



# Juniper: A Functional Reactive Programming Language for the Arduino

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# Project Ideas

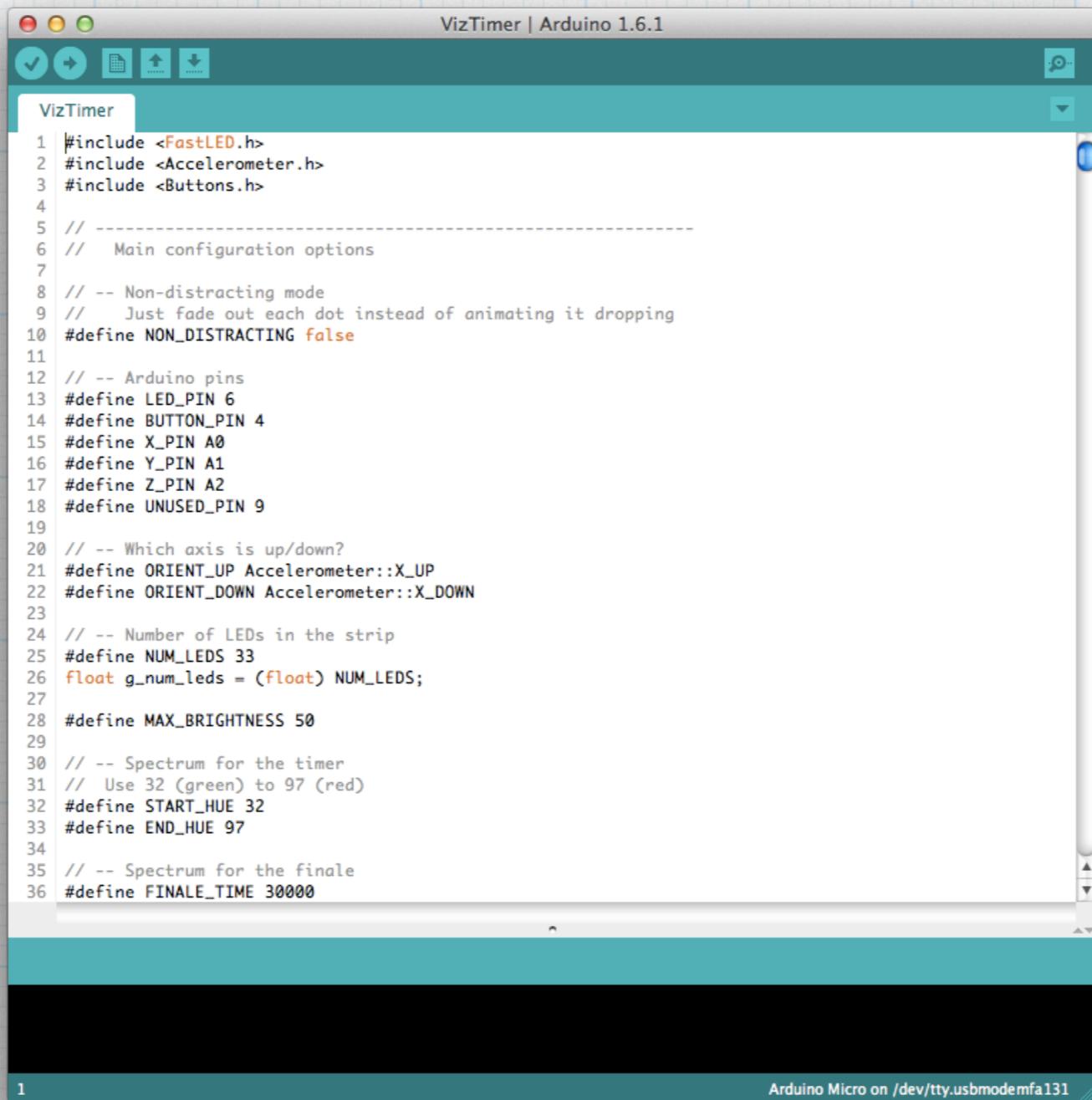


# From the Arduino Web Site

“**Simple, clear** programming environment - The Arduino programming environment is **easy-to-use for beginners**, yet flexible enough for advanced users to take advantage of as well. For teachers, it's conveniently based on the Processing programming environment, so **students learning to program** in that environment will be familiar with the look and feel of Arduino”

Nope

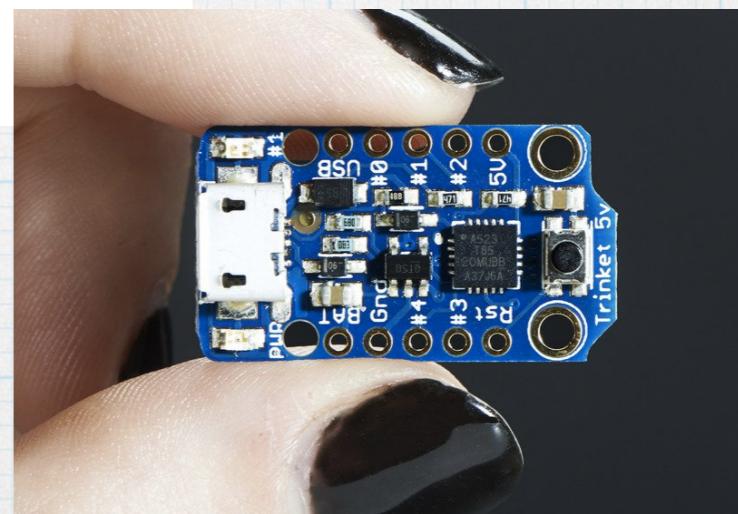
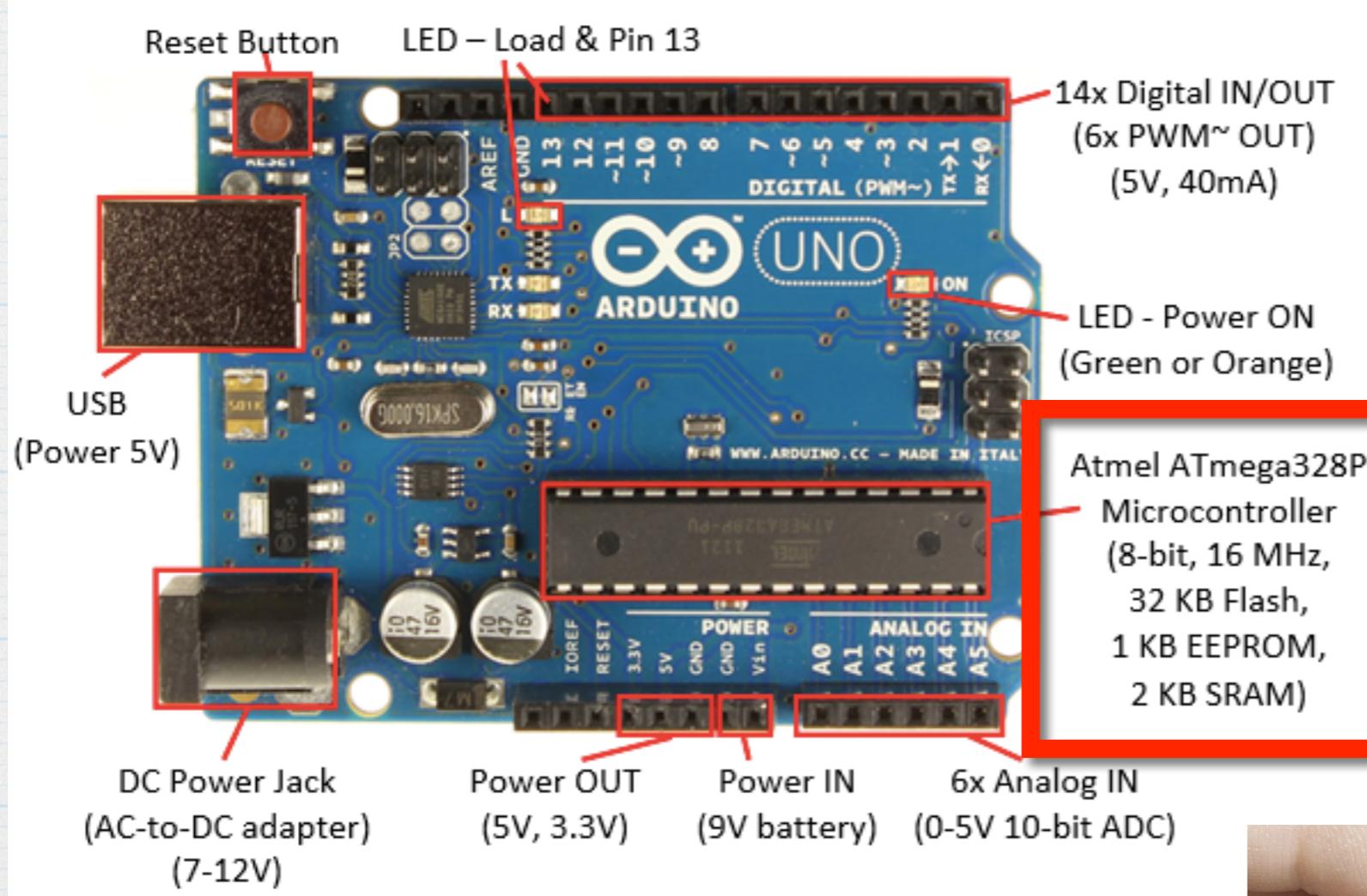
# Surprise! It's C++



The screenshot shows the Arduino IDE interface with the title bar "VizTimer | Arduino 1.6.1". The main window displays the C++ code for the "VizTimer" sketch. The code includes includes for FastLED.h, Accelerometer.h, and Buttons.h. It defines constants for LED\_PIN (6), BUTTON\_PIN (4), X\_PIN (A0), Y\_PIN (A1), Z\_PIN (A2), and UNUSED\_PIN (9). It also defines ORIENT\_UP and ORIENT\_DOWN for the accelerometer. The NUM\_LEDS is set to 33, and g\_num\_leds is a float variable initialized to NUM\_LEDS. MAX\_BRIGHTNESS is defined as 50. The START\_HUE is 32 and the END\_HUE is 97. The FINALE\_TIME is defined as 30000. The code is presented in a monospaced font with line numbers from 1 to 36.

```
1 #include <FastLED.h>
2 #include <Accelerometer.h>
3 #include <Buttons.h>
4
5 // -----
6 // Main configuration options
7
8 // -- Non-distracting mode
9 // Just fade out each dot instead of animating it dropping
10 #define NON_DISTRACTING false
11
12 // -- Arduino pins
13 #define LED_PIN 6
14 #define BUTTON_PIN 4
15 #define X_PIN A0
16 #define Y_PIN A1
17 #define Z_PIN A2
18 #define UNUSED_PIN 9
19
20 // -- Which axis is up/down?
21 #define ORIENT_UP Accelerometer::X_UP
22 #define ORIENT_DOWN Accelerometer::X_DOWN
23
24 // -- Number of LEDs in the strip
25 #define NUM_LEDS 33
26 float g_num_leds = (float) NUM_LEDS;
27
28 #define MAX_BRIGHTNESS 50
29
30 // -- Spectrum for the timer
31 // Use 32 (green) to 97 (red)
32 #define START_HUE 32
33 #define END_HUE 97
34
35 // -- Spectrum for the finale
36 #define FINALE_TIME 30000
```

*(but it kinda needs to be)*



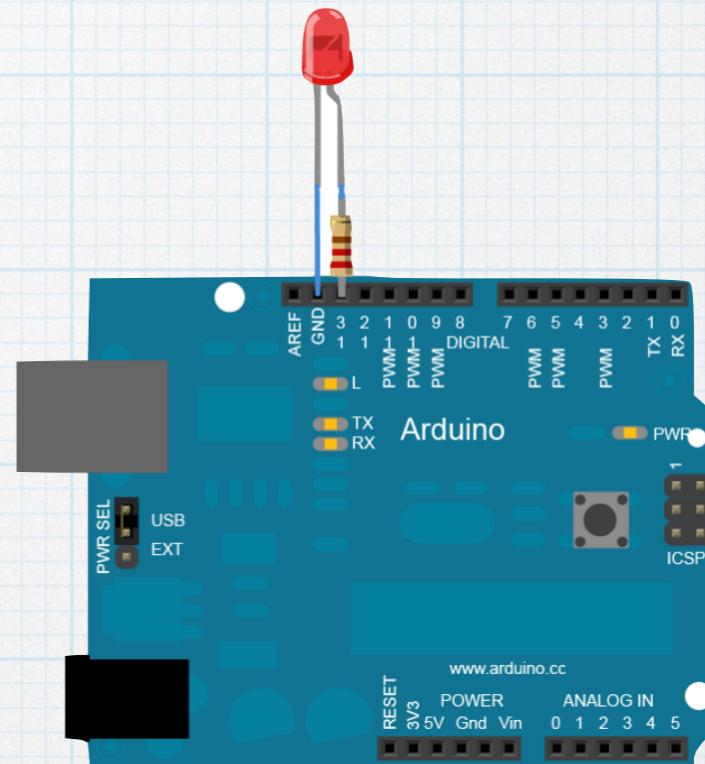
# Hello, blinky world!

```
// -- Attach an LED to pin 13
int led = 13;

// -- The setup routine runs once
void setup() {
    // -- Initialize the pin for output
    pinMode(led, OUTPUT);
}

// -- Loop is called over and over
forever:

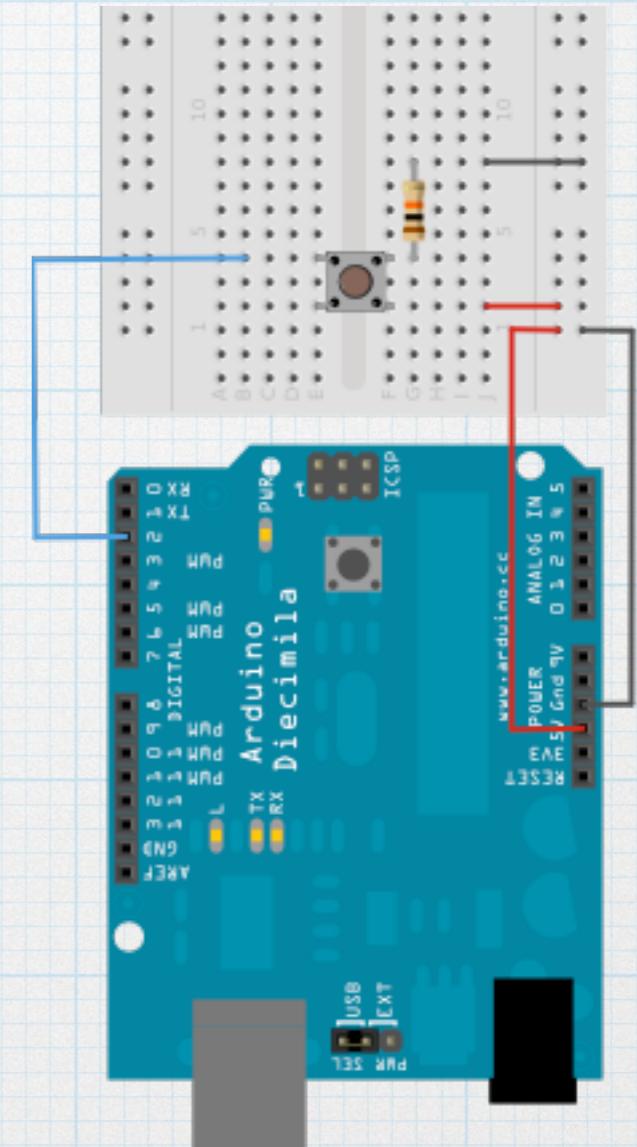
void loop() {
    digitalWrite(led, HIGH);
    delay(1000);
    digitalWrite(led, LOW);
    delay(1000);
}
```



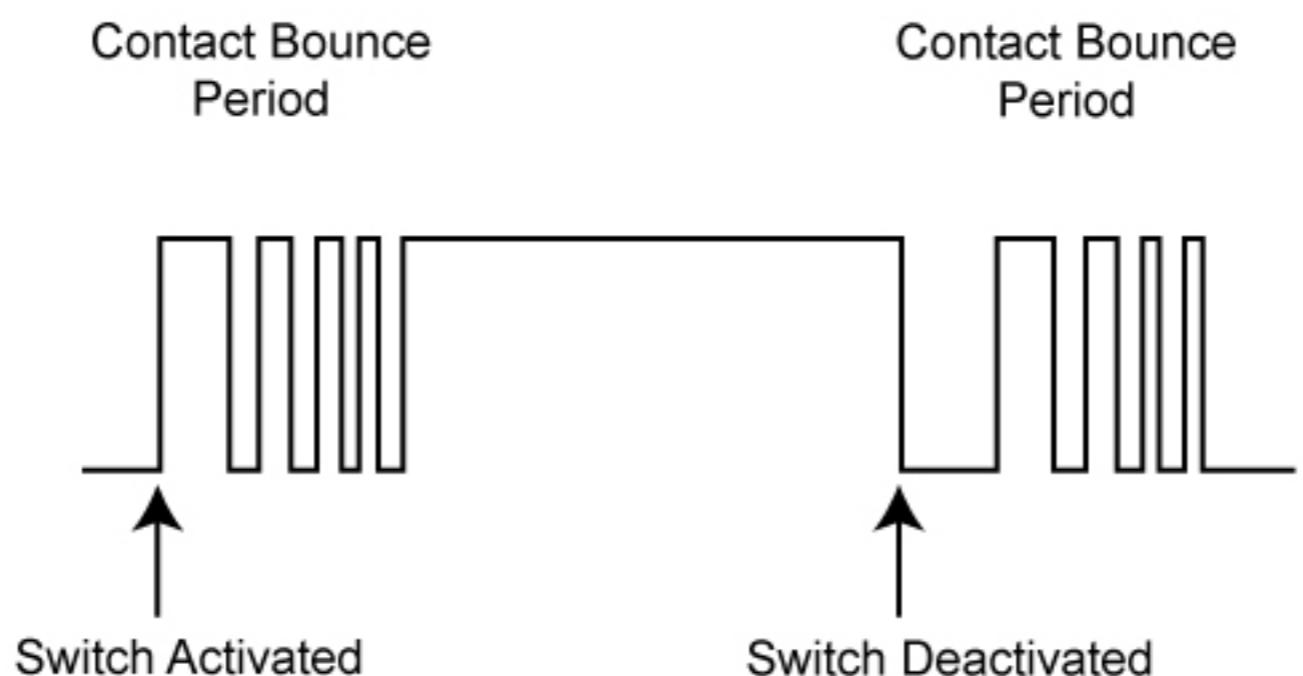
```
void blink(int pin, int interval)
{
    digitalWrite(pin, HIGH);
    delay(interval);
    digitalWrite(pin, LOW);
    delay(interval);
}
```

# Add a momentary button

```
int buttonPin = 2;  
  
int ledPin = 13;  
  
bool ledOn = false;  
  
  
void loop(){  
    // -- Look for press  
    if (digitalRead(buttonPin) == HIGH) {  
        // -- Wait for button release  
        while (digitalRead(buttonPin) != LOW) { }  
        // -- Toggle LED on or off  
        if ( ! ledOn) {  
            digitalWrite(ledPin, HIGH);  
            ledOn = true;  
        } else {  
            digitalWrite(ledPin, LOW);  
            ledOn = false;  
        }  
    }  
}
```



# Signal bounce



```
bool isPressed(int pin)
{
    // -- Look for press
    if (digitalRead(pin) == HIGH) {
        // -- Wait 50ms
        delay(50);

        // -- Still pressed? OK, continue
        if (digitalRead(pin) == HIGH) {
            // Wait for the release
            while (digitalRead(pin) != LOW)
                return true;
        }
    }
    return false;
}
```

Challenge: button  
turns blinking led  
on and off



Debounce

```
void loop()
{
    if (isPressed(buttonPin)) {
        if ( ! ledOn) {
            digitalWrite(ledPin, HIGH);
            ledOn = true;
        } else {
            digitalWrite(ledPin, LOW);
            ledOn = false;
        }
    }
}
```

```
void blink(int pin, int interval)
{
    digitalWrite(pin, HIGH);
    delay(interval);
    digitalWrite(pin, LOW);
    delay(interval);
}

void loop()
{
    if (isPressed(buttonPin)) {
        if ( ! ledOn) {
            ledOn = true;
        } else {
            ledOn = false;
        }
    }
    if (ledOn) {
        blink(13, 1000);
    }
}
```

Does this work?

Stuck waiting  
for button release

Stuck here for  
2 seconds!

*This doesn't work*

```
void blink(int pin,
           int interval)
{
    digitalWrite(pin, HIGH);
    delay(interval);
    digitalWrite(pin, LOW);
    delay(interval);
}

void loop()
{
    blink(13, 1000);
    blink(9, 300);
}
```

Even simpler:  
blink two lights  
at different intervals

```
uint32_t last_time_2 = 0;
bool led_state_2 = false;

void loop()
{
    uint32_t curtime = millis();

    if (curtime - last_time_1 > 1000) {
        last_time_1 = curtime;
        if (led_state_1)
            digitalWrite(13, LOW);
        else
            digitalWrite(13, HIGH);
        led_state_1 = ! led_state_1;
    }

    if (curtime - last_time_2 > 300) {
        last_time_2 = curtime;
        if (led_state_2)
            digitalWrite(9, LOW);
        else
            digitalWrite(9, HIGH);
```

Functions that use `delay()`  
do not compose

Combining concurrent activities  
requires explicit scheduling

“Blinking” is an ongoing process

Need composition in time

A.k.a., concurrency

Any reasonably sophisticated software application for the Arduino consists of:

ad hoc discrete event scheduler +  
finite state machine(s)

Fairly advanced to implement

## Our Approach

Use Functional Reactive Programming to handle  
events/streams of events

Use the “foldP” (fold over the past) FRP function to simulate  
state machines

# FRP Classification

Juniper is a higher-order discrete impure monadic FRP Language

What this actually means:

Dynamic signal graphs allowed

Signals of signals are allowed

Lose equational reasoning to avoid space leak

No continuous signals

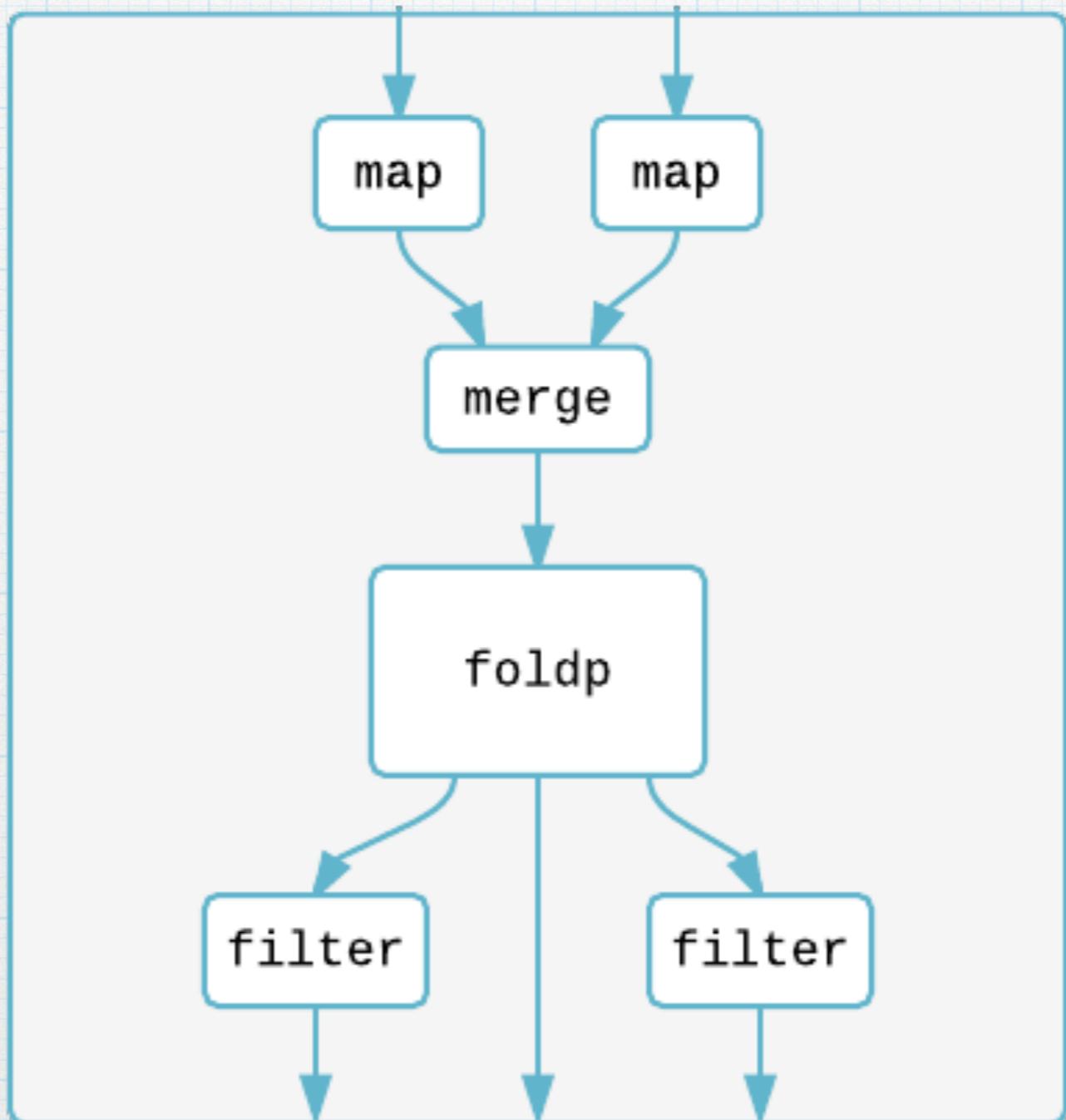
# Language Features

- Algebraic data types
- Parametric polymorphic functions
- Lambdas
- Closures
- Type inference
- Limited dependent typing (size is part of an array type)
- Pattern matching
- Immutable data structures
- Imperative features
- Mutable references
- Inline C++

# Signal Graphs

Events “flow” along signals or signals are time varying values

Signals connected together form a **directed graph**



# Signal graph representation

2 KB RAM → Not enough space to store the data structure itself + necessary runtime components

One possibility: static signal graph known at compile time -  
use adjacency list

Our approach: Signal graph embedded within the call graph

# Signals in Juniper

```
type maybe<'a> = just of 'a  
| nothing
```

```
type sig<'a> = signal of maybe<'a>
```

# Blinking LED in Juniper

```
module Blink
open Prelude, Io, Time

let boardLed = 13
let tState = Time:state()
let ledState = ref low()

fun blink() = ...

fun setup() =
  Io:setPinMode(boardLed, Io:output())

fun main() = (
  setup();
  while true do
    blink()
  end
)
```

# Blinking LED in Juniper

```
module Io  
...  
type pinState = high | low  
...
```

```
fun blink() = (  
    let timerSig = Time:every(1000, tState);  
    let ledSig =  
        Signal:foldP(  
            fn (currentTime, lastState) ->  
                Io:toggle(lastState)  
            end,  
            ledState, timerSig);  
    Io:digOut(boardLed, ledSig)  
)
```

# Compilation

type maybe<'a> = just of 'a | nothing

```
template<typename a>
struct maybe {
    uint8_t tag;
    bool operator==(maybe rhs) {
        if (this->tag != rhs.tag) { return false; }
        switch (this->tag) {
            case 0:
                return this->just == rhs.just;
            case 1:
                return this->nothing == rhs.nothing;
        }
        return false;
    }

    bool operator!=(maybe rhs) { return !(rhs == *this); }
    union {
        a just;
        uint8_t nothing;
    };
};
```

# Compilation

```
while true do  
    ...  
end
```

```
(([&]() -> Prelude::unit {  
    while (true) {  
        ...  
    }  
    return {};  
})());
```

# Case Study: Digital Hourglass

## Rich Set of Behaviors

- Program Mode
  - Timing Mode
    - Pause Mode
    - Finale Mode

C++: 950 lines

(and it required a lot of thought)

Juniper: 350 lines

(and it worked the first time)

# Conclusion

- Juniper is a new FRP language designed to be run on small microcontrollers like the Arduino
- Has many functional programming features
- Compiles to C++
- Shows clear benefits for logic re-use; specifically with time dependent behaviors

Thank you!

<http://www.juniper-lang.org/>

