{y}|\mathbf{z})$ or $f(\mathbf{x}|\mathbf{y}, \mathbf{z}) = f(\mathbf{x}|\mathbf{z})$. For discrete random vectors, replace densities with mass functions.³

Independence, conditional and unconditional, is such an important concept in statistics and econometrics that it has its own symbol: “ \perp .” If we write $X \perp Y$ this means that X is independent of Y ; if we write $X \perp Y|Z$, this means that X is independent of Y , given Z . The same notation is used for random variables and random vectors.

2.2 Independence versus Mean Independence

Because our goal is to identify average treatment effects, we will be particularly interested in the consequences that conditional independence has for *means*.

Lemma 2.1. *Let X, Y, Z be random variables. If $X \perp Y|Z$ then*

- (i) $\mathbb{E}[XY|Z] = \mathbb{E}[X|Z]\mathbb{E}[Y|Z]$
- (ii) $\mathbb{E}[Y|X, Z] = \mathbb{E}[Y|Z]$
- (iii) $\mathbb{E}[X|Y, Z] = \mathbb{E}[X|Z]$.

Proof. The general case follows as a corollary of [Proposition 2.1](#). Here we will assume that X, Y, Z are continuous random variables. Results for discrete RVs follow by

²There are in fact many equivalent definitions of conditional independence. For full details see the Technical Appendix ([section 2.6](#)).

³For a fully general definition of conditional independence, see the Technical Appendix ([section 2.6](#)).

replacing integrals with sums. For (i), use $f(x, y|z) = f(x|z)f(y|z)$ and the definition of conditional expectation to write

$$\begin{aligned} E[XY|Z = z] &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xyf(x, y|z) dx dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xyf(x|z)f(y|z) dx dy \\ &= \int_{-\infty}^{\infty} yf(y|z) \left(\int_{-\infty}^{\infty} xyf(x|z) dx \right) dy = E[X|Z = z] \int_{-\infty}^{\infty} yf(y|z) dy \\ &= E[X|Z = z]E[Y|Z = z]. \end{aligned}$$

For (ii), use $f(y|x, z) = f(y|z)$ and the definition of conditional expectation to write

$$E[Y|X = z, Z = z] = \int_{-\infty}^{\infty} yf(y|x, z) dy = \int_{-\infty}^{\infty} yf(y|z) dy = E[Y|Z = z].$$

The argument for (iii) is nearly identical, combining $f(x|y, z) = f(x|z)$ with the definition of conditional expectation. \square

Properties (ii) and (iii) of the lemma are often called **mean independence**. It is important to remember that conditional independence implies mean independence but *not the other way around*. Conditional independence is the stronger assumption. There is also a version of [Lemma 2.1](#) that holds without conditioning on Z : $X \perp\!\!\!\perp Y$ implies that $E[XY] = E[X]E[Y]$, $E[Y|X] = E[Y]$, and $E[X|Y] = E[X]$. A good exercise would be to prove these implications for yourself if X and Y are continuous. Similar results also hold for random *vectors*: if $\mathbf{X} \perp\!\!\!\perp \mathbf{Y}|\mathbf{Z}$ then $E[\mathbf{Y}|\mathbf{X}, \mathbf{Z}] = E[\mathbf{Y}|\mathbf{Z}]$ and $E[\mathbf{X}|\mathbf{Y}, \mathbf{Z}] = E[\mathbf{X}|\mathbf{Z}]$. Moreover, if $\mathbf{X} \perp\!\!\!\perp \mathbf{Y}$ then $E[\mathbf{Y}|\mathbf{X}] = E[\mathbf{Y}]$ and $E[\mathbf{X}|\mathbf{Y}] = E[\mathbf{X}]$.

2.3 Randomize treatments to eliminate selection bias.

Now that we know something about mean independence, we can propose our first solution to the problem of selection bias, as described in [section 1.8](#) above. Suppose that, instead of arising naturally from the decisions people make, treatments were *randomly assigned* to people, independently of any of their characteristics. In this case, D would be *independent* of (Y_0, Y_1) . By an argument nearly identical to that in [Lemma 2.1](#) only without the “ Z ” this would imply that $E(Y_0|D) = E(Y_0)$ and $E(Y_1|D) = E(Y_1)$. Thus,

$$\begin{aligned} \beta_{OLS} &= E(Y|D = 1) - E(Y|D = 0) \\ &= E(Y_1|D = 1) - E(Y_0|D = 0) \\ &= E(Y_1 - Y_0) = \text{ATE} \end{aligned}$$

if $D \perp\!\!\!\perp (Y_0, Y_1)$. In words: there is no selection bias in a randomized experiment in which subjects are not free to choose their treatment.⁴ Because randomized experiments are immune to selection bias, experimental studies are considered by many to be a “gold standard” against which other kinds of studies, such as those based on observational data, are to be judged. Valuable though they can be when applied carefully and interpreted correctly, however, randomized controlled trials are no panacea. For a thoughtful recent critique, see Deaton & Cartwright (2018).

2.4 The Axioms of Conditional Independence

Now that we understand that conditional independence means, we have to learn how to work with it mathematically. Our approach will be *axiomatic*: we will state a number of abstract properties that the independence operator $\perp\!\!\!\perp$ satisfies and see how to use these to derive new properties. The result will be a kind of “algebra” of conditional independence: we will learn a number of rules with which we can manipulate a given conditional independence assumption to transform it into new conditional independence assumptions. All of the axioms of conditional independence can be rigorously proved from first principles: see the Technical Appendix for details (section 2.6). The names attached to axioms (i) and (iii)–(v) are taken from Pearl (1988). Axiom (ii) has not been given a name in the literature, so I have christened it the “redundancy” property. Note that when we write $W = h(Y)$ where h is a measurable function, this is equivalent to saying that W is Y -measurable: in other words, knowing the realization of Y tells us with certainty the realization of W .

Theorem 2.1 (Axioms of Conditional Independence). *Let X, Y, Z, W be random variables defined on a common probability space, and let h be a measurable function. Then:*

- (i) (*Symmetry*): $X \perp\!\!\!\perp Y | Z \implies Y \perp\!\!\!\perp X | Z$.
- (ii) (*Redundancy*): $X \perp\!\!\!\perp Y | Y$.
- (iii) (*Decomposition*): $X \perp\!\!\!\perp Y | Z$ and $W = h(Y) \implies X \perp\!\!\!\perp W | Z$.
- (iv) (*Weak Union*): $X \perp\!\!\!\perp Y | Z$ and $W = h(Y) \implies X \perp\!\!\!\perp Y | (W, Z)$.
- (v) (*Contraction*): $X \perp\!\!\!\perp Y | Z$ and $X \perp\!\!\!\perp W | (Y, Z) \implies X \perp\!\!\!\perp (Y, W) | Z$.

We begin with some important discussion of what these properties mean, how they can be used, and how they relate to properties used by other authors.

⁴This rules out settings in which some experimental subjects refuse to comply with the treatment they have been randomly assigned. We take up this more challenging case in a later chapter.

Random Variables vs. Vectors All of the results from above and the Technical Appendix, including [Proposition 2.1](#) and [Theorem 2.1](#), hold regardless of whether X, Y, Z, W are real-valued random variables, random vectors, or arbitrary collections of random variables and vectors. This is important, as it is typically necessary to find “clever” choices of X, Y, Z, W when applying the axioms of conditional independence. Often this requires defining one or more of these to be a *collection* of random variables, as we will see in many of the examples below.

Conditional vs. Unconditional Axioms Axioms (i) and (iii)–(v) are stated conditional on Z , but these same statements also hold *unconditionally* by dropping Z .⁵ Because it is easier to put these unconditional versions of the axioms into words, I omit explicit conditioning on Z in some of the verbal explanations below.

Symmetry The symmetry property says that if learning Y does not give us any information about X , then learning X does not give us any information about Y . This is actually somewhat surprising, as the equality $\mathbb{E}(\mathbb{1}\{A_X\} | Y, Z) = \mathbb{E}(\mathbb{1}\{A_X\} | Z)$ does *not* treat X and Y symmetrically. Symmetry only becomes intuitively clear after establishing [Proposition 2.1](#).

Redundancy The redundancy property says that if I already know Y , then learning Y *a second time* provides no additional information about X . Since $X \perp\!\!\!\perp Y | Y$ implies $Y \perp\!\!\!\perp X | Y$ by symmetry, another way of interpreting this condition is that, conditional on itself, a random variable Y is independent of *any other random variable*. In fact we can establish a more general result using similar reasoning, namely $X \perp\!\!\!\perp W | Y$ if W is Y -measurable. A proof of this fact using the axioms of conditional independence appears in the following section.

Decomposition The decomposition property says that if learning Y provides no information about X , then learning a *function* of Y likewise provides no information about X . If W is a measurable function of Y then it contains *at most* the same information content as Y . A common use of decomposition is to *drop* a random variable from a conditional independence statement. For example, suppose that $X_1 \perp\!\!\!\perp (X_2, X_3) | Z$. Since X_2 is (X_2, X_3) -measurable, it follows that $X_1 \perp\!\!\!\perp X_2 | Z$. Analogously, $X_1 \perp\!\!\!\perp X_3 | Z$. This *consequence* of the decomposition axiom is what some authors call “the decomposition property.”

Weak Union The weak union property says that if learning Y provides no information about X , then learning Y after having *already learned* a function of Y likewise provides no

⁵Formally, this is equivalent to taking $\sigma(Z) = \emptyset$.

information about X . In effect, weak union allows us to *add* something to our conditioning set. A common application of this property is to move a random variable from the “left” of the conditioning bar to the “right.” For example, suppose that $X_1 \perp\!\!\!\perp (X_2, X_3) | Z$. Since X_2 is (X_2, X_3) -measurable, weak union gives $X_1 \perp\!\!\!\perp (X_2, X_3) | (X_3, Z)$. It follows by decomposition that $X_1 \perp\!\!\!\perp X_2 | (X_3, Z)$. Naturally, the same logic shows that $X_1 \perp\!\!\!\perp X_3 | (X_2, Z)$. This *consequence* of the weak union and decomposition axioms is what some authors call the “weak union property.”

Contraction The contraction property is a bit complicated to put into words. In effect, it allows us to move a random variable from the “right” of the conditioning bar to the “left”. For example, suppose that $X_1 \perp\!\!\!\perp X_2 | (X_3, X_4)$ and we want to show that $X_1 \perp\!\!\!\perp (X_2, X_3) | X_4$. If $X_1 \perp\!\!\!\perp X_3 | X_4$, then contraction will give us our desired result.

2.5 More Properties of Conditional Independence

The axioms of conditional independence from [Theorem 2.1](#) provide a simple but powerful way to deduce new conditional independence relationships from old ones.

Corollary 2.1. $X \perp\!\!\!\perp Y | Z$ implies $(X, Z) \perp\!\!\!\perp Y | Z$.

Proof of Corollary 2.1. By symmetry,

$$Y \perp\!\!\!\perp X | Z \tag{2.1}$$

and by redundancy,

$$Y \perp\!\!\!\perp (X, Z) | (X, Z). \tag{2.2}$$

Now, applying the decomposition property to [\(2.2\)](#)

$$Y \perp\!\!\!\perp Z | (X, Z) \tag{2.3}$$

and hence, applying the contraction property to [\(2.1\)](#) and [\(2.3\)](#), we obtain $Y \perp\!\!\!\perp (X, Z) | Z$. The result follows by symmetry. \square

Another simple result that can be derived from the axioms of conditional probability is the following extension of the redundancy property. This does not appear in any references that I have seen, but it is easy to establish using the axioms of conditional independence.

Corollary 2.2. Let $W = h(Y)$ where h is a measurable function. Then $X \perp\!\!\!\perp W | Y$.

Proof of Corollary 2.2. By redundancy $X \perp\!\!\!\perp Y | Y$. By decomposition, taking Y to be “ Z ,” this yields $X \perp\!\!\!\perp W | Y$. \square

The well known-result that $X \perp\!\!\!\perp Y|Z$ implies $f(X) \perp\!\!\!\perp g(Y)|Z$ also follows directly from the axioms of conditional independence.

Corollary 2.3. *Let f and g be measurable functions. Then $X \perp\!\!\!\perp Y|Z \implies f(X) \perp\!\!\!\perp g(Y)|Z$.*

Proof of Corollary 2.3. By decomposition, $X \perp\!\!\!\perp g(Y)|Z$. Hence, by symmetry $g(Y) \perp\!\!\!\perp X|Z$. Applying decomposition a second time, $g(Y) \perp\!\!\!\perp f(X)|Z$. The result follows by a final application of symmetry. \square

2.6 Appendix: Technical Details

Definition 2.1 (Conditional Independence). Let X, Y, Z be random variables defined on a common probability space $(\Omega, \mathcal{A}, \mathbb{P})$. We say that X is conditionally independent of Y given Z (with respect to \mathbb{P}), written $X \perp\!\!\!\perp Y|Z$ if for all events $A_X \in \sigma(X)$ we have $\mathbb{E}(\mathbb{1}\{A_X\} | Y, Z) = \mathbb{E}(\mathbb{1}\{A_X\} | Z)$, \mathbb{P} -almost surely.

Proposition 2.1 (Equivalent Definitions of Conditional Independence). *Let X, Y, Z be random variables defined on a common probability space $(\Omega, \mathcal{A}, \mathbb{P})$. Then the following statements are equivalent:*

- (i) $X \perp\!\!\!\perp Y|Z$
- (ii) For all real, bounded, measurable functions f , $\mathbb{E}[f(X)|Y, Z] = \mathbb{E}[f(X)|Z]$
- (iii) For all, real, bounded, measurable functions f, g , $\mathbb{E}[f(X)g(Y)|Z] = \mathbb{E}[f(X)|Z] \mathbb{E}[g(Y)|Z]$
- (iv) For all $A_X \in \sigma(X)$ and all $A_Y \in \sigma(Y)$, $\mathbb{E}[\mathbb{1}\{A_X \cap A_Y\} | Z] = \mathbb{E}[\mathbb{1}\{A_X\} | Z] \mathbb{E}[\mathbb{1}\{A_Y\} | Z]$

where all equalities of conditional expectations are understood to hold \mathbb{P} -almost surely.

Proof of the Symmetry Property. The symmetry property follows immediately from the alternative definition of conditional independence given in [Proposition 2.1](#) (iii). \square

Proof of the Redundancy Property. Let f and g be real-valued, bounded, measurable functions. Since $g(Y)$ is Y -measurable,

$$\mathbb{E}[f(X)g(Y)|Y] = \mathbb{E}[f(X)|Y]g(Y) = \mathbb{E}[f(X)|Y] \mathbb{E}[g(Y)|Y]$$

so the result follows by [Proposition 2.1](#) (iii). \square

Proof of the Decomposition Property. Let f be a real-valued, bounded, measurable function. Since W is a measurable function of Y , we have $\sigma(W) \subseteq \sigma(Y)$ and consequently $\sigma(W, Z) \subseteq \sigma(Y, Z)$. Hence, by the *tower property* of conditional expectation,

$$\mathbb{E}[f(X)|W, Z] = \mathbb{E}\{\mathbb{E}[f(X)|Y, Z] | W, Z\}.$$

But since $X \perp\!\!\!\perp Y|Z$, **Proposition 2.1** (ii) gives $\mathbb{E}[f(X)|Y, Z] = \mathbb{E}[f(X)|Z]$. And because $\mathbb{E}[f(X)|Z]$ is (W, Z) -measurable,

$$\mathbb{E}\{\mathbb{E}[f(X)|Z] | W, Z\} = \mathbb{E}[f(X)|Z] \mathbb{E}[1 | W, Z] = \mathbb{E}[f(X)|Z].$$

Thus, $\mathbb{E}[f(X)|W, Z] = \mathbb{E}[f(X)|Z]$ so the result follows by **Proposition 2.1** (ii). \square

Proof of the Weak Union Property. Let f be a real-valued, bounded, measurable function. Since W is a measurable function of Y , we have $\sigma(W) \subseteq \sigma(Y)$. As a result, it follows that $\sigma(Y, W, Z) = \sigma(Y, Z)$ and hence $\mathbb{E}[f(X)|Y, W, Z] = \mathbb{E}[f(X)|Y, Z]$. Now, since $X \perp\!\!\!\perp Y|Z$, **Proposition 2.1** (ii) gives $\mathbb{E}[f(X)|Y, Z] = \mathbb{E}[f(X)|Z]$. Finally, since $X \perp\!\!\!\perp Y|Z$ and W is Y -measurable, the decomposition property, **Theorem 2.1** (iii), gives $X \perp\!\!\!\perp W|Z$ and hence $\mathbb{E}[f(X)|Z] = \mathbb{E}[f(X)|Z, W]$. Hence, the result follows by **Proposition 2.1** (ii). \square

Proof of the Contraction Property. Let f be a real, bounded, measurable function. Now, since $X \perp\!\!\!\perp W|(Y, Z)$ we have $\mathbb{E}[f(X)|Y, W, Z] = \mathbb{E}[f(X)|Y, Z]$ by **Proposition 2.1** (ii). Similarly, since $X \perp\!\!\!\perp Y|Z$ we have $\mathbb{E}[f(X)|Y, Z] = \mathbb{E}[f(X)|Z]$. Combining these equalities gives $\mathbb{E}[f(X)|Y, W, Z] = \mathbb{E}[f(X)|Z]$ so the result follows by **Proposition 2.1** (i). \square

Chapter 3

Selection on Observables

As we saw in [chapter 2](#), there is no selection bias when D is randomly assigned: a simple comparison of mean outcomes between treated and untreated individuals identifies the ATE. In many examples, however, carrying out a randomized controlled trial may be infeasible, unethical, or even impossible. In this chapter we will consider an assumption called *selection on observables* that allows us to identify the ATE from observational data by conditioning on observed characteristics \mathbf{X} . We'll consider two different approaches to identification that both rely on the selection on observables assumption: one based on regression adjustment and another based on propensity score weighting.

3.1 Does education cause political participation?

University graduates are more likely to vote, volunteer for political campaigns, contact their elected representatives, and participate in demonstrations. Does this show that education *causes* political participation? Let $D = 1$ if you attended university and $D = 0$ otherwise. Further let Y be an index of political participation, where high values indicate greater participation and lower values indicate less. It seems hard to believe that D could be independent of the potential outcomes (Y_0, Y_1) in this example. University graduates differ from non-graduates in myriad ways that could also influence political participation. People from wealthy backgrounds are more likely to graduate from college. They are also more likely to have the leisure time required for political participation; if you are struggling to make ends meet it will be hard to find time to attend a political rally. Because it seems far-fetched to imagine anyone carrying out an experiment that forced some people to attend college and others not to, observational data is the best we can hope for if our goal is to identify the causal effect of education on political participation.

The assumption that $(Y_0, Y_1) \perp\!\!\!\perp D$ is clearly untenable, so what could we use instead? Our main reason for doubting that a simple comparison of mean political participation across groups could be given a causal interpretation was that university graduates are

different from non-graduates in more ways than their education level. But perhaps if we were to *condition* on these differences, effectively holding them fixed, we could find a way to make progress. In other words, even if (Y_0, Y_1) are not independent of D , perhaps there is a collection of observable individual characteristics \mathbf{X} such that $(Y_0, Y_1) \perp\!\!\!\perp D | \mathbf{X}$. For example, perhaps by conditioning on sex, race, family background and so on we could break the dependence between college graduation and the potential outcomes. This idea is called *selection on observables* because it assumes that selection bias operates solely through characteristics that we can observe.

3.2 Selection on Observables and Overlap

The methods explored in this chapter rely on two assumptions. First is *selection on observables*, as outlined in the previous section. The precise version of this condition that we will rely on below is as follows.

Assumption 3.1 (Selection on Observables).

$$\mathbb{E}(Y_0 | \mathbf{X}, D) = \mathbb{E}(Y_0 | \mathbf{X}), \quad \text{and} \quad \mathbb{E}(Y_1 | \mathbf{X}, D) = \mathbb{E}(Y_1 | \mathbf{X}).$$

Assumption 3.1 says that the potential outcomes (Y_0, Y_1) are *mean independent* of the treatment D conditional on \mathbf{X} . This is weaker than but implied by the conditional independence assumption, namely $(Y_0, Y_1) \perp\!\!\!\perp D | \mathbf{X}$, described in the previous section.¹ Because our goal is to identify a mean, the ATE, we only require a mean independence assumption. To introduce our second assumption we require the following definition.

Definition 3.1 (Propensity Score). The probability $p(\mathbf{X}) \equiv \mathbb{P}(D = 1 | \mathbf{X})$ of treatment conditional on an observed random vector \mathbf{X} is called the propensity score.

Assumption 3.2 (Overlap). $0 < p(\mathbf{x}) < 1$ for all \mathbf{x} in the support of \mathbf{X} .

Assumption 3.2 states that the propensity score is *strictly* between zero and one for any value that the covariates \mathbf{X} could take on. Since $p(\mathbf{x}) \equiv \mathbb{P}(D = 1 | \mathbf{X} = \mathbf{x})$, this requires that, among people with any fixed value \mathbf{x} of the covariates \mathbf{X} , some are treated ($D = 1$) and some are untreated ($D = 0$).

Both **Assumption 3.1** and **Assumption 3.2** are crucial for the methods described below. Unfortunately the two are somewhat at odds with each other. The more observed controls \mathbf{X} that we condition on, the more plausible the selection on observables assumption (**Assumption 3.1**) becomes.² At the same time, conditioning on a richer set of controls makes it *harder* to satisfy the overlap condition. Suppose that \mathbf{X} includes race,

¹See part (ii) of **Lemma 2.1**.

²But beware of *bad controls*! See **section 3.8** for details.

sex, whether or not you attended an independent secondary school, year of birth, and post code. It is distinctly possible that *every* white male who attended an independent secondary school and was born in 1995 to a wealthy North Oxford family in fact graduated from university. If so, the overlap assumption fails for this particular value of \mathbf{x} . A common although not entirely satisfactory solution to the failure of [Assumption 3.2](#) is to redefine the population of interest by restricting attention to only those values \mathbf{x} for which overlap holds. For example, we might be forced to exclude people born to wealthy North Oxford families from our population of interest. Note that if we take this route, we will identify a *different* ATE than the one we initially set out to recover: one that corresponds to the restricted population.

3.3 Identification by Regression Adjustment

Our first approach to identifying the ATE using [Assumption 3.1](#) and [Assumption 3.2](#) is called *regression adjustment*. The idea is to compare mean values of Y between treated and untreated individuals within *strata* defined by a common value \mathbf{x} of the covariates. This yields a conditional ATE given that $\mathbf{X} = \mathbf{x}$. This quantity, which we denote $\text{ATE}(\mathbf{x})$, is the average treatment effect for a certain kind of person, namely someone with covariates equal to \mathbf{x} , e.g. a white male born to a wealthy North Oxford family in 1995. To convert this into an unconditional ATE we average $\text{ATE}(\mathbf{x})$ over the distribution of \mathbf{X} in the population using the law of iterated expectations ([Lemma 1.2](#)).

Theorem 3.1. *Under [Assumption 3.1](#) and [Assumption 3.2](#),*

$$\text{ATE} \equiv \mathbb{E}(Y_1 - Y_0) = \mathbb{E}_{\mathbf{X}} [\mathbb{E}(Y|\mathbf{X}, D = 1)] - \mathbb{E}_{\mathbf{X}} [\mathbb{E}(Y|\mathbf{X}, D = 0)].$$

Proof. Since $Y = Y_0 + D(Y_1 - Y_0)$, under selection on observables

$$\begin{aligned} \mathbb{E}(Y|\mathbf{X}, D) &= \mathbb{E}(Y_0|\mathbf{X}, D) + D [\mathbb{E}(Y_1|\mathbf{X}, D) - \mathbb{E}(Y_0|\mathbf{X}, D)] \\ &= \mathbb{E}(Y_0|\mathbf{X}) + D [\mathbb{E}(Y_1|\mathbf{X}) - \mathbb{E}(Y_0|\mathbf{X})] \end{aligned}$$

where the first equality follows by the properties of conditional expectation, and the second from [Assumption 3.1](#). Substituting $D = 0$ and $D = 1$ into the preceding expression,

$$\mathbb{E}(Y|\mathbf{X}, D = 0) = \mathbb{E}(Y_0|\mathbf{X}), \quad \mathbb{E}(Y|\mathbf{X}, D = 1) = \mathbb{E}(Y_1|\mathbf{X})$$

which in turn implies that

$$\text{ATE}(\mathbf{X}) = \mathbb{E}(Y_1 - Y_0|\mathbf{X}) = \mathbb{E}(Y|\mathbf{X}, D = 1) - \mathbb{E}(Y|\mathbf{X}, D = 0).$$

The overlap assumption ([Assumption 3.2](#)) implies that $\text{ATE}(\mathbf{X})$ is well-defined for all

points in the support of \mathbf{X} , since it ensures that there are individuals with $D = 1$ and $D = 0$ for any value of the covariates. Hence, taking the expectation of both sides,

$$\text{ATE} = \mathbb{E}_{\mathbf{X}} [\text{ATE}(\mathbf{X})] = \mathbb{E}_{\mathbf{X}} [\mathbb{E}(Y|\mathbf{X}, D = 1)] - \mathbb{E}_{\mathbf{X}} [\mathbb{E}(Y|\mathbf{X}, D = 0)]$$

by the law of iterated expectations. □

3.4 Estimation by Regression Adjustment

Let $\hat{\mu}_0(\mathbf{X})$ be a consistent estimator of $\mathbb{E}(Y|\mathbf{X}, D = 0)$ and $\hat{\mu}_1(\mathbf{X})$ be a consistent estimator of $\mathbb{E}(Y|\mathbf{X}, D = 1)$. Then, under general conditions,

$$\widehat{\text{ATE}}_{RA} \equiv \frac{1}{n} \sum_{i=1}^n [\hat{\mu}_1(\mathbf{X}_i) - \hat{\mu}_0(\mathbf{X}_i)]$$

is a consistent estimator of the ATE, where *RA* stands for *regression adjustment*. The question remains: how do we obtain $\hat{\mu}_0(\cdot)$ and $\hat{\mu}_1(\cdot)$? If \mathbf{X} is discrete and takes on a small number of values, we can simply calculate the sample mean of Y at each combination of $(D = 0, \mathbf{X} = \mathbf{x})$ for $\hat{\mu}_0(\mathbf{x})$ and at each combination of $(D = 1, \mathbf{X} = \mathbf{x})$ for $\hat{\mu}_1(\mathbf{x})$. If \mathbf{X} contains any continuous variables, or is discrete but takes on a large number of values, however, this approach fails. Non-parametric methods, either series or kernel-based, provide an alternative but perform poorly when the dimension of \mathbf{X} is large. Model-based approaches are also possible, e.g. assuming that $\mathbb{E}[Y|D = d, \mathbf{X}]$ is linear in \mathbf{X} for a given value of d . If the model is a poor description of the true conditional mean function, however, this can produce misleading results. Model-based approaches can also mask failures of the overlap assumption: they will always generate a value for $\mathbb{E}[Y|D = d, \mathbf{X} = \mathbf{x}]$ even if there are no individuals in the dataset with $(D = d, \mathbf{X} = \mathbf{x})$. The model extrapolates from values that are actually contained in the dataset. Whichever method is used to construct estimates $\hat{\mu}_0(\cdot)$ and $\hat{\mu}_1(\cdot)$, a simple way to carry out inference that correctly accounts for this first-stage estimation step is to bootstrap pairs (Y_i, \mathbf{X}_i) .

3.5 Identification by Propensity Score Weighting

Our second approach to identifying the ATE using [Assumption 3.1](#) and [Assumption 3.2](#) is called *propensity score weighting*. Whereas regression adjustment compares average values of Y between treated and untreated individuals with the same value of \mathbf{X} , propensity score weighting calculates the average value of Y across *everyone in the population* with weights that depend on each person's actual treatment D and her predicted probability of treatment: the propensity score.

Theorem 3.2. Under *Assumption 3.1* and *Assumption 3.2*,

$$ATE \equiv \mathbb{E}(Y_1 - Y_0) = \mathbb{E} \left[\frac{\{D - p(\mathbf{X})\} Y}{p(\mathbf{X}) \{1 - p(\mathbf{X})\}} \right].$$

Proof. Since D is binary, $D^2 = D$, $(1 - D)^2 = (1 - D)$, and $D(1 - D) = 0$. Hence,

$$\begin{aligned} DY &= D^2 Y_1 + D(1 - D)Y_0 = DY_1 \\ (1 - D)Y &= (1 - D)DY_1 + (1 - D)^2 Y_0 = (1 - D)Y_0 \end{aligned}$$

since $Y = DY_1 + (1 - D)Y_0$. Thus,

$$\mathbb{E} \left[\frac{DY}{p(\mathbf{X})} \middle| \mathbf{X} \right] = \frac{1}{p(\mathbf{X})} \mathbb{E} [DY_1 | \mathbf{X}] \quad (3.1)$$

$$\mathbb{E} \left[\frac{(1 - D)Y}{1 - p(\mathbf{X})} \middle| \mathbf{X} \right] = \frac{1}{1 - p(\mathbf{X})} \mathbb{E} [(1 - D)Y_0 | \mathbf{X}]. \quad (3.2)$$

Now, by iterated expectations and *Assumption 3.1*,

$$\begin{aligned} \mathbb{E}[DY_1 | \mathbf{X}] &= \mathbb{E}_{D|\mathbf{X}} [\mathbb{E}(DY_1 | D, \mathbf{X})] = \mathbb{E}_{D|\mathbf{X}} [D \mathbb{E}(Y_1 | D, \mathbf{X})] = \mathbb{E}_{D|\mathbf{X}} [D \mathbb{E}(Y_1 | \mathbf{X})] \\ &= \mathbb{E}[D | \mathbf{X}] \mathbb{E}[Y_1 | \mathbf{X}] = p(\mathbf{X}) \mathbb{E}[Y_1 | \mathbf{X}] \end{aligned}$$

where the final equality uses $\mathbb{E}[D | \mathbf{X}] = \mathbb{P}(D = 1 | \mathbf{X})$. Similarly,

$$\begin{aligned} \mathbb{E}[(1 - D)Y_1 | \mathbf{X}] &= \mathbb{E}_{D|\mathbf{X}} [\mathbb{E}\{(1 - D)Y_0 | D, \mathbf{X}\}] = \mathbb{E}_{D|\mathbf{X}} [(1 - D) \mathbb{E}(Y_0 | D, \mathbf{X})] \\ &= \mathbb{E}_{D|\mathbf{X}} [(1 - D) \mathbb{E}(Y_0 | \mathbf{X})] = \mathbb{E}[1 - D | \mathbf{X}] \mathbb{E}[Y_0 | \mathbf{X}] \\ &= [1 - p(\mathbf{X})] \mathbb{E}[Y_0 | \mathbf{X}] \end{aligned}$$

Substituting these expressions for $\mathbb{E}[DY_1 | \mathbf{X}]$ and $\mathbb{E}[(1 - D)Y_0 | \mathbf{X}]$ into (3.1) and (3.2)

$$\mathbb{E} \left[\frac{DY}{p(\mathbf{X})} \middle| \mathbf{X} \right] = \mathbb{E}(Y_1 | \mathbf{X}), \quad \mathbb{E} \left[\frac{(1 - D)Y}{1 - p(\mathbf{X})} \middle| \mathbf{X} \right] = \mathbb{E}(Y_0 | \mathbf{X})$$

so we see that

$$\begin{aligned} ATE(\mathbf{X}) &\equiv \mathbb{E}(Y_1 - Y_0 | \mathbf{X}) = \mathbb{E} \left[\frac{DY}{p(\mathbf{X})} - \frac{(1 - D)Y}{1 - p(\mathbf{X})} \middle| \mathbf{X} \right] \\ &= \mathbb{E} \left[\frac{DY \{1 - p(\mathbf{X})\} - (1 - D)Y p(\mathbf{X})}{p(\mathbf{X}) \{1 - p(\mathbf{X})\}} \middle| \mathbf{X} \right] \\ &= \mathbb{E} \left[\frac{DY - DY p(\mathbf{X}) - Y p(\mathbf{X}) + DY p(\mathbf{X})}{p(\mathbf{X}) \{1 - p(\mathbf{X})\}} \middle| \mathbf{X} \right] \\ &= \mathbb{E} \left[\frac{\{D - p(\mathbf{X})\} Y}{p(\mathbf{X}) \{1 - p(\mathbf{X})\}} \middle| \mathbf{X} \right]. \end{aligned}$$

Therefore, taking iterated expectations,

$$\text{ATE} = \mathbb{E}_{\mathbf{X}} [\text{ATE}(\mathbf{X})] = \mathbb{E}_{\mathbf{X}} \left(\mathbb{E} \left[\frac{\{D - p(\mathbf{X})\} Y}{p(\mathbf{X}) \{1 - p(\mathbf{X})\}} \middle| \mathbf{X} \right] \right) = \mathbb{E} \left[\frac{\{D - p(\mathbf{X})\} Y}{p(\mathbf{X}) \{1 - p(\mathbf{X})\}} \right].$$

□

3.6 Estimation by Propensity Score Weighting

Suppose we already have a consistent estimator $\hat{p}(\cdot)$ of the propensity score. Then,

$$\widehat{\text{ATE}}_{PSW} \equiv \frac{1}{n} \sum_{i=1}^n \frac{[D_i - \hat{p}(\mathbf{X}_i)] Y_i}{\hat{p}(\mathbf{X}_i) [1 - \hat{p}(\mathbf{X}_i)]}$$

where *PSW* stands for *propensity score weighting* is a consistent estimator of the ATE under [Assumption 3.1](#), [Assumption 3.2](#), and appropriate regularity conditions. But how can we estimate the propensity score? If \mathbf{X} is discrete and only takes on a small number of values, we can estimate the propensity score directly using the sample fraction of observations with $\mathbf{X} = \mathbf{x}$. This approach is no longer possible when any of the elements of \mathbf{X} is continuous and can perform poorly even for discrete \mathbf{X} if some values \mathbf{x} are shared by only a small number of people in the sample. A common model-based approach is to fit a “flexible” logit model, including levels, squares, and interactions of \mathbf{X} . Although fairly widespread and convenient, this approach has the potential to mask failures of overlap: the logit model will never give $p(\mathbf{X}) = 0$ or 1 regardless of whether there are values of \mathbf{x} for which everyone in the sample is either treated or untreated. Moreover, the particular logit model that we specify could be a poor reflection of the true propensity score. Another approach uses non-parametric methods, either series or kernel based, to estimate the propensity score. While less prone to mis-specification than model-based approaches, non-parametric methods perform poorly when \mathbf{X} is high-dimensional. Regardless of the particular method used, inference for propensity score weighting is somewhat complicated by the first-stage estimation of $\hat{p}(\mathbf{X})$. An easy solution is to bootstrap pairs (\mathbf{X}_i, Y_i) .

3.7 Regression Adjustment versus Propensity Score Weighting

In theory, both [Theorem 3.1](#) and [Theorem 3.2](#) identify the *same* quantity, namely the ATE.³ In practice, however, because they require us to use the data in different ways, estimators based on regression adjustment and propensity score weighting will differ,

³If [Assumption 3.2](#) fails and we are forced to restrict attention individuals with values of \mathbf{X} for which overlap holds, then both theorems identify the ATE for this *restricted* population.

sometimes substantially. Recall that regression adjustment requires us to model and estimate the conditional mean of Y given $(D = 0, \mathbf{X})$ and $(D = 1, \mathbf{X})$ whereas propensity score weighting requires us to model and estimate the conditional probability that $D = 1$ given \mathbf{X} . A particular challenge for propensity score weighting is values of $\hat{p}(\mathbf{X}_i)$ that are close to zero or one, as this causes the fraction in $\widehat{\text{ATE}}_{PSW}$ to become unstable.

3.8 Don't condition on an intermediate outcome!

The key message of this chapter is that conditioning on the right information can allow us to identify causal effects even when treatment is not randomly assigned. The key message of this section is that conditioning on the *wrong* information can lead us to draw erroneous causal conclusions even when treatment *is indeed* randomly assigned. This problem is commonly known as **bad control** or **conditioning on an intermediate outcome**. We'll use a simple example to explain the problem and how to avoid it. For simplicity our discussion will be limited to a binary covariate X that is potentially a “bad control.” Very similar reasoning applies to any covariate, binary or not.

Gwynnaeth attended a bilingual French and English high school in Canada. She is now a university senior lecturer and earns a good living. Did attending a bilingual high school *cause* her earnings to be higher than they otherwise would have been? Let Y be a person's wage, and define $D = 1$ if she attends a bilingual high school and zero otherwise. Gwynnaeth chose to attend a bilingual high school: her D was not randomly assigned. But imagine that we were to carry out an experiment in which we *did* randomly assign D , sending half of a group of students to a bilingual high school and the rest to a regular high school. Since $D \perp\!\!\!\perp (Y_0, Y_1)$, we have $\mathbb{E}(Y_0|D) = \mathbb{E}(Y_0)$ and $\mathbb{E}(Y_1|D) = \mathbb{E}(Y_1)$. Thus,

$$\mathbb{E}(Y|D = 1) - \mathbb{E}(Y|D = 0) = \mathbb{E}(Y_1|D = 1) - \mathbb{E}(Y_0|D = 0) = \mathbb{E}(Y_1 - Y_0) = \text{ATE}$$

since $Y = (1 - D)Y_0 + DY_1$. Because students in this hypothetical experiment are randomly assigned to high schools, we don't need to condition on *anything* to identify the average treatment effect D on Y : a simple comparison of means suffices. But what would happen if we nevertheless *did* choose to condition on something?

Given that she is a university senior lecturer, it will come as no surprise that Gwynnaeth attended university herself. Let $X = 1$ if a person attended university and zero otherwise. Should we condition on X to estimate the ATE in our hypothetical experiment? *Absolutely not!* College attendance X is an **intermediate outcome** aka a **bad control**. Because D causes X as well as Y , the treatment D is no longer randomly assigned if we *condition* on X . In other words, conditioning on X introduces selection bias that was not present unconditionally. We will examine this in two ways: first intuitively using a simple stylized model, and then mathematically, building on our earlier derivations. Consider

the following stylized model:

- (i) Two factors increase a person's wage: knowledge K and innate ability A .
- (ii) Attending a bilingual high school increases K more than attending a regular one.
- (iii) The top 30% of people in the population distribution of $(K + A)$ attend university.

Because D was randomly assigned it is independent of A . This is no longer true, however, conditional on X . First consider the group of people from our experiment who attended university ($X = 1$). Among them, those who didn't attend a bilingual high school ($D = 0$) will have *higher* average ability than those who did ($D = 1$). Why is this the case? Our second assumption was that those who didn't attend a bilingual school end up with a lower value of K , on average, than those who did. Thus, for them to make it into the top 30% of $(K + A)$ requires a *higher* value of A . Putting it another way, if you did attend a bilingual school, then you can make it into the top 30% of $(K + A)$ with a lower value of A . Because those with $(D = 1, X = 1)$ have lower ability than those with $(D = 0, X = 1)$ and lower ability implies lower wages,

$$\mathbb{E}[Y|D = 1, X = 1] - \mathbb{E}[Y|D = 1, X = 0] < \mathbb{E}[Y_1|X = 1] - \mathbb{E}[Y_0|X = 1] = \text{ATE}(X = 1).$$

A similar argument shows that, among those who did not attend university, those with $D = 1$ will have lower average ability than those with $D = 0$.⁴ It follows that

$$\mathbb{E}[Y|D = 1, X = 0] - \mathbb{E}[Y|D = 0, X = 0] < \mathbb{E}[Y_1|X = 0] - \mathbb{E}[Y_0|X = 0] = \text{ATE}(X = 0).$$

In this simple model, conditioning on university attendance would lead us to *understate* the true treatment effect. Now that we understand the basic intuition, we'll take a more mathematical look at the problem of a bad control.

Lemma 3.1. *Let X be a binary RV and suppose that $\mathbb{E}(Y_j) = \mathbb{E}(Y_j|D)$ for $j = 0, 1$. If $\mathbb{E}(Y_j|X, D) = \mathbb{E}(Y_j|X)$ for $j = 0, 1$ then at least one of the following must hold:*

$$(i) \ X \perp\!\!\!\perp D$$

$$(ii) \ \mathbb{E}(Y_j|X) = \mathbb{E}(Y_j) \text{ for } j = 0, 1$$

Proof of Lemma 3.1. Since Y_j is mean independent of D for $j = 0, 1$ and X is binary, the law of iterated expectations gives

$$\begin{aligned} \mathbb{E}(Y_1) &= \mathbb{E}(Y_1|D) = \mathbb{E}_{X|D} [\mathbb{E}(Y_1|D, X)] \\ &= \mathbb{E}(Y_1|D, X = 0)\mathbb{P}(X = 0|D) + \mathbb{E}(Y_1|D, X = 1)\mathbb{P}(X = 1|D) \end{aligned}$$

⁴If you did not make it into the top 30% of the distribution of $(K + A)$ in spite of receiving the extra boost to K that comes from $D = 1$, then you must have had a low value of A .

and similarly for Y_0 . Further imposing that (Y_0, Y_1) are mean independent of D given X

$$\mathbb{E}(Y_0) = \mathbb{E}(Y_0|X=0)\mathbb{P}(X=0|D=d) + \mathbb{E}(Y_0|X=1)\mathbb{P}(X=1|D=d) \quad (3.3)$$

$$\mathbb{E}(Y_1) = \mathbb{E}(Y_1|X=0)\mathbb{P}(X=0|D=d) + \mathbb{E}(Y_1|X=1)\mathbb{P}(X=1|D=d). \quad (3.4)$$

The left-hand sides of (3.3) and (3.4) do not depend on the value d that the treatment D takes on. Thus, to avoid a contradiction between $\mathbb{E}(Y_j|D) = \mathbb{E}(Y_j)$ and $\mathbb{E}(Y_j|X, D) = \mathbb{E}(Y_j|X)$, the RHS *cannot* depend on d either. There are only two ways that this is possible. The first is if $X \perp\!\!\!\perp D$ so that $\mathbb{P}(X=x|D=d) = \mathbb{P}(X=x)$ and

$$\begin{aligned} \mathbb{E}(Y_0) &= \mathbb{E}(Y_0|X=0)\mathbb{P}(X=0) + \mathbb{E}(Y_0|X=1)\mathbb{P}(X=1) \\ \mathbb{E}(Y_1) &= \mathbb{E}(Y_1|X=0)\mathbb{P}(X=0) + \mathbb{E}(Y_1|X=1)\mathbb{P}(X=1). \end{aligned}$$

If X and D are *dependent*, then the only way that the RHS (3.3) and (3.4) could *not* involve d is if $\mathbb{E}(Y_1|X=0) = \mathbb{E}(Y_1|X=1) = \mathbb{E}(Y_1)$ and similarly for Y_0 , so that

$$\begin{aligned} \mathbb{E}(Y_0|X=0)\mathbb{P}(X=0|D=d) + \mathbb{E}(Y_0|X=1)\mathbb{P}(X=1|D=d) &= \mathbb{E}(Y_0) \\ \mathbb{E}(Y_1|X=0)\mathbb{P}(X=0|D=d) + \mathbb{E}(Y_1|X=1)\mathbb{P}(X=1|D=d) &= \mathbb{E}(Y_1) \end{aligned}$$

since $\mathbb{P}(X=0|D=d) + \mathbb{P}(X=1|D=d) = 1$ for any value of d . □

Lemma 3.1 tells us that if treatment is randomly assigned, then any covariate X that is both related to treatment *and* affects the average potential outcomes is *necessarily* a bad control. Given that D is mean independent of (Y_0, Y_1) , such an X cannot satisfy $\mathbb{E}(Y_j|X, D) = \mathbb{E}(Y_j|X)$, the selection on observables assumption. This means that we *cannot* identify the ATE by conditioning on X and using, for example, regression adjustment or propensity score weighting. In our example from above, college attendance (X) was both affected by attending a bilingual high school (D) and in turn affected wages. Given that D was randomly assigned, the lemma shows that college attendance is a bad control in the wages and high-school experiment.

Lemma 3.1 does *not* say that conditioning on a covariate that is related to D and Y is always bad. Indeed the whole point of this chapter is to try to eliminate selection bias by finding covariates that *are* related to D and Y . The lemma concerns a setting where we have already solved the selection problem by randomly assigning D . It tells us when conditioning on X would *introduce* selection bias that was not there to begin with. This may strike you as odd: why would we bother to condition on X if we already knew that the treatment had been randomly assigned? There are two answers to this question. First, it is fairly common in practice for researchers to condition on covariates when analyzing experimental data, either to estimate conditional ATEs for people with different characteristics or to reduce the variance of their overall ATE estimator by “projecting

out” sources of noise in Y . [Lemma 3.1](#) tells us that this is perfectly fine *provided that these covariates were measured before assigning the treatment*: because D is randomly assigned, we know that any *pre-existing* characteristics of individuals, e.g. sex or age, will be independent of treatment and hence cannot be bad controls.

Second, the reasoning used in our proof of [Lemma 3.1](#) also applies to settings in which D is not randomly assigned. Suppose that we have a set of “good controls” \mathbf{W} that satisfy [Assumption 3.1](#), i.e. (Y_0, Y_1) are mean independent of D given \mathbf{W} . Now suppose that we are considering adding an *additional* binary variable X to our set of controls. We should only add X if (Y_0, Y_1) are mean independent of D given the *full* set of controls (\mathbf{W}, X) . Suppose this is the case. Then, by iterated expectations and our two of mean independence assumptions,

$$\begin{aligned}\mathbb{E}(Y_1|\mathbf{W}) &= \mathbb{E}(Y_1|\mathbf{W}, D) = \mathbb{E}_{X|\mathbf{W}, D} [\mathbb{E}(Y_1|\mathbf{W}, D, X)] \\ &= \mathbb{E}(Y_1|\mathbf{W}, D, X=0)\mathbb{P}(X=0|\mathbf{W}, D) + \mathbb{E}(Y_1|\mathbf{W}, D, X=1)\mathbb{P}(X=1|\mathbf{W}, D) \\ &= \mathbb{E}(Y_1|\mathbf{W}, X=0)\mathbb{P}(X=0|\mathbf{W}, D) + \mathbb{E}(Y_1|\mathbf{W}, X=1)\mathbb{P}(X=1|\mathbf{W}, D)\end{aligned}$$

and similarly for Y_0 , yielding

$$\begin{aligned}\mathbb{E}(Y_0|\mathbf{W}) &= \mathbb{E}(Y_0|\mathbf{W}, X=0)\mathbb{P}(X=0|\mathbf{W}, D) + \mathbb{E}(Y_0|\mathbf{W}, X=1)\mathbb{P}(X=1|\mathbf{W}, D) \\ \mathbb{E}(Y_1|\mathbf{W}) &= \mathbb{E}(Y_1|\mathbf{W}, X=0)\mathbb{P}(X=0|\mathbf{W}, D) + \mathbb{E}(Y_1|\mathbf{W}, X=1)\mathbb{P}(X=1|\mathbf{W}, D).\end{aligned}$$

The left hand sides of these equations do not depend on D . By reasoning similar to that used in the proof of [Lemma 3.1](#), the only way that the right hand sides could *not* depend on D is if either $X \perp\!\!\!\perp D|\mathbf{W}$ or $\mathbb{E}(Y_j|\mathbf{W}, X) = \mathbb{E}(Y_j|\mathbf{W})$. If X is determined after D , it is unlikely that the first of these conditions hold. If X satisfies the second condition, then conditioning on it is completely irrelevant in any case: it will neither help us to identify ATEs, conditional or unconditional, nor will it improve the precision of our estimates.