

2021 Synopsys ARC 盃 AIoT 設計應用競賽 決賽作品

基於邊緣運算架構結合手勢辨識的智慧電梯

Smart elevator based on edge computing architecture combined with gesture recognition

隊員：陳冠瑋、袁鈺彬、羅翊瑄、邱序之

隊名：威鵝·史密斯 / WE-I Goose·Smith



2021.07.25



Agenda

- 作品概述
- 難點與創新
- 設計與實現
- 作品進度
- 測試結果
- 總結展望



作品概述

Introduction

Introduction

- ▷ **Zero-contact technology**
 - Market consumption
 - Medical care
 - School education
 - Restaurant service
 - Public transportation
- ▷ **The virus spread in elevator quickly and easily**
 - 2003 SARS
 - 2019 COVID-19



Introduction

- Gesture recognition
- Always – On system
- Ultra Low Consumption
- Embedded AI Acceleration
- Edge Computing

SYNOPSYS
Silicon to Software™



Himax
Drive for better vision

Himax WE-I Plus

Introduction

	Himax WE-I Plus	ESP8266	Raspberry Pi 4B	NVIDIA Jetson Nano
Price (NT\$)	1,800	240	2,500	3,400
GPIO	4	16	40	40
Flexibility	Low	Medium	High	High
OS	X	X	V	V
Size	47 x 16 (mm x mm)	48.26 x 25.4 (mm x mm)	85.6 x 53.98 (mm x mm)	100 x 80 (mm x mm)
Clock Rate	400 MHz	160 MHz	1.5 GHz	1.5 GHz
Power	< 2.5 mW	250 mW	3.4W / 7.6 W	5W / 10W
ML	V	v	V	V



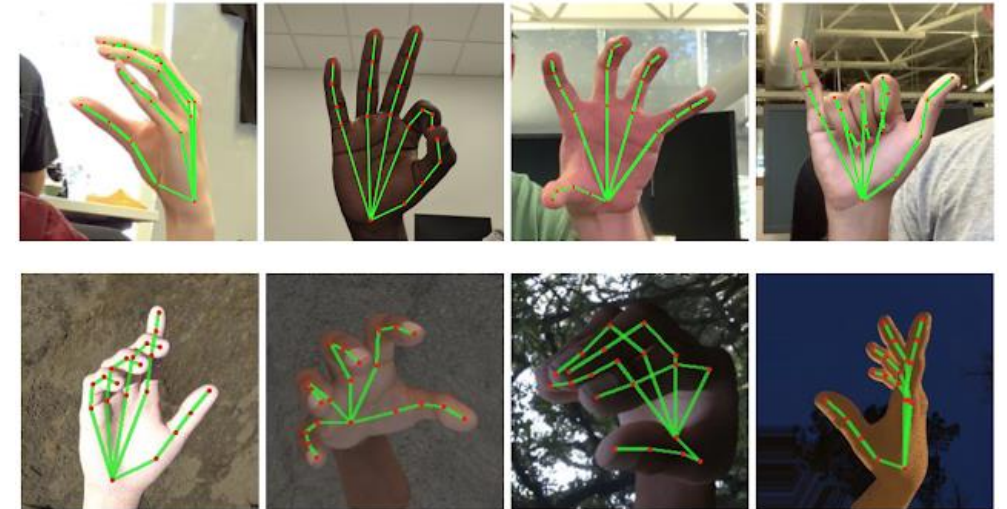
創新與難點

Innovation & Difficulties

Innovation & Difficulties

▷ Difficulties

- Privacy
- Multi-gesture recognition
- Scenes variation
- Different skin color
- Different type of gestures
- Handicapped unfriendly
- 10⁺ flows control & cancelling control
- Recognition speed leads to errors





Innovation & Difficulties

▷ Innovation

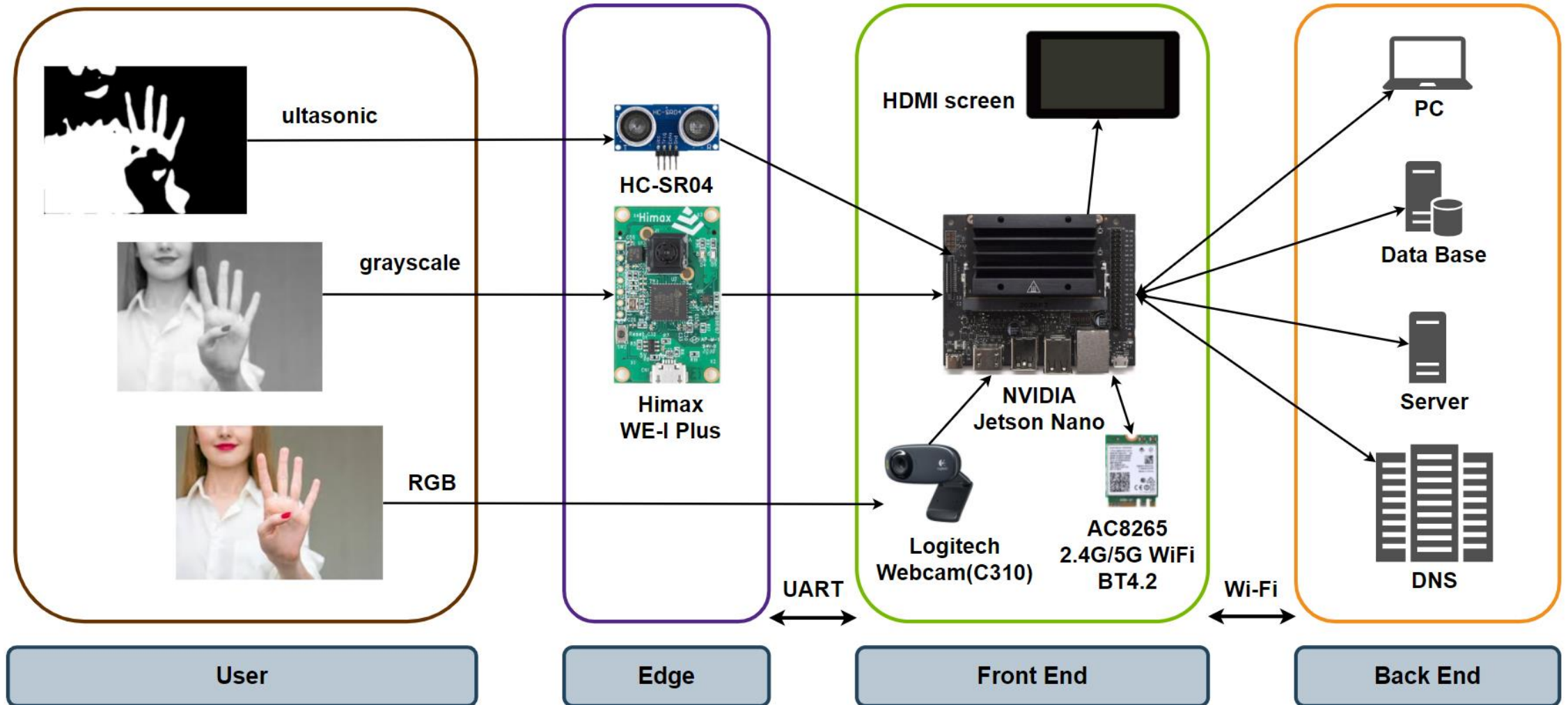
- Control the elevator with **gesture recognition**
- **Always-on** system
- Use ultra-low power AI ASIC (Himax WE-I Plus) as the **trigger** unit
- **Low latency, real-time** hand detection and gesture recognition
- Support **continuous** floors input
- **Simulate** elevator flow control through JavaScript
- Use gesture recognition to **remotely control server**
- **Combination** of high OPS unit and low power edge sensor



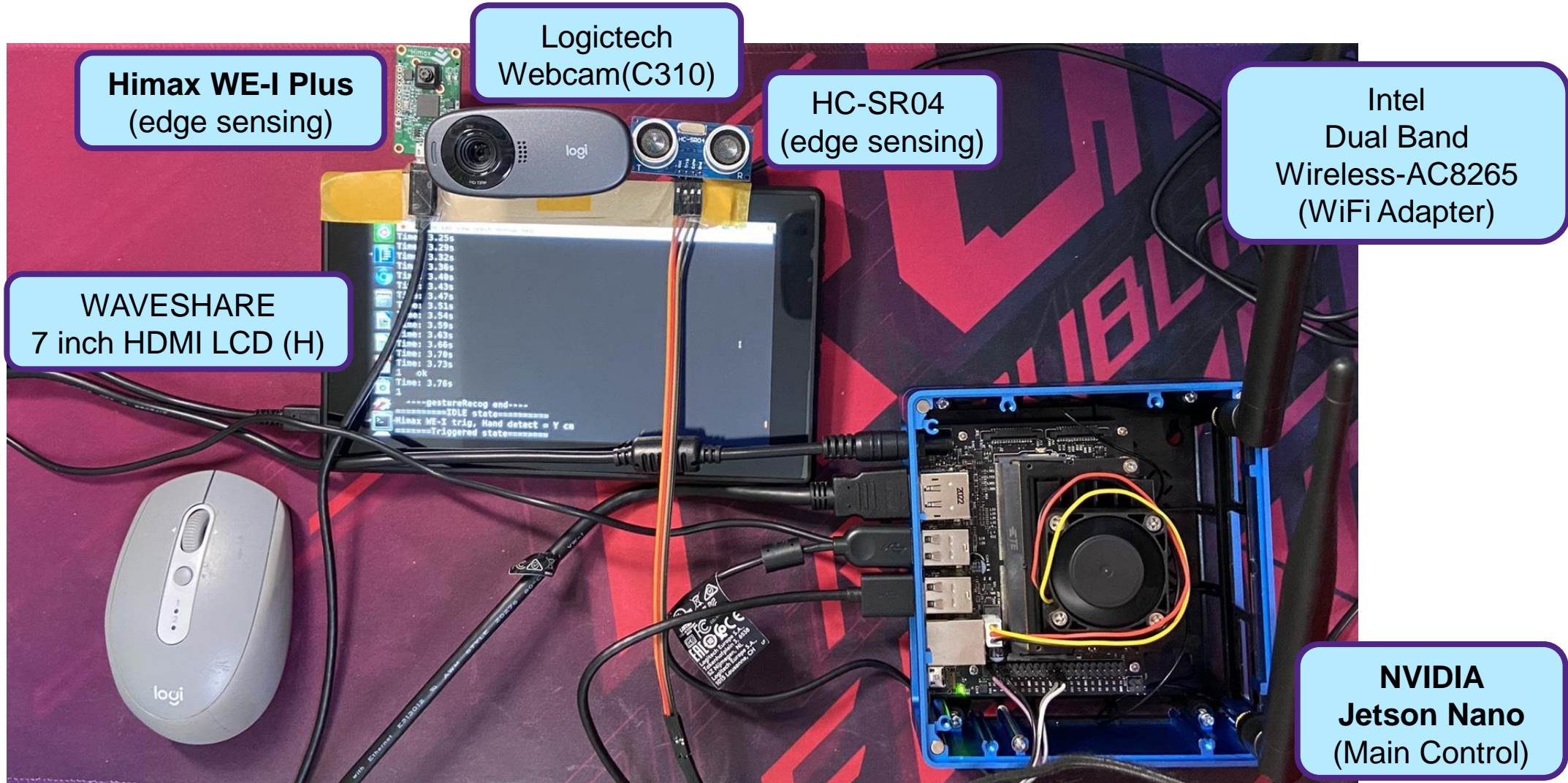
設計與實現

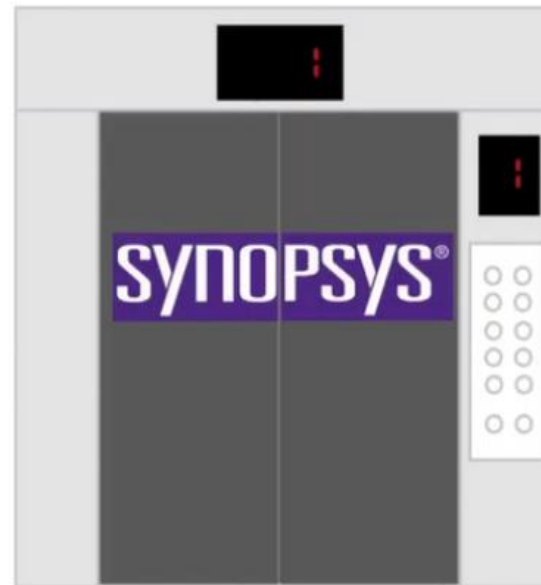
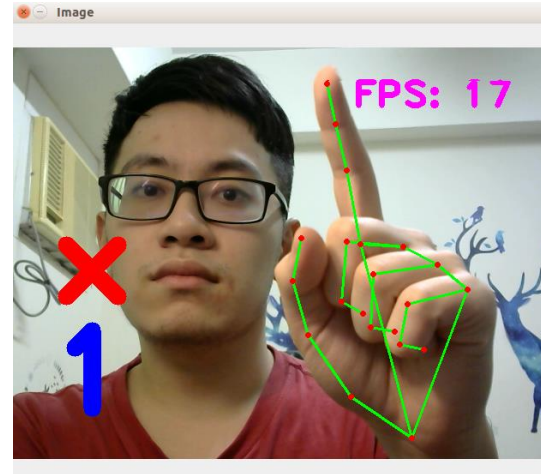
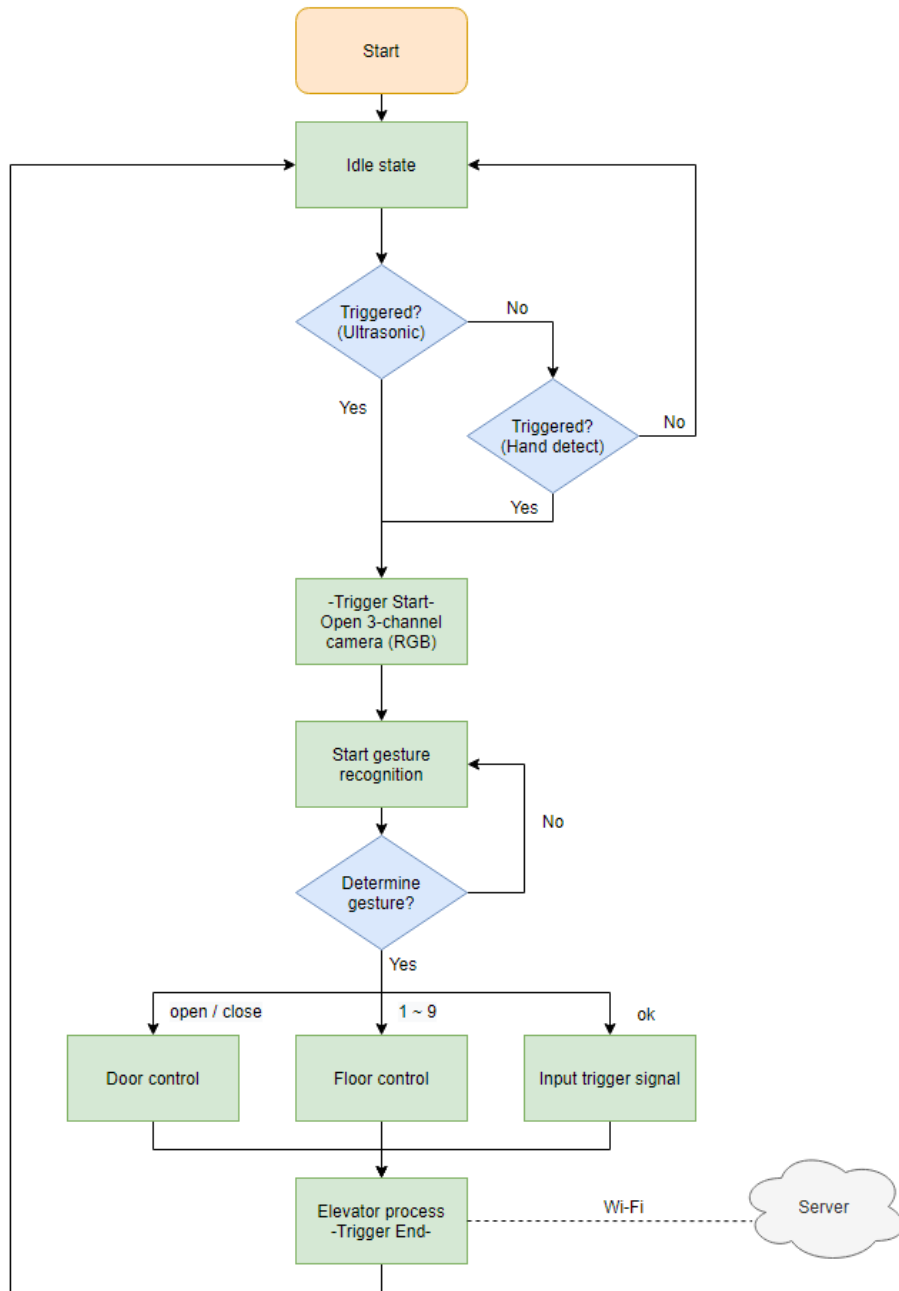
Design & Implementation

Design – System Architecture & System Flow



Design – Physical Design





Gesture Detection

- Himax WE-I Plus
- TensorFlow Lite
- Keras

Gesture Recognition

- NVIDIA Jetson Nano
- OpenCV
- MediaPipe API

Control Simulation

- Elevator animation
- Flask
- jQuery
- Express.js

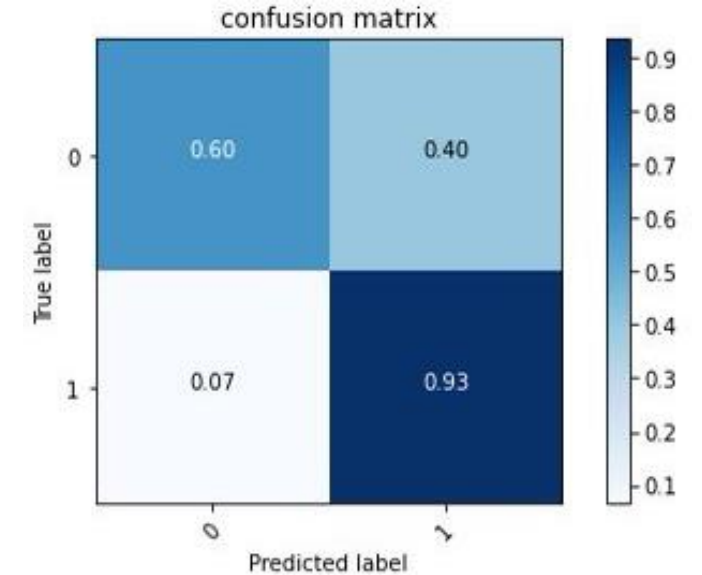
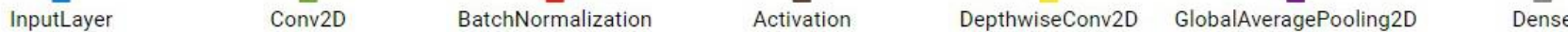
Implementation – Hand Detection

- ▷ **Always-on detector**
 - Real time hand & object detection
 - Always – on & wake up system
 - Edge computing architecture
 - Trigger high OPS units
 - Reduce power consumption



Bring Smart Everything to Life

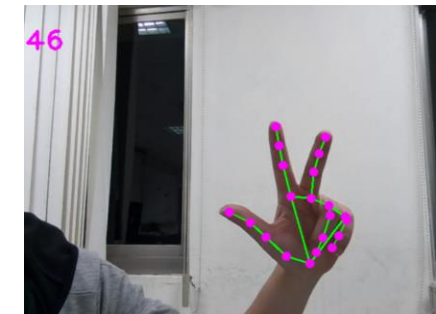
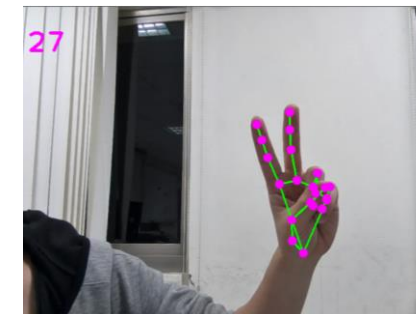
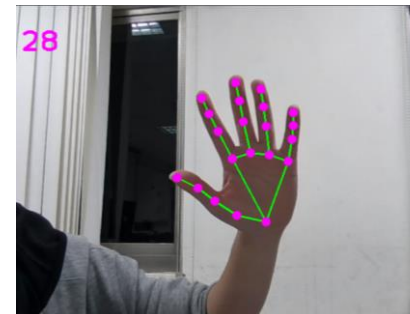
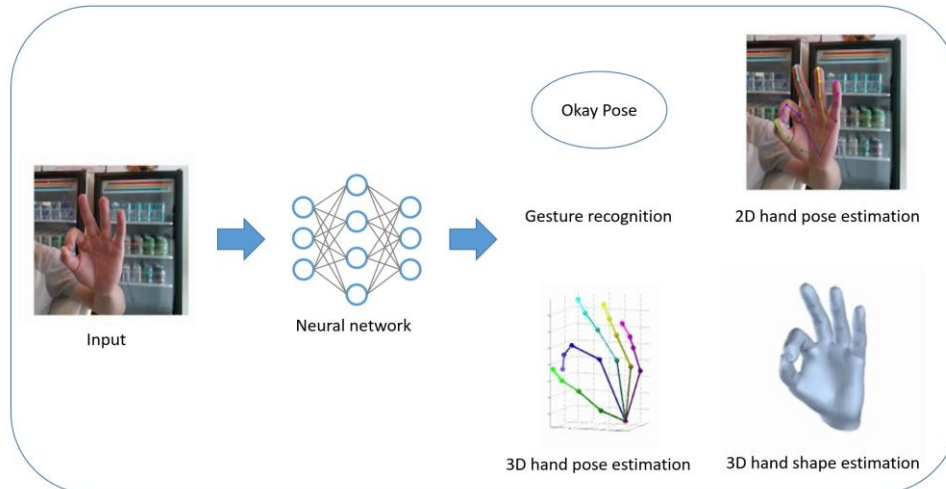
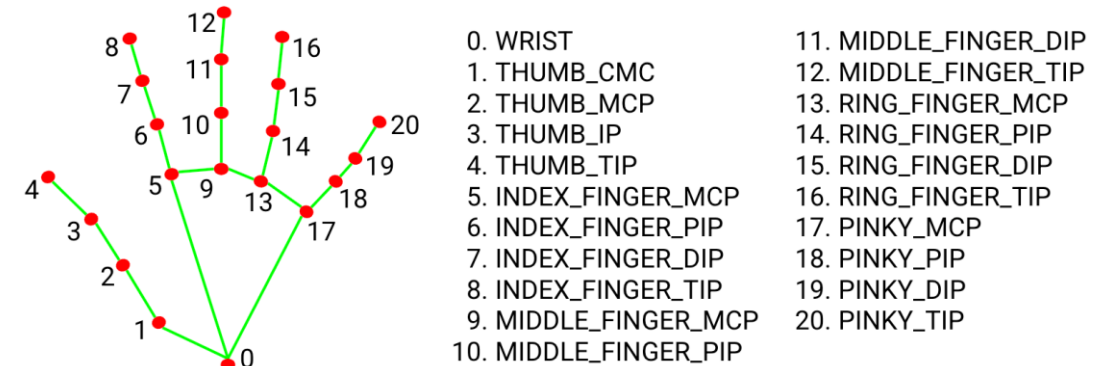
```
Total params: 137,090
Trainable params: 134,146
Non-trainable params: 2,944
```



Implementation – Gesture Recognition

▷ MediaPipe Hand

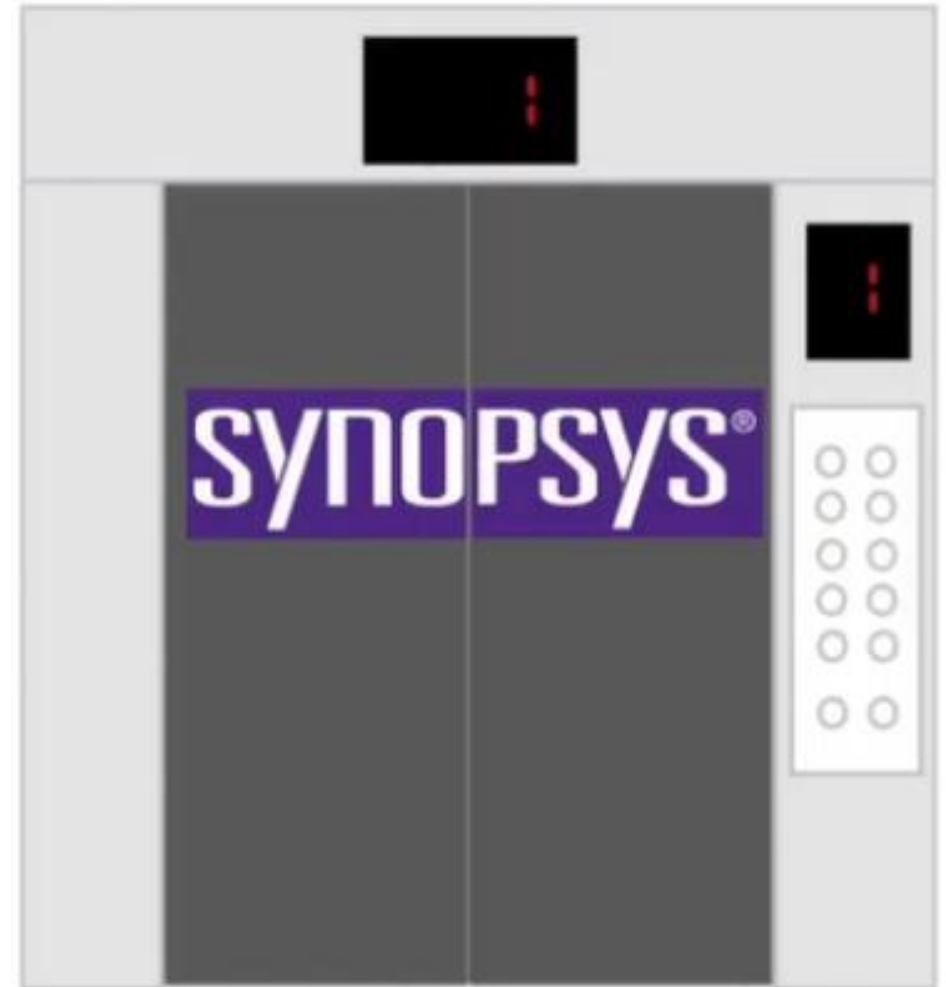
- Hand pose estimation & tracking
- Hand gesture recognition
- Robust real-time hand perception



Implementation – Elevator Animation

▷ Simulate Animation

- Express.js
- jQuery
- Flask (for testing)
- requests (python)
- Talend API Tester



Implementation – Power Analysis

```

NVIDIA Jetson Nano (Developer Kit Version) - Jetpack 4.5.1 [L4T 32.5.1]
CPU1 [|||||] Schedutil - 4% 102MHz
CPU2 [|||||] Schedutil - 10% 204MHz
CPU3 [|||||] Schedutil - 13% 204MHz
CPU4 [|||||] Schedutil - 14% 204MHz

Mem [|||||] 1.6G/4.1GB (lfb 455x4MB)
Imm [|||||] 0.0k/252.0kB (lfb 252kB)
Swp [|||||] 0.0GB/2.0GB (cached 0MB)
EMC [|||||] 4% 1.6GHz

GPU [|||||] 0% 230MHz
Dsk [|||||] 15.6GB/58.4GB

[info] [Sensor] [Temp] [Power/mW] [Cur] [Avr]
UpT: 0 days 0:4:6
FAN [|||||] 0% Ta= 0%
Jetson Clocks: inactive
NV Power[0]: MAXN
PLL 30.00C
thermal 33.75C
APE: 25MHz
NVENC: [OFF] NVDEC: [OFF]
NVJPG: [OFF]
  
```

Standby

```

NVIDIA Jetson Nano (Developer Kit Version) - Jetpack 4.5.1 [L4T 32.5.1]
CPU1 [|||||] Schedutil - 100% 1.5GHz
CPU2 [|||||] Schedutil - 22% 1.5GHz
CPU3 [|||||] Schedutil - 18% 1.5GHz
CPU4 [|||||] Schedutil - 22% 1.5GHz

Mem [|||||] 2.3G/4.1GB (lfb 182x4MB)
Imm [|||||] 0.0k/252.0kB (lfb 252kB)
Swp [|||||] 0.0GB/2.0GB (cached 0MB)
EMC [|||||] 4% 1.6GHz

GPU [|||||] 0% 153MHz
Dsk [|||||] 15.6GB/58.4GB

[info] [Sensor] [Temp] [Power/mW] [Cur] [Avr]
UpT: 0 days 0:17:28
FAN [|||||] 0% Ta= 0%
Jetson Clocks: inactive
NV Power[0]: MAXN
PLL 43.00C
thermal 46.75C
APE: 25MHz
NVENC: [OFF] NVDEC: [OFF]
NVJPG: [OFF]
  
```

Idle

```

NVIDIA Jetson Nano (Developer Kit Version) - Jetpack 4.5.1 [L4T 32.5.1]
CPU1 [|||||] Schedutil - 92% 1.5GHz
CPU2 [|||||] Schedutil - 90% 1.5GHz
CPU3 [|||||] Schedutil - 91% 1.5GHz
CPU4 [|||||] Schedutil - 92% 1.5GHz

Mem [|||||] 3.6G/4.1GB (lfb 79x4MB)
Imm [|||||] 0.0k/252.0kB (lfb 252kB)
Swp [|||||] 0.822GB/2.0GB (cached 9MB)
EMC [|||||] 21% 1.6GHz

GPU [|||||] 40% 921MHz
Dsk [|||||] 15.6GB/58.4GB

[info] [Sensor] [Temp] [Power/mW] [Cur] [Avr]
UpT: 0 days 0:30:7
FAN [|||||] 31% Ta= 31%
Jetson Clocks: inactive
NV Power[0]: MAXN
PLL 53.00C
thermal 57.00C
APE: 25MHz
NVENC: [OFF] NVDEC: [OFF]
NVJPG: [OFF]
  
```

Triggered

NVIDIA Jetson Nano	Standby	Idle	Triggered
Total power consumption (mW)	2408	3413	6064
Always-on thermal zone temp. (AO)	38.50C	52.50C	62.50C
CPU clock rate (GHz)	0.204	1.5	1.5
GPU clock rare (MHz)	230	153	921

With the help of Himax WE-I

Implementation – Power Analysis

Dynamic power:

$$P_{avg} = \alpha \cdot f \cdot 1/2 \cdot c \cdot V_{dd}^2$$

NVIDIA Jetson Nano	Standby	Idle	Triggered
Total power consumption (mW)	2408	3413	6064
Always-on thermal zone temp. (AO)	38.50C	52.50C	62.50C
CPU clock rate (GHz)	0.204	1.5	1.5
GPU clock rare (MHz)	230	153	921

Power saving:

$$P_{Trig} - P_{Idle} \approx 6000 - 3500 = 2500 \text{ mW}$$

With the help of Himax WE-I
(Ultra Low Power AI ASIC)

Assume 90% idle state & 10% triggered state.

Estimate the wasted power & energy consumption over a year for one device.

$$[P_{Trig} - (P_{Idle} \times 0.9 + P_{Trig} \times 0.1)] \cdot 60 \cdot 60 \div 10^6 \approx 8.1 \text{ kWh}$$

$$[P_{Trig} - (P_{Idle} \times 0.9 + P_{Trig} \times 0.1)] \cdot 60 \cdot 60 \cdot 24 \cdot 365 \div 1000 \approx 71 \text{ MJ}$$



作品進度

Work Progress



Work Progress

▷ Himax WE-I

- Real time hand detect
- Edge computing architecture
- Trigger high OPS units
- Reduce power consumption

▷ NVIDIA Jetson Nano

- Real time gesture recognition
- High accuracy & Quick response

▷ Elevator Simulation

- Create elevator animation through webpage (1~9 Floors)

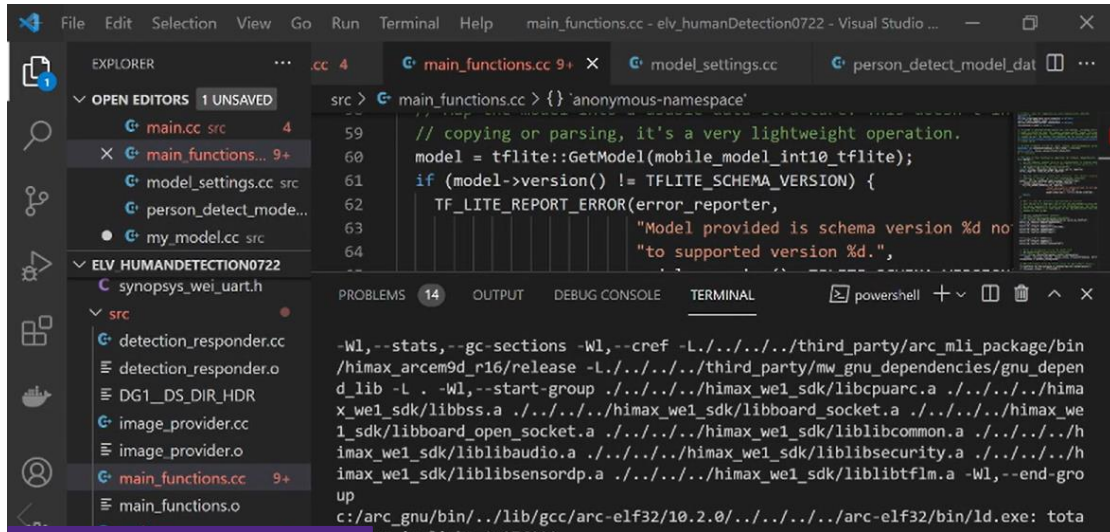


測試結果

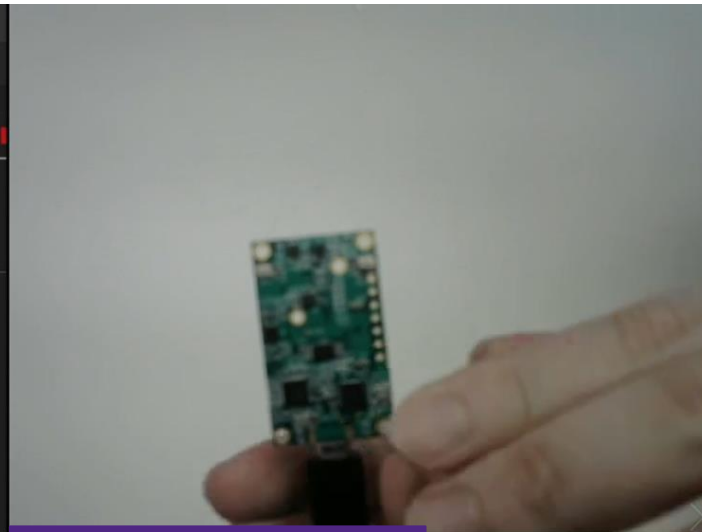
Results & Demo



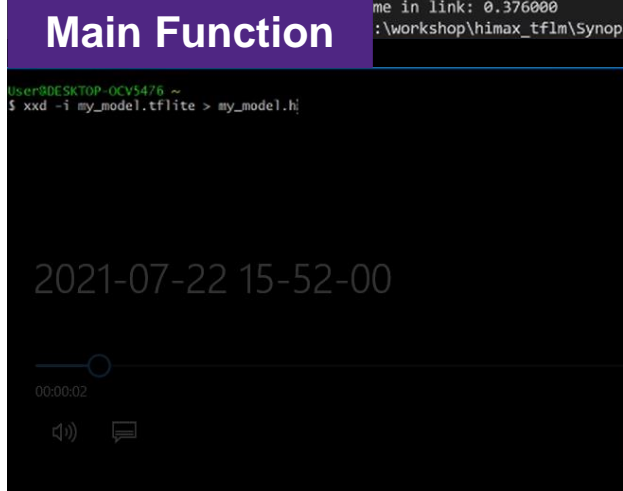
Result & Demo – Hand Detection



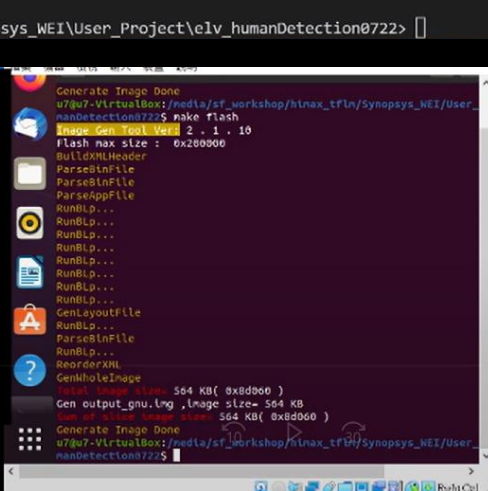
Main Function



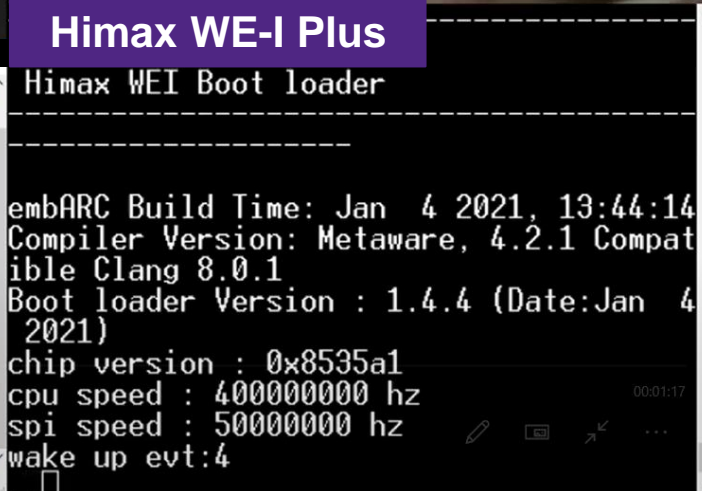
Himax WE-I Plus



Generate .h

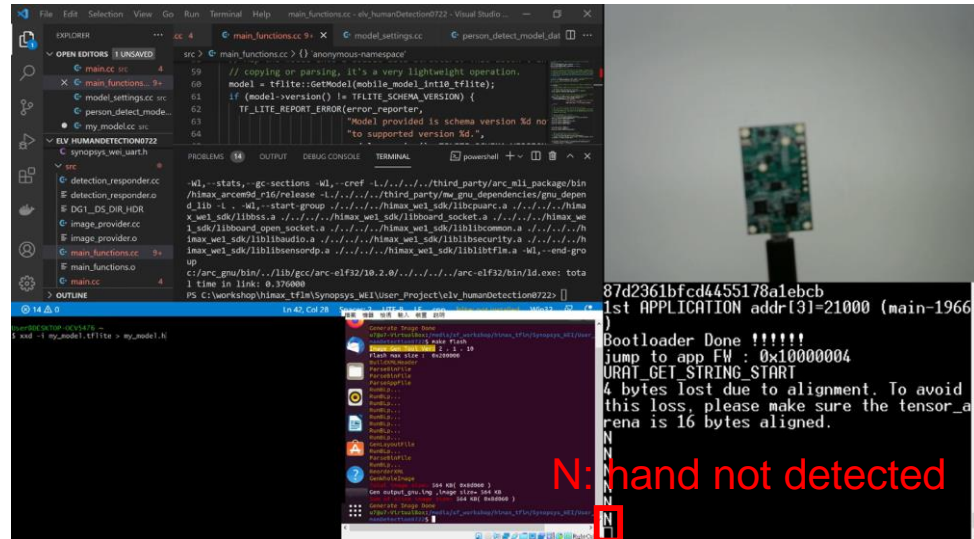


Make flash



Tera Term terminal

Result & Demo – Hand Detection

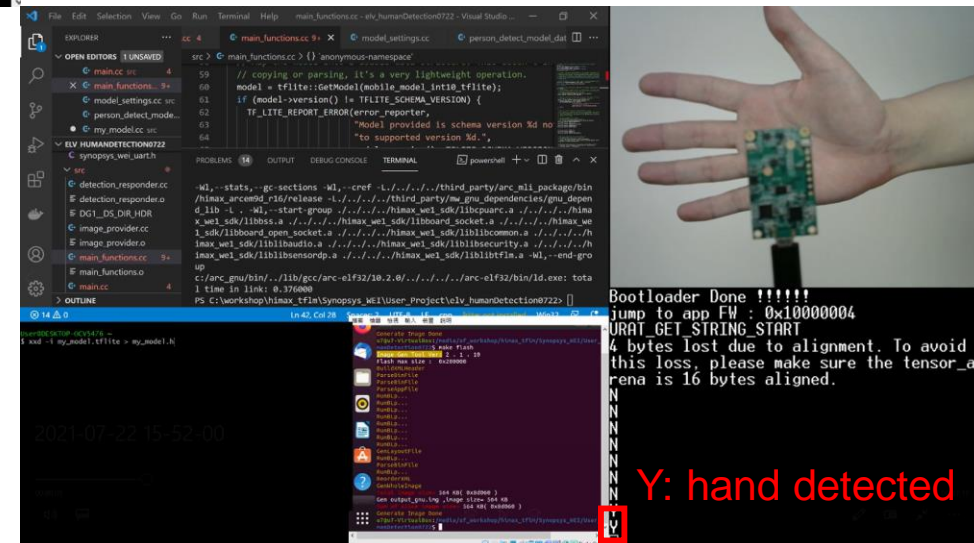


Hand NOT detected

- Simple background
- Pure background

Hand detected

- Hand detection

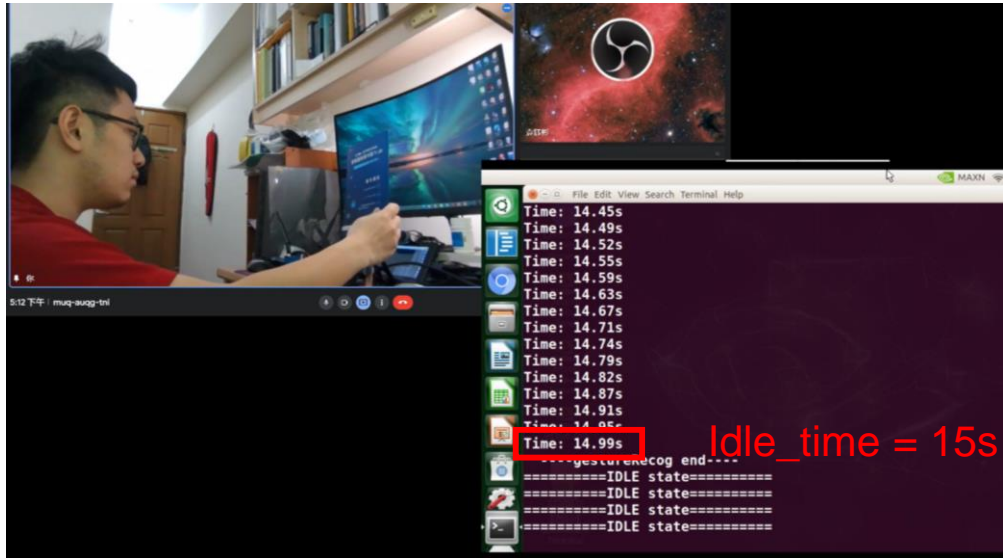


-
- 5:11 下午 muq-auxg-tnl
- Triggered state
- ```

=====Triggered state=====
gestureenergy start...
[libprotobuf WARNING external/com_google_protobuf/src/google/protobuf/text_format.cc:324] Warning parsing text-format mediapipe.CalculatorGraphProto: 125:5: text format contains deprecated field "use_gpu"
I20210722 17:11:44.475251 11824 gl_context_egl.cc:163] Successfully initialized EGL. Major : 1 Minor: 5
I20210722 17:11:44.504089 11868 gl_context.cc:331] GL version: 3.2 (Open GL ES 3.2 NVIDIA 32.5.1)
I20210722 17:11:44.504403 11824 gl_context_egl.cc:163] Successfully initialized EGL. Major : 1 Minor: 5
I20210722 17:11:44.572005 11869 gl_context.cc:331] GL version: 3.2 (Open GL ES 3.2 NVIDIA 32.5.1)
W20210722 17:11:44.573877 11868 tf_lite_model_loader.cc:32] Trying to resolve path manually as GetResourceContents failed: ; Can't find file: mediapipe/modules/palm_detection/palm_detection.tflite
Time: 0.14s
W20210722 17:11:44.962119 11868 tf_lite_model_loader.cc:32] Trying to resolve path manually as GetResourceContents failed: ; Can't find file: mediapipe/modules/hand_landmark/hand_landmark.tflite

```



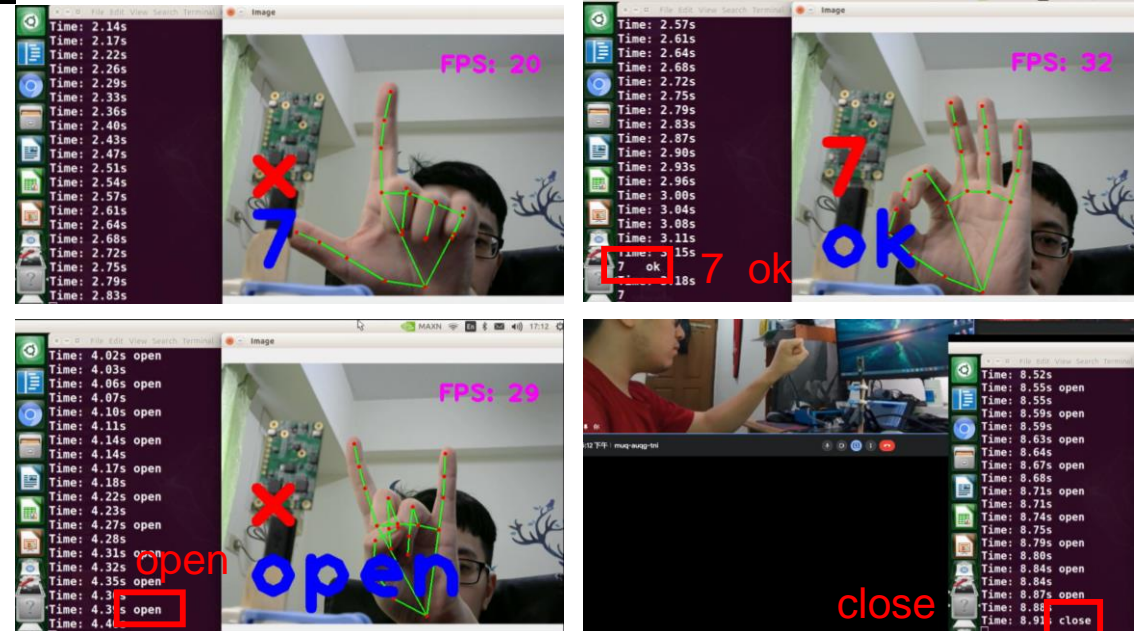


## Back to IDIE STATE

- Over the idle time
- Recognition finish

## Successfully identified

- “ok” gesture as input trigger signal
- “1” ~ “9” gesture as select floors signal
- “👉” gesture as close door signal
- “👉” gesture as open door signal
- Other gesture as unknown (x)





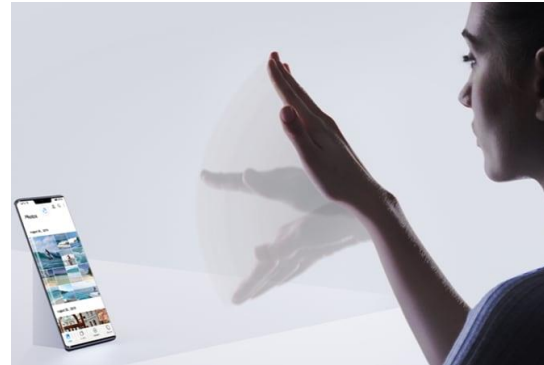
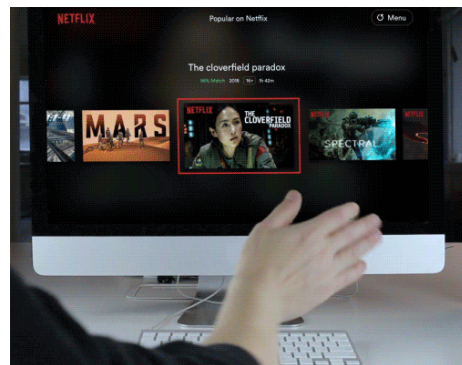
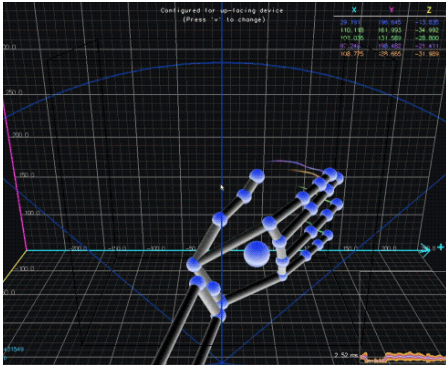
# 總結展望

## Prospect

# Prospect

## ▷ Smart Elevator

- Himax WE-I Plus vs. traditional sensors → get more accurate detection results
- Gesture control vs. touch screen interface → AR, VR applications
- Combine face recognition to predict users' floor
- With the help of face recognition, we can build the visitor-management system effectively



Bring Smart Everything to Life

# Thank You





**SYNOPSYS<sup>®</sup>**

*Silicon to Software<sup>™</sup>*