The problem being solved in this directory is:

$$\ddot{\theta} = -\frac{g}{l}\cos\theta$$

integrating both sides with respect to θ yields:

$$\frac{\dot{\theta}^2}{2} = -\frac{g}{l}\sin\theta + C$$

$$\dot{\theta} = \pm\sqrt{-\frac{2g}{l}\sin\theta + C}$$

$$\implies C = \dot{\theta}_0^2$$

$$\therefore \dot{\theta} = \pm\sqrt{\dot{\theta}_0^2 - \frac{2g}{l}\sin\theta}$$

where $\dot{\theta}_0$ is $\dot{\theta}$ when $\sin \theta = 0$ (therefore $\theta = n\pi$ where $n \in \mathbb{Z}$). t can therefore be computed as:

$$t = \pm \int_{\theta_0}^{\theta_1} \frac{d\theta}{\sqrt{\dot{\theta}_0^2 - \frac{2g}{l}\sin\theta}}.$$

In this repository, the initial conditions are:

$$\theta(t=0) = \dot{\theta}(t=0) = 0.$$

In other words, the pendulum bob starts at the positive x axis with zero velocity and moves solely under the influence of gravity. If we imagine a pendulum subject to these conditions, it becomes clear that theta will range from $-\pi$ (the bob being right on the negative x-axis) to 0. If we wish to determine the period of θ (i.e. the value of χ such that $\theta(t + \chi) = \theta(t) \forall t$), we must set $\theta_0 = 0$, $\theta_1 = -\pi$ and multiply our final result by two (as our result will only reflect how long it takes to go from the positive x axis to the

negative x axis, not how long it will take to make the return trip)

$$\chi = -2 \int_0^{-\pi} \frac{d\theta}{\sqrt{-\frac{2g}{l}\sin\theta}}$$
$$= 2 \int_{-\pi}^0 \frac{d\theta}{\sqrt{-\frac{2g}{l}\sin\theta}}.$$

Above we chose the negative on the \pm sign because otherwise we will get a negative value for t, and we are choosing to keep time positive. It is impossible to solve this integral analytically and use it to express θ in terms of t, therefore we are reduced to using numerical methods to approximate θ . The three numerical methods used in this directory are:

- ode78 from the ODE.jl Julia module.
- Runge-Kutta 4th order method.
- The Newton-Kantorovich method to linearize the problem, and then a Chebyshev spectral method to approximate the solution to the linearized version of the problem.