

## 1 Frame Theory

If  $\text{rank}(A) = m$  for  $A \in \mathbb{C}^{n \times m}, n \geq m$ , then  $A^\dagger = (A^*A)^{-1}A^*$  is a left-inverse of  $A$  and the solutions to  $LA = I$  are

$$L = A^\dagger + M(I - AA^\dagger), \quad M \in \mathbb{C}^{n \times m}.$$

**Definition 1.1** (Frame). *Let  $H$  be a Hilbert space. A set  $(g_k)_k \in H$  is called a frame if there exist  $0 < A \leq B < \infty$  such that*

$$A\|x\|^2 \leq \sum_k \|\langle x, g_k \rangle\|^2 \leq B\|x\|^2, \quad \text{for all } x \in H.$$

**Definition 1.2** (Analysis & Synthesis).

$$T: H \rightarrow \ell^2, \quad T(x) = (\langle x, g_k \rangle)_k$$

$$T^*: \ell^2 \rightarrow H, \quad T^*(y) = \sum_k y_k g_k$$

### Theorem 1: Frame Operator

The frame operator  $S = T^*T$  satisfies:

- (i)  $S^* = S$ .
- (ii)  $S$  is positive definite.
- (iii)  $S$  has a square root  $S^{1/2}$ .
- (iv)  $S$  is invertible.

### Theorem 2: Frame Bounds

The tightest possible frame bounds are given by the smallest and largest eigenvalues of  $S$ .

### Theorem 3: Dual Frame

For a frame  $(g_k)_k$  with frame bounds  $A$  and  $B$ , the set  $(\tilde{g}_k)_k = (S^{-1}g_k)_k$  is frame with frame bounds  $1/B$  and  $1/A$ , and with analysis operator  $\tilde{T} = TS^{-1}$ . We have  $\tilde{T}^*T = T^*\tilde{T} = \text{id}$ .

**Definition 1.3** (Tight Frame). *A frame with frame bounds  $A = B$  is called a tight frame.*

### Theorem 4: Tight Frame

A frame is tight with frame bound  $A$  iff its frame operator is of the form  $S = A \text{id}$ .

### Theorem 5

For any frame  $(g_k)_k$ , the set  $(S^{-1/2}g_k)_k$  is a tight frame with frame bound 1.

### Theorem 6

A tight frame  $(g_k)_k$  with frame bound  $A = 1$  and  $\|g_k\| = 1$  for all  $k$  is an ONB.

**Definition 1.4.** *A set  $(g_k)_k$  is called complete, if*

$$\langle x, g_k \rangle = 0 \quad \forall k \Rightarrow x = 0.$$

**Definition 1.5.** *A frame  $(g_k)_k$  is called exact if for all  $n$ , the set  $(g_k)_{k \neq n}$  is incomplete.*

### Theorem 7: Exactness

Let  $(g_k)_k$  be a frame and  $(\tilde{g}_k)_k$  its canonical dual. Then,  $(g_k)_k$  is exact iff  $\langle g_j, \tilde{g}_k \rangle = \delta_{jk}$ .

### Theorem 8: Sampling theorem

Let  $x \in L^2(\mathbb{R})$  be bandlimited to  $B$ , i.e.  $\hat{x}(f) = 0$  if  $|f| > B$ . Then, for  $1/T \geq 2B$ ,

$$x(t) = 2BT \sum_{k=-\infty}^{\infty} x(kT) \text{sinc}(2B(t - kT)).$$

## 2 Uncertainty Relations

**Definition 2.1** (Operator Norm).

$$\|A\| = \max_{\|x\|=1} \|Ax\|.$$

**Definition 2.2** (Frobenius Norm).

$$\|A\| = \sqrt{\text{tr}(AA^H)}.$$

### Theorem 9

$$\frac{\|A\|}{\sqrt{\text{rank } A}} \leq \|A\| \leq \|A\|.$$

**Definition 2.3.** *For unitary  $U$ , we set*

$$\Delta_{P,Q}(U) = \left\| D_P U D_Q U^H \right\|.$$

### Theorem 10

$$\Delta_{P,Q}(U) = \max_{x \in \text{im } U D_Q U^H} \frac{\|D_P x\|}{\|x\|}.$$

### Theorem 11

$$\frac{\sqrt{\text{tr}(D_P U D_Q U^H)}}{\min\{|P|, |Q|\}} \leq \Delta_{P,Q}(U) \leq \sqrt{\text{tr}(D_P U D_Q U^H)}.$$

**Definition 2.4** (Coherence). *For  $A = (a_1 \dots a_n) \in \mathbb{C}^{m \times n}$  with normalized columns, the coherence is defined as  $\mu(A) = \max_{i \neq j} |a_i^H a_j|$ .*

### Theorem 12

$$\Delta_{P,Q}(U) \leq \sqrt{|P||Q|} \mu([I \ U]).$$

**Definition 2.5.** *Let  $P \subseteq \{1, \dots, m\}$  and  $\varepsilon_P \in [0, 1]$ . A vector  $x \in \mathbb{C}^m$  is called  $\varepsilon_P$ -concentrated if  $\|x - x_P\|_2 \leq \|\varepsilon_P\|_2 \|x\|_2$ .*

### Theorem 13

Let  $A, B \in \mathbb{C}^{m \times m}$  be unitary and  $P, Q \subseteq \{1, \dots, m\}$ . Suppose there exists a nonzero  $\varepsilon_P$ -concentrated  $p \in \mathbb{C}^m$  and a nonzero  $\varepsilon_Q$ -concentrated  $q \in \mathbb{C}^m$  such that  $Ap = Bq$ . Then,

$$|P||Q| \geq \frac{[1 - \varepsilon_P - \varepsilon_Q]_+^2}{\mu([A \ B])^2}.$$

### Theorem 14

Let  $A, B \in \mathbb{C}^{m \times m}$  be unitary. If  $Ap = Bq$  for nonzero  $p, q \in \mathbb{C}^m$ , then

$$\|p\|_0 \|q\|_0 \geq \frac{1}{\mu([A \ B])^2}.$$

## 3 Compressive Sensing

**Definition 3.1** (Spark). *The spark of a matrix is denfined as the cardinality of the smallest set linearly dependent columns.*

**Theorem 15**

For a matrix  $D \in \mathbb{C}^{m \times n}$ , uniqueness of recovery of  $s$ -sparse vectors  $x$  from the observation  $y = Dx$  is guaranteed if

$$\text{spark}(D) > 2s.$$

**Definition 3.2** (P0).  $\arg \min \|x\|_0$  subject to  $y = Dx$ .

**Theorem 16**

$$1 + \frac{1}{\mu(D)} \leq \text{spark}(D)$$

**Theorem 17**

If

$$\|x_0\|_0 < \frac{1}{2} \left( 1 + \frac{1}{\mu(D)} \right),$$

then  $x_0$  is the unique solution of (P0).

**Definition 3.3** (P1).  $\arg \min \|x'\|_1$  subject to  $y = Dx'$ .

**Theorem 18**

Let  $y = Dx_0$  and assume  $x_0$  has support set  $S$ . If

$$\max_{x \in \ker D \setminus \{0\}} \frac{\sum_{k \in S} |x_k|}{\sum_k |x_k|} < \frac{1}{2},$$

then  $x_0$  is the unique solution of (P1).

**Theorem 19**

If,

$$\|x_0\|_0 < \frac{1}{2} \left( 1 + \frac{1}{\mu(D)} \right), \quad (1)$$

then

$$\max_{x \in \ker D \setminus \{0\}} \frac{\sum_{k \in S} |x_k|}{\sum_k |x_k|} < \frac{1}{2}.$$

Hence, (1) is a sufficient condition such that  $x_0$  is the unique solution of (P1).

**Theorem 20**

If  $D \in \mathbb{C}^{m \times n}$ , then

$$\mu(D) \geq \sqrt{\frac{n-m}{m(n-1)}}.$$

**Theorem 21**

$$\|x\|_\infty \leq \|x\|_2 \leq \|x\|_1 \leq \sqrt{|\text{supp } x|} \|x\|_2$$

## 4 Sampling Spectally Sparse Signals

**Theorem 22**

Consider a signal with spectral occupancy contained in  $I$ . To reconstruct the signal, we need

$$\lim_{r \rightarrow \infty} \inf_{t \in \mathbb{R}} \frac{|P \cap [t, t+r]|}{r} \geq |I|,$$

where  $P = \{t_n\}_n$  denotes the sampling set.

## 5 Restricted Isometry Property

**Definition 5.1.** For each  $s = 1, \dots, n$ , the isometry constant  $\delta_s$  of a matrix  $\Phi \in \mathbb{C}^{m \times n}$  is the smallest number such that

$$(1 - \delta_s) \|x\|_2^2 \leq \|\Phi x\|_2^2 \leq (1 + \delta_s) \|x\|_2^2$$

for every  $s$ -sparse  $x$ .

**Theorem 23**

Let  $y = \Phi x$ . Assume that  $\delta_{2s} < \sqrt{2} - 1$ . Then, the solution  $x^*$  to

$$\arg \min \|x'\|_1 \quad \text{subject to } \Phi x' = y$$

satisfies

$$\|x^* - x\|_1 \leq C_0 \|x - x_s\|_1$$

and

$$\|x^* - x\|_2 \leq C_0 s^{-1/2} \|x - x_s\|_1$$

for some constant  $C_0$ . In particular, if  $x$  is  $s$ -sparse, recovery is exact.

**Theorem 24**

Let  $y = \Phi x + n$ . Assume that  $\delta_{2s} < \sqrt{2} - 1$  and  $\|n\|_2 \leq \varepsilon$ . Then, the solution  $x^*$  to

$$\arg \min \|x'\|_1 \quad \text{subject to } \|y - \Phi x'\| \leq \varepsilon$$

satisfies

$$\|x^* - x\|_2 \leq C_0 s^{-1/2} \|x - x_s\|_1 + C_1 \varepsilon$$

for some constants  $C_0, C_1$ .

**Definition 5.2.** A matrix  $\Phi$  is said to satisfy the restricted null-space property w.r.t  $S$  if

$$\max_{x \in \ker \Phi \setminus \{0\}} \frac{\sum_{k \in S} |x_k|}{\sum_k |x_k|} < \frac{1}{2}.$$

**Theorem 25**

If the isometry constant of order  $2s$  of  $\Phi$  satisfies  $\delta_{2s} < 1/3$ , then  $\Phi$  satisfies the restricted null-space property for any  $S$  with  $|S| \leq s$ .

## 6 Johnson-Lindenstrauss Lemma

**Theorem 26**

Let  $\varepsilon \in (0, 1)$  and suppose

$$k \geq \frac{8}{\varepsilon^2 - \varepsilon^3} \log(2m).$$

Then, for every set  $X \subset \mathbb{R}^n$  of  $m$  points, there exists a (linear) map  $f: \mathbb{R}^n \rightarrow \mathbb{R}^k$  such that for all  $x, x' \in X$  we have

$$(1 - \varepsilon) \|x - x'\|^2 \leq \|f(x) - f(x')\|^2 \leq (1 + \varepsilon) \|x - x'\|^2.$$

## 7 Approximation Theory

Consider a set  $C \subseteq L^2(\Omega)$ .

**Definition 7.1.** Denote by

$$\mathfrak{E}^l = \{E: C \rightarrow \{0, 1\}^l\}$$

the set of binary encoders of length  $l$  and by

$$\mathfrak{D}^l = \{D: \{0, 1\}^l \rightarrow C\}$$

the set of binary decoders of length  $l$ .

**Definition 7.2.** The minimax code length  $L(\varepsilon, C)$  for  $\varepsilon$  is

$$L(\varepsilon, C) = \min \{l \in \mathbb{N} : \exists (E, D) \in \mathfrak{E}^l \times \mathfrak{D}^l : \sup_{f \in C} \|D(E(f)) - f\|_2 \leq \varepsilon\}.$$

The optimal exponent  $\gamma^*(C)$  is defined as

$$\gamma^*(C) = \sup \left\{ \gamma \in \mathbb{R} : L(\varepsilon, C) \in O(\varepsilon^{-1/\gamma}), \varepsilon \rightarrow 0 \right\}.$$

**Definition 7.3.** A metric is a function  $d : X \times X \rightarrow \mathbb{R}$  that satisfies

1.  $d(x, y) \geq 0$ ,
2.  $d(x, y) = 0 \Leftrightarrow x = y$ ,
3.  $d(x, y) = d(y, x)$ ,
4.  $d(x, z) \leq d(x, y) + d(y, z)$ .

**Definition 7.4** ( $\varepsilon$ -covering). An  $\varepsilon$ -covering of a compact set  $C$  with respect to the metric  $d$  is a set  $\{x_1, \dots, x_n\} \subset C$  such that for any  $x \in C$  there exists an  $x_i$  such that  $d(x, x_i) \leq \varepsilon$ .

**Definition 7.5** (Covering Number). The  $\varepsilon$ -covering number  $N(\varepsilon, C, d)$  is the cardinality of the smallest  $\varepsilon$ -covering.

**Definition 7.6** (Metric Entropy). The metric entropy of  $C$  is defined as

$$\log_2 N(\varepsilon, C, d).$$

**Definition 7.7** ( $\varepsilon$ -packing). An  $\varepsilon$ -packing of a compact set  $C$  with respect to the metric  $d$  is a set  $\{x_1, \dots, x_n\} \subset C$  such that  $d(x_i, x_j) > \varepsilon$  if  $i \neq j$ .

**Definition 7.8** (Packing Number). The  $\varepsilon$ -packing number  $M(\varepsilon, C, d)$  is the cardinality of the largest  $\varepsilon$ -packing.

### Theorem 27

The packing and covering number are related according to

$$M(2\varepsilon, C, d) \leq N(\varepsilon, C, d) \leq M(\varepsilon, C, d).$$

## 8 Uniform Laws of Large Numbers

### Theorem 28: Markov's Inequality

Let  $X$  be a random variable and assume  $g : \mathbb{R} \rightarrow [0, \infty)$  is increasing. Then, for any  $c$  with  $g(c) > 0$ ,

$$\mathbb{P}(X \geq c) \leq \frac{\mathbb{E}g(X)}{g(c)}.$$

### Theorem 29: Glivenko-Cantelli

For any distribution, the empirical CDF  $\hat{F}_n$  satisfies

$$\|\hat{F}_n - F\|_\infty \rightarrow 0 \quad \text{a.s.}$$

**Definition 8.1.** Let  $\mathcal{F}$  be a set of integrable real-valued functions and let  $\{X_i\}_{i=1}^n$  be a collection of i.i.d. samples from some distribution  $\mathbb{P}$ . Then we write

$$\|\mathbb{P}_n - \mathbb{P}\|_{\mathcal{F}} = \sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^n f(X_i) - \mathbb{E}f(X) \right|.$$

**Definition 8.2** (Glivenko-Cantelli Class). We say that  $\mathcal{F}$  is a Glivenko-Cantelli class for  $\mathbb{P}$  if  $\|\mathbb{P}_n - \mathbb{P}\|_{\mathcal{F}}$  converges to zero in probability as  $n \rightarrow \infty$ .

**Definition 8.3** (Rademacher Complexity). For any fixed collection  $x_1^n = (x_1, \dots, x_n)$ , consider the set

$$\mathcal{F}(x_1^n) = \{(f(x_1), \dots, f(x_n)) \mid f \in \mathcal{F}\}.$$

The empirical Rademacher complexity is defined as

$$\mathcal{R}(\mathcal{F}(x_1^n)/n) = \mathbb{E}_\varepsilon \left[ \sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^n \varepsilon_i f(x_i) \right| \right],$$

where  $(\varepsilon_i)_{i=1}^n$  is a sequence of Rademacher random variables (uniform on  $\{-1, +1\}$ ).

The Rademacher complexity is defined as

$$\mathcal{R}_n(\mathcal{F}) = \mathbb{E}_X \mathcal{R}(\mathcal{F}(x_1^n)/n) \quad (2)$$

$$= \mathbb{E}_{\varepsilon, X} \left[ \sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^n \varepsilon_i f(x_i) \right| \right]. \quad (3)$$

### Theorem 30

For any  $b$ -uniformly bounded function class, i.e.  $\|f\|_\infty \leq b$  for all  $f \in \mathcal{F}$ , any  $n$  and  $\delta \geq 0$  we have

$$\|\mathbb{P}_n - \mathbb{P}\|_{\mathcal{F}} \leq 2\mathcal{R}_n(\mathcal{F}) + \delta$$

with probability at least  $1 - e^{-\frac{n\delta^2}{2b^2}}$ . Consequently, if  $\mathcal{R}_n(\mathcal{F}) = o(1)$ , we have  $\|\mathbb{P}_n - \mathbb{P}\|_{\mathcal{F}} \rightarrow 0$  a.s.

**Definition 8.4** (Polynomial Discrimination). A class  $\mathcal{F}$  of functions has polynomial discrimination of order  $\nu \geq 1$  if for each  $n$  and  $x_1^n = (x_1, \dots, x_n)$  the set  $\mathcal{F}(x_1^n)$  has cardinality upper bounded according to

$$|\mathcal{F}(x_1^n)| \leq (n+1)^\nu.$$

### Theorem 31

Suppose that  $\mathcal{F}$  has polynomial discrimination of order  $\nu$ . Then, for all  $n$  and  $x_1^n = (x_1, \dots, x_n)$  we have

$$\mathcal{R}(\mathcal{F}(x_1^n)/n) \leq 4D(x_1^n) \sqrt{\frac{\nu \log(n+1)}{n}},$$

where  $D(x_1^n) = \sup_{f \in \mathcal{F}} \sqrt{\frac{\sum_{i=1}^n f(x_i)^2}{n}}$ .

**Definition 8.5** (VC Dimension). Given a class  $\mathcal{F}$  of binary-valued functions, we say that the set  $x_1^n = (x_1, \dots, x_n)$  is shattered by  $\mathcal{F}$  if  $|\mathcal{F}(x_1^n)| = 2^n$ . The VC dimension  $\nu(\mathcal{F})$  is the largest integer  $n$  for which there is some collection  $x_1^n = (x_1, \dots, x_n)$  of  $n$  points that is shattered by  $\mathcal{F}$ .

### Theorem 32: Sauer-Shelah

Consider a set class  $S$  with  $\nu(S) < \infty$ . Then, for any collection of points  $x_1^n = (x_1, \dots, x_n)$  with  $n \geq \nu(S)$  we have

$$|S(x_1^n)| \leq \sum_{i=0}^{\nu(S)} \binom{n}{i} \leq (n+1)^{\nu(S)}.$$