FrancescoArgentieri

Mechatronic Engineer

contact

education

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languages

Italian-mother tongue English-upper intermediate 2015 – 2020 **M. Sc.** in Mechatronics Engineering

University of Trento

Thesis "Enhancing UAV capabilities with machine learning on board".

Specialization in Mechanics-Mechatronics

2008 – 2015 **Bachelor** in Mechanics Engineering

Marche Polytechnic University

Thesis "Structural analysis of an automotive hot formed sheet component

with variable thickness".

Specialization in Energy-Thermomechanical

experience

05/2022 - PRESENT

Rimac Technologies - Kineton

Naples, Italy

"Software developer - Consultant".

"Embedded software developer".

Infotainment software developments for Hyper/Luxury cars. Program-

ming in C++17 language and use of Qt framework.

software: C++, Qt, QML, Git, BitBucket, JIRA

06/2020 - 05/2022

Kineton

Naples, Italy

I developed the applications Qt/QML and services for Automotive Grade Linux. So, I have gained experience in software development using OOP, enhancing my knowledge regarding C++17, STL and Linux Environment.

software: C++, Qt, QML, AGL (Automotive Grade Linux), Git, GitLab

academic projects

04/2019 - 03/2020

University of Trento

Trento, Italy

"Enhancing UAV capabilities with machine learning on board".

This project focuses on the activity of providing the drone's ability to take advantage of the detection and classification of objects with TensorFlow Lite. The whole system is run on ARM cortex-A53 and TPU processors for tensor calculation, the project uses Raspberry Pi3b and Coral Dev-Board.

software: Python, Tensorflow, Altair PBS (HPC), C++/Qt, LATEX.

09/2018 - 11/2018

University of Trento

Trento, Italy

"Rapid development CNN for image classification using fine-tuning techniques and implementation on SoC systems".

Train CNN for binary classification by refinement techniques starting from already known models. Optimization and execution for devices low power consumption hardware such as Intel Movidius USB and Raspberry Pi 3B.

software: Python, Keras, Tensorflow, Altair PBS (HPC), LATEX



09/2017 - 06/2018

University of Trento

Trento, Italy

"Distributed robots mapping exploration".

The project explores the problem of localization and mapping for an unknown environment with a team of robots. The simulation shows SLAM techniques based on Montecarlo to reconstruct the map using several robots at the same time to map the environment.

software: Matlab, mex, C++, LATEX

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05/2017 - 08/2017

University of Trento

Trento, Italy

"Helicopter's tail-boom and rotor vibration analysis".

The project finite-element developed to predict and analyzing free vibration characteristics of two different helicopters tail structures using static structural and dynamic analysis emphasis on the rotor's starting phase.

software: Ansys Mechanical (APDL), LATEX

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02/2015 - 06/2015

DIISM, Marche Polytechnic University

Ancona, Italy

"Structural analysis of an automotive hot formed sheet component with variable thickness".

The project developed regarding automotive components hot formed with variable thickness by FEM analysis. The purpose was to compare the components with variables thickness, verify its response to static stresses respect a previous study where the same component had constant thickness.

 $\textbf{software:} \ \, \textbf{Ansys Mechanical, Altair HyperMesh, LsDyna, Qt,} \ \, \underline{\textbf{AT}_{E}}\!\textbf{X}$

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skills

Programming

C, C++, Qt, Python, Ruby

Software

Microsoft Office, Visual Studio

Code

Package

Ansys, HyperWorks, Maple, Matlab, FreeCad

Other

LATEX, Arduino, Raspberry Pi

OS

Linux, MacOS, Windows

certification

2022 Solid C++

Udemy

2021 ROS For Beginners (ROS Noetic, Melodic, Kinetic)

Udemy

2021 Autonomous Robots: Kalman Filter

Udemy

2020 Graduation to Professional Engineer (Italian legislation)

24 July - I session - University of Trento

2018 Safety in the laboratory

University of Trento

2015 Council of Europe Level B1 (PET)

Cambridge English, University of Cambridge

driver's license B

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