

The T-calculus : Towards a structured programming of (musical) time and space.

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1. An example

The bebop problem and the bebop solution [1]...

My little blue suede shoes (Ch. Parker)



Musical analysis

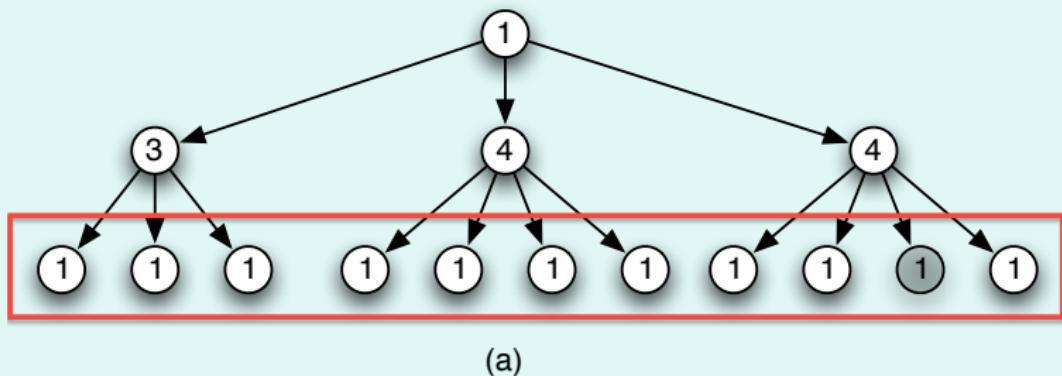
Three times motive (a) followed by its conclusive variant (b).

Play

String modeling (a)



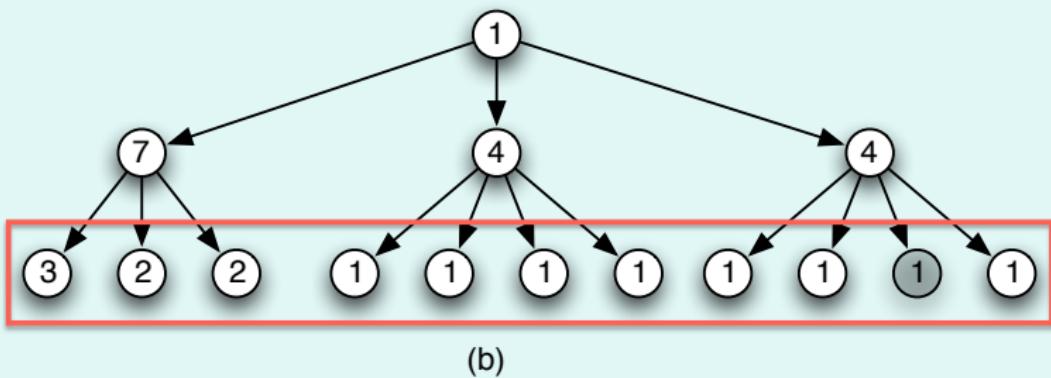
modeled by:



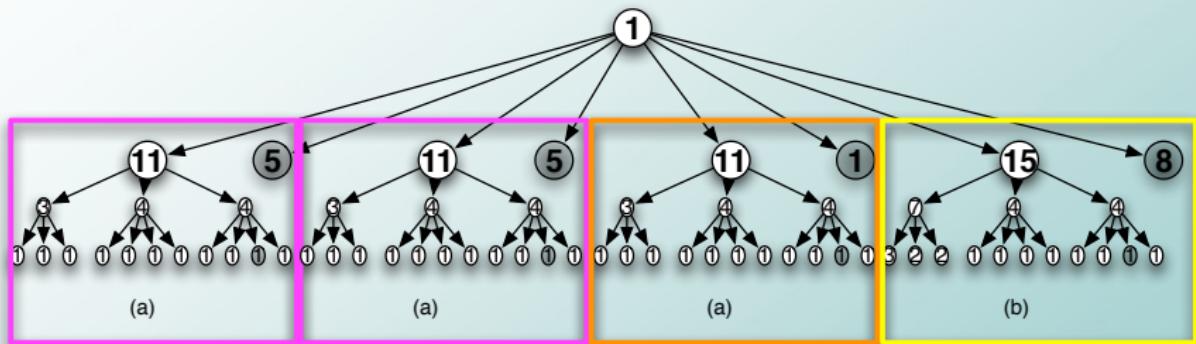
String modeling (b)



modeled by:



Resulting modeling



Problem:

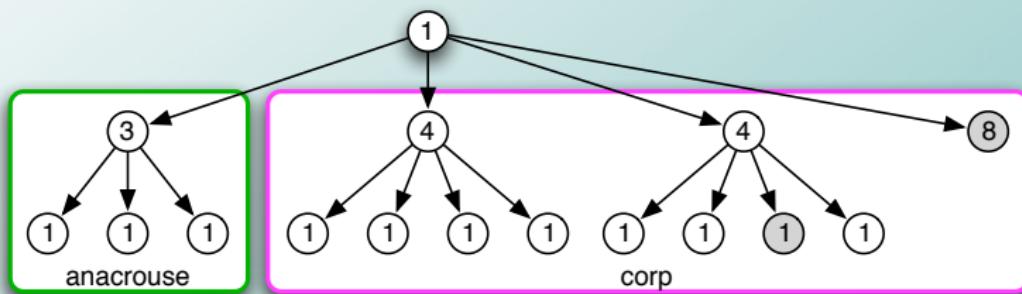
- we have inserted rests of various size : 5, 5, 1 and 8,
- we have lost the logical structure (3x(a) + (b)),
- handling variations will be even more messy.

Alternative : make the anacrusis and synchronization point explicit

The “real” first pattern:



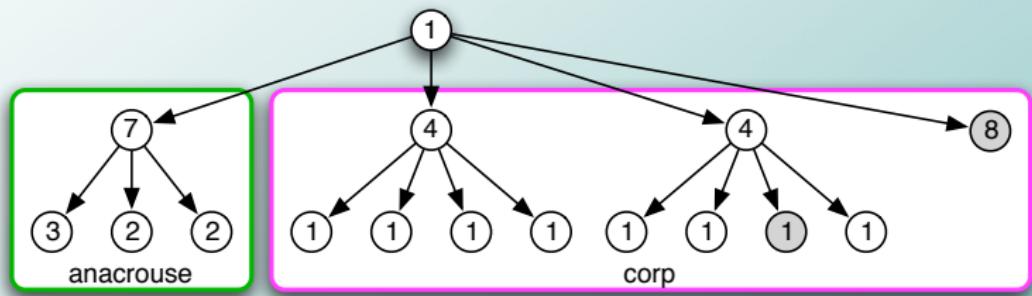
modeled by:



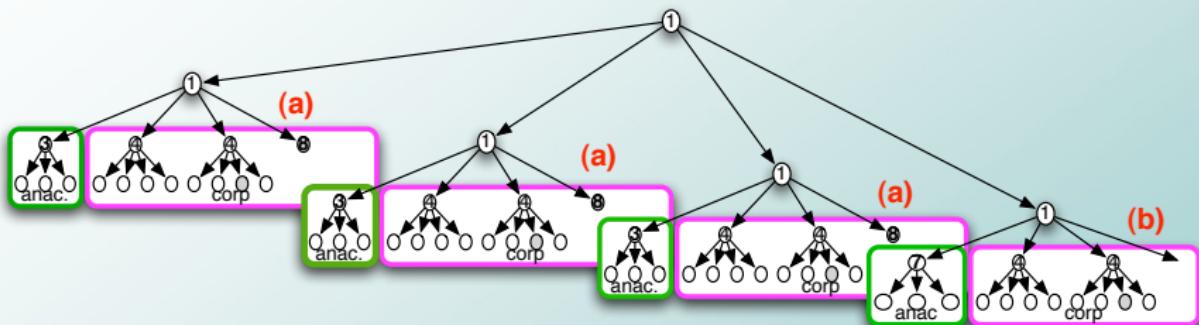
The “real” second pattern:



which give:



with resulting *mixed composition*:



defined with both sequential and parallel features.

Here comes back the logical structure: $3 \times (a) + (b)$!

This is **tiled strings (or streams) modeling** !

2. Tiled streams

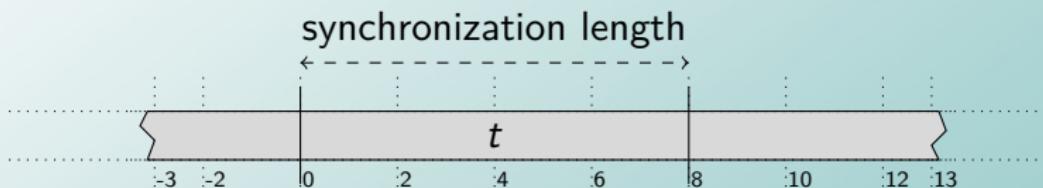
Embedding (audio) strings and (audio) streams into tiled streams [2]

Tiled streams

Basic types A, B, \dots , extended with a special silence value 0.

Tiled stream

A “*bi-infinite*” sequence of values $t : \mathbb{Z} \rightarrow A$ with
an additional *synchronization length* $d(t) \in \mathbb{N}$.

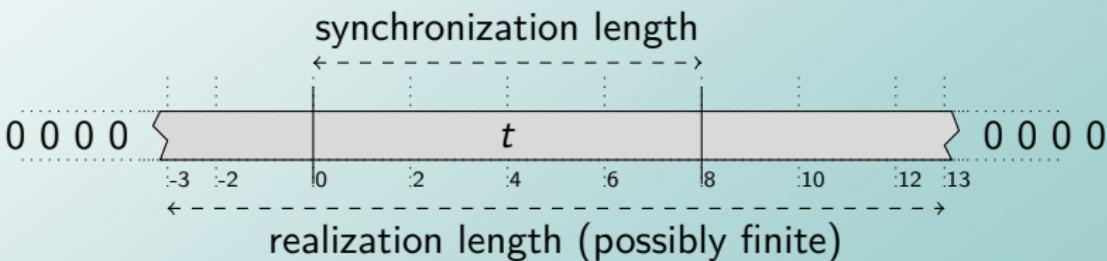


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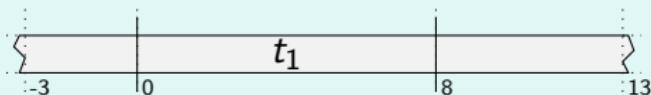


Tiled stream product: the “free” case

Tiled stream product

Two tiled stream $t_1 : \mathbb{Z} \rightarrow A$ and $t_2 : \mathbb{Z} \rightarrow B$ and their product $t_1; t_2 : \mathbb{Z} \rightarrow A \times B$ defined, for every $k \in \mathbb{Z}$, by

$$(t_1; t_2)(k) = (t_1(k), t_2(k - d(t_1)))$$



with resulting synchronization length

$$d(t_1; t_2) = d(t_1) + d(t_2)$$

Tiled stream product: the parameterized case

Let $op : A \times B \rightarrow C$

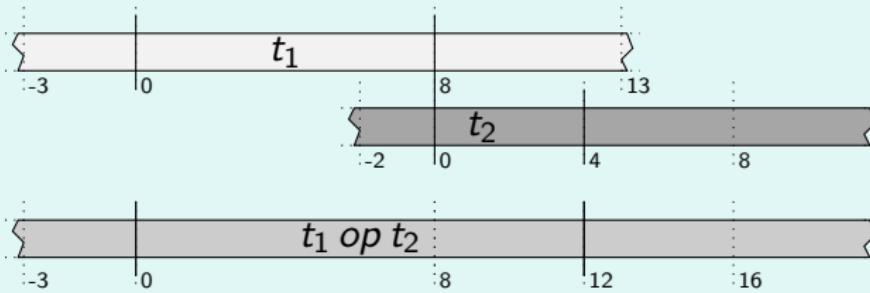
Operator lifting

Two tiled streams $t_1 : \mathbb{Z} \rightarrow A$ and $t_2 : \mathbb{Z} \rightarrow B$ let $t_1 op t_2 : \mathbb{Z} \rightarrow C$ defined by $d(t_1 op t_2) = d(t_1) + d(t_2)$ and

$$(t_1 op t_2)(k) = t_1(k) op t_2(k - d(t_1))$$

for every $k \in \mathbb{Z}$.

Synchronization + Fusion : $t_1 op t_2$



Tiled stream product: the parameterized case

Let $op : A \times B \rightarrow C$

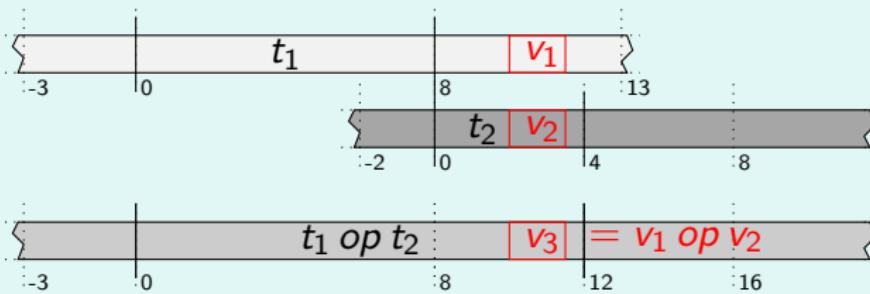
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Synchronization + Fusion : $t_1 op t_2$



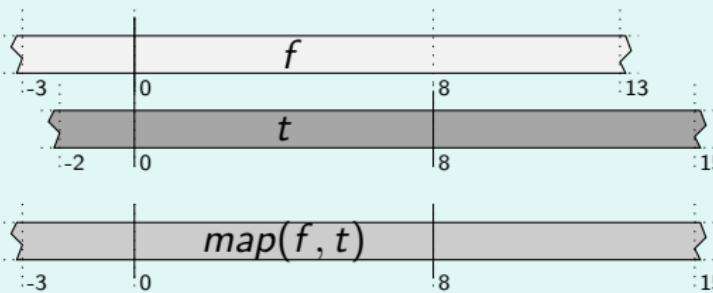
Tiled stream product: the “map” example

Let $\text{map} : (A \rightarrow B) \times A \rightarrow B$ defined by $\text{map}(x, y) = x(y)$

Tiled map

Two tiled streams $f : \mathbb{Z} \rightarrow (A \rightarrow B)$ and $t : \mathbb{Z} \rightarrow A$ with $d(f) = 0$ consider $\text{map}(f, t) : \mathbb{Z} \rightarrow B$.

$\text{map}(f, t)$



3. Re-synchronization

Reset and co-reset for resynchronization

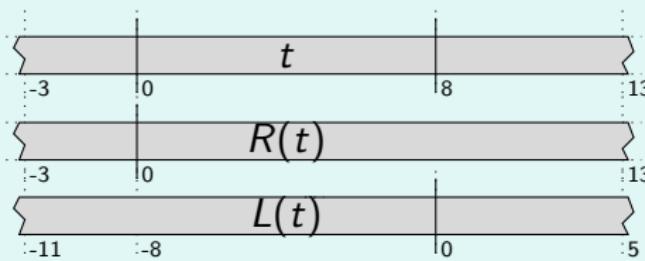
Natural operators: resynchronization

Left and right resynchronization

A tiled stream $t : \mathbb{Z} \rightarrow A$, the synchronization reset $R(t)$ and the synchronization co-reset $L(t)$ of the tiled stream t defined, for every $k \in \mathbb{Z}$, by

$$R(t)(k) = t(k) \text{ and } L(t)(k) = t(k - d(t))$$

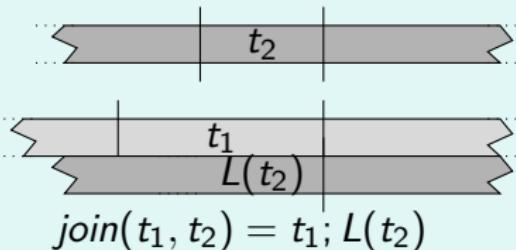
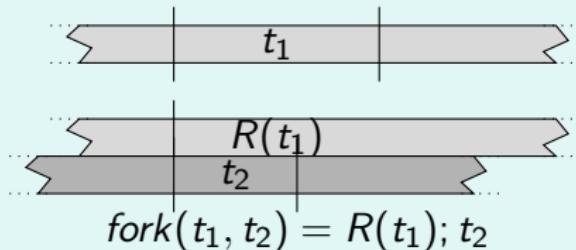
with synchronization length $d(R(t)) = d(L(t)) = 0$.



Derived operators: fork and join

Parallel fork and join

Tiled product and resets allows for defining parallel products:



with synchronization length $d(fork(t_1, t_2)) = d(t_2)$ and $d(join(t_1, t_2)) = d(t_1)$.

4. Embeddings

Links with Hudak's *Polymorphic Temporal Media* [3] and
 ω -semigroups [4]

Embedding strings and concatenation

Finite strings and concatenation

Two A -strings $u : [0, d_u[\rightarrow A$ and $v : [0, d_v[\rightarrow A$ and their concatenation

$$u \cdot v : [0, d_u + d_v[\rightarrow A$$

defined by

$$u \cdot v(k) = \begin{cases} u(k) & \text{when } 0 \leq k < d_u, \\ v(k - d_u) & \text{when } d_u \leq k < d_u + d_v. \end{cases}$$

$$\varphi : \textit{strings} \rightarrow \textit{tiledStreams}$$

String embedding: $\varphi(u) \cdot \varphi(v) = \textit{sum}(\varphi(u); \varphi(v))$

$$\textit{sum} \left(\begin{array}{c|c|c|c} 0 & 0 & 0 & \\ \hline & \varphi(u) & & \\ \hline & 0 & 0 & 0 \\ \hline & & \varphi(v) & \\ \hline & & 0 & 0 & 0 \end{array} \right)$$

Embedding streams and parallel streams

Infinite streams and zip

Two A -streams $u : [0, +\infty[\rightarrow A$ and $v : [0, +\infty[\rightarrow B$ and their zip

$$u|v : [0, +\infty[\rightarrow A \times B$$

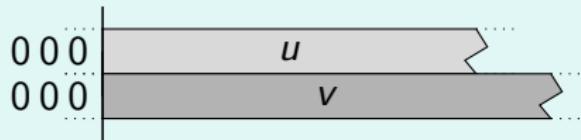
defined by

$$u|v(k) = (u(k), v(k))$$

for every $0 \leq k$.

$$\psi : \text{streams} \rightarrow \text{tiledStreams}$$

Streams embedding : $\psi(u)|\psi(v) = \psi(u); \psi(v)$



Embedding strings and streams with mixed product

Mixed product

An A -string $u : [0, d_u[\rightarrow A$ and an A -stream $v : [0, +\infty[\rightarrow A$ and their mixed product

$$u :: v : [0, +\infty[\rightarrow A$$

defined by

$$u :: v(k) = \begin{cases} u(k) & \text{when } 0 \leq k < d_u \\ v(k - d_u) & \text{when } d_u \leq k \end{cases}$$

for every $0 \leq k$.

Mixed embedding: $\varphi(u) :: \psi(v) = R(sum(\varphi(u); \psi(v)))$

$$R \left(sum \left(\begin{array}{c|c|c} 0 & u & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 0 \end{array} \right) \right)$$

5. T-calculus

A syntax for the tiled algebra and some type systems

Syntax

$p ::=$	<i>– primitive constructs –</i>
c	(constant)
x	(variable)
f(p_1, p_2, \dots, p_n)	(function lifting)
x = p_1	(declaration)
R(p_1)	(sync. reset)
L(p_1)	(sync. co-reset)
	<i>– derived constructs –</i>
$p_1 \text{ op } p_2$	(operator)
$p_1 ; p_2$	(synchronization product)

Example

Assume A with operator $+$ with neutral element 0.

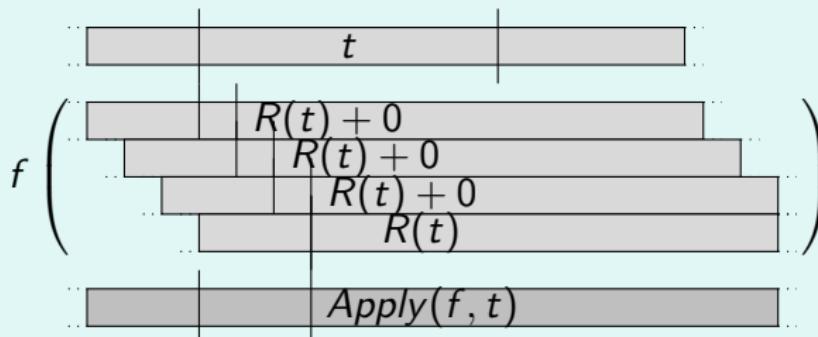
Sound processing

A sound processing function $f : A^n \rightarrow A$ on sliding windows of length $n \geq 1$. The constant A -tiled stream 0 with $d(0) = 1$.

$$Apply(f, t) = f\left(\underbrace{(R(t) + 0; R(t) + 0; \dots; R(t) + 0; R(t))}_{n \text{ times}}\right)$$

for an arbitrary tiled stream t with $d(p) = n - 1$.

In picture with $n = 4$



Semantics (principle)

The semantic mapping

An environment \mathcal{E} that maps variables to tiled streams.

An program interpretation $\llbracket p \rrbracket_{\mathcal{E}}$ in a tiled stream is sound when it satisfies the inductive rules (next slide) and the fixpoint rule:

(Y) *For every x occurring in p we have $\mathcal{E}(x) = \llbracket p_x \rrbracket_{\mathcal{E}}$.*

with p_x the unique definition of x in p .

Canonical fixpoint semantics (a little adhoc)

Start with silent interpretation (i.e. 0) for every variable and iterate semantics rules till a fixpoint is reach.

Semantics (inductive rules)

- ▷ Const.: $d(\llbracket c \rrbracket_{\mathcal{E}}) = 0$ and $\llbracket c \rrbracket_{\mathcal{E}}(k) = \begin{cases} c & \text{when } k = 0, \\ 0 & \text{when } k \neq 0, \end{cases}$
- ▷ Variable: $\llbracket x \rrbracket_{\mathcal{E}}(k) = \mathcal{E}(x)(k)$,
- ▷ Mapping: $d(\llbracket f(p_1, \dots, p_n) \rrbracket_{\mathcal{E}}) = \sum_{i \in [1, n]} d(\llbracket p_i \rrbracket_{\mathcal{E}})$
and $\llbracket f(p_1, \dots, p_n) \rrbracket_{\mathcal{E}}(k) = f(v_1, \dots, v_n)$
with $v_i = \llbracket p_i \rrbracket_{\mathcal{E}} \left(k - \sum_{1 \leq j < i} d(\llbracket p_j \rrbracket_{\mathcal{E}}) \right)$,
- ▷ Decl.: $d(\llbracket x = p_x \rrbracket_{\mathcal{E}}) = d(\llbracket p_x \rrbracket_{\mathcal{E}})$ and
 $\llbracket x = p_x \rrbracket_{\mathcal{E}}(k) = \llbracket p_x \rrbracket_{\mathcal{E}}(k)$,
- ▷ Reset: $d(\llbracket R(p_1) \rrbracket_{\mathcal{E}}) = 0$ and $\llbracket R(p_1) \rrbracket_{\mathcal{E}}(k) = \llbracket p_1 \rrbracket_{\mathcal{E}}(k)$,
- ▷ Co-res.: $d(\llbracket L(p_1) \rrbracket_{\mathcal{E}}) = 0$ and
 $\llbracket L(p_1) \rrbracket_{\mathcal{E}}(k) = \llbracket p_1 \rrbracket_{\mathcal{E}}(k + d(\llbracket p_1 \rrbracket_{\mathcal{E}}))$

Typing I : basic types and sync. length inference

▷ Constants:

$$\frac{}{\Gamma \vdash c : (1, \alpha_c)}$$

▷ Variables:

$$\frac{(x, (d, \alpha)) \in \Gamma}{\Gamma \vdash x : (d, \alpha)}$$

▷ Mapping:

$$\frac{\Gamma \vdash p_i : (d_i, \alpha_i) \quad (i \in [1, n])}{\Gamma \vdash f(p_1, \dots, p_n) : (d_1 + \dots + d_n, \alpha)}$$

with $f : \alpha_1 \times \alpha_2 \times \dots \times \alpha_n \rightarrow \alpha$

▷ Declaration:

$$\frac{\Gamma \vdash x : (d, \alpha) \quad \Gamma \vdash p : (d, \alpha)}{\Gamma \vdash x = p : (d, \alpha)}$$

▷ Sync. reset:

$$\frac{\Gamma \vdash p : (d, \alpha)}{\Gamma \vdash R(p) : (0, \alpha)}$$

▷ Sync. co-reset:

$$\frac{\Gamma \vdash p : (d, \alpha)}{\Gamma \vdash L(p) : (0, \alpha)}$$

Typing II: Synchronization profile

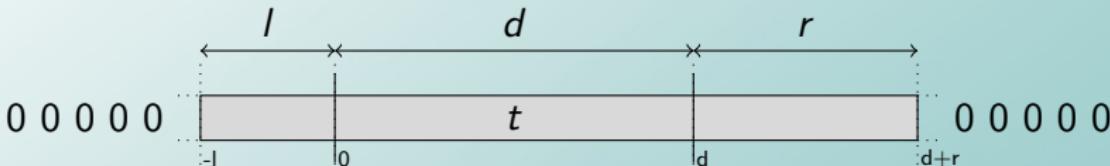
Sync. profile definition

A tiled stream $t : \mathbb{Z} \rightarrow A$.

The triple $(l, d, r) \in \overline{\mathbb{N}} \times \mathbb{N} \times \overline{\mathbb{N}}$ is a *synchronization profile* for t when $d(t) = d$ and for every $k \in \mathbb{Z}$,

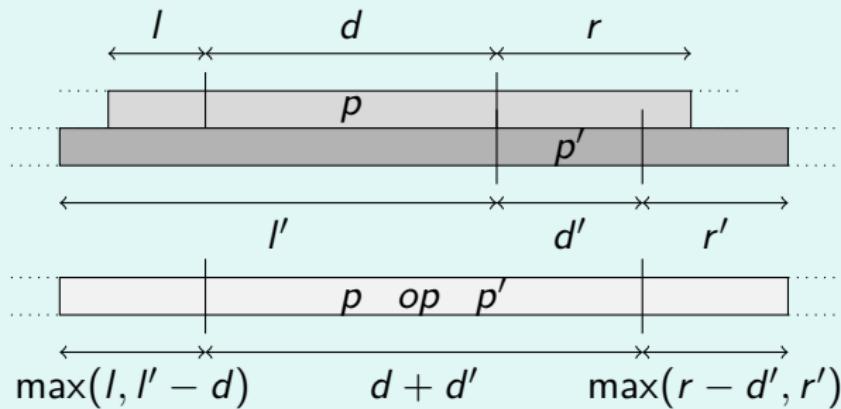
$$\text{if } t(f) \neq 0 \text{ then } -l \leq k \leq d + r$$

with $\overline{\mathbb{N}} = \mathbb{N} + \infty$ and $x + \infty = \infty + x = \infty$ for every $x \in \overline{\mathbb{N}}$.



Typing II: Induced monoid

Remark: *op*-product of two tiled streams



Lemma

The set $\overline{\mathbb{N}} \times \mathbb{N} \times \overline{\mathbb{N}}$ with product

$$(l, d, r) \cdot (l', d', r') = (\max(l, l' - d), d + d', \max(r - d', r'))$$

is related with the free inverse monoid with one generator [5, 6] with neutral element $(0, 0, 0)$.

Typing II: Synchronization profile rules

▷ Constants:

$$\frac{\Delta \vdash c : (0, 1, 0)}{(x, (l, d, r)) \in \Delta}$$

$$\frac{}{\Delta \vdash x : (l, d, r)}$$

▷ Variables:

$$\frac{\Delta \vdash p_i : (l_i, d_i, r_i) \quad (i \in [1, n])}{\Delta \vdash f(p_1, \dots, p_n) : (l, d, r)}$$

with $l = \max(l_i - \sum_{1 \leq j < i} d_j)$, $d = \sum_i d_i$,

and $r = \max(r_i - \sum_{i < j \leq n} d_j)$,

▷ Declaration:

$$\frac{\Delta \vdash x : (l, d, r) \quad \Delta \vdash p : (l, d, r)}{\Delta \vdash x = p : (l, d, r)}$$

▷ Sync. reset:

$$\frac{\Delta \vdash p : (l, d, r)}{\Delta \vdash R(p) : (l, 0, d + r)}$$

▷ Sync. co-reset:

$$\frac{\Delta \vdash p : (l, d, r)}{\Delta \vdash L(p) : (l + d, 0, r)}$$

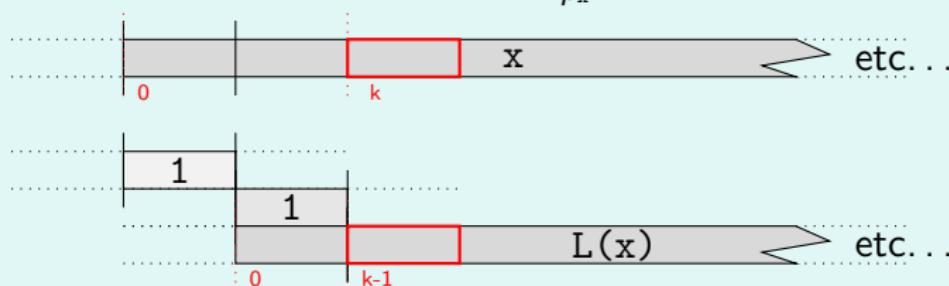
6. Transducers

When computing is easy

Operational semantics: example

Example

A program p defined by $x = \underbrace{1 + R(1 + L(x))}_{p_x}$



with x indices marked in red. And, for every $k \in \mathbb{Z}$, we have:

$$\llbracket p_x \rrbracket_{\mathcal{E}}(k) = 1 + \llbracket x \rrbracket_{\mathcal{E}}(k+1) \text{ and } \delta(p_x, x) = \{-1\}.$$

Remark

Iterative semantics is thus uniquely determined by (1) 0 everywhere in the past and (2) a computation rule compatible with time flow.

Operational semantics: temporal dependencies

Definition

We look for

$$\delta : \text{Program} \times \text{Variables} \rightarrow \text{Offsets}$$

such that, for every program

$$p = t(x_1, x_2, \dots, x_n)$$

there exists a function

$$f_p : \prod \{\alpha_{x_i} : 1 \leq i \leq n, d \in \delta(p, x_i)\} \rightarrow \alpha_p$$

such that, for every “good” valuation \mathcal{E} :

$$[\![p]\!]_{\mathcal{E}}(\textcolor{red}{k}) = f_p(\{[\![x_i]\!]_{\mathcal{E}}(\textcolor{red}{k} + \textcolor{red}{d}) : 1 \leq i \leq n, \textcolor{red}{d} \in \delta(p, x_i)\})$$

for every $k \in \mathbb{Z}$.

Operational semantics: direct temporal dependencies

Direct temporal dependencies rules

- ▷ Constants: $\delta(c, x) = \emptyset$,
- ▷ Variable: $\delta(y, x) = \emptyset$ when x and y are distinct
and $\delta(x, x) = \{0\}$ otherwise,
- ▷ Mapping: $\delta(f(p_1, \dots, p_n), x) =$

$$\bigcup_{1 \leq i \leq n} \left(\delta(p_i, x) - \sum_{1 \leq j < i} d(p_j) \right),$$

- ▷ Declaration: $\delta(y = p_y, x) = \delta(y, x)$,
- ▷ Sync. reset: $\delta(R(p_1), x) = \delta(p_1, x)$,
- ▷ Sync. co-reset: $\delta(L(p_1), x) = \delta(p_1, x) + d(p_1)$.

Operational semantics: iterated temporal dependencies

Definition

For every program p , every variable x that occurs in p , every subprogram q of p , let:

$$\delta^*(q, x) = \delta(q, x) \cup \bigcup_{y \in \mathcal{X}_p} (\delta(q, y) + \delta^*(p_y, x))$$

with $X + Y = \{x + y \in \mathbb{Z} : x \in X, y \in Y\}$.

Theorem

Assume that for every variable x that occurs in p the set $\delta^*(x, x)$ only contained strictly negative values.

Then the program p admits an iterative semantics that is **causal** and with **finite past**.

Moreover, it can be compiled into a **finite state synchronous transducer/mealy machine** [7].

7. Conclusion

Summary

- Programming time with tiled streams,
- The underlying algebra (SEQ, RESET, CO-RESET),
- A type system for causality and effective start,
- A finite state operational semantics (mealy machine).

Dynamical tilings

Question

Computing sync. length out of RT input via input monitoring ?

Induced conditionals and loops ?

Multi-tempo semantics ?

- Distinguishing active tiled streams, e.g. score follower,
- Passive/reactive tiled streams, e.g. generated tiled streams.

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- [3] P. Hudak, "A sound and complete axiomatization of polymorphic temporal media," Tech. Rep. RR-1259, Department of Computer Science, Yale University, 2008.
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