HW4 - due 6/12 Krister OH Change 6/10

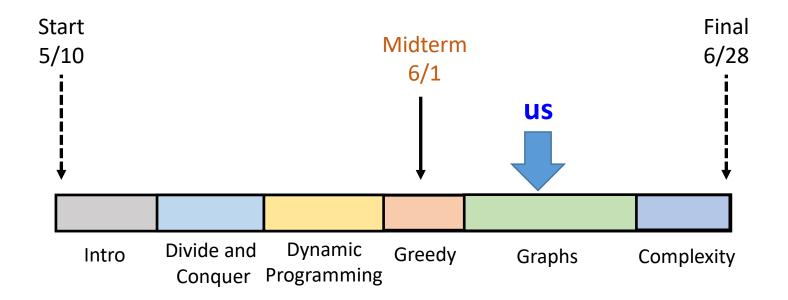
CS3000: Algorithms & Data Drew van der Poel

Lecture 17

- Strongly Connected Components
- Dijkstra's

June 9, 2021

Outline



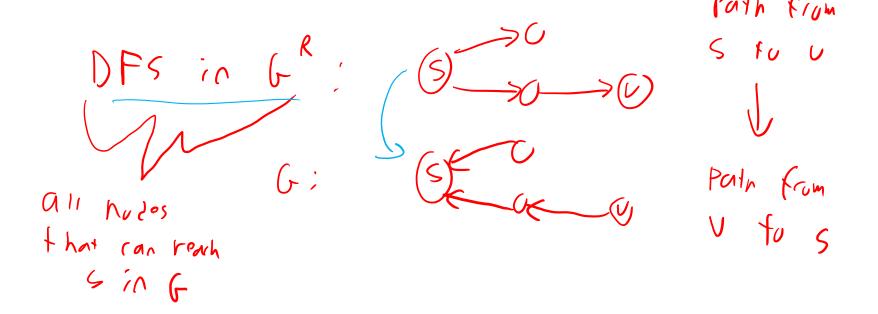
Last class: Graphs: Topological Orderings, Connected Components

Next class: Graphs: Dijkstra's



Strongly Connected Components

- Observation: SCC(s) is all nodes $v \in V$ such that v^{\vee} is reachable from s and vice versa
 - Can find all nodes reachable from s using DFS
 - How do we find all nodes that can reach s?
 - DFS(s) in reverse of the graph!

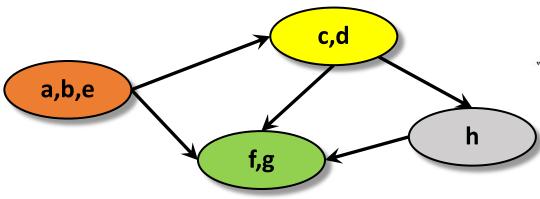


```
SCC-Slow():
   GR = G with all edges "reversed"
   // Initialize an array and counter
   comp[1:n] = \bot, c = 1
   for (u = 1, ..., n) : \leftarrow O(\land)
    // If u has not been explored
 if (comp[u] == \bot):
O(h+n) S = set of nodes found by DFS(G,u) - nodes which
T = set of nodes found by DFS(GR,u) = which

// S N T contains SCC(u)
 Total: O(n(m+n))
   return comp
```

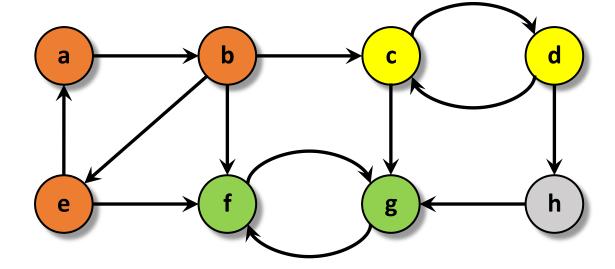
SCCs Form a DAG!

SCC Graph: acyclic





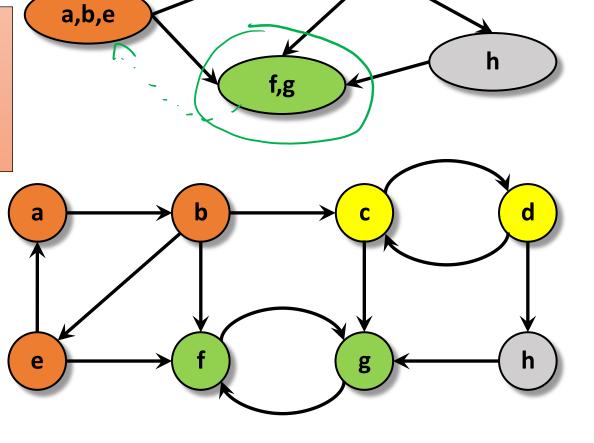
"Before I begin, one of the acronyms I'm going to use is completely made up. See if you can figure out which one."



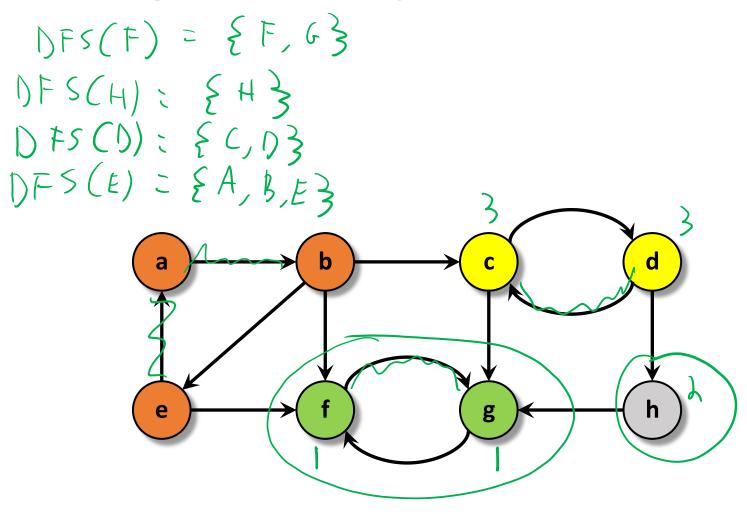
Clever use of DFS for SCC

Sinki Compunent: has out-deg = 0
in SCC Graph

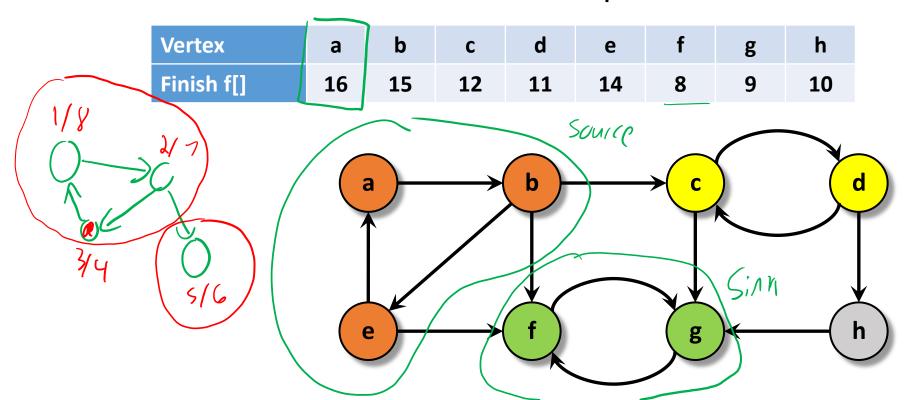
Observation: DFS from any node in a sink component finds that component



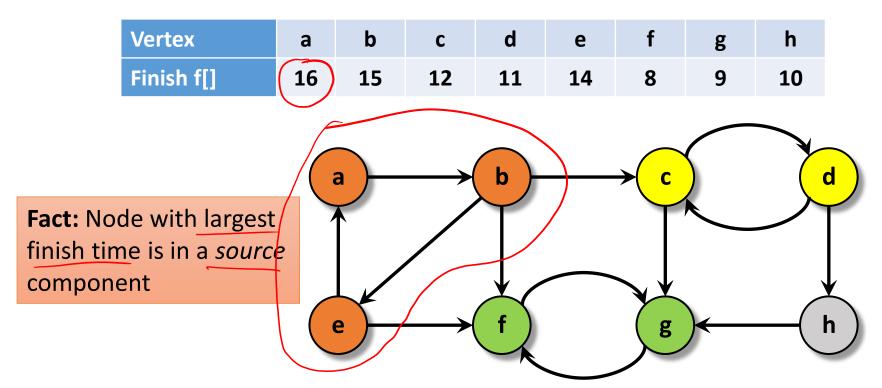
c,d



- Repeat until all nodes marked:
 - Find a node in a sink component of G
 - Run DFS(u) to find SCC of u
 - Mark the nodes in SCC of u so not visited again
- How to find a node in a sink component?

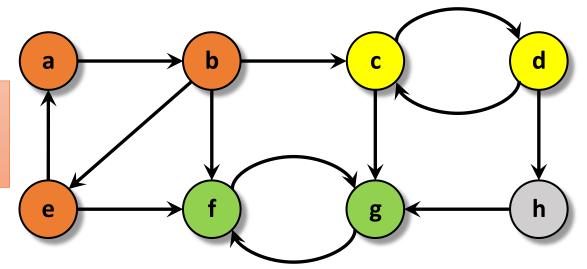


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- Repeat until all nodes marked:
 - Find a node in a sink component of G
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 - Mark the nodes in SCC of u so not visited again
- How to find a node in a sink component?
 - Node with largest finish time in reverse of G!

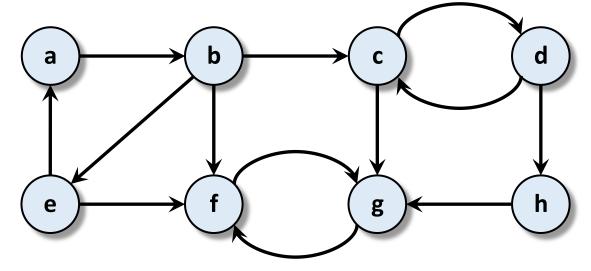
Fact: Node with largest finish time is in a *source* component



Linear-time algorithm for SCC

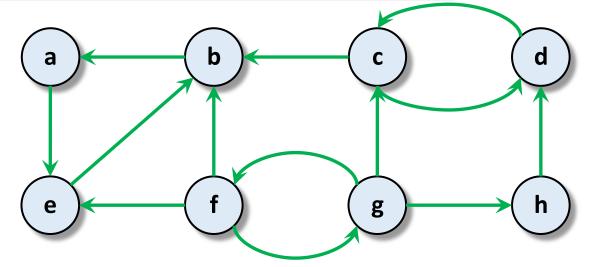
```
SCC(G):
    GR = G with all edges "reversed"

DFS of GR to compute finish times fR
comp[1:n] = \(\perp \), c = 1
for (u in reverse order of fR)
    if (comp[u] == \(\perp \)):
        S = set of nodes found by DFS(u) of G
        for v in S: comp[v] = c
        c = c + 1
return comp
```



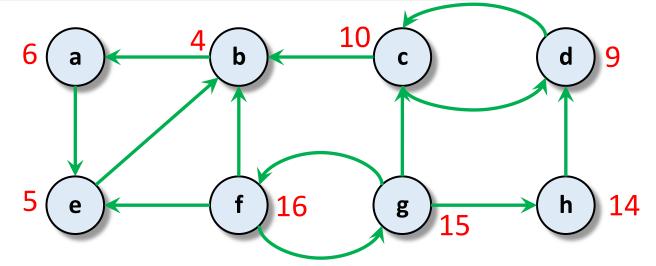
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```
SCC(G):
   GR = G with all edges "reversed"
   DFS of GR to compute finish times fR
   comp[1:n] = \( \triangle \), c = 1
   for (u in reverse order of fR)
    if (comp[u] == \( \triangle \)):
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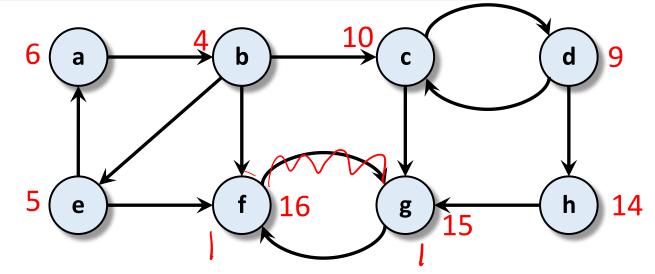
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SCC(G):
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DFS of GR to compute finish times fR
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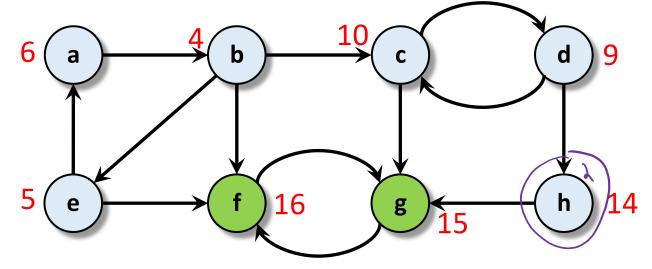
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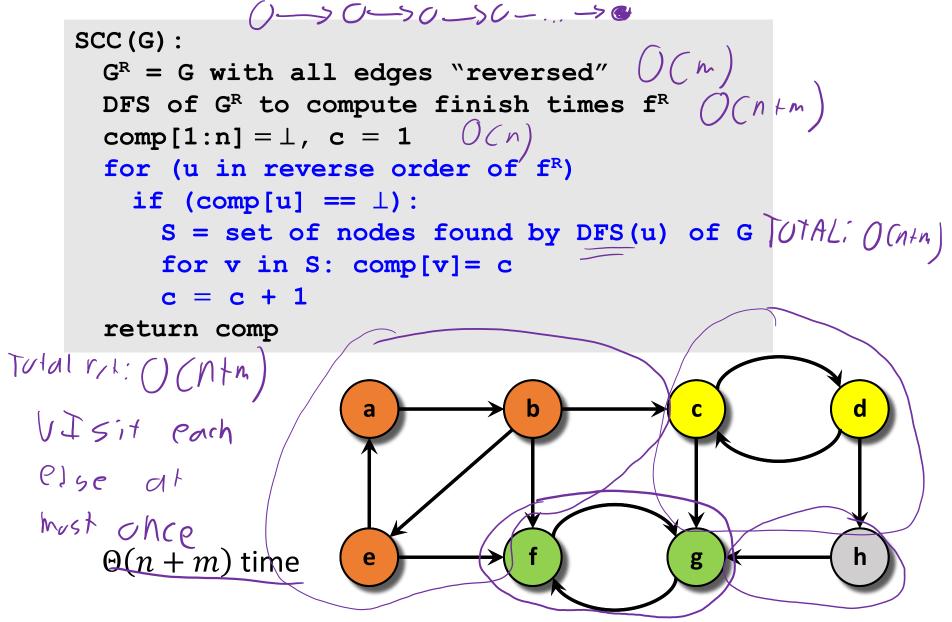


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      for v in S: comp[v] = c
      c = c + 1
  return comp
                 6
                                  16
```



- Problems: counting students, stable matching, sorting, ndigit multiplication, array searching, selection, weighted interval scheduling, segmented least squares, knapsack, prefix-free encoding, graph exploration, bipartiteness, topological sorting, (strongly) connected components
- Alg. techniques: divide & conquer, dynamic programming, greedy

 Analysis: asymptotic analysis, recursion trees, Master Thm., Graph Terminology/representations

 Proof techniques: (strong) induction, contradiction, greedy stays ahead, exchange argument

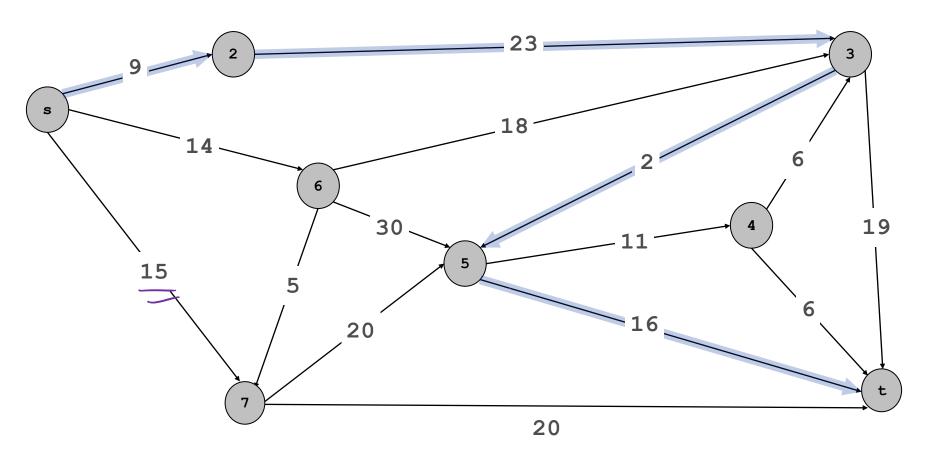
Strongly Connected Components Recap

- **Problem:** Given a directed graph G, split it into strongly connected components
- Input: Directed graph G = (V, E)
- Output: A labeling of the vertices by their strongly connected component
- Punchline: O(n + m) time algorithm for SCCs
 - Clever use of DFS on G and reverse of G
 - Can also compute the meta-graph DAG of SCCs
- Can be directly invoked in other algorithms

Shortest Paths



Weighted Graphs



Weighted Graphs

- **Definition:** A weighted graph $G = (V, E, \{w(e)\})$
 - V is the set of vertices
 - $E \subseteq V \times V$ is the set of edges
 - $w(e) \in \mathbb{R}$ are edge weights
 - Can be directed or undirected

- Today:
 - Directed graphs (one-way streets)
 - Non-negative edge weights $(w(e) \ge 0)$

Shortest Paths

• In weighted graphs, the length of a path $P = v_1 - v_2 - \cdots - v_k$ is the sum of its edge weights:

- The distance d(s,t) is the length of the shortest path from s to t
- Shortest Path: given nodes $s, t \in V$, find the shortest path from s to t
- Single-Source Shortest Paths: given a node $s \in V$, find the shortest paths from s to every $t \in V$
- All-Pairs Shortest Paths: find the shortest path between every $(s,t) \in V$



 Problems: counting students, stable matching, sorting, n-digit multiplication, array searching, selection, weighted interval scheduling, segmented least squares, knapsack, prefix-free encoding, graph exploration, bipartiteness, topological sorting, (strongly) connected components, shortest paths

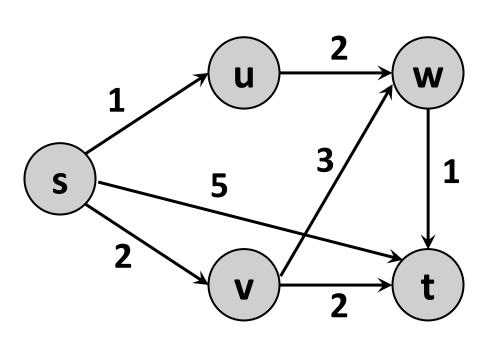
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Distance

- In weighted graphs, the length of a path $P=v_1-v_2-\cdots-v_k$ is the sum of the edge weights:
- The distance d(s,t) is the length of the shortest path from s to t



$$d(s,t) = 4$$

$$e(s-u-w-t) = 4 = 1+\lambda+1$$

$$e(s-t) = 5$$

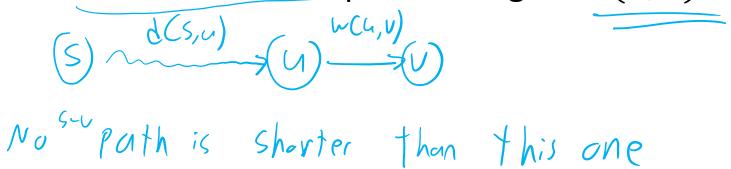
$$e(s-v-t) = 4$$

$$e(s-v-w-t) = 6$$

Structure of Shortest Paths

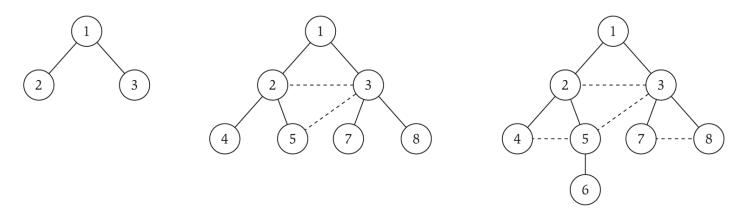
• If $(u,v) \in E$, then $d(s,v) \leq d(s,u) + w(u,v)$ for every node $s \in V$ $\exists a \text{ path from } s \text{ to } v \text{ where } v \text{ the final of length } d(s,u) + w(u,v)$ The shiftst path (ant be any larger than this Λ

• If $(u, v) \in E$, and d(s, v) = d(s, u) + w(u, v) then there is a shortest $s \sim v$ -path ending with (u, v)



Compare to BFS

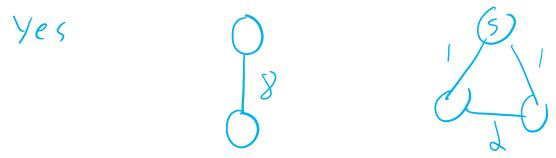
- **Thm.:** BFS finds distances from *s* to other nodes in unweighted graphs
 - L_i contains all nodes at distance i from s
 - Nodes not in any layer are not reachable from s



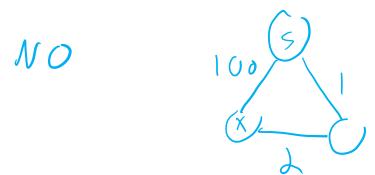
- Question: Does running a BFS from s ever solve the SSSP problem on weighted graphs?
- Question: Does running a BFS from s always solve the SSSP problem on weighted graphs?

Compare to BFS

Question: Does running a BFS from *s* **ever** solve the SSSP problem on weighted graphs?



Question: Does running a BFS from *s* **always** solve the SSSP problem on weighted graphs?

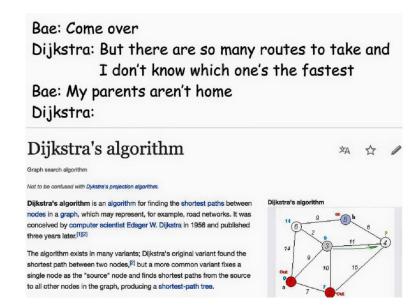


Dijkstra's Algorithm

- Dijkstra's Shortest Path Algorithm is a modification of BFS for non-negatively weighted graphs
- Informal Version:
 - Maintain a set X of explored nodes
 - Maintain an upper bound on distance for all unexplored nodes
 - If u is explored, then we know d(s, u) (from the source s) (Key Invariant)
 - If u is explored, and (u, v) is an edge, then we know $d(s, v) \le (d(s, u) + w(u, v))$
 - Explore the "closest" unexplored node
 - Repeat until we're done

Dijkstra's Algorithm

- Explore the "closest" unexplored node
 - The unexplored node with the smallest upper bound on its distance
 - Tighten (lower) its out-neighbors' upper bounds (when possible)

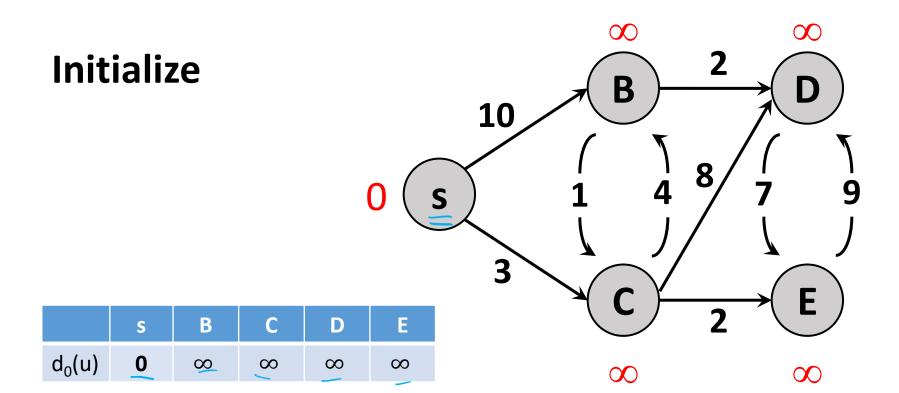




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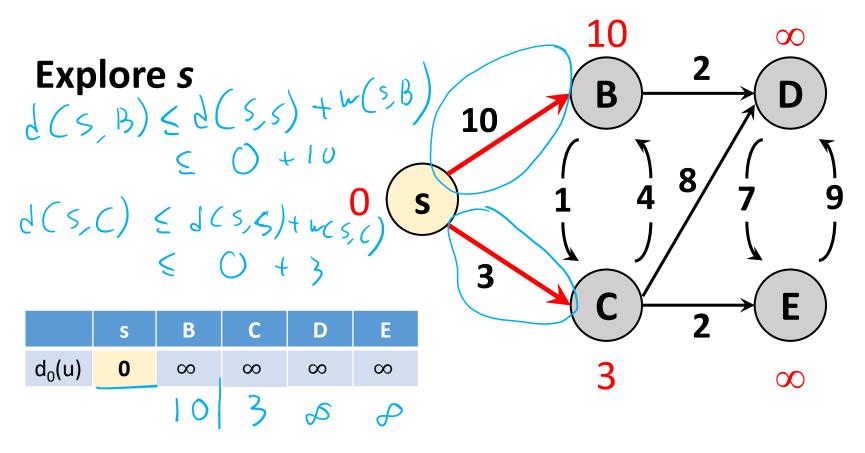
$$X = \{$$



Dijkstra's Algorithm

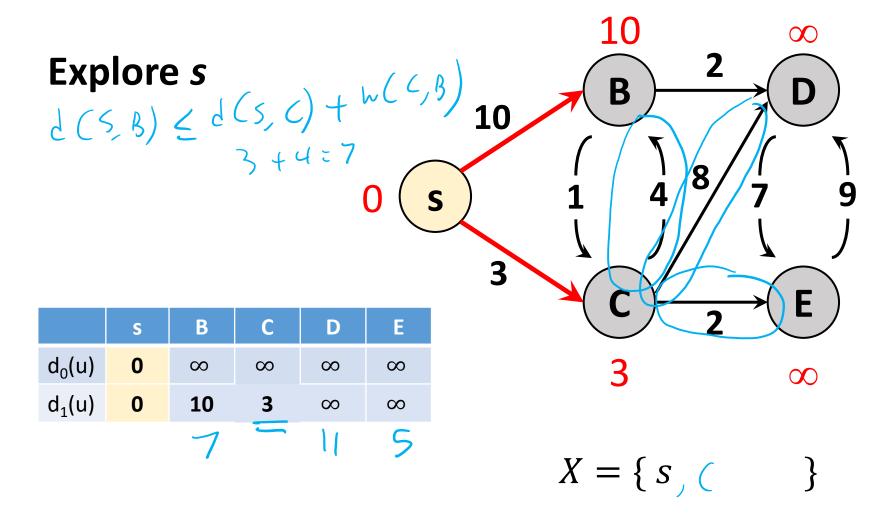
- Explore the "closest" unexplored node
 - The unexplored node with the smallest upper bound on its distance
 - Tighten its out-neighbors' upper bounds (if we can)

| | S | В | С | D | E | | |
|----------|---|----------|----------|----------|----------|--|--|
| $d_0(u)$ | 0 | ∞ | ∞ | ∞ | ∞ | | |
| | | | | | | | |



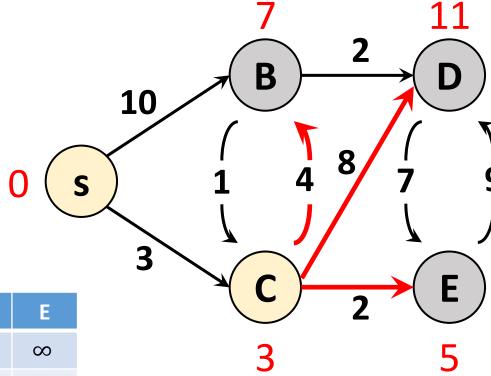
$$X = \{ s, (s) \}$$







Explore C

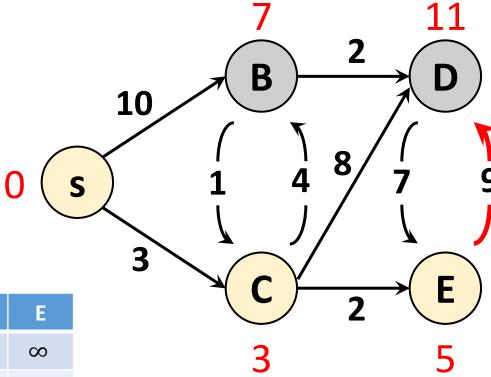


| | S | В | С | D | Е |
|--------------------|---|----------|----------|----------|----------|
| $d_0(u)$ | 0 | ∞ | ∞ | ∞ | ∞ |
| d ₁ (u) | 0 | 10 | 3 | ∞ | ∞ |
| $d_2(u)$ | 0 | 7 | 3 | 11 | 5 |

$$X = \{s, C\}$$



Explore E

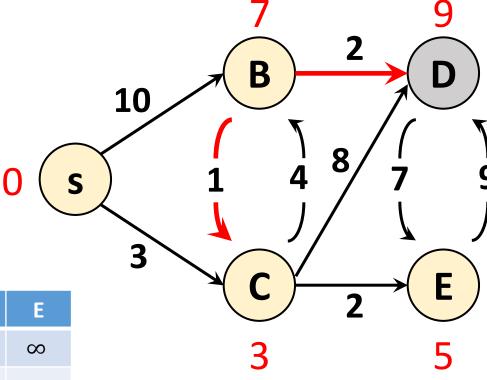


| | S | В | С | D | Е |
|----------|---|----------|----------|----------|----------|
| $d_0(u)$ | 0 | ∞ | ∞ | ∞ | ∞ |
| $d_1(u)$ | 0 | 10 | 3 | ∞ | ∞ |
| $d_2(u)$ | 0 | 7 | 3 | 11 | 5 |
| $d_3(u)$ | 0 | 7 | 3 | 11 | 5 |

$$X = \{s, C, E\}$$



Explore B

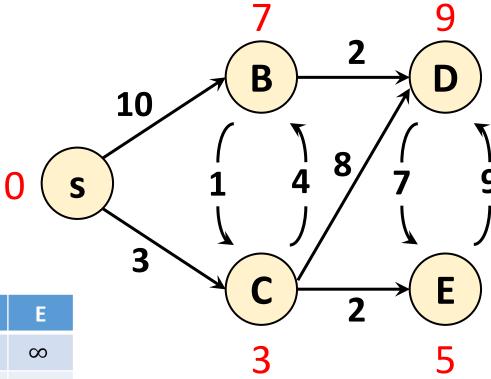


| | S | В | С | D | E |
|--------------------|---|----------|----------|----------|----------|
| $d_0(u)$ | 0 | ∞ | ∞ | ∞ | ∞ |
| d ₁ (u) | 0 | 10 | 3 | ∞ | ∞ |
| $d_2(u)$ | 0 | 7 | 3 | 11 | 5 |
| $d_3(u)$ | 0 | 7 | 3 | 11 | 5 |
| d ₄ (u) | 0 | 7 | 3 | 9 | 5 |

$$X = \{s, C, E, B\}$$



Don't need to explore D

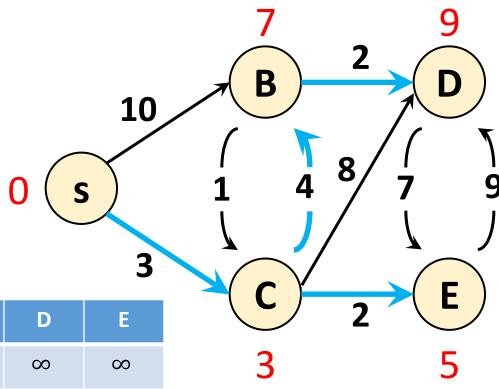


| | S | В | С | D | Ε |
|--------------------|---|----------|----------|----------|----------|
| $d_0(u)$ | 0 | ∞ | ∞ | ∞ | ∞ |
| d ₁ (u) | 0 | 10 | 3 | ∞ | ∞ |
| $d_2(u)$ | 0 | 7 | 3 | 11 | 5 |
| $d_3(u)$ | 0 | 7 | 3 | 11 | 5 |
| d ₄ (u) | 0 | 7 | 3 | 9 | 5 |

$$X = \{s, C, E, B, D\}$$



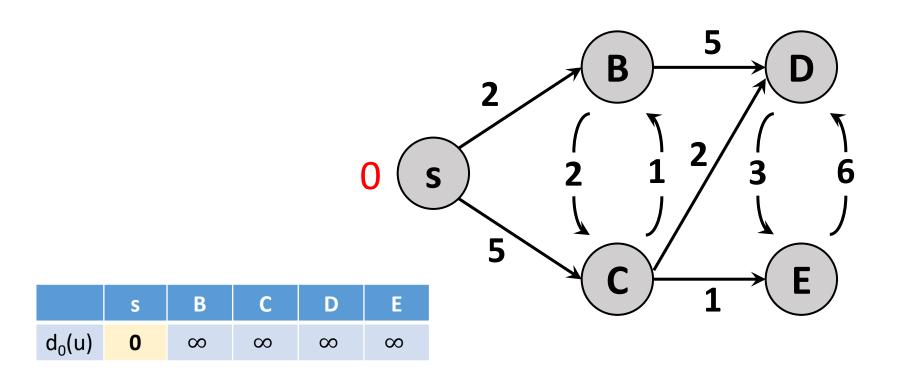
Maintain parent pointers so we can find the shortest paths



| | S | В | С | D | E |
|--------------------|---|----------|----------|----------|----------|
| d ₀ (u) | 0 | ∞ | ∞ | ∞ | ∞ |
| d ₁ (u) | 0 | 10 | 3 | ∞ | ∞ |
| $d_2(u)$ | 0 | 7 | 3 | 11 | 5 |
| $d_3(u)$ | 0 | 7 | 3 | 11 | 5 |
| d ₄ (u) | 0 | 7 | 3 | 9 | 5 |



Dijkstra's Algorithm: Practice



$$X = \{$$

