Graver basis

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Chapter 1

Introduction

The underlying problem we try to solve is the clasical *Integer program* (IP) that we formulate in the following way:

$$(IP)\equiv \max\{c^tx:Ax=b,l\leq x\leq u,x\in\mathbb{Z}^n\}$$
 $A\in\mathbb{Z}^{mxn},b\in\mathbb{Z}^m,c\in\mathbb{Z}^n,l$ and u lower and upper bounds for x

Despite its simplicity, it's well known the importance of IP. Several problems in diverse fields of the mathematics and algorithms admit an IP equivalent formulation (examples?). Unfortunately, IP is NP-Complete. This means that there is no efficient (polynomial) algorithm for solving IP in the general case (say general techniques and complexity?) and, therefore, knowing their importance and the lack of a general efficient algorithm for their resolution, there has been a great interest in restricted formulations of the problem and their resolution techniques.

In this project we present the concept of **Graver Basis** and its applications for solving the IP with, of course, the theoretical justification of this based on its properties. We apply this to a concrete IP formulation, the N-Fold IP and prove that it leads to a polynomial and efficient algorithm for this case.

Chapter 2

Graver Basis

Definition 2.1. Two vectors $u, v \in \mathbb{R}^n$ are said to be **sign compatible** if $u_i \cdot v_i \geq 0$ for all $i \in \{1, ..., n\}$.

Definition 2.2. A vector $u \in ker(A)$ is **indecomposable** if it is not the sum of two sign compatible and non zero elements in ker(A).

Definition 2.3 (Graver basis). The Graver Basis of a given matrix $A \in \mathbb{Z}^{mxn}$ is defined as the set of integral indecomposable elements in the kernel of A. (Initially defined as *universal integral test set* in [Graver 1975])

Proposition 2.4. For every matrix A, Gr(A) is a finite set.

Proposition 2.5. Every integral element in ker(A) can be expressed as positive integral linear combination of elements in Gr(A).

Proposition 2.6. Given z in the feasible region of an IP, z is not optimum if and only if there exists $g \in Gr(A)$ s.t. $c^tg > 0$ and $l \le z + g \le u$

Proposition 2.7 (Graver basis bounds). Given $A \in \mathbb{Z}^{mxn}$ and Δ an upper bound for the absolute value of each component of A, for every $g \in Gr(A)$:

- $||g||_1 \le m^{m/2} \Delta^m \cdot (n-m)$ [Onn 2010]
- $||g||_1 \leq (2m\Delta + 1)^m$ [Eisenbrand, Hunkenschröder, Klein 2018]

Bases of augmentation algorithm

• If not optimal, an element in Graver basis is an improvement direction.

Contents 3

• If Graver basis bounded, we can restrict our improvement direction search.

General IP algorithm using Graver basis norm bound

- 1. From a feasible solution z_i
- 2. Find g^* optimum for the sub-problem:

$$max\{c^tg: Ag = 0, l - z_i \le g \le u - z_i, g \in \mathbb{Z}^n, ||g||_1 \le ||Gr(A)||\}$$

- $g^* = 0 \implies z_i$ optimal solution.
- $g^* \neq 0 \implies g^*$ improvement direction, loop back to 1 with $z_{i+1} = z_i + \lambda \cdot g^*$ with the biggest λ respecting the bounds.

[Hemmecke, Onn, Romanchuk 2013]

Appendix A

Graver basis computation with 4ti2

Appendix B

IP resolution with Graver Basis example

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