```
1
       PROGRAM Robot_Drive_Select
2
3
          Robot_Drive_Type : INT ;
4
      END_VAR
5
1
       //Selects the control style of robot motor drive
       CASE Robot_Drive_Type OF
3
4
          // This is the F,R,L,R on the GUI control
5
               Robot_Drive_1 ();
7
8
          //This is the joystick control
9
10
               Robot_Drive_2 ();
11
12
     END_CASE
13
```