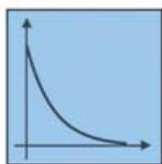


ESE 406/505 & MEAM 513 – 2011-Feb-14 – Quiz – Name: _____

- Choose only one answer for each question by circling the letter.
 - A correct answer is worth 2 points.
 - No answer is worth 0 points.
 - An incorrect answer is worth -1 point. Random guessing will lower your score, on average.
- Which of the following is **MOST CORRECT** concerning the constant, K , we used in our description of the DC motor?
 - K expresses the relationship between the power required to run the motor and the speed of the motor, $P = K\Omega$.
 - K expresses the relationship between the torque generated by the motor and the current flowing in the motor coils, $Q = Ki$.
 - Both of the above.
 - Neither of the above.
 - Which of the following is **NOT** correct concerning time-domain specifications that we discussed in class?
 - Settling time is defined as the time required for the step response to get permanently within 1% of the final value and results in a minimum necessary level of damping.
 - The rise time is the time required for the response to go between 25% and 75% of the final value and results in a minimum necessary DC gain.
 - The peak overshoot is defined as the maximum percentage by which the response exceeds the final value and results in a minimum necessary damping ratio.
 - Which of the following is **NOT** correct concerning the in-class demonstration of DC motor control of a pendulum, constructed using legos?
 - The angular position was measured using a digital encoder.
 - The inverted pendulum (trim at an angle of 180 degrees) was stable even without feedback.
 - The proportional gain acted like a spring in a spring-mass-damper system.
 - The derivative gain acted like a damper in a spring-mass-damper system.
 - Match the transient response shown below to the corresponding letter identifying a pole in the complex plane at right.



- Match the transient response shown below to the corresponding letter identifying a pole in the complex plane at right.

