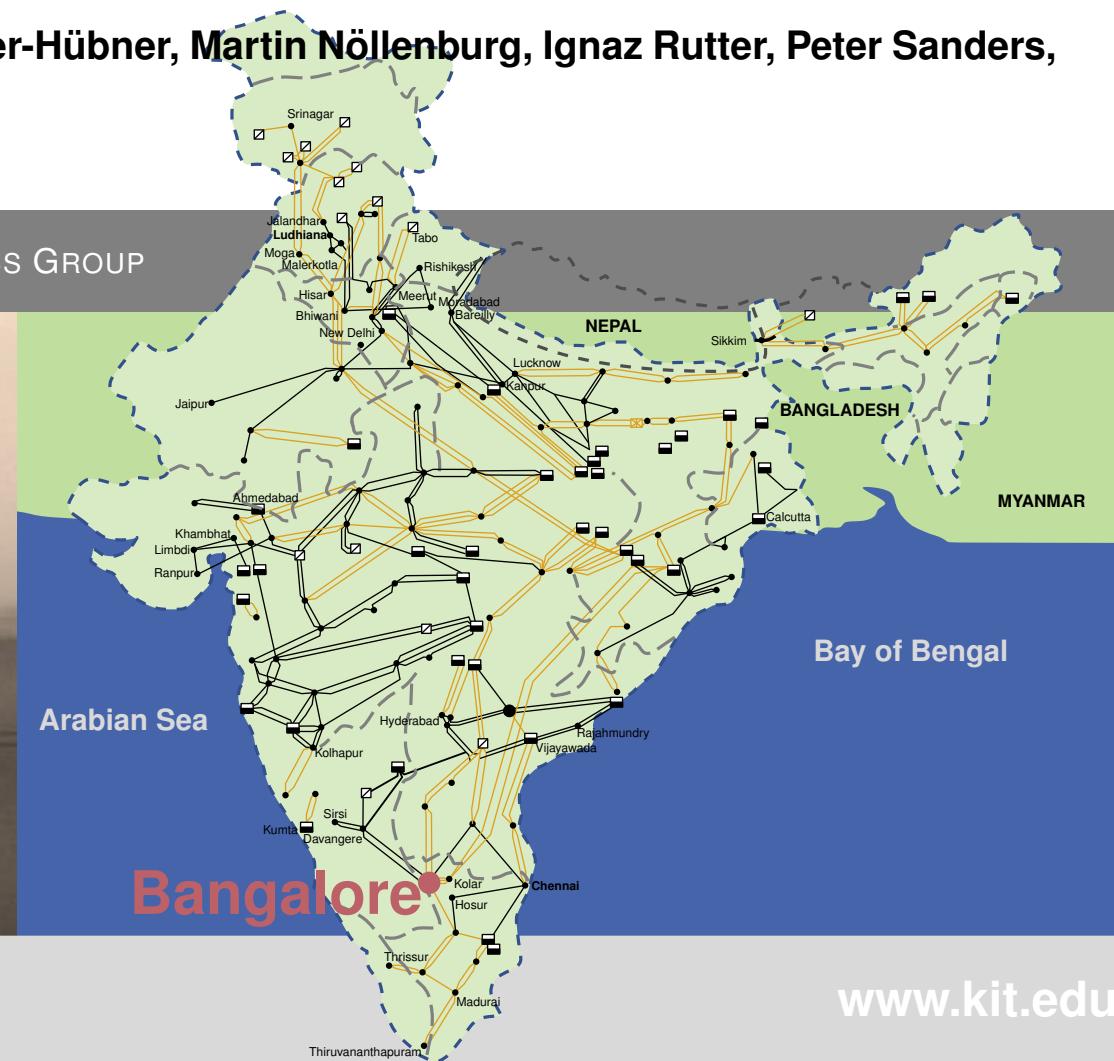


Operating Power Grids with Few Flow Control Buses

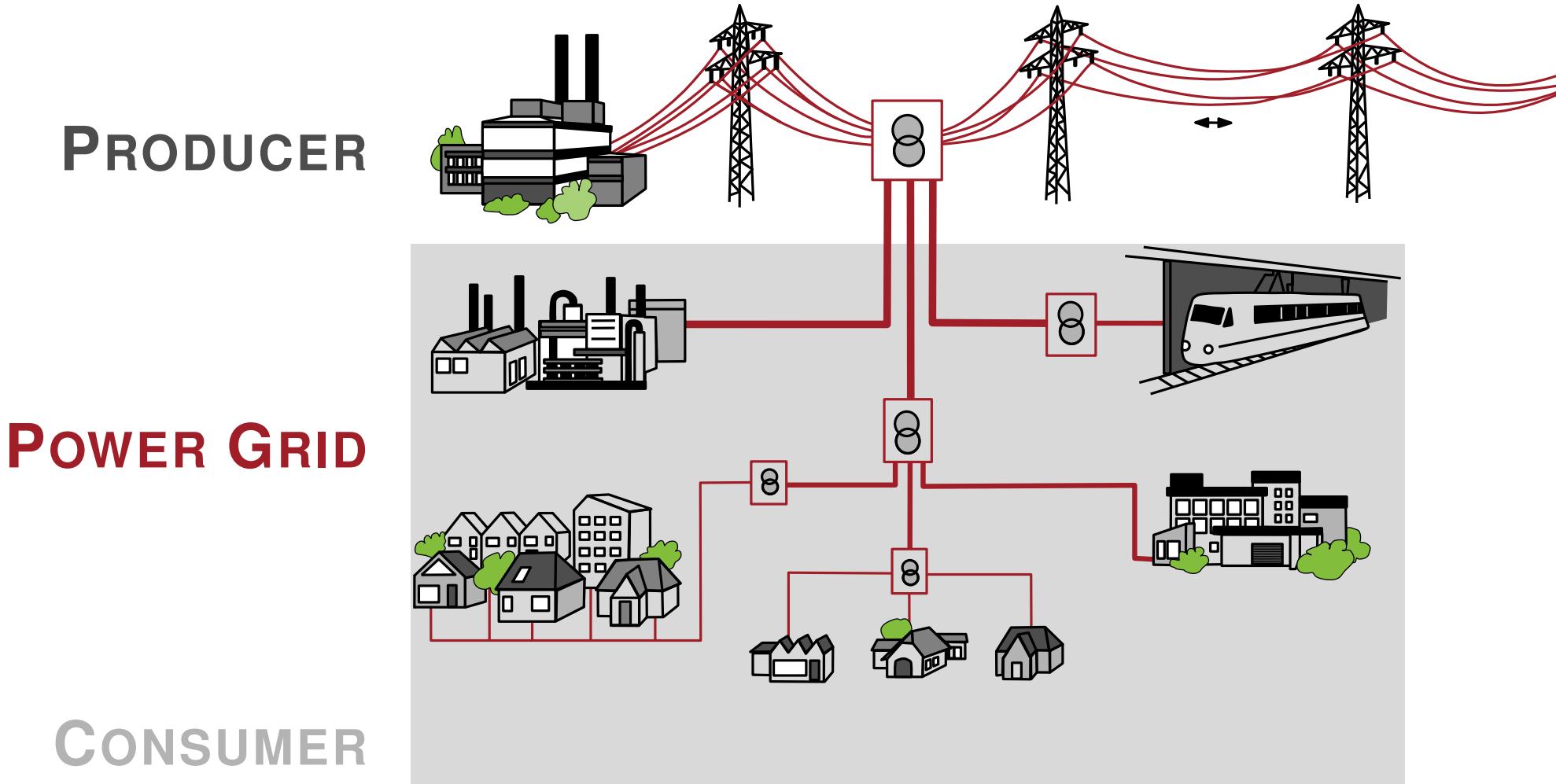
DEN Workshop · July 14, 2015

Thomas Leibfried, Tamara Mcchedlidze, Nico Meyer-Hübler, Martin Nöllenburg, Ignaz Rutter, Peter Sanders,
Dorothea Wagner and Franziska Wegner

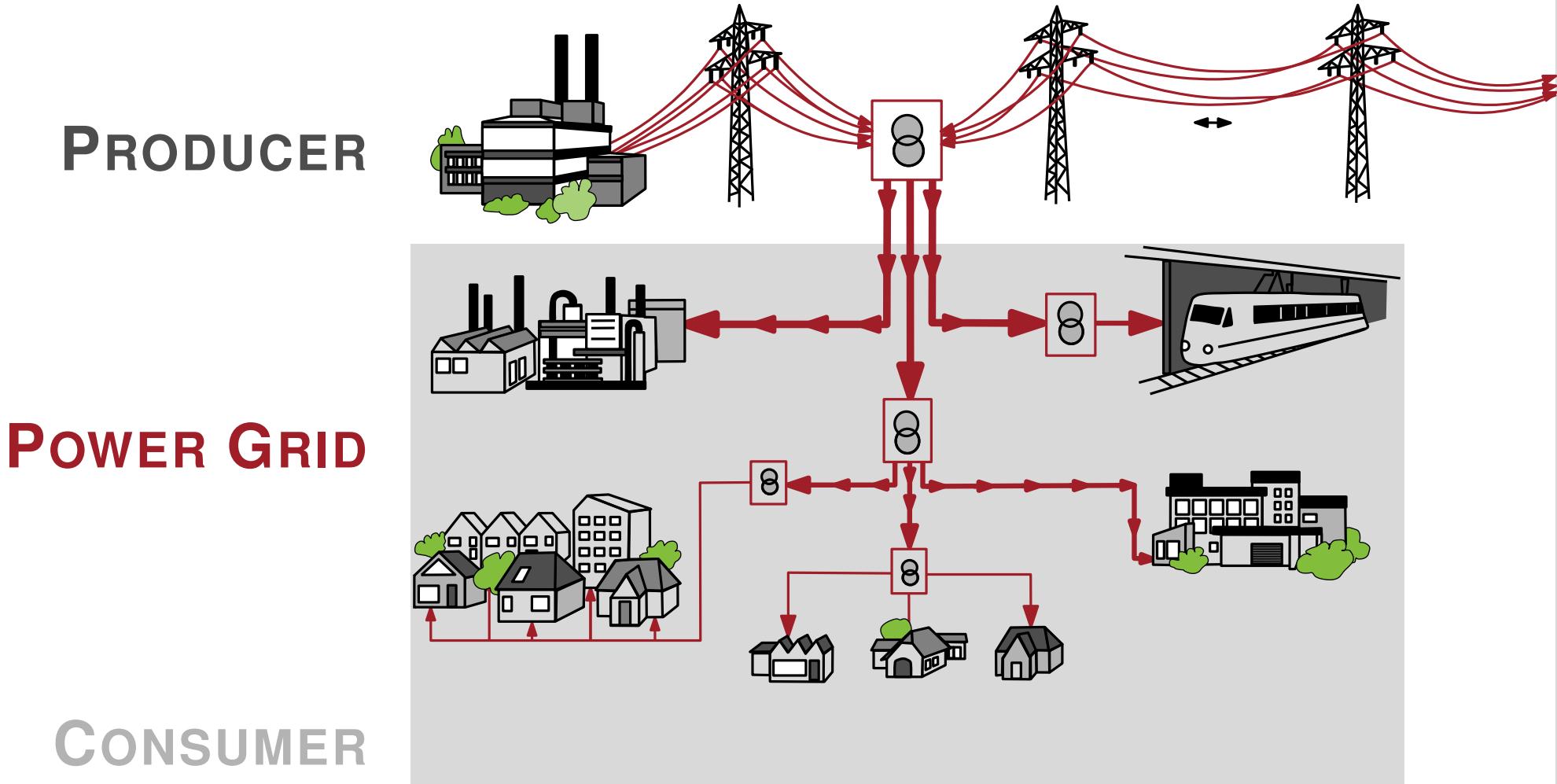
INSTITUTE OF THEORETICAL INFORMATICS · ALGORITHMIC GROUP



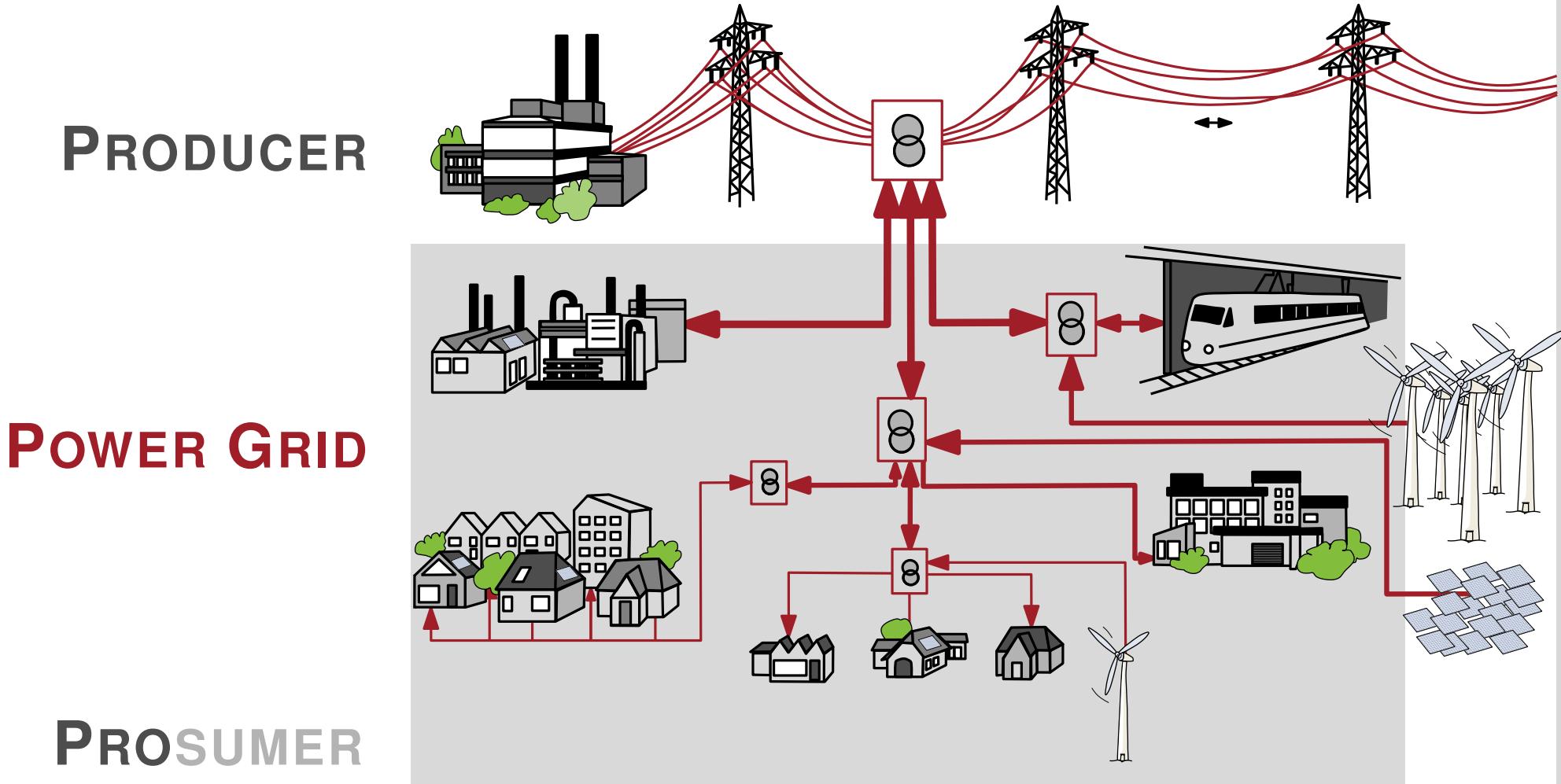
Recent Development in Power Grids



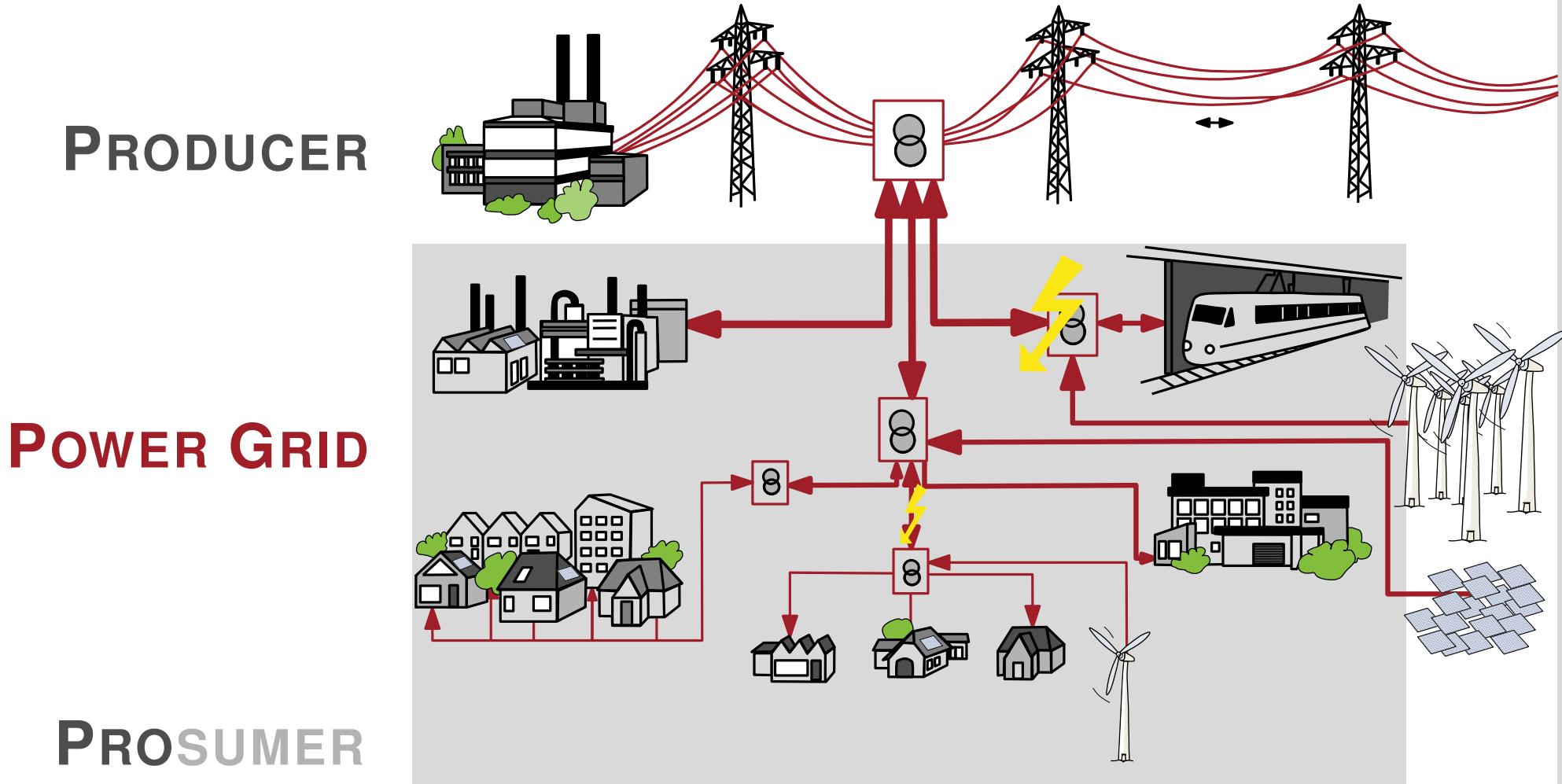
Recent Development in Power Grids



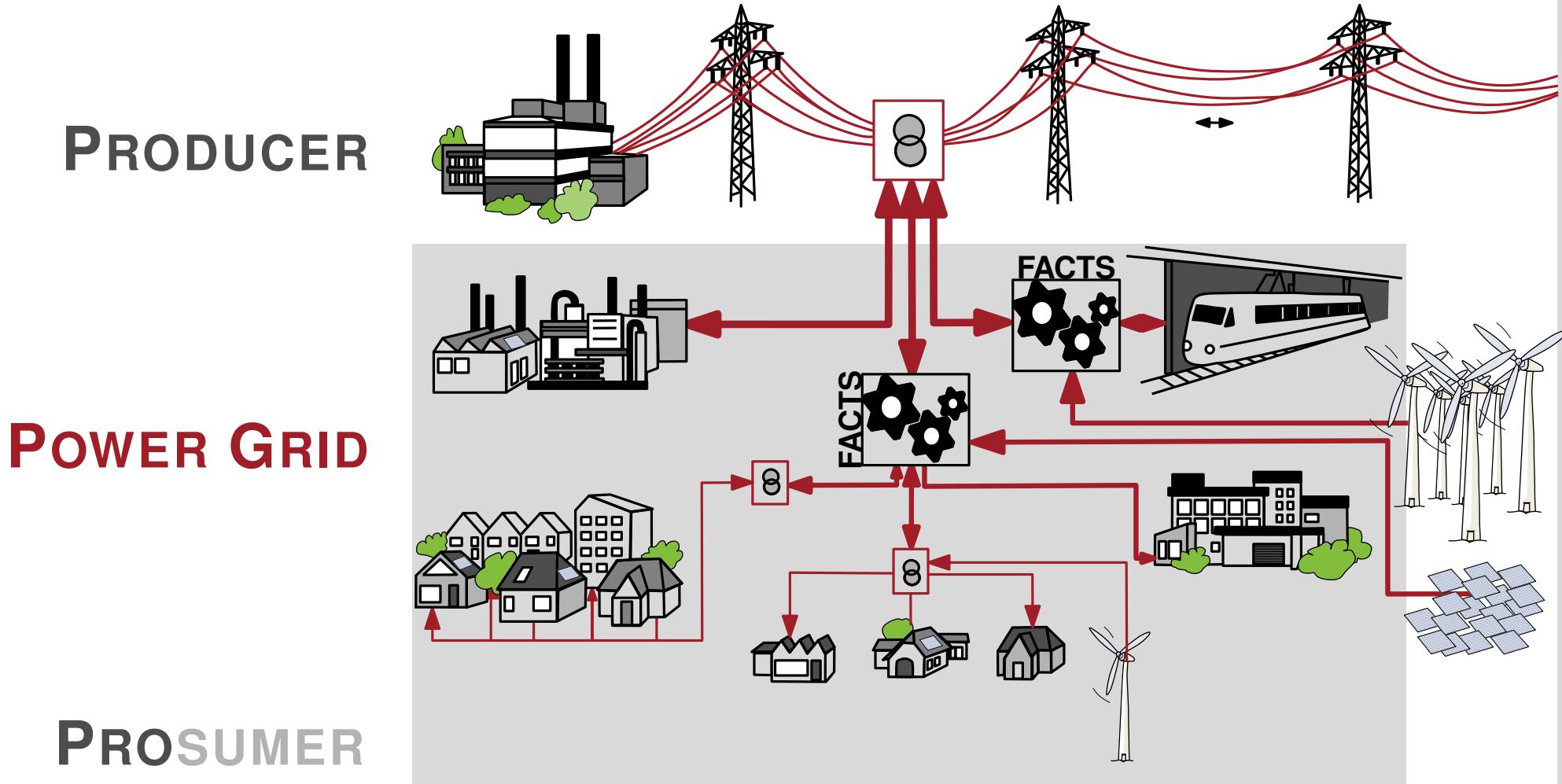
Recent Development in Power Grids



Recent Development in Power Grids



Recent Development in Power Grids



Challenges

- Increasingly distributed energy production
 - Independent power producers
 - Volatile power flows and flow directions
- ⇒ Operating the power grid gets more demanding

Strategies to cope with the challenges

- Network expansion
- Investment in advanced control units (e.g. FACTS) for better utilization of existing grid

Problem of Power Grid Operator

Given:

- Power grid with parameters

Find:

- Valid operation point (respecting thermal line limits) for power grid with control units at selected buses
- Energy production of each power generator

Goals:

- Minimize production cost (similar to OPF)
 - Minimize line losses
- } operation cost

How may we simplify the power grid operator's work?

Problem of Power Grid Operator

Given:

- Power grid with parameters

Find:

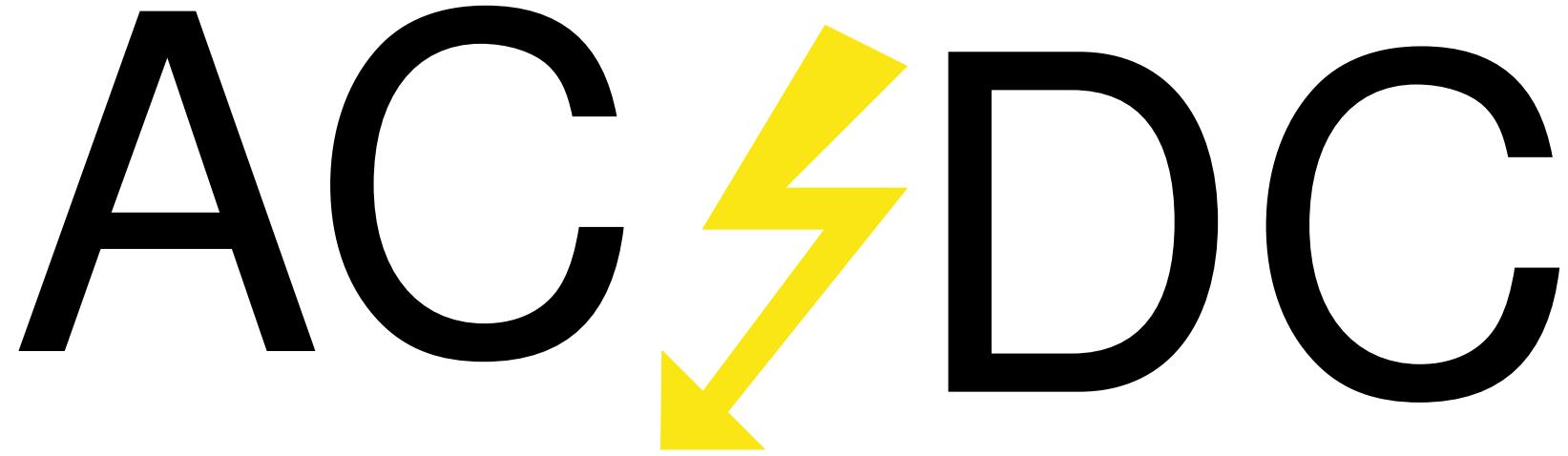
- Valid operation point (respecting thermal line limits) for power grid with control units at selected buses
- Energy production of each power generator

Goals:

- Minimize production cost (similar to OPF)
 - Minimize line losses
- } operation cost

How may we simplify the power grid operator's work?

⇒ Place FACTS to enhance controllability.



DC-based Flow Models

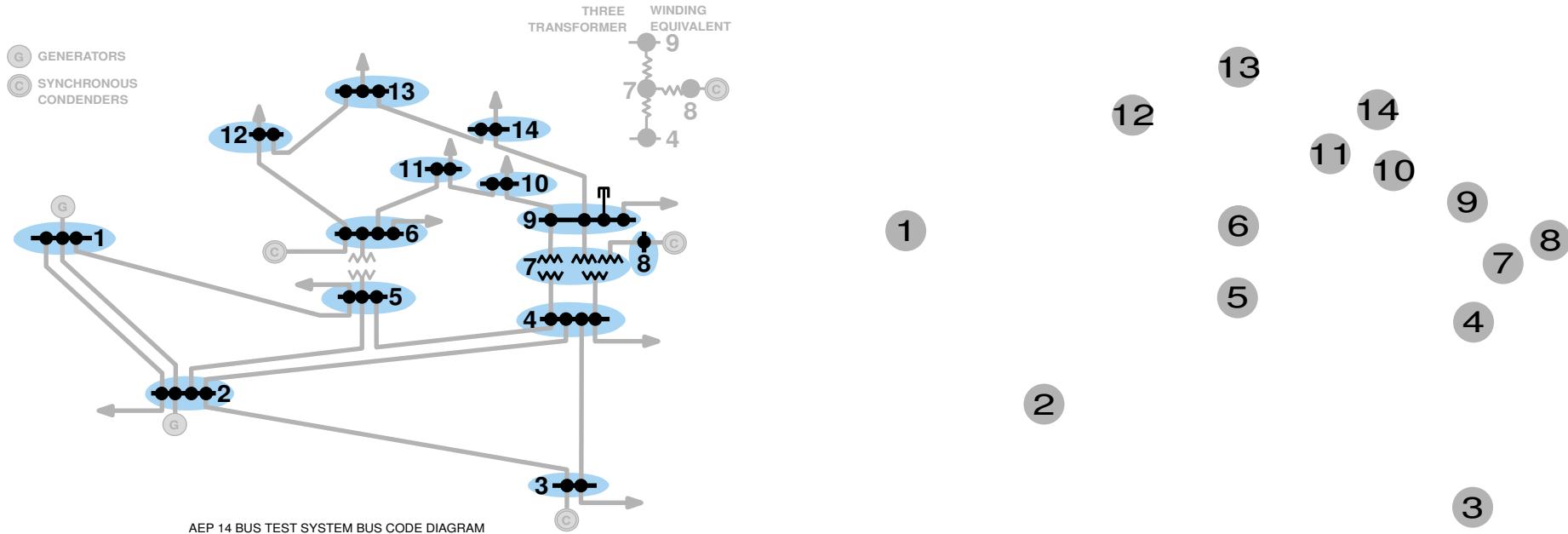
Straight-forward transformation:

- Power grid \rightarrow graph $G = (V, E)$

Graph Model

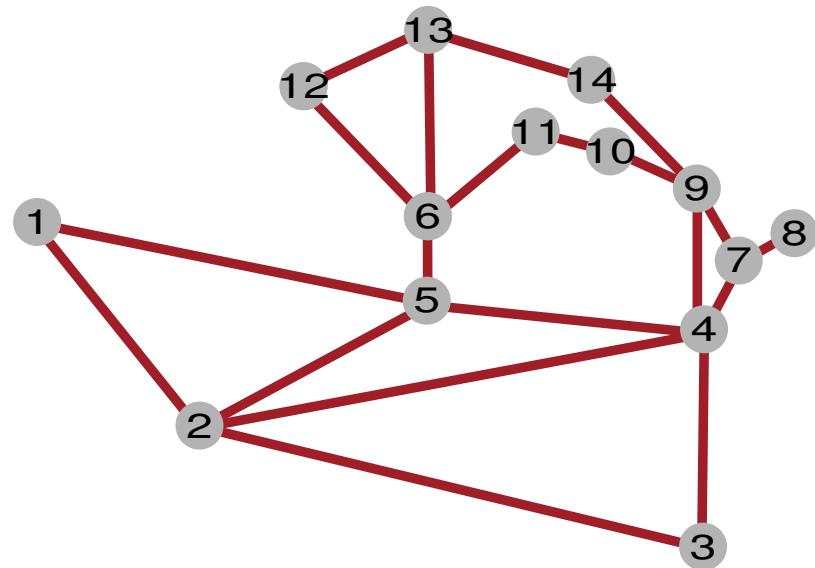
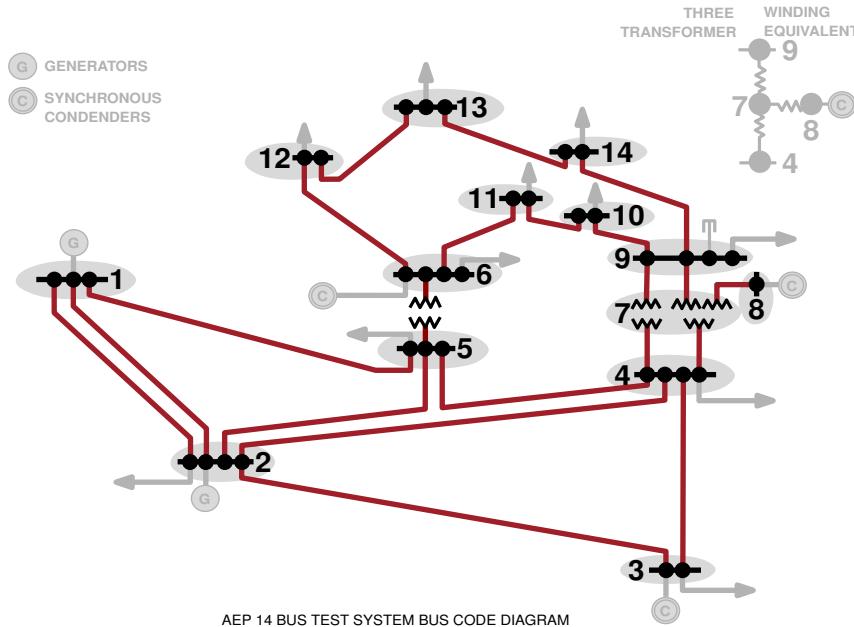
Straight-forward transformation:

- Power grid \rightarrow graph $G = (V, E)$
- Buses \rightarrow vertex set V



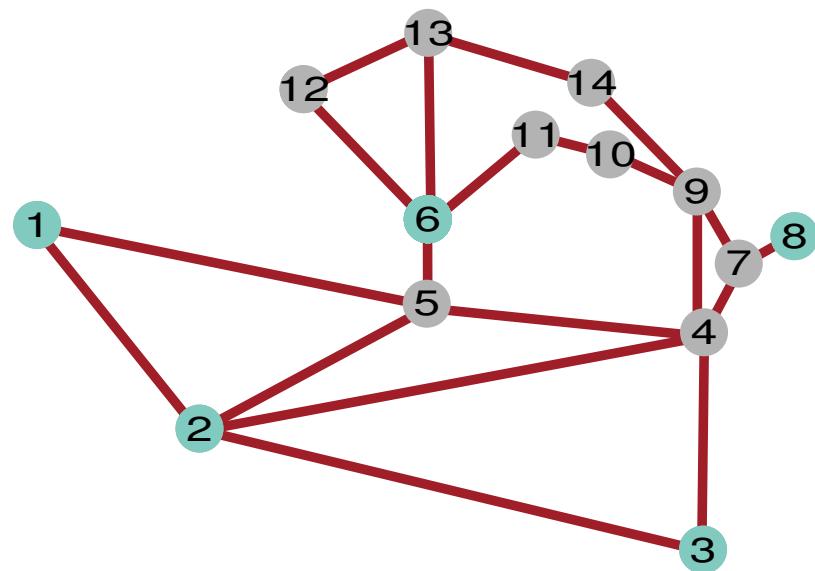
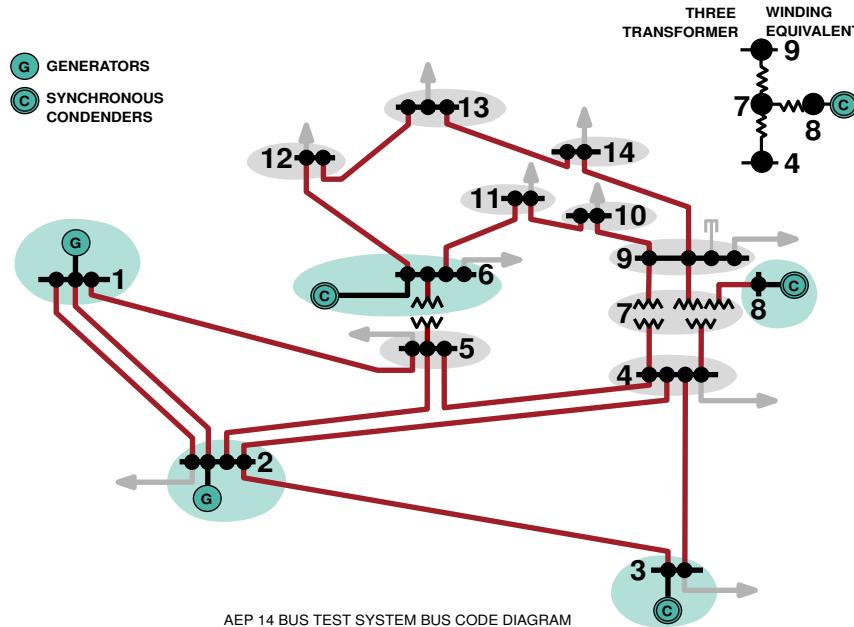
Straight-forward transformation:

- Power grid \rightarrow graph $G = (V, E)$
- Buses \rightarrow vertex set V
- Transmission lines \rightarrow edge set E with capacity function $c(e)$



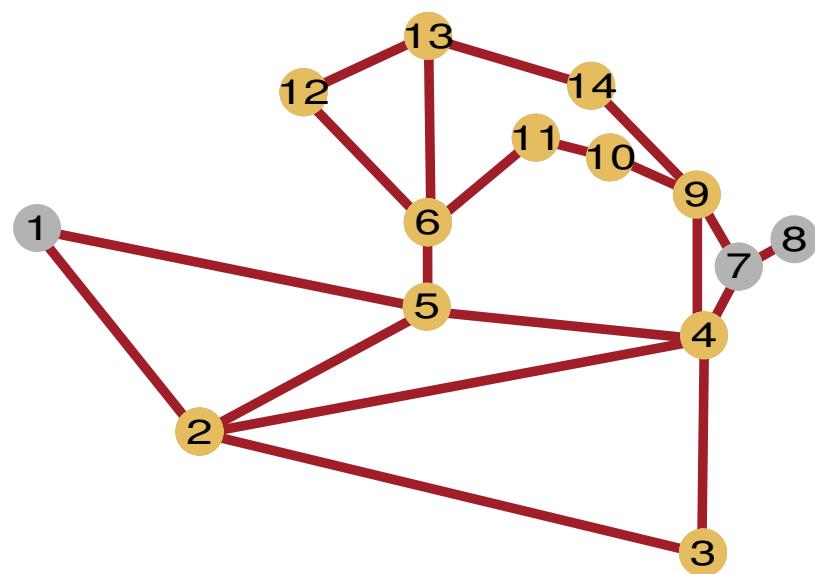
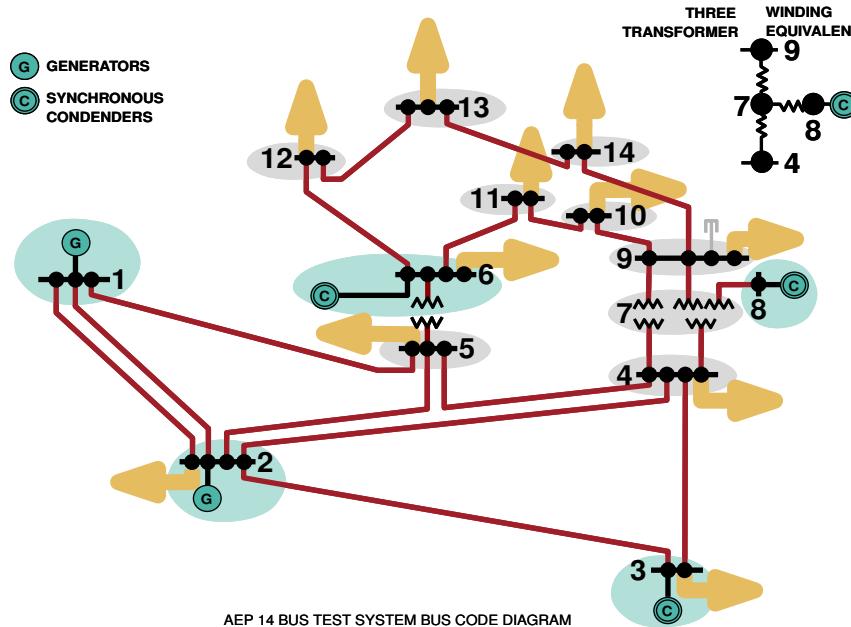
Straight-forward transformation:

- Power grid \rightarrow graph $G = (V, E)$
- Buses \rightarrow vertex set V
- Transmission lines \rightarrow edge set E with capacity function $c(e)$
- Generators \rightarrow set $V_G \subseteq V$ of generator buses

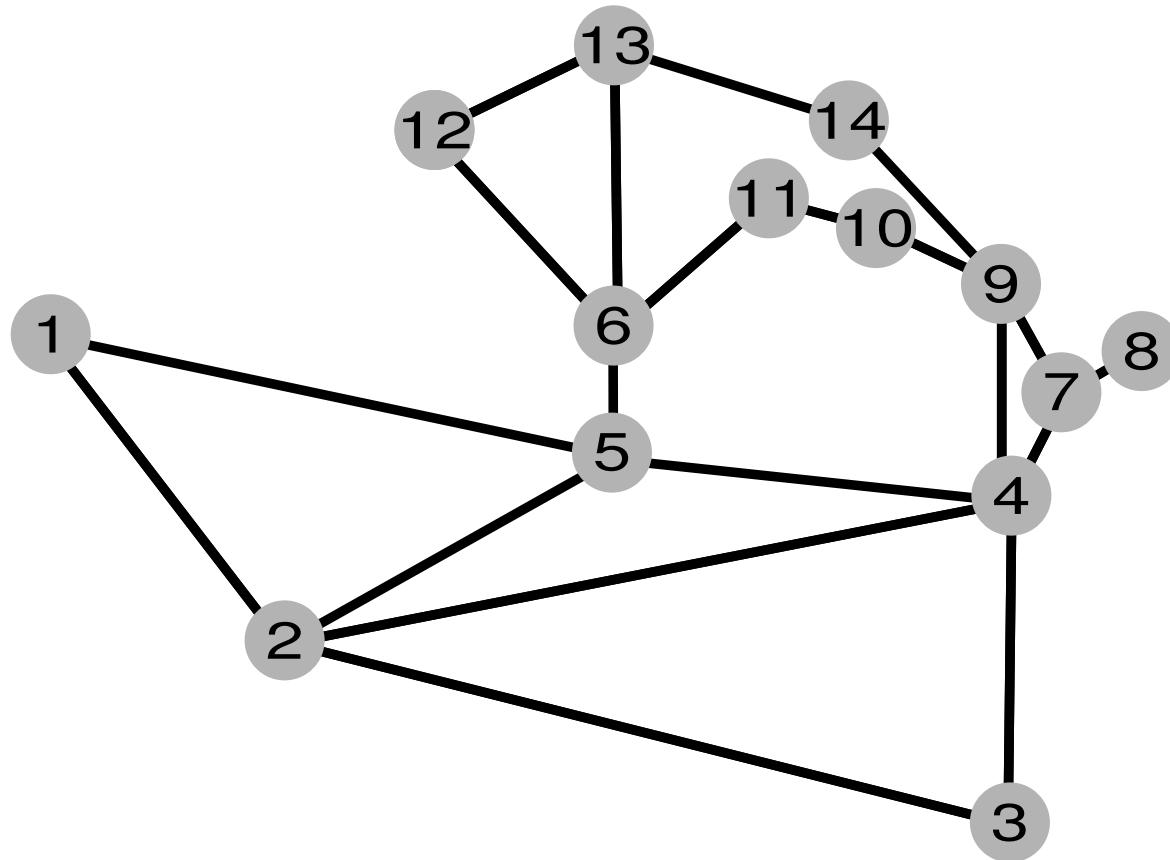


Straight-forward transformation:

- Power grid \rightarrow graph $G = (V, E)$
- Buses \rightarrow vertex set V
- Transmission lines \rightarrow edge set E with capacity function $c(e)$
- Generators \rightarrow set $V_G \subseteq V$ of generator buses
- Load \rightarrow set $V_L \subseteq V$ of load buses



Hybrid Flow Model



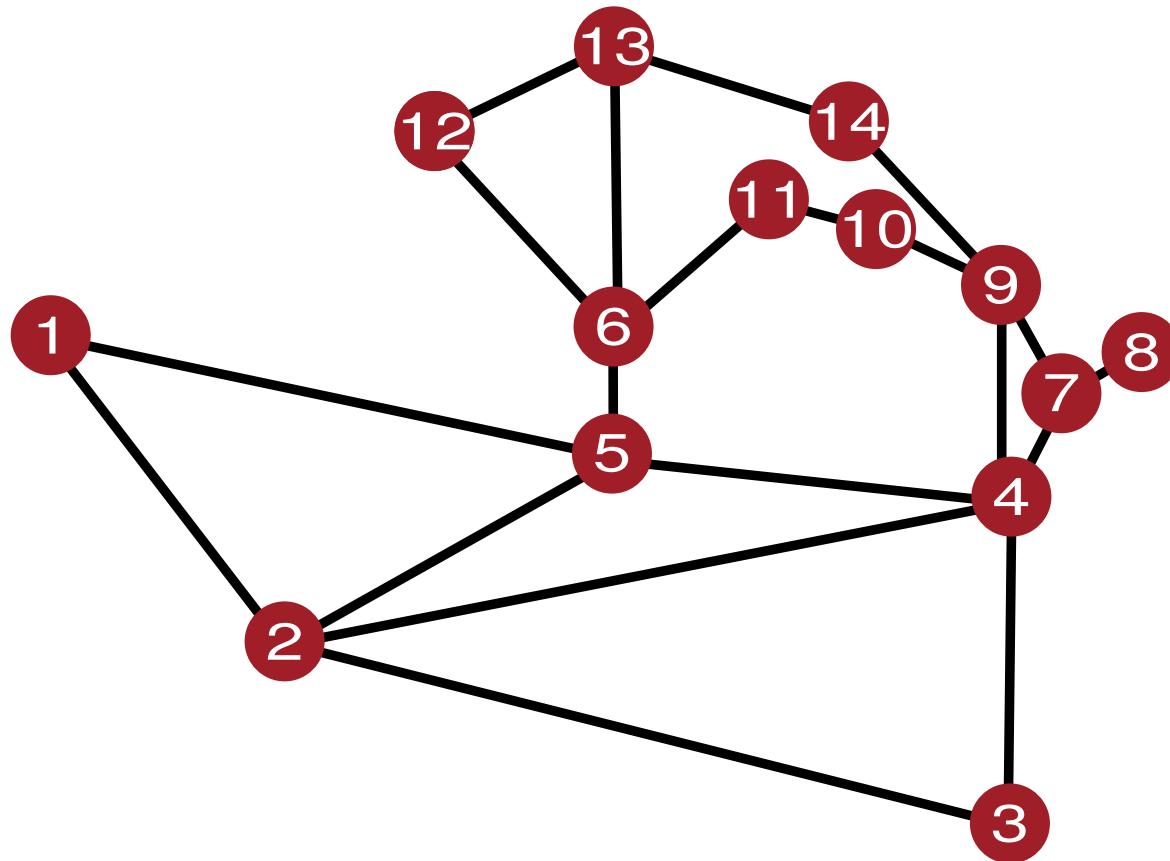
Kirchhoff's circuit laws:

Kirchhoff's current law ✓

Kirchhoff's voltage law ✓

Physical Model
(as a DC approximation)

Hybrid Flow Model



Flow Model

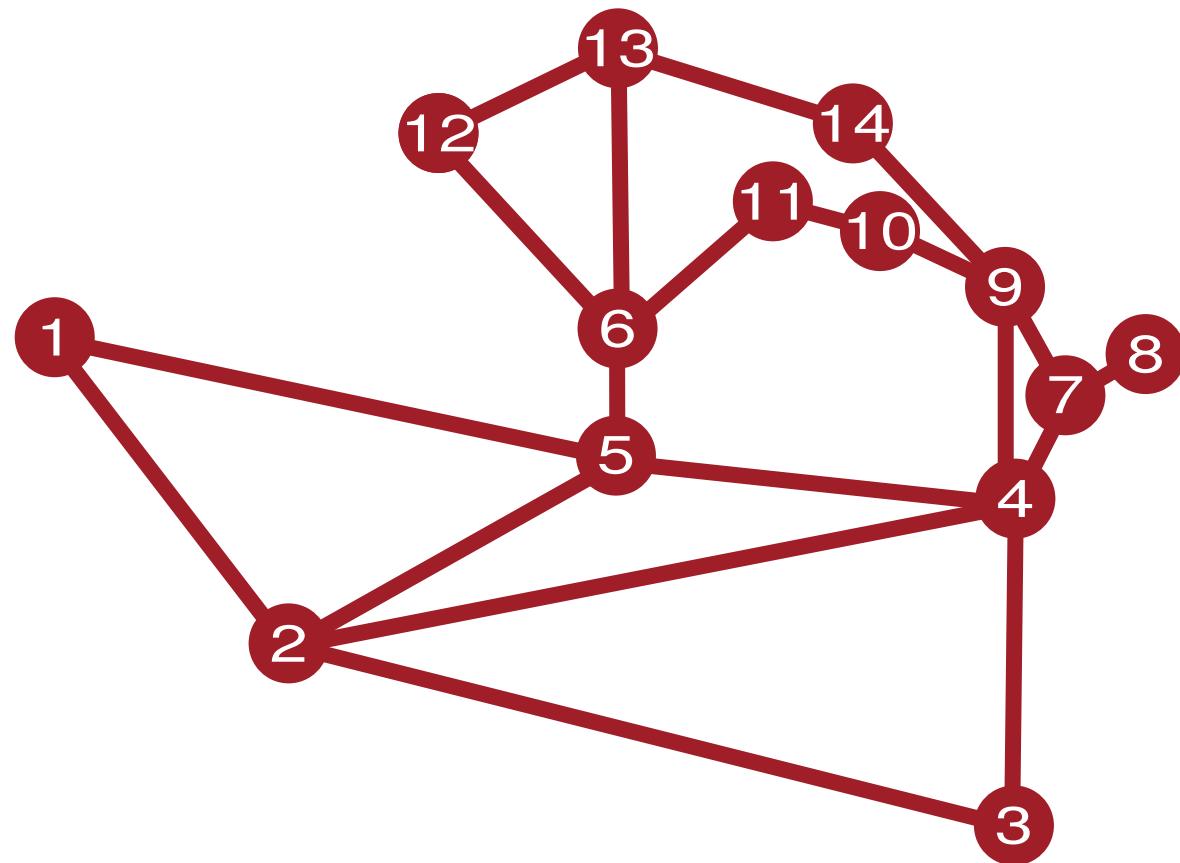
- control unit
- controlled flow

Kirchhoff's circuit laws:

Kirchhoff's current law ✓

Kirchhoff's voltage law

Hybrid Flow Model



Flow Model

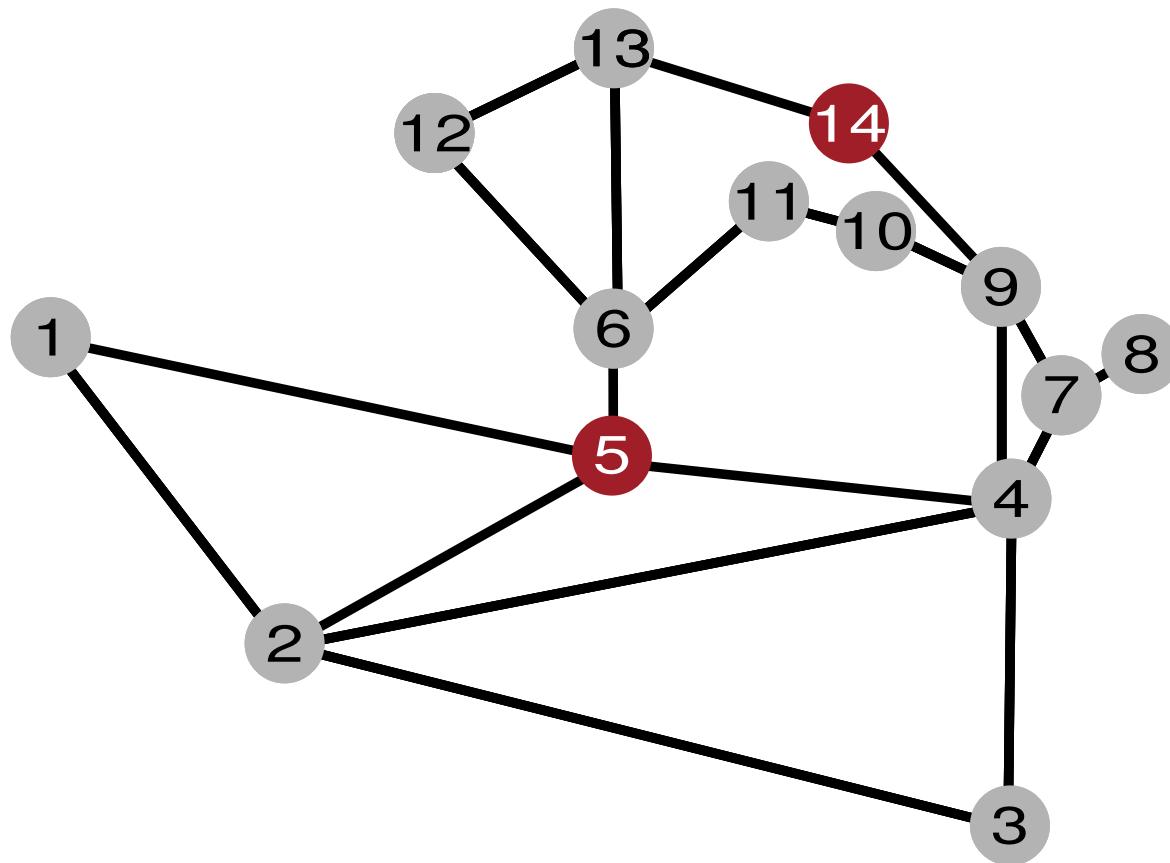
- control unit
- controlled flow

Kirchhoff's circuit laws:

Kirchhoff's current law ✓

Kirchhoff's voltage law

Hybrid Flow Model



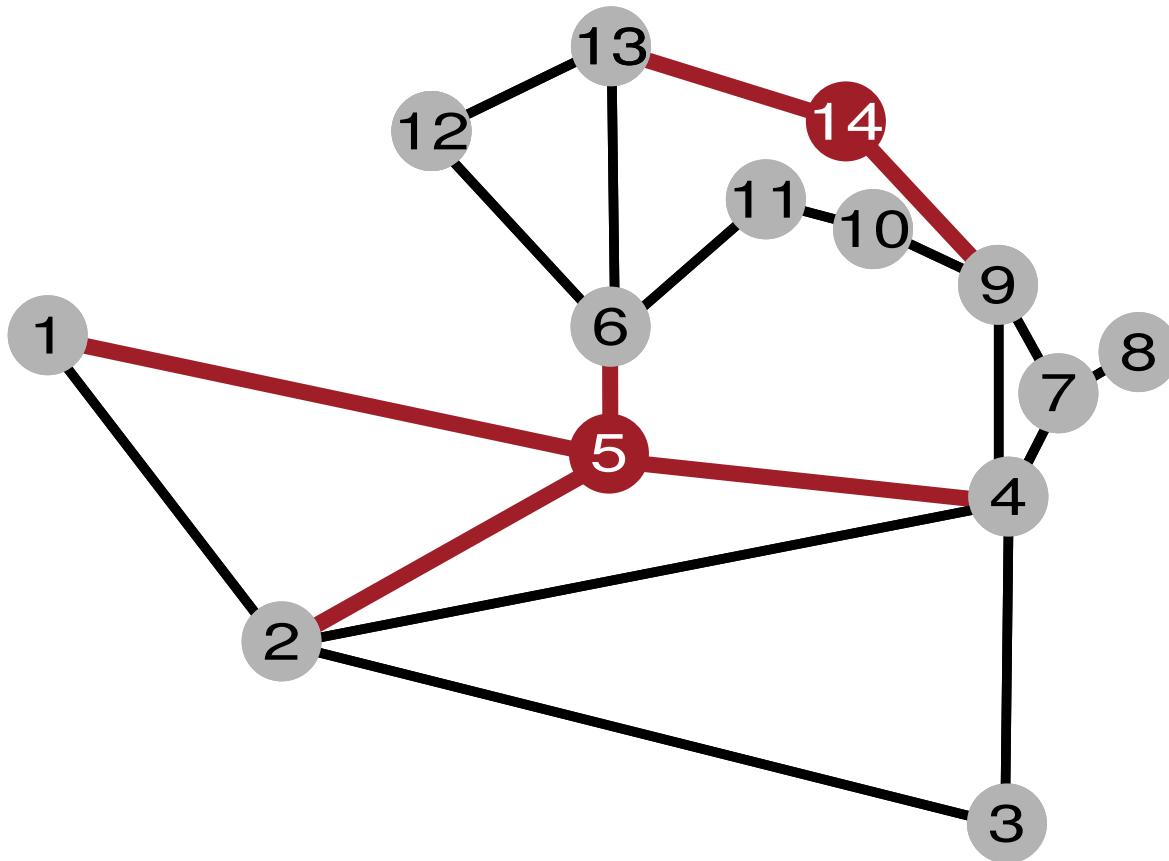
- control unit
- controlled flow

Kirchhoff's circuit laws:

- Kirchhoff's current law ✓
- Kirchhoff's current law ✓
- Kirchhoff's voltage law ✓

Hybrid Model = Flow Model + Physical Model

Hybrid Flow Model



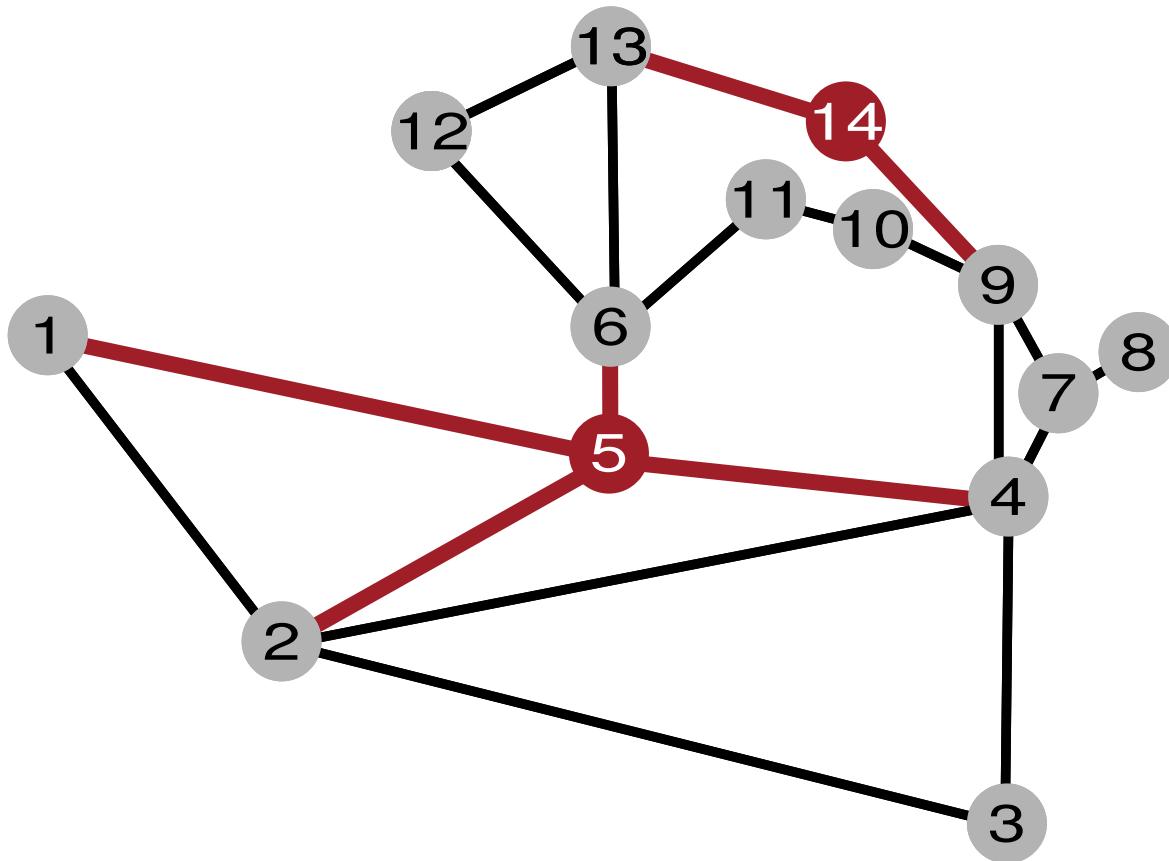
- control unit
- controlled flow

Kirchhoff's circuit laws:

- Kirchhoff's current law ✓
- Kirchhoff's current law ✓
- Kirchhoff's voltage law ✓

Hybrid Model = Flow Model + Physical Model

Hybrid Flow Model



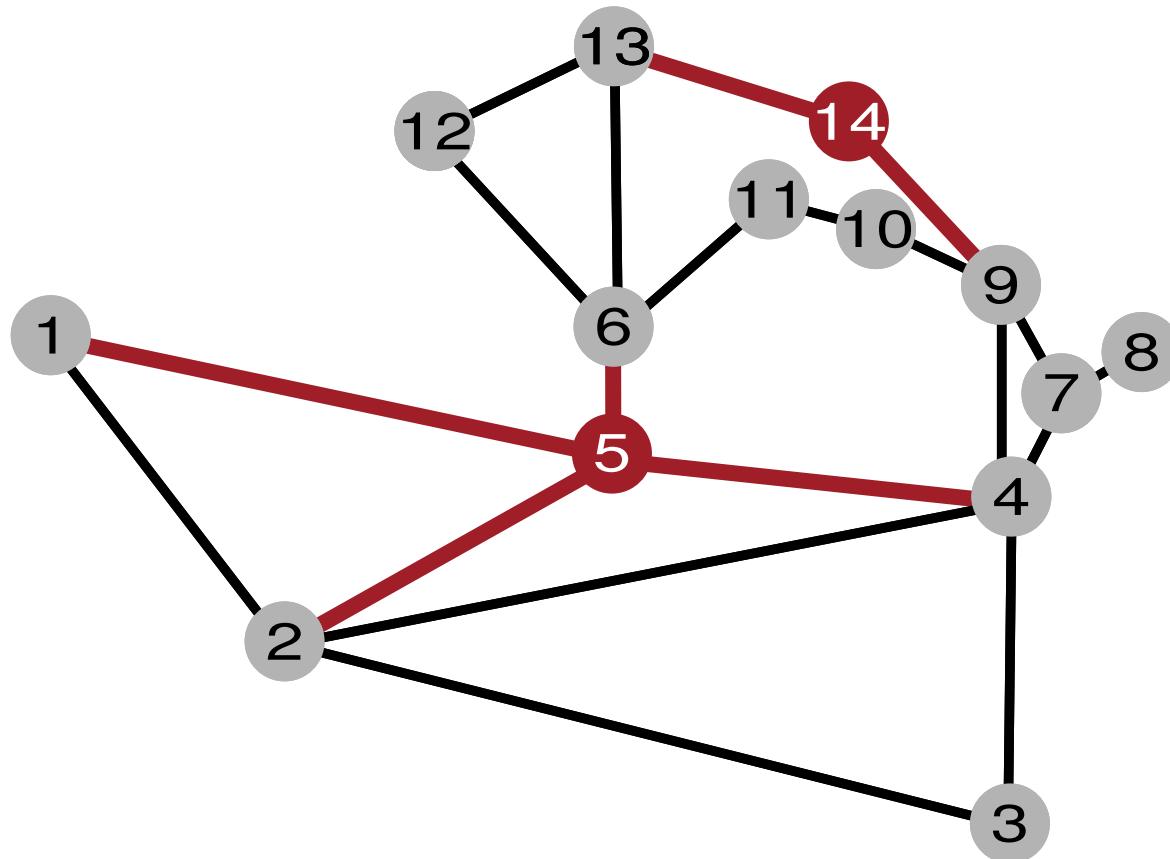
- control unit
- controlled flow

Kirchhoff's circuit laws:

- Kirchhoff's current law ✓
- Kirchhoff's current law ✓
- Kirchhoff's voltage law ✓

Hybrid Model = Flow Model + Physical Model
↓
Lower Bound

Hybrid Flow Model



- control unit
- controlled flow

Kirchhoff's circuit laws:

- Kirchhoff's current law ✓
- Kirchhoff's current law ✓
- Kirchhoff's voltage law ✓

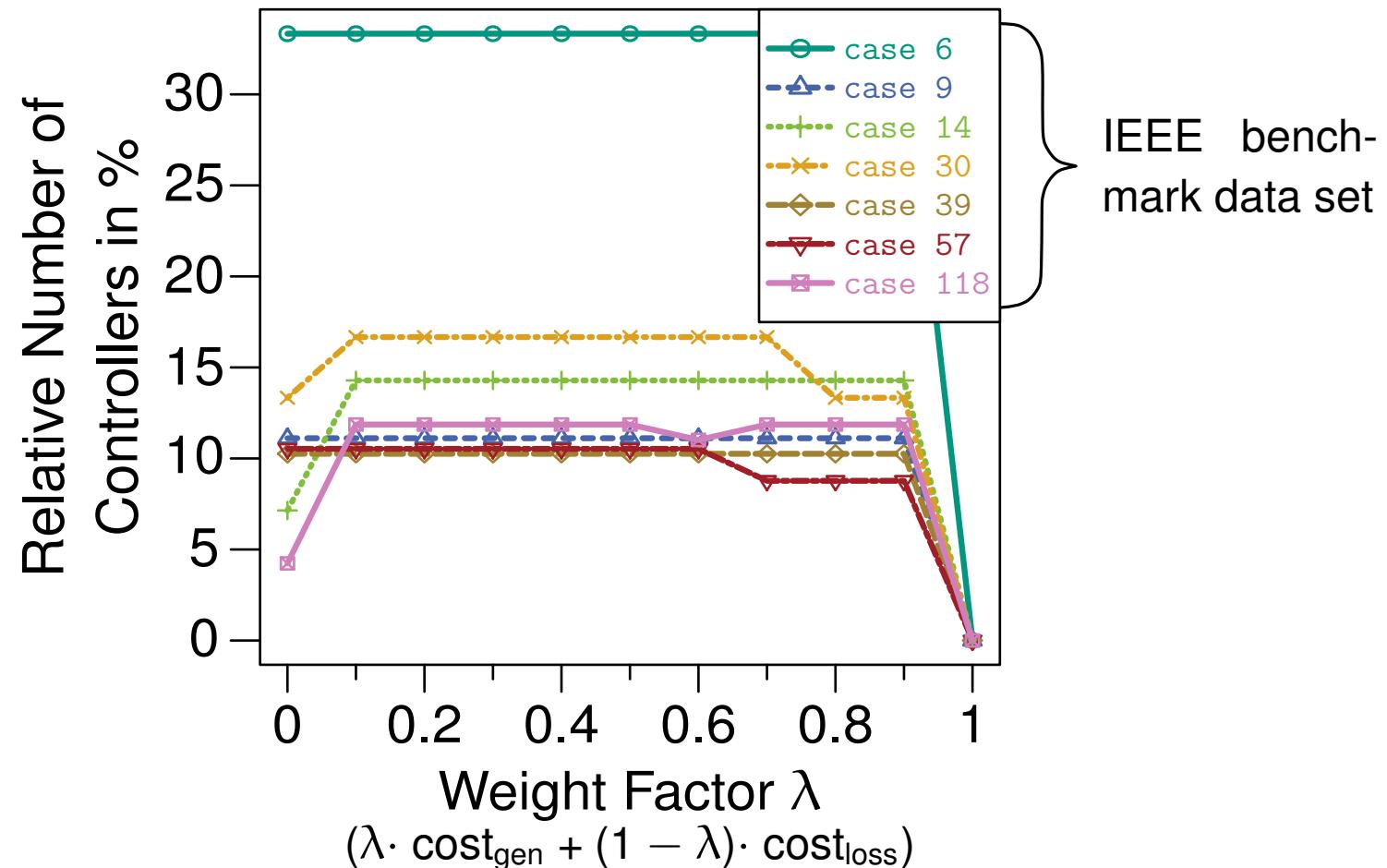
Hybrid Model = **Flow Model** + Physical Model
↓ ↓
Lower Bound Upper Bound

Research Questions

Control units are expensive – how many do we need?

- (Q1) How many controlled buses are necessary for globally optimal power flows? Which buses need to be controlled?
- (Q2) For a given number of available control buses, is there a positive effect on flow costs and operability when approaching grid capacity limits?

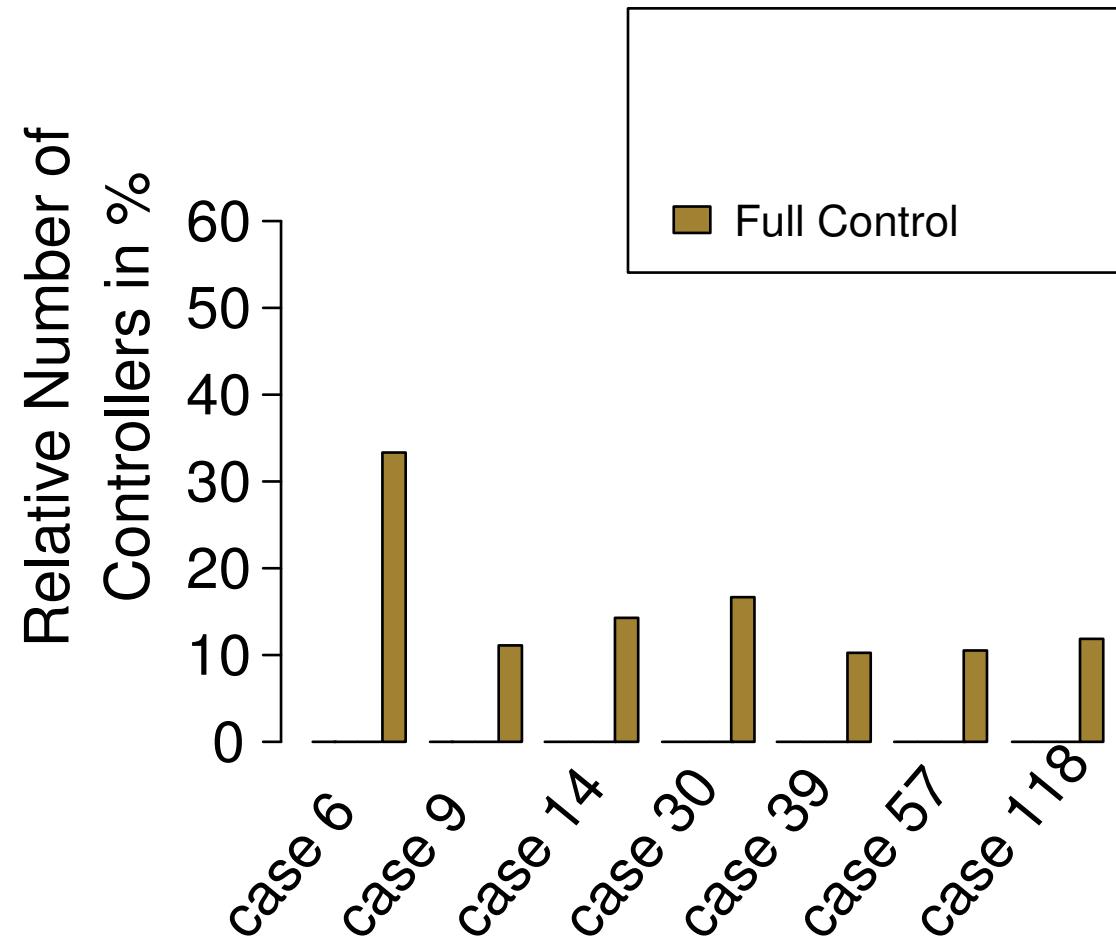
Number of Control Buses



Observation from experiments:

- Few control buses suffice for obtaining optimal solutions

Number of Control Buses



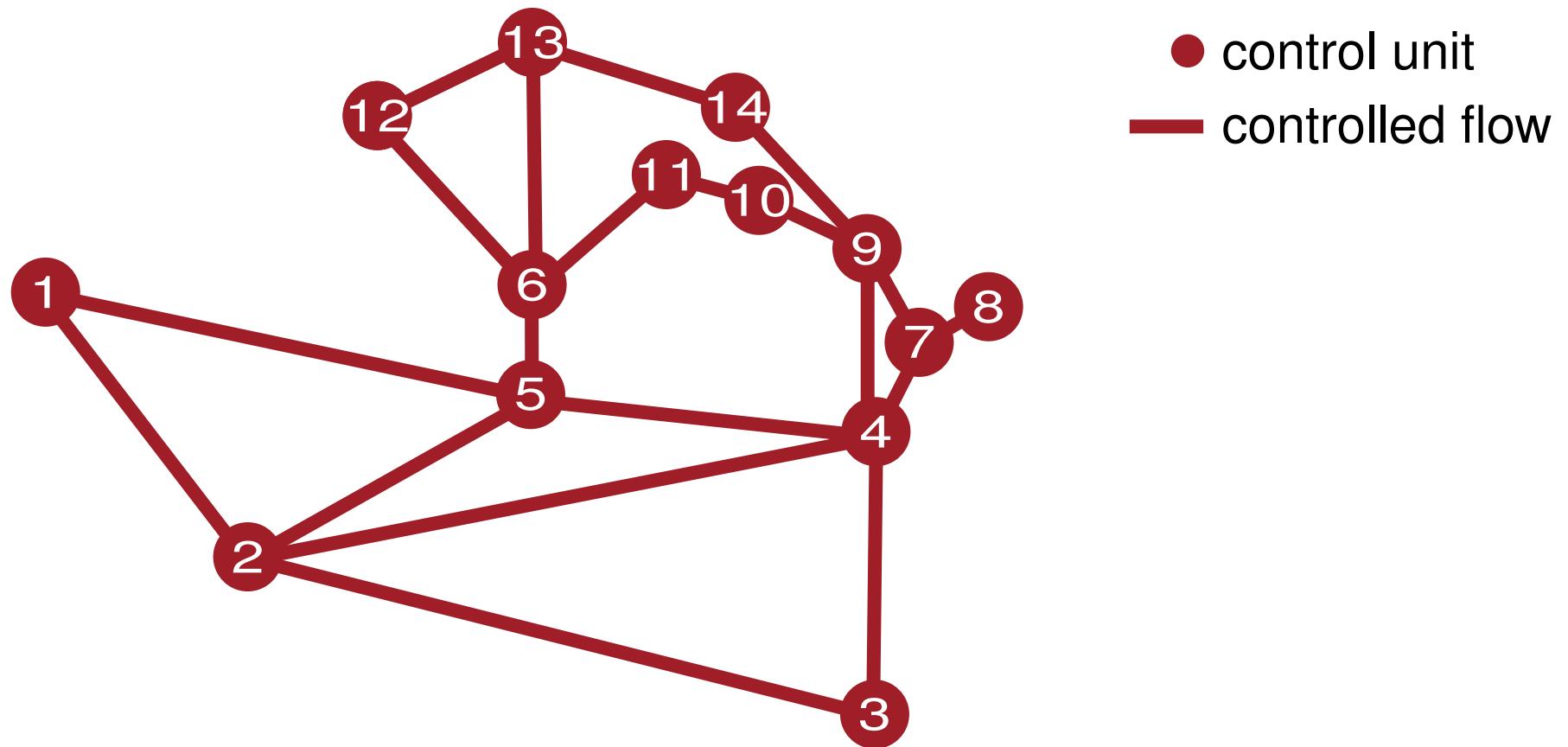
- For each benchmark case: $\max_{\lambda} \min \#Controller$



Matching the Flow Model (Q1)

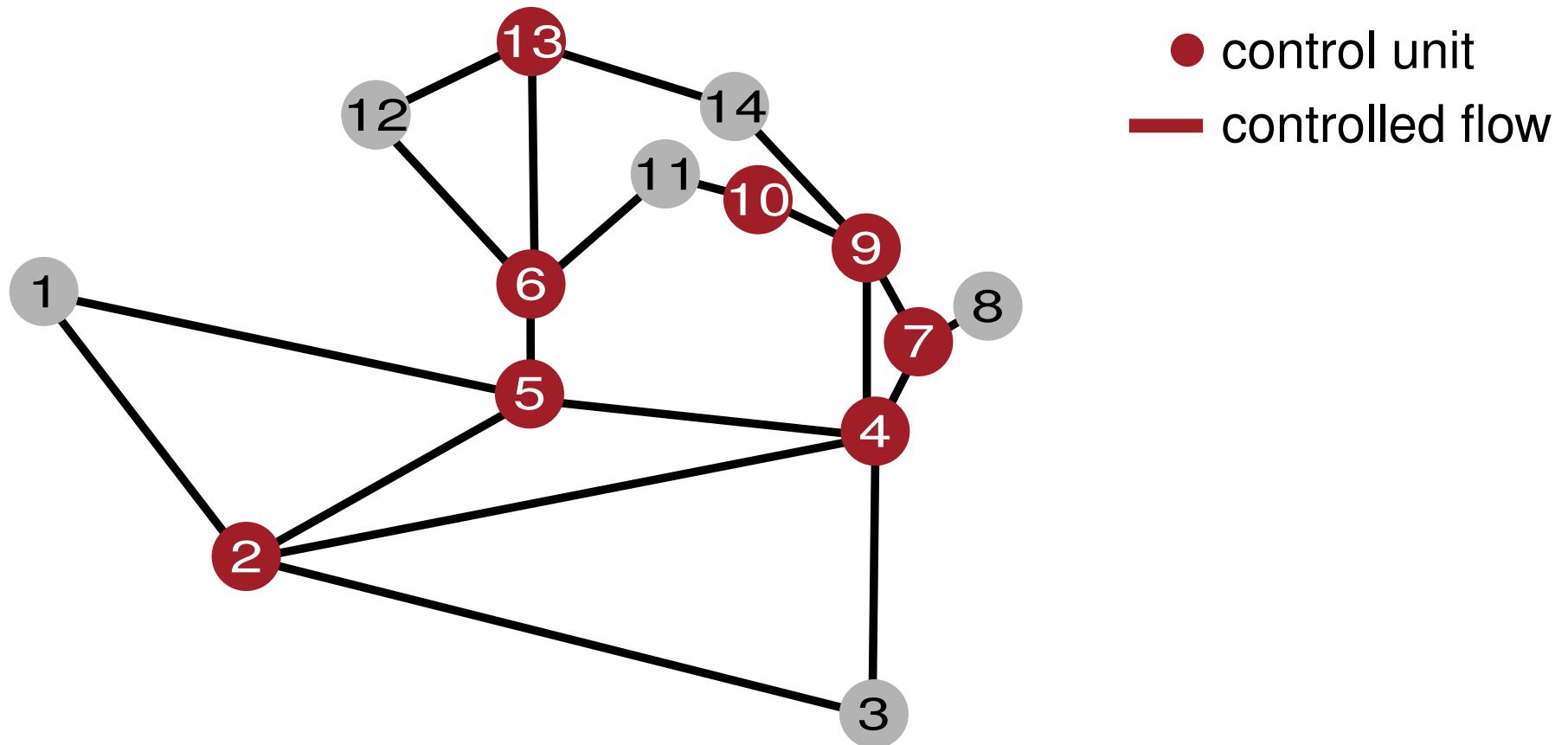
- How many flow control buses are necessary to obtain globally optimal power flows and which buses need to be controlled?

Globally Optimal Power Flows

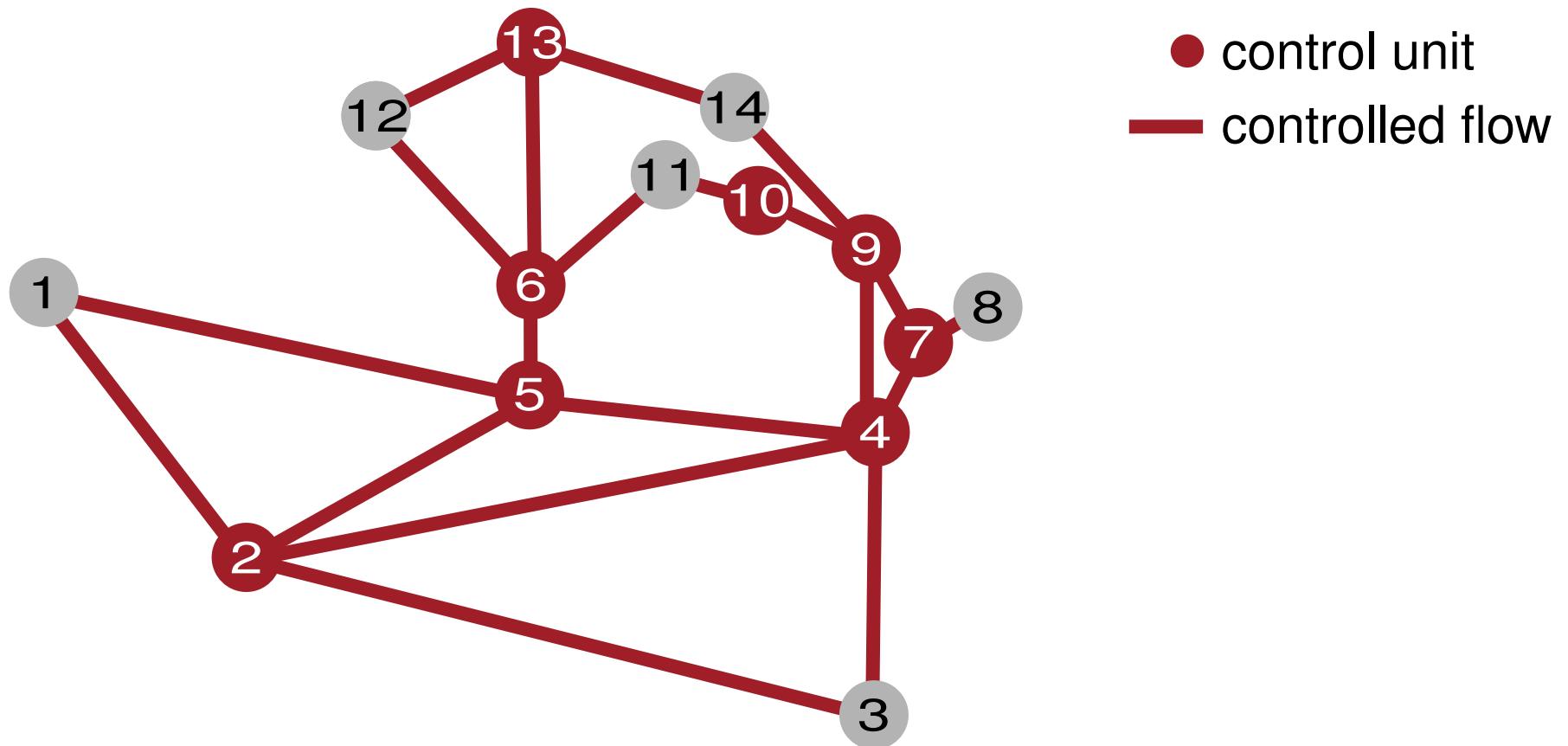


Can we become as good as the Flow Model
with fewer control busses?

Vertex Cover

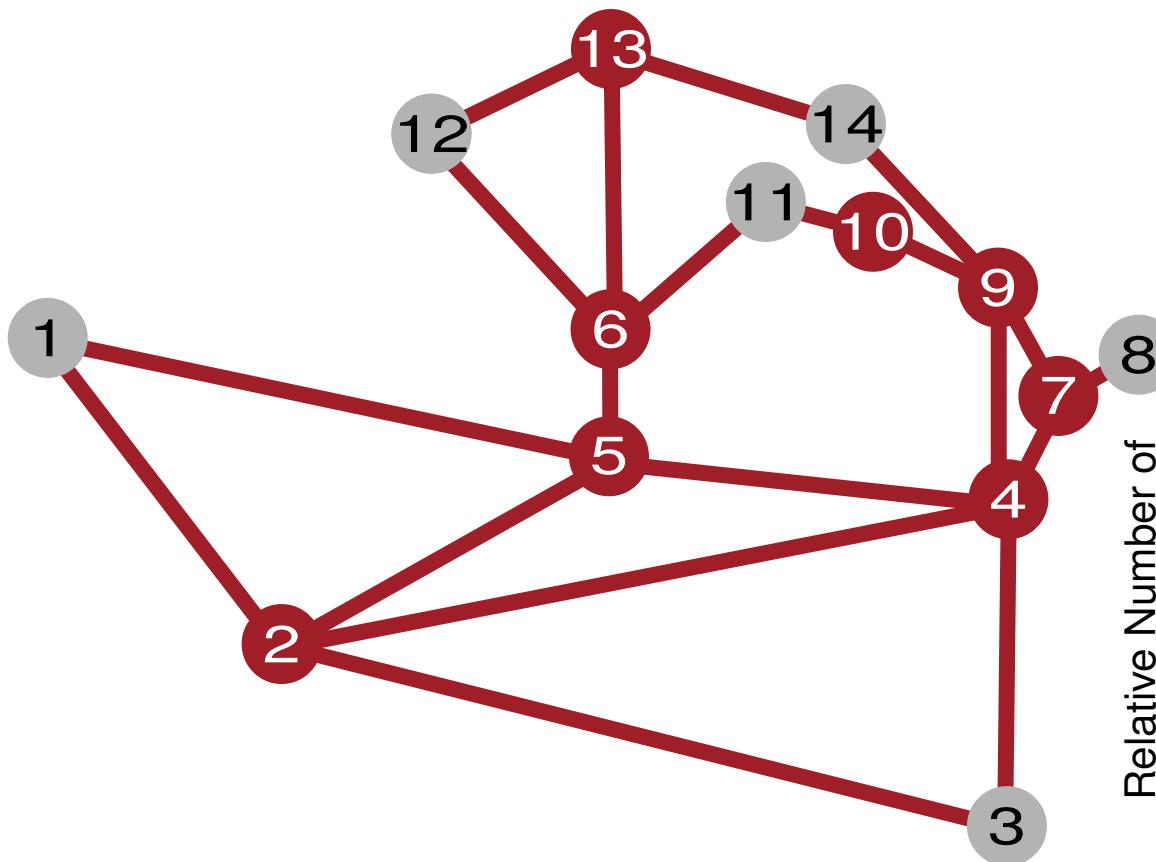


Vertex Cover

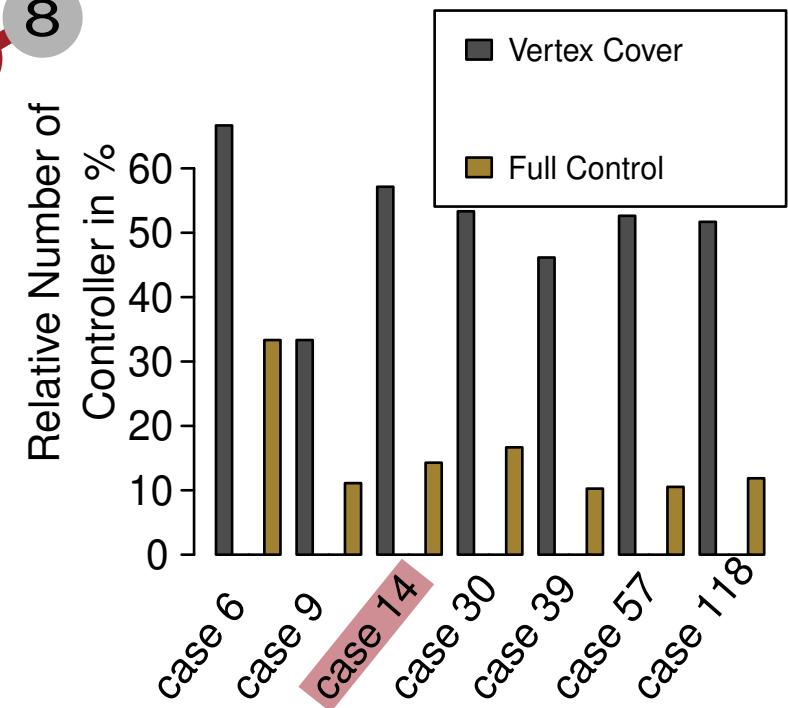


- Control flow on all edges
 - As good as Flow Model
- ⇒ Still too many flow control buses

Vertex Cover



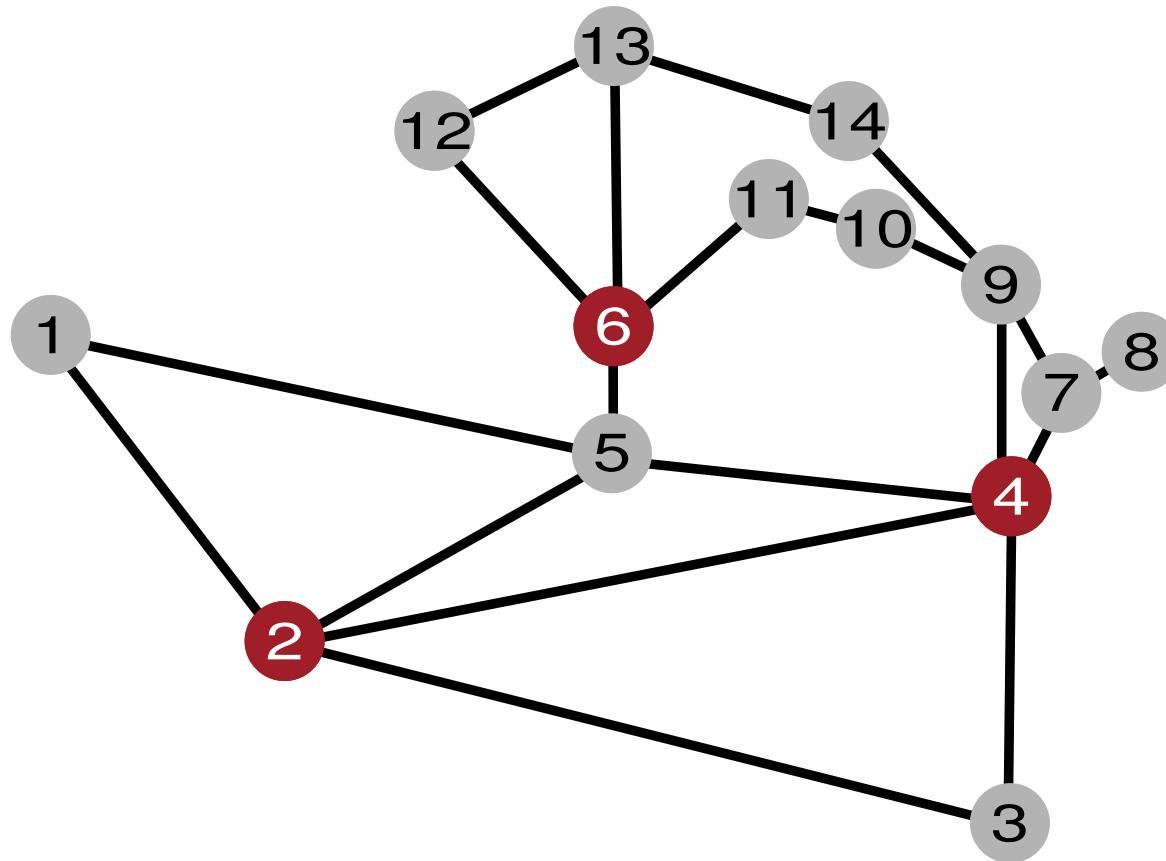
● control unit
— controlled flow



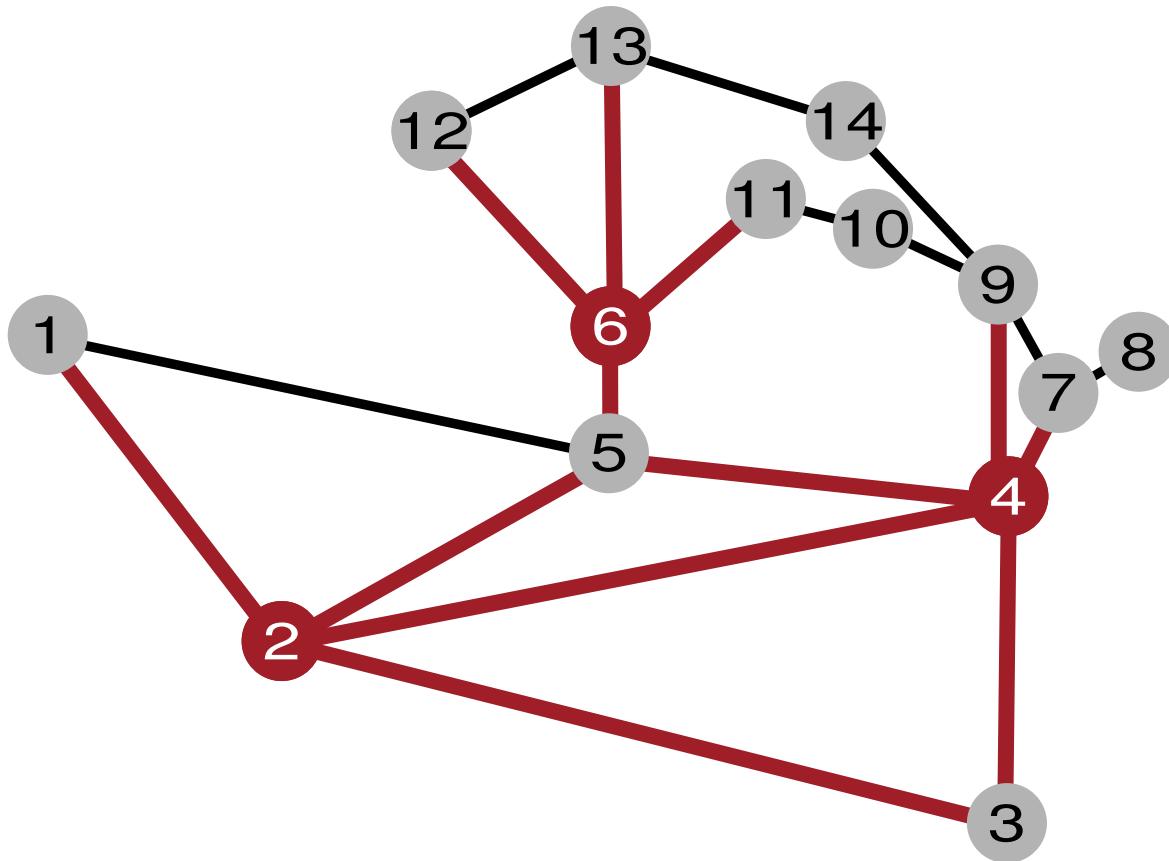
Fewer than 8 flow control buses sufficient?

Feedback Forest Set

 *feedback forest set*

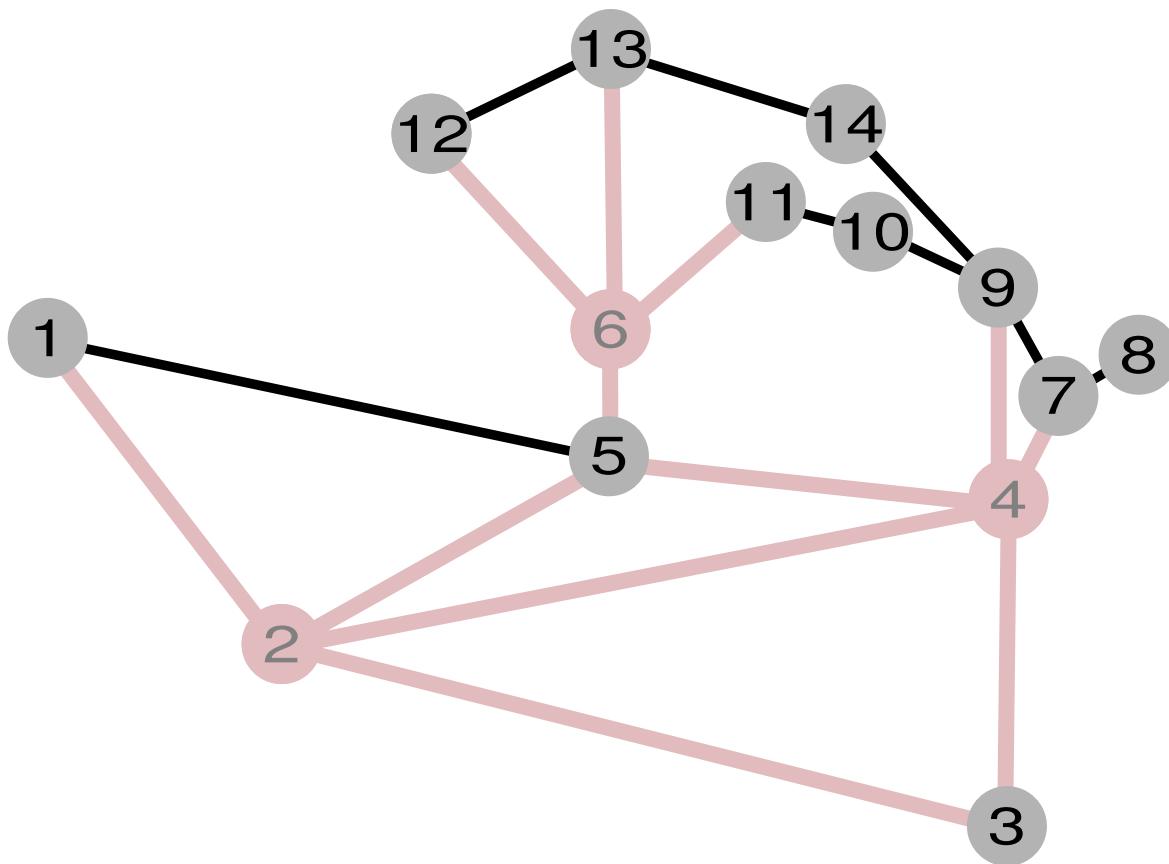


Feedback Forest Set



 *feedback forest set*
↓
A set of trees (*forest*) remains!

Feedback Forest Set

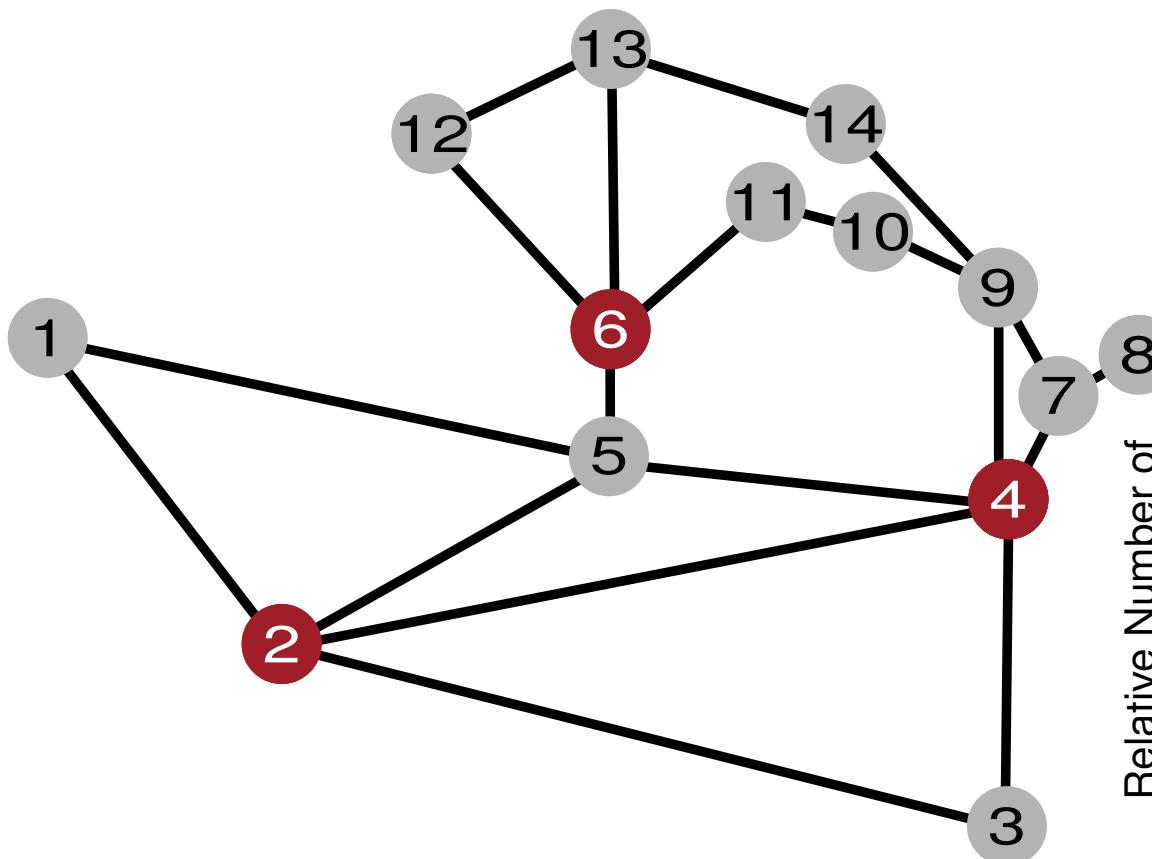


 *feedback forest set*
↓
A set of trees (*forest*) remains!

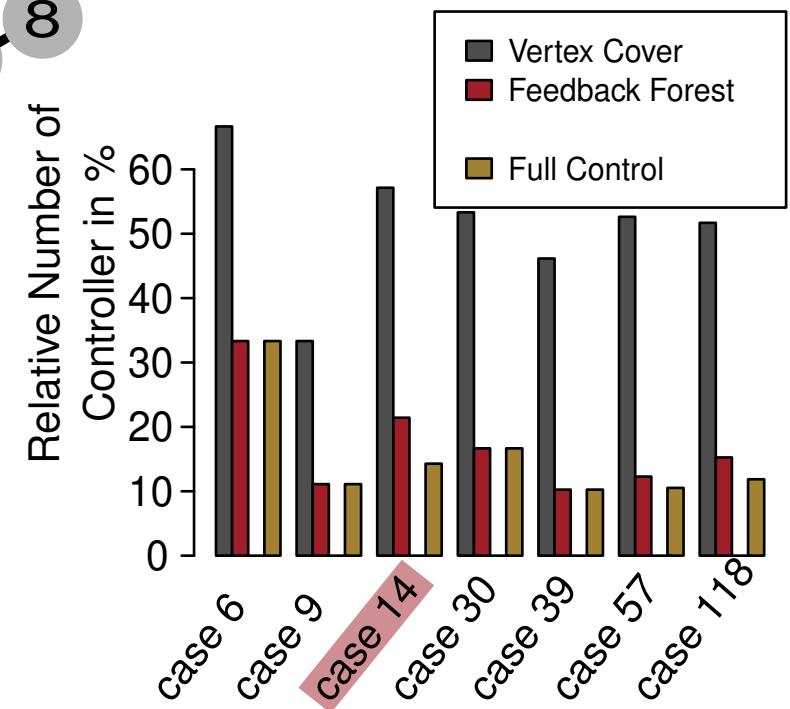
Theorem 1

Physical subgrid forest \Rightarrow All flows obey voltage laws

Feedback Cactus Set

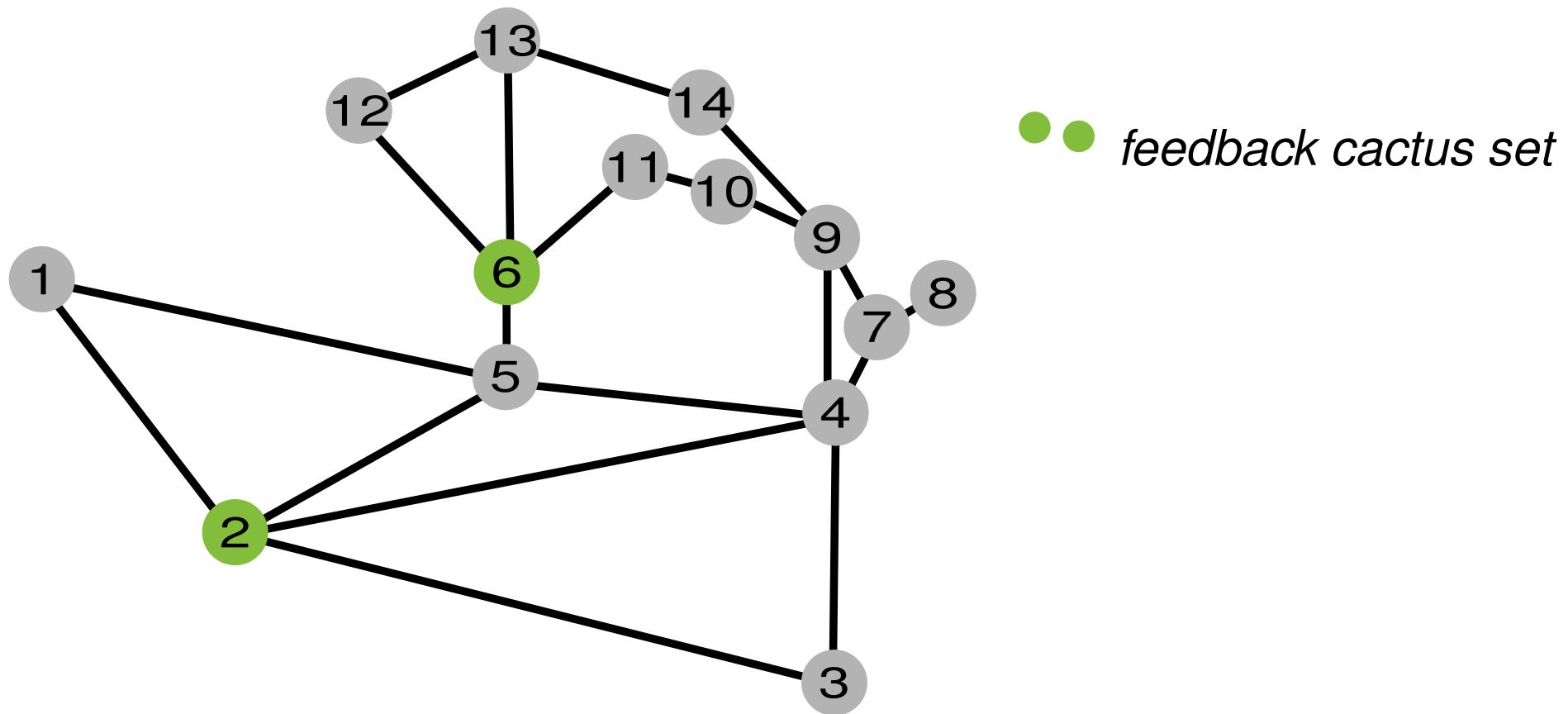


feedback forest set



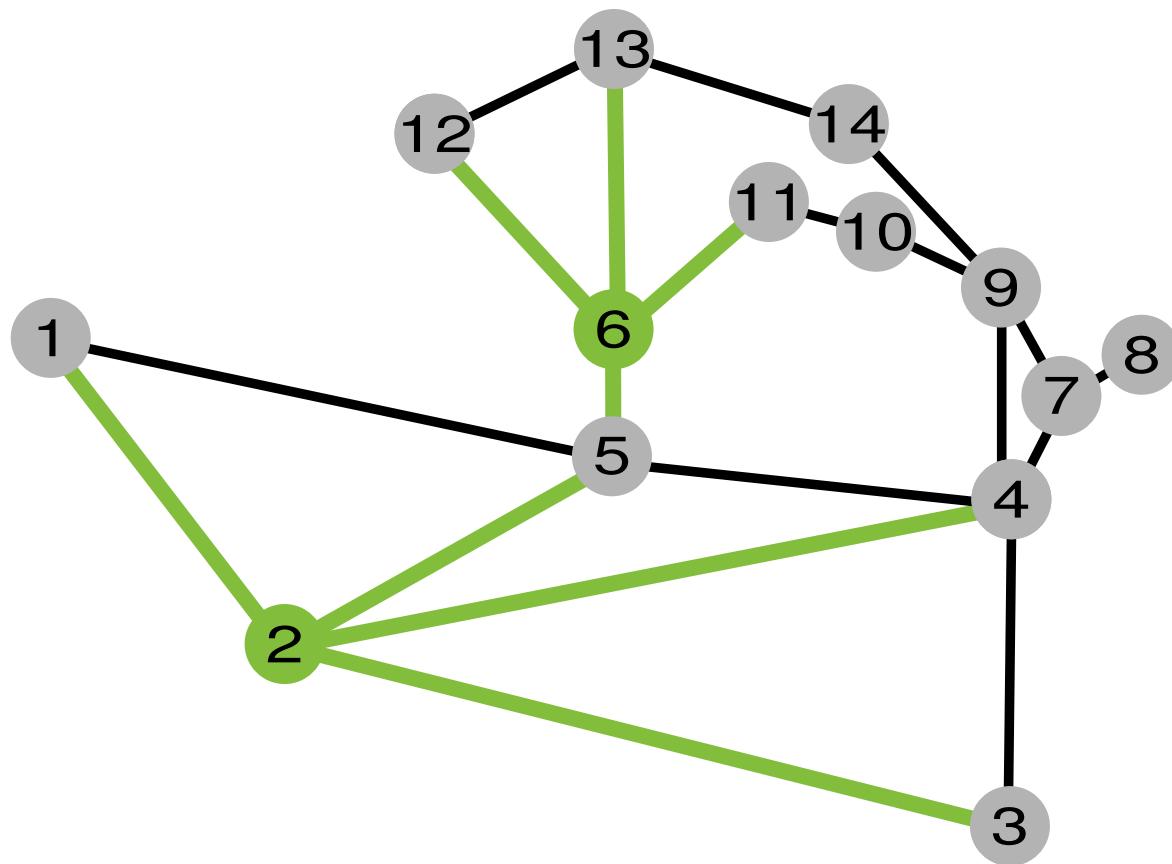
Fewer than 3 flow control buses sufficient?

Feedback Cactus Set



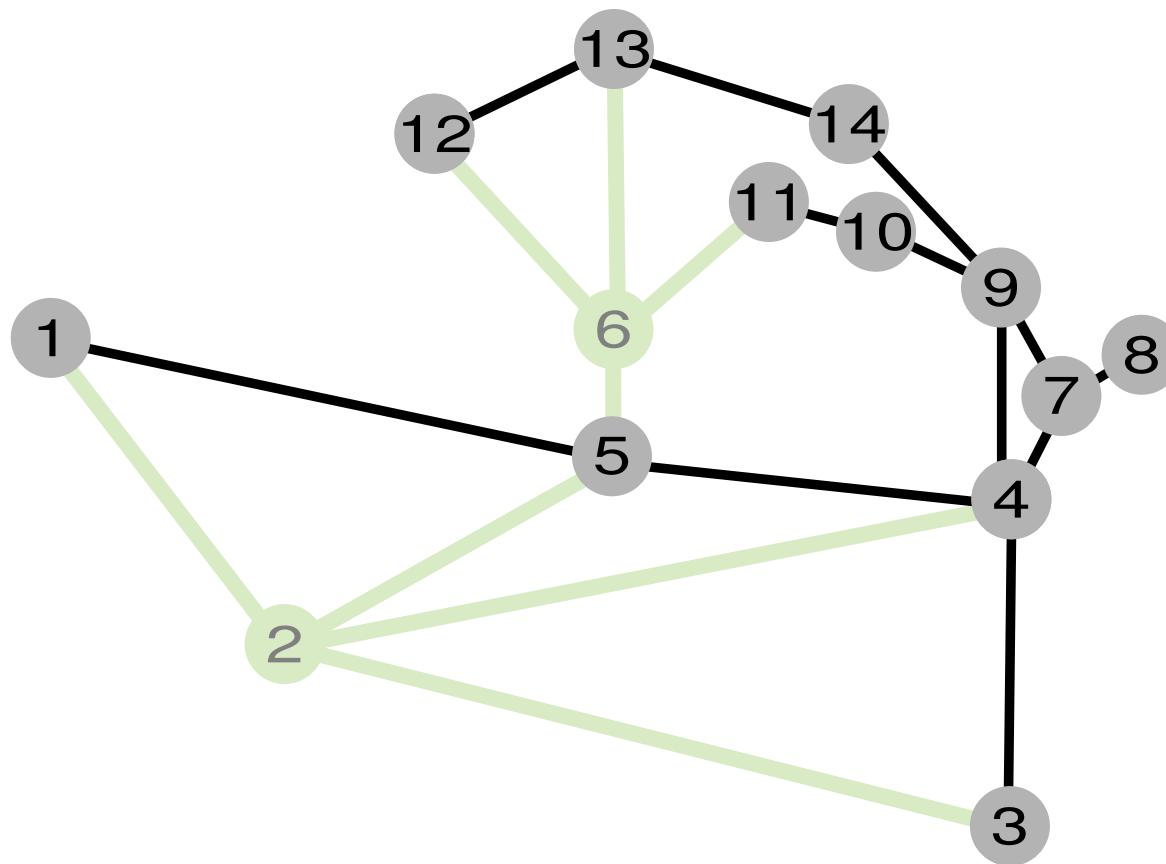
● ● *feedback cactus set*

Feedback Cactus Set



● ● *feedback cactus set*
↓
A set of *cacti* remains!

Feedback Cactus Set



● ● *feedback cactus set*
↓
A set of *cacti* remains!

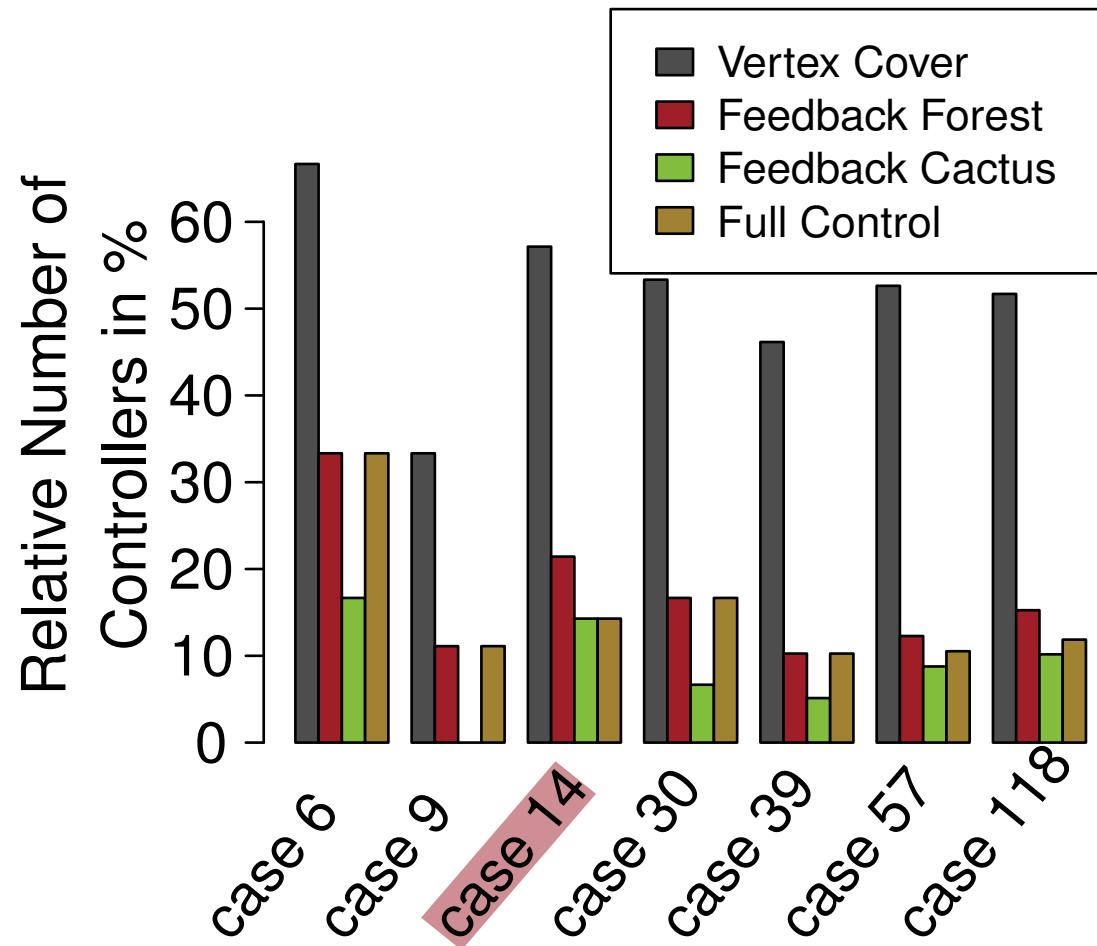
Theorem 2

Physical subgrid cactus, line limits on cactus suitably bounded.

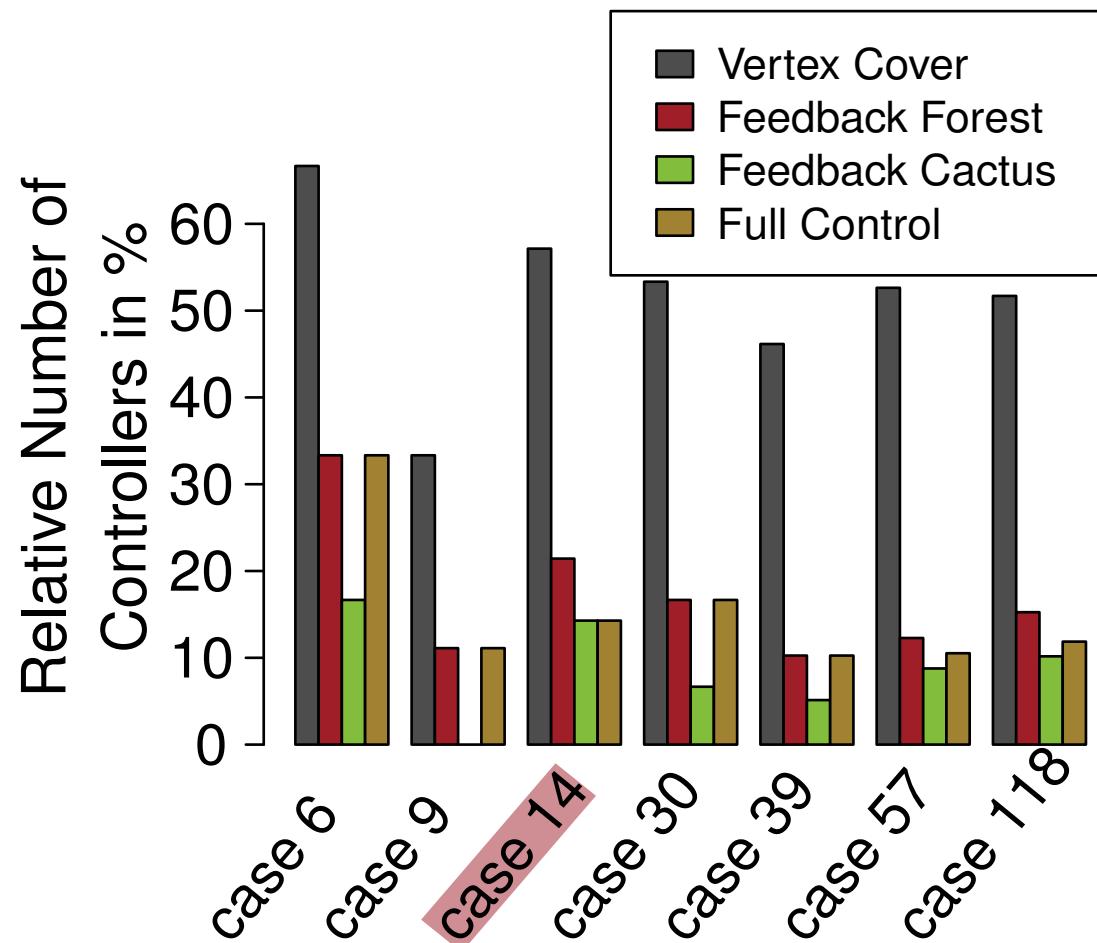


For every flow there is a cost-equivalent flow obeying voltage laws.

Number of Control Buses vs. Structural Results



Number of Control Buses vs. Structural Results



Findings

Often a small number of flow control buses suffices for matching cost of the flow model.



Effect of Few Flow Control Buses (Q2)

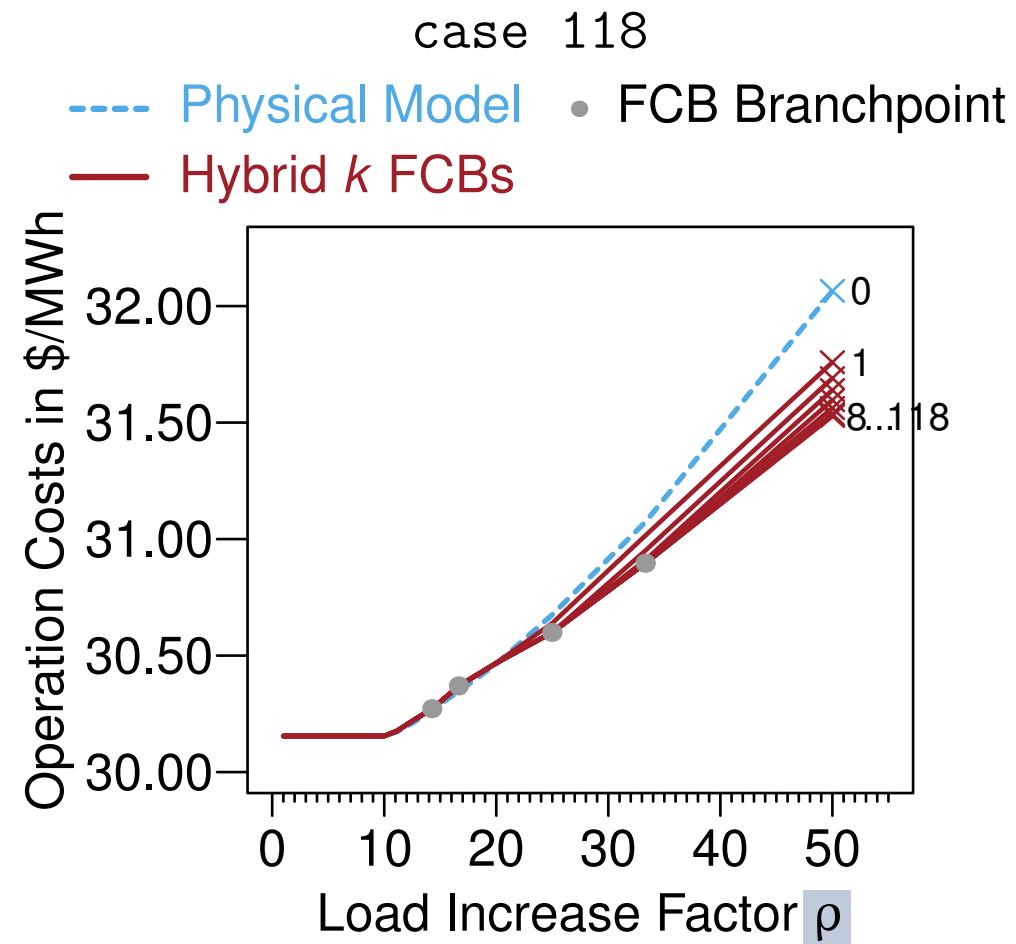
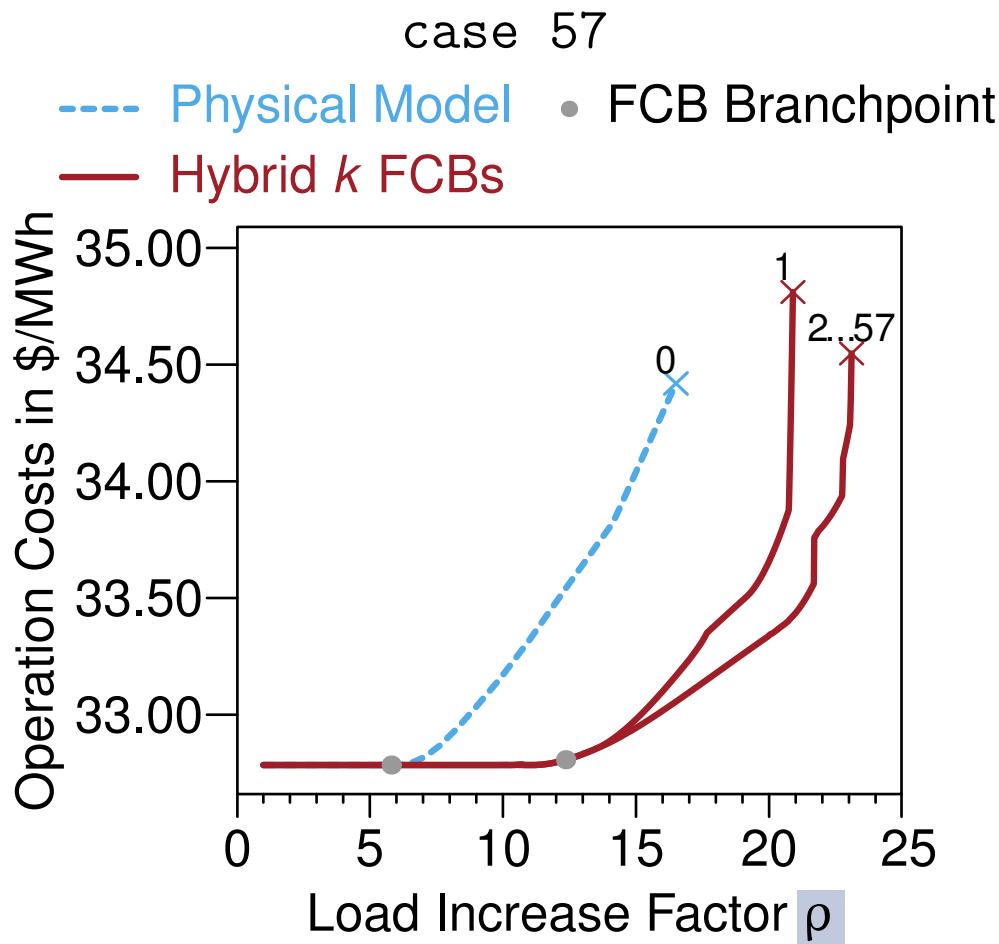
- For a given number of available control buses, is there a positive effect on flow costs and operability when approaching grid capacity limits?

- Simulate load increase by a load increase factor ρ
- Simulations with different numbers of flow controllers

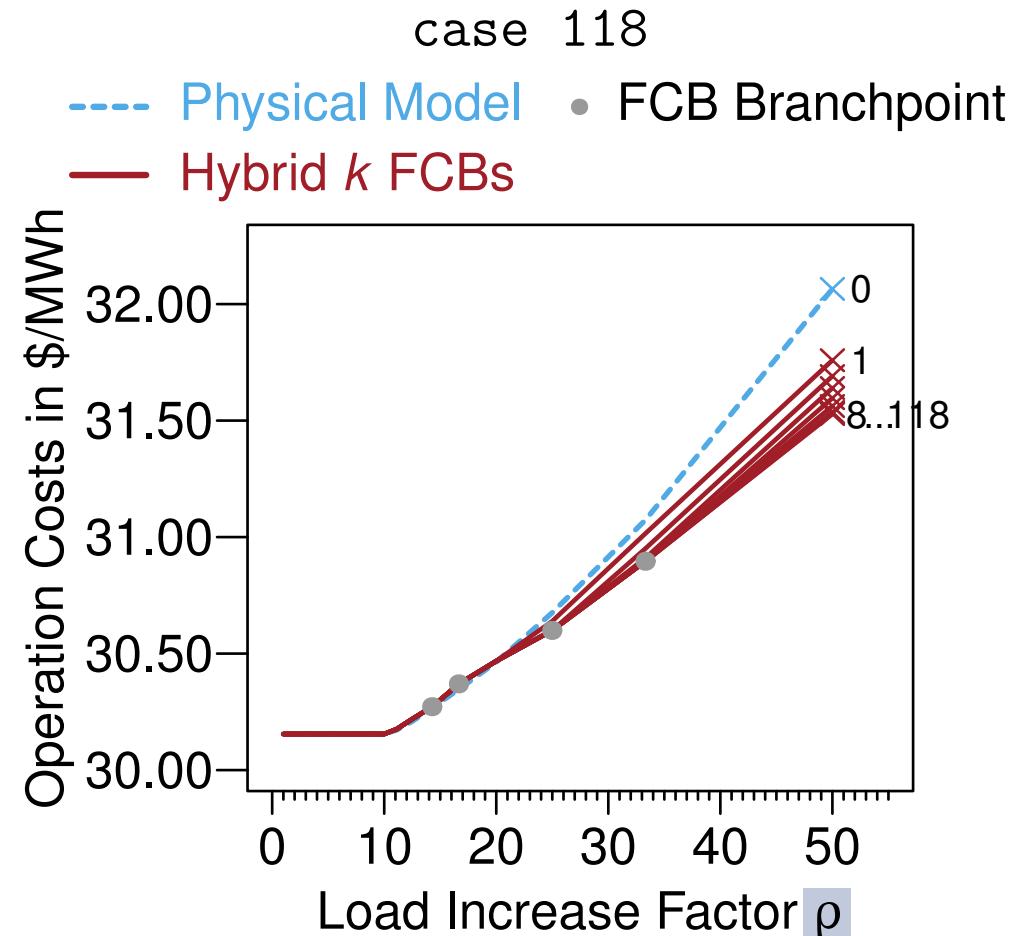
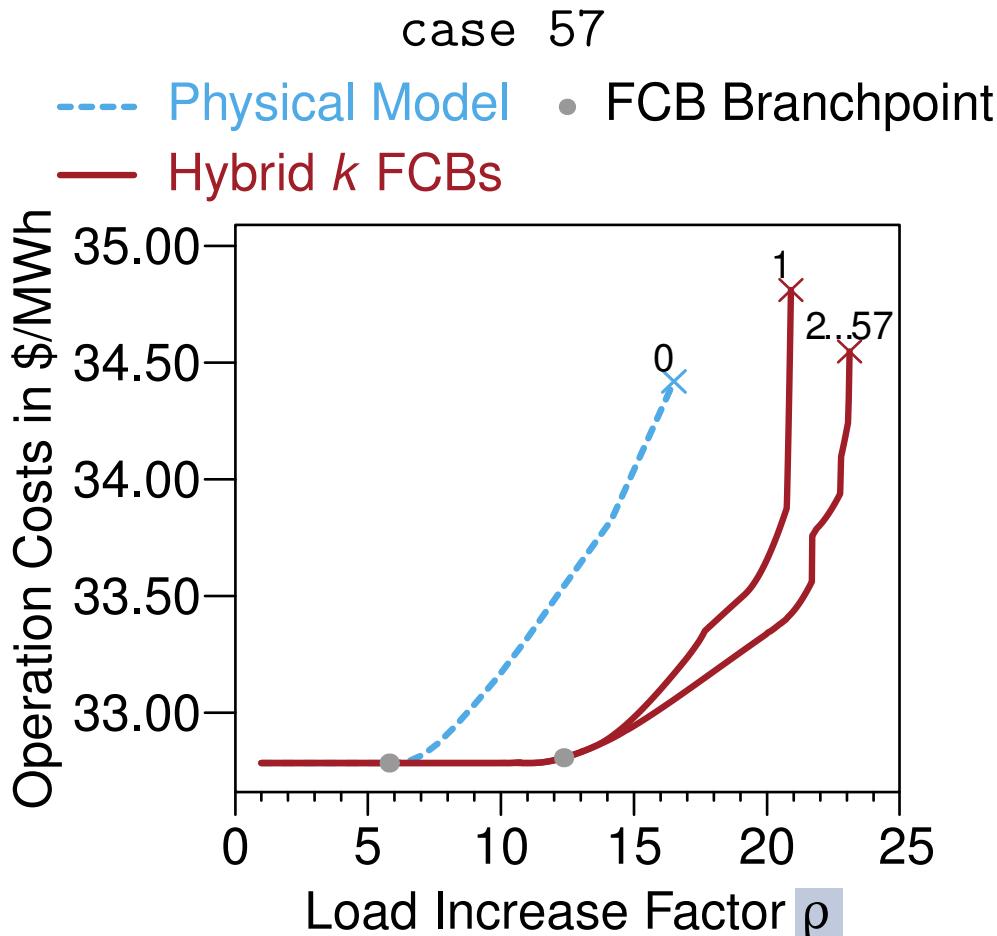
Test Data:

- IEEE instances have basically “unlimited” edge capacities
- Reduce capacities to total demand (no effect on cost and feasibility)
- Gradually increase all loads by factor ρ , or, alternatively, reduce all capacities by $1/\rho$
- Compute generation cost and required number of controllers for optimality

Hybrid Model Operation under Increasing Loads



Hybrid Model Operation under Increasing Loads



Findings

Very few flow control buses extend the operation point, while having lower operation cost.

Hybrid Model = Flow Model + Physical Model

Question 1: Optimality

- How many controlled buses?
- Which buses need control?

Question 2: Cost & Operability

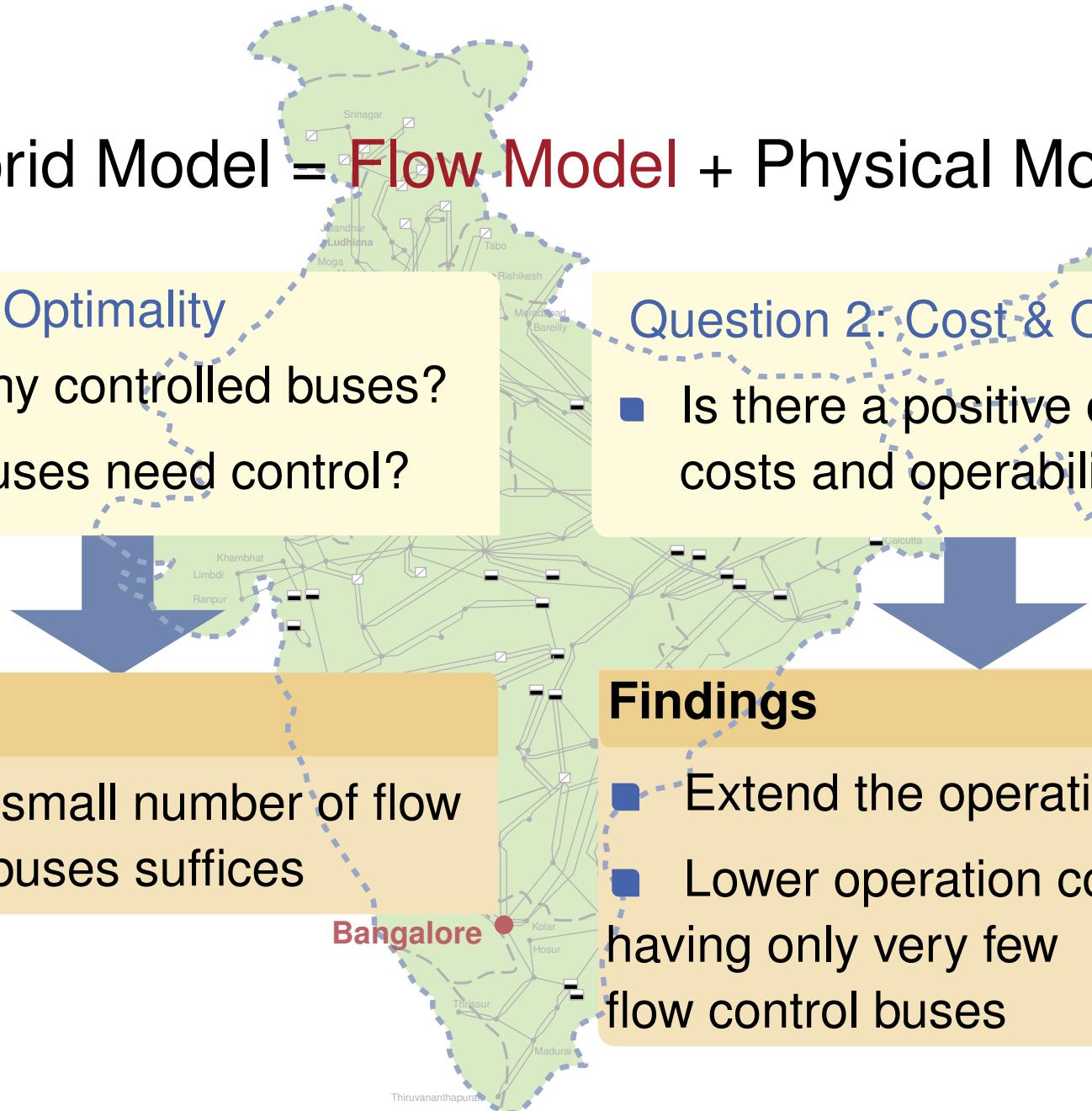
- Is there a positive effect on flow costs and operability?

Findings

- Often a small number of flow control buses suffices

Findings

- Extend the operation point
- Lower operation cost having only very few flow control buses



Hybrid Model = Flow Model + Physical Model

Question 1: Optimality

- How many controlled buses?
- Which buses need control?

Question 2: Cost & Operability

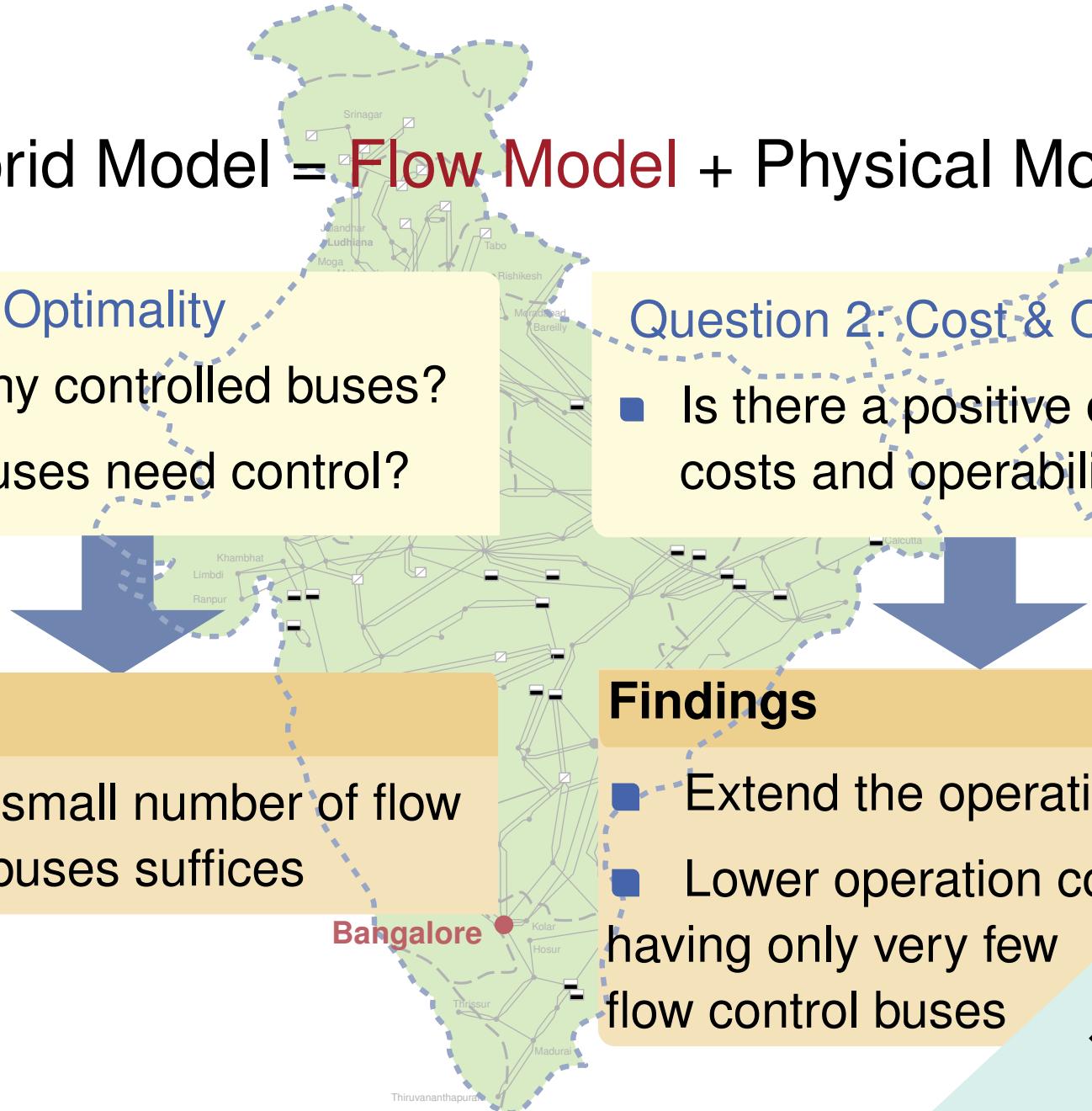
- Is there a positive effect on flow costs and operability?

Findings

- Often a small number of flow control buses suffices

Findings

- Extend the operation point
- Lower operation cost having only very few flow control buses



Backup 1

Weighted cost function $\lambda \cdot \text{cost}_{\text{gen}} + (1 - \lambda) \cdot \text{cost}_{\text{loss}}$

