

Particle Swarm Optimization

A parallelized approach

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Particle Swarm Optimization

Particle Swarm Optimization is an optimization algorithm for nonlinear functions based on bird swarms.

In PSO, a particle is characterized by:

- position x ;
- velocity v ;
- performance measure $f(x)$;
- personal best y ;
- global best position z .

The solution is achieved by perturbing each particle according to the neighbors:

- 1 $v' = w \cdot v + \phi_1 U_1 \cdot (y - x) + \phi_2 U_2 \cdot (z - x)$
- 2 $x' = x + v'$

Particle Swarm Optimization

Easom function

$$f(x) = -\cos(x_1) \cos(x_2) \exp(-(x_1 - \pi)^2 - (x_2 - \pi)^2)$$

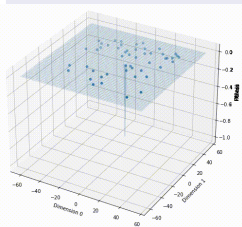


Figure 1: PSO start

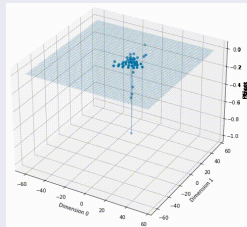


Figure 2: PSO mid

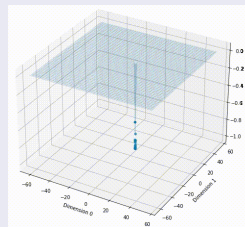


Figure 3: PSO end

Work in progress. . .

Analyzing the program behavior

In order to know each process and thread state and visualize we have employed a thread-safe logging library: The logs follows a common pattern so as to be easily processed.

```
15:27:58 DEBUG : PSODATA      :: problem dimension :: 2
...
15:27:58 DEBUG : New best global solution found
...
15:27:58 INFO  : COMPUTING    :: iteration 10/10
Best fitness 4.690962
```

To recover the particles' positions during the entire program execution, we have stored each particle position at each iteration within a SQLite database.

Serial version of the algorithm

Algorithm 1 Particle Swarm Optimization (Nearest Neighbors)

```
1: function PSO( $\mathcal{S}, \mathcal{D}, MAX\_IT, n, f, v, x, x_{min}, x_{max}, v_{max}$ )
2:   INITIALIZE( $\mathcal{S}, \mathcal{D}, f, v, x, x_{min}, x_{max}, v_{max}$ )
3:    $it = 0$ 
4:   repeat
5:     for each particle  $i \in \mathcal{S}$  do
6:       if  $f(x_i) < f(pb_i)$  then
7:          $pb_i \leftarrow x_i$ 
8:       end if
9:     end for
10:     $S' = \text{COPY}(\mathcal{S})$ 
11:    for each particle  $i \in \mathcal{S}$  do
12:       $S' = \text{SORT}(S', i)$ 
13:      for each particle  $j \in S'$  do
14:        if  $f(x_j) < f(gb_i)$  then
15:           $gb_i \leftarrow x_j$ 
16:        end if
17:      end for
18:    end for
19:    for each particle  $i \in \mathcal{S}$  do
20:      for each dimension  $d \in \mathcal{D}$  do
21:         $v_{i,d} = v_{i,d} + C_1 \cdot \text{Rnd}(0,1) \cdot [pb_{i,d} - x_{i,d}] + C_2 \cdot \text{Rnd}(0,1) \cdot [gb_d - x_{i,d}]$ 
22:         $x_{i,d} = x_{i,d} + v_{i,d}$ 
23:      end for
24:    end for
25:     $it \leftarrow it + 1$ 
26:  until  $it < MAX\_ITERATIONS$ 
27:  return  $x$ 
28: end function
```

Hybrid parallelization

We propose an all-to-all parallel computational pattern using `MPI_Allgather`.

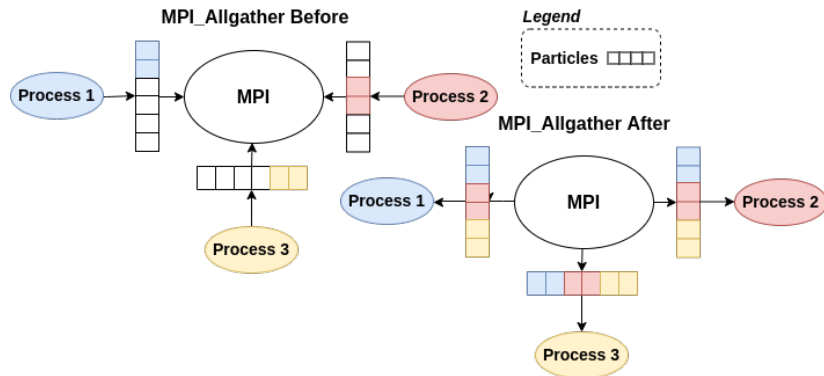
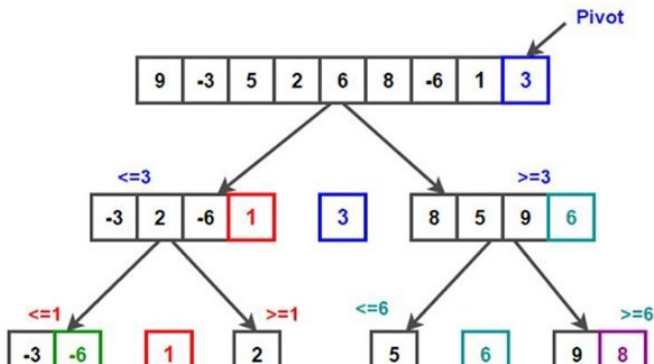


Figure 4: Parallel Architecture

Hybrid parallelization (cont'd)

Once each process knows everything about the others, PSO considers the neighbor contributions in order to update the process particles' position and velocity.

To compute the particle's neighboring positions we have employed the quicksort algorithm.



Benchmarking, first conclusions

The problem we have decided to address consists in solving the sphere function $\left(f(x_1, x_2, \dots, x_n) = \sum_{i=1}^n x_i^2 \right)$ with:

- 50 particle dimensions;
- 500 iterations;
- 5000 particles.

We have run around 1280 tests considering every possible combination of different parameters:

- processes: [1 2 4 8 16 32 64];
- threads: [1 2 4 8 16 32 64];
- chunks: [1 2 3 4 5];
- places: [pack scatter pack:excl scatter:excl].

Benchmarking, first conclusions (cont'd)

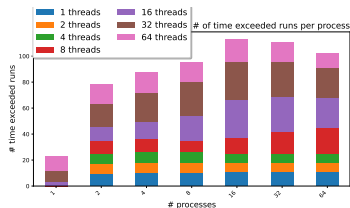


Figure 6: Number of failed run per process

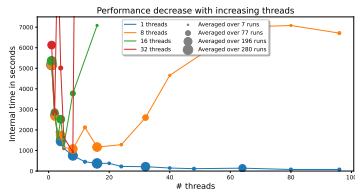


Figure 7: Thread and time exceeded correlation

Benchmarking, first conclusions (cont'd)

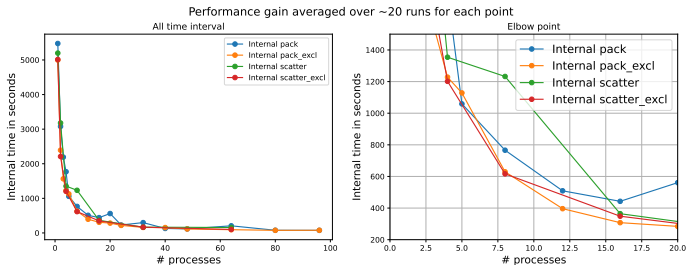


Figure 8: Processes performance

State of the Art Analysis

Ref.	Year	Type	Code	Note
Kennedy et al. (1995)	1995	Serial	No	-
toddguant (2019)	2019	Serial	Yes	1
souusouho (2019)	2019	Serial	Yes	1
kkentzo (2020)	2020	Serial	Yes	1
fisherling (2020)	2020	Serial	Yes	1
Moraes et al. (2015)	2014	MPI	No	-
Nedja et al. (2017)	2017	MPI/MP	No	-
abhi4578 (2019)	2019	MPI/MP,CUDA	Yes	1
LaSEEB (2020)	2020	OpenMP	Yes	2
pg443 (2021)	2021	Serial,OpenMP	Yes	1

Note: (1) only global neighborhood (2) several option but not

Benchmarking, final remarks

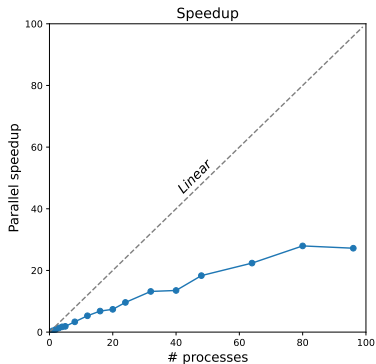


Figure 9: Speedup

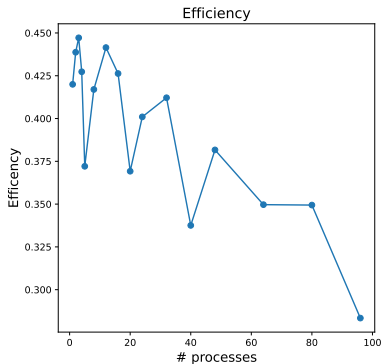


Figure 10: Efficiency

Up until this point, we produced a hybrid OpenMP-MPI algorithm to solve complex continuous optimization problems.

From the benchmarking analysis we claim:

- thread parallelization does not fit well our solution;
- benchmarking the algorithm is far from being trivial;
- the program provides its best result when the number of processes is limited.

As a future work, it would be interesting to:

- complement the already present architecture with different type of neighborhood;
- analyze which configuration brought the best results.

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