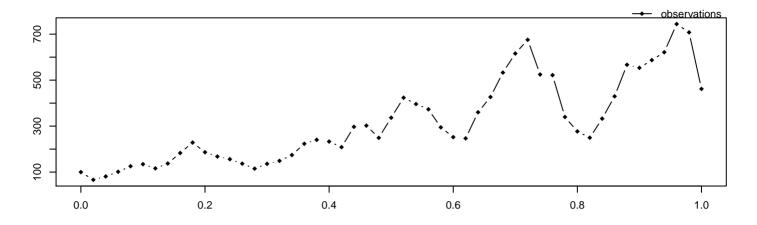
alpha = 1, $sigma^2 = 2$, M = 50, m = 1, path = 1, seed = 9948



methodPathUpdate = leftConditioned, methodParamUpdate = RandomWalk, approxTransDens = Euler, approxPropDens = Euler

 mean_alpha
 hpd_alpha_I
 hpd_alpha_u
 mean_sigma^2
 hpd_sigma^2_I
 hpd_sigma^2_u

 2.16
 -0.55
 4.61
 2.17
 1.41
 3.06

