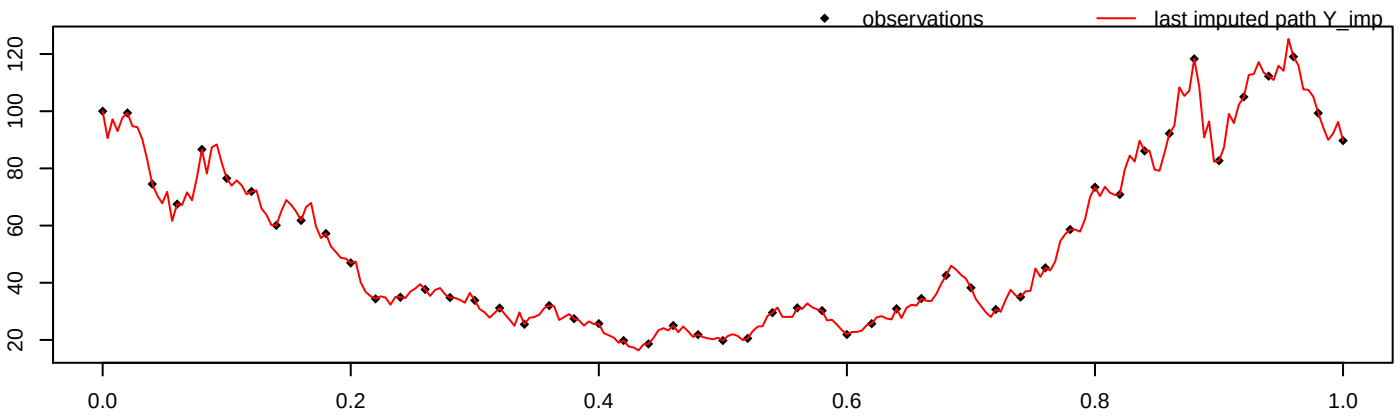
alpha = 1, sigma^2 = 2, M = 50, m = 5,
path = 4, seed = 3094



methodPathUpdate = leftConditioned, methodParamUpdate = RandomWalk,
approxTransDens = Euler, approxPropDens = Milstein

mean_alpha	hpd_alpha_l	hpd_alpha_u	mean_sigma^2	hpd_sigma^2_l	hpd_sigma^2_u
0.57	−1.76	2.95	1.62	1.12	2.24

acceptRatePath	acceptRateParam	duration	# of neg. point proposals	# of switches to MBEuler
0.388	0.208	61.516	0	0