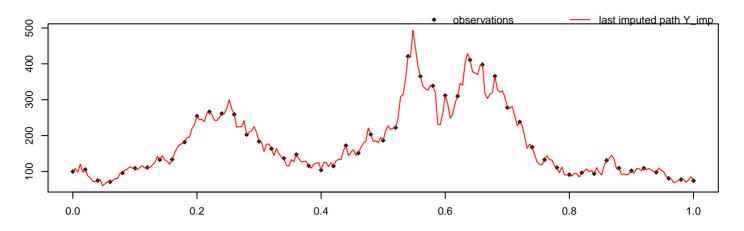
alpha = 1, $sigma^2 = 2$, M = 50, m = 5, path = 3, seed = 5886



methodPathUpdate = leftConditioned, methodParamUpdate = RandomWalk, approxTransDens = Milstein, approxPropDens = Euler

 mean_alpha
 hpd_alpha_I
 hpd_alpha_u
 mean_sigma^2
 hpd_sigma^2_I
 hpd_sigma^2_u

 0.58
 -2.05
 3.14
 2.21
 1.4
 3.26

