tfarima: an R package to build customized TFARIMA models

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Abstract

The R package tfarima provides classes and methods to build and use customized Transfer Function and ARIMA models with multiple operators and/or parameter restrictions. Model estimation can be accomplished by exact or conditional maximum likelihood (EML/CML). Procedures for automatic outlier detection, calendar effect estimation, prediction and seasonal adjustment based on this general class of models are also provided. Some classic time series are analyzed to illustrate the usage of the package.

Keywords: ARIMA models, transfer function models, prediction, outliers, R.

1. Introduction

Box and Jenkins (1970) provided a methodology to build a general and flexible class of parsimonious ARIMA and Transfer Function time series models following a three-stages iterative process based on identification, estimation, and diagnostic checking. The fifth edition of the book (Box, Jenkins, Reinsel, and Ljung 2016) includes for first time R code (R Core Team 2018) to replicate many of the applications illustrated along the different chapters of the book. Some of the R packages used in that edition are **stats**, which comes with the base distribution of R, **TSA** (Chan and Ripley 2018), **astsa** (Stoffer 2021) and **MTS** (Tsay, Wood, and Lachmann 2022).

The $\operatorname{arima}()$ function of the stats package enables to fit traditional multiplicative ARIMA $(p,d,q)(P,D,Q)_s$ models to time series with at most two types of serial correlation: regular, dependence between consecutive observations in the series, and seasonal, dependence between observations that are s interval apart. Explanatory and intervention variables such as pulses and steps can be included to predict the output or to handle additive outliers and level shifts. This class of models, sometimes called regARIMA models, is extended by the wrapper $\operatorname{arimax}()$ function of the TSA package to allow for transfer functions (TFs) and innovational outliers. Other R packages with ARIMA modeling capabilities, but oriented to the seasonal adjustment, are the RJDemetra (la Tente, Michalek, Palate, and Baeyens 2021) and seasonal (Sax and Eddelbuettel 2018) packages. TF and ARIMA models can be also estimated in state space form using Kalman filter. Some packages with these capabilities are reviewed by Tusell (2011).

Although the arima() and arimax() functions are useful to analyze and forecast a great variety of time series, sometimes it is needed to formulate ARIMA models taking into account not only the possibility of multiple dependencies between observations in the series, but

also the type and nature of its different unobserved components that can impose of certain restrictions on the parameters. The um() and tfm functions of the tfarima package here presented extend the arima() and arimax() functions in these two directions to allow the estimation of univariate models (UMs) and TF models (TFMs) with multiple AR, I and MA operators, as well as with restrictions on the coefficients of these operators. The tfarima also provides classes to apply the Box-Jenkins three stages procedures when building TF-ARIMA models, which can be estimated by exact or conditional maximum likelihood. The evaluation of the likelihood function is based on the closed form of the inverse covariance matrix following the algorithm of Ljung and Box (1979). Other capabilities of the package are the implementation of the Box, Pierce, and Newbold (1987) method to decompose seasonal time series using the eventual forecast function, which is compared with the Tramo-Seats method used by RJDemetra, as well as the automatic treatment of outliers and calendar effects following the methods of Chen and Liu (1993) and Bell and Hillmer (1983). A recent, and still in progress, addition to the package is the estimation of basic structural time series models (Durbin and Koopman 2001) following a similar approach to that used for ARIMA models, which allows not only a direct comparison of the results obtained by these two class of models but a productive interaction between both. To this end, functions are provided to obtain the ARIMA reduced form of a basic structural time series model and, vice versa, to obtain the structural form of an ARIMA model.

This manual is organized as follows. Section 2 describes the general class of univariate ARIMA models that can be specified with um() function. These models can contain multiple lag polynomials with restricted coefficients that are created with the lagpol() function. Section 3 illustrates the Box-Jenkins methodology to build ARIMA models, as well as its use in forecasting and decomposing time series. Section 4 shows how to build customized seasonal ARIMA models with identical or similar properties to those of seasonal regression, Holt-Winters and structural models. Section 5 describes the general class of TF models and how they can be created and estimated with the tfm() function, which is illustrated with two applications of the Box et al. (2016) book. Section 6 concerns with the estimation of intervention models, the automatic or supervised treatment of outliers and the calendar effects. Finally, some conclusions and future developments are described in Section 7.

2. Univariate models

The general class of ARIMA(p,d,q) models that can be handled with the **tfarima** package is defined by the equation

$$\varphi_p(B)[\delta_d(B)z_t^{(\lambda)} - \mu] = \vartheta_q(B)a_t, \quad t = 1, 2, \dots, n;$$
(1)

where z_t is a time series of length n; $z_t^{(\lambda)}$ is the power Box-Cox transformation $z_t^{(\lambda)} = (z_t^{\lambda} - 1)/\lambda$; $\varphi_p(B)$, $\delta_d(B)$ and $\vartheta_q(B)$ are the AR, I and MA operators, respectively, which are polynomials in the backshift operator B of degree p, d and q; μ is the mean of the transformed time series $\delta_d(B)z_t^{(\lambda)}$, and a_t is a Gaussian white noise process with variance σ_a^2 . Each one of the three operators AR, I and MA can in turn be expressed as the product of several lag polynomials of the form

$$a_d(B^s)^p = (1 - a_1 B^s - \dots - a_d B^{sd})^p,$$
 (2)

which is a polynomial in B^s of degree d, raised to the integer power p, that is, a polynomial of order (d, s, p). Note that, following the Box-Jenkins notation (Box $et\ al.\ 2016$), the polynomial (2) is normalized to $a_d(1) = 1$ and the coefficients (a_1, \ldots, a_d) are preceded by a minus sign. Such coefficients can be expressed as functions of a set of parameters (b_1, \ldots, b_k) :

$$a_j = f_j(b_1, \dots, b_k), \quad j = 1, \dots, d \text{ and } k \le d.$$
 (3)

In this way, the **tarima** package allows us to specify customized ARIMA models with multiple operators and parameter restrictions.

2.1. The lagpol class: lag polynomials

Lag polynomials of order (d, s, p) defined by equations (2)-(3) can be created with the lagpol() function of the **tfarima** package,

where param is a numeric vector of named parameters, coef is a vector of expressions to compute the coefficients of the polynomial as functions of the parameters, s is the power of the backshift operator, p is the power to the which the polynomial is raised and lags is an optional integer vector for unequally spaced polynomials indicating the non-null coefficients.

For example, to create and print the nonseasonal polynomial $(1 - \theta B)^2$ with $\theta = 0.5$, we run the following lines:

R> lp1 <- lagpol(param =
$$c(theta = 0.5)$$
, $p = 2L)$ R> lp1

$$(1 - 0.5B)^2 = 1 - B + 0.25B^2$$

where param = c(theta = 0.5) is a single-parameter vector and p = 2L indicates that this lag polynomial is raised to the power of 2. Here, the default value for coef = NULL is equivalent to coef = "theta". Note that lag polynomials are created following the Box-Jenkins notation. If the notation $(1 + \theta B)^2$ with $\theta = -0.5$ is preferred, the sign of the coefficients must be changed in the coef argument,

R>
$$1p2 \leftarrow 1agpol(param = c(theta = -0.5), p = 2L, coef = "-theta")$$
 R> $1p2$

$$(1 - 0.5B)^2 = 1 - B + 0.25B^2$$

where coef = "-theta" would be the coefficient in $(1 - (-\theta)B)^2$.

The so-called seasonal polynomials are created in a similar way, but using the s argument to indicate the seasonal period. For example, the second-order seasonal polynomial $1 - \Theta_1 B^{12} - \Theta_2 B^{24}$ with $\Theta_1 = 1.2$ and $\Theta_2 = -0.9$ is created as follows:

$$R > 1p3 < -1agpol(param = c(Theta1 = 1.2, Theta2 = -0.9), s = 12)$$

 $R > 1p3$

```
1 - 1.2B^12 + 0.9B^24
```

Customized lag polynomials with restrictions on the coefficients can be created passing to the coeff argument a vector of strings with such restrictions. For example, to create the lag polynomial with three-coefficients and two-parameters $1 - \theta B - \Theta B^{12} + \theta \Theta B^{13}$, with $\theta = 0.8$ and $\Theta = 0.9$, we run the following sentence:

```
R> 1p4 \leftarrow 1agpol(param = c(theta = 0.8, Theta = 0.9),
+ coef = c("theta", "Theta", "-theta*Theta"),
+ 1ags = c(1, 12, 13))
R> 1p4
```

where lags = c(1, 12, 13) contains the positions of the three non-null coefficients.

The lagpol() function returns an S3 object of class lagpol, which is a building block to create ARIMA and TF models. Some useful methods of the lagpol class are roots() and inv().

R> roots(lp4)[c(1:4,10:13),]

```
Real Imaginary Modulus Frequency Period Mult.
[1,]
      1.009 -1.75e-13
                                   0.0000
                          1.01
                                              Inf
[2,]
      1.250 1.10e-13
                          1.25
                                   0.0000
                                              Inf
                                                      1
      0.874 -5.04e-01
                                   0.0833
                                             12.0
[3,]
                          1.01
                                                      1
[4,]
     0.874 5.04e-01
                          1.01
                                   0.0833
                                             12.0
                                                      1
[5,] -0.504 8.74e-01
                          1.01
                                   0.3333
                                             3.0
                                                      1
[6,] -0.874 5.04e-01
                          1.01
                                   0.4167
                                              2.4
                                                      1
[7,] -0.874 -5.04e-01
                          1.01
                                   0.4167
                                              2.4
                                                      1
[8,] -1.009 -7.36e-16
                          1.01
                                   0.5000
                                              2.0
                                                      1
```

```
R > inv(1p4, lag.max = 9)
```

```
[B0] [B1] [B2] [B3] [B4] [B5] [B6] [B7] [B8] [B9] 1.000 0.800 0.640 0.512 0.410 0.328 0.262 0.210 0.168 0.134
```

2.2. The um class: univariate models

Univariate ARIMA models belonging to the class defined by (1) can be created using the um() function,

where z is an object of class ts; bc is a logical value that indicates whether or not to take logs; ar, i and ma are lists of objects of class lagpol, character and/or numeric representing

lag polynomials; mu is a numeric value for the mean of the stationary series $\delta(B)z_t^{(\lambda)}$; sig2 is a numeric value for the variance of the error, and fit is a logical value indicating whether or not to estimate the model. The function returns an object of class um.

To illustrate the usage of this function we create a multiplicative ARIMA model with orders $(0,1,1)(0,1,1)_3(0,1,1)_{12}$,

$$\nabla \nabla_3 \nabla_{12} Z_t = (1 - \theta_1 B)(1 - \theta_2 B^3)(1 - \theta_3 B^{12}) a_t$$

where $\theta_1 = \theta_2 = \theta_3 = 0.8$ and $\sigma_a^2 = 1$. We can set the arguments ar, i and ma providing three types of objects:

1. Lists of objects of class lagpol:

```
R> d1 <- lagpol(coef = 1)
R> d3 <- lagpol(coef = 1, s = 3)
R> d12 <- lagpol(coef = 1, s = 12)
R> ma1 <- lagpol(param = c(th1 = 0.8))
R> ma3 <- lagpol(param = c(th2 = 0.8), s = 3)
R> ma12 <- lagpol(param = c(th3 = 0.8), s = 12)
R> um1 <- um(i = list(d1, d3, d12), ma = list(ma1, ma3, ma12))</pre>
```

In this code chunk, we first create six lagpol objects, one for each operator of the model, and then we pass them as lists to the arguments of the um function. This approach is recommended to create customized models since it provides a way to specify names, preestimates and restrictions for parameters.

2. Character strings with the equations of the polynomials:

```
R> um2 <- um(i = "(1 - B)(1 - B3)(1 - B12)",
+ ma = "(1 - .8B)(1 - .8B3)(1 - .8B12)")
```

Here we provide to each argument i and ma the equations of the operators as character strings. This way of creating a model is more compact than the previous one, but doesn't allow us neither to set the names of the parameters nor create customized models. It is useful to study the statistical properties of common ARMA models (Section 4.1).

3. Lists containing the orders c(d, s = 1, p = 1) of the operators:

```
R> um3 <- um(i = list(1, c(1, 3), c(1, 12)),
+ ma = list(1, c(1, 3), c(1, 12)))
```

In this case, we only provide the orders of each type of operator and the function sets the names and values of the parameters: .1 for AR parameters, .2 for MA parameters and 1 for I coefficients. Hence, ar = list(1, c(1, 3), c(1, 12)) and ma = list(1, c(1, 3), c(1, 12)) are equivalent to ar = "(1 - .1B)(1 - .1B3)(1 - .1B12)" and ma = "(1 - .2B)(1 - .2B3)(1 - .2B12)", whereas i = list(1, c(1, 3), c(1, 12)) is equivalent to i = "(1 - B)(1 - B3)(1 - B12)". This approach is convenient to fit conventional models to time series.

We can combine these three types of objects to set the arguments ar, i and ma:

$$R> um4 < -um(i = list(1, "1 - B3", d12), ma = list("1 - .8B", c(1, 3), ma12))$$

Each list of operators AR, I and MA in a um object, and the corresponding extended polynomials, are stored into the data members ar, i and ma, phi, nabla and theta.

```
R> printLagpolList(um1$i)
```

```
[1] 1 - B [2] 1 - B<sup>3</sup> [3] 1 - B<sup>12</sup>
```

R> printLagpolList(um1\$ma)

R> nabla(um1)

```
1 - B - B<sup>3</sup> + B<sup>4</sup> - B<sup>12</sup> + B<sup>13</sup> + B<sup>15</sup> - B<sup>16</sup>
```

R> theta(um1)

```
1 - 0.8B - 0.8B^3 + 0.64B^4 - 0.8B^12 + 0.64B^13 + 0.64B^15 - 0.51B^16
```

Note that we have created the object um1 without providing a time series, which is useful, for example, to study the statistical properties of a particular model, to simulate data or to fit the same model to several time series. These and other capabilities for objects of class um are explained in the next sections.

3. ARIMA model building

This section illustrates the use of the **tfarima** package to build ARIMA models following the Box-Jenkins three-stage procedure, which requires to be familiar with the characteristics of some representative members of this general class of stochastic processes.

3.1. Statistical properties

We can create an object of class um to study the characteristics of a particular ARMA model in terms of the simple and partial autocorrelation functions (ACF and PACF) and the spectral density function. The following code creates five basic time series models and displays their main functions (see Figure 1):

```
R> ar1p <- um(ar = "(1 - 0.9B)")
R> ar1n <- um(ar = "(1 + 0.9B)")
R> ma1p <- um(ma = "(1 - 0.9B)")
R> ma1n <- um(ma = "(1 + 0.9B)")
R> ar2c <- um(ar = "(1 - 1.52B + 0.8B^2)")
R> display(list(ar1p, ar1n, ma1p, ma1n, ar2c), lag.max = 20)
```

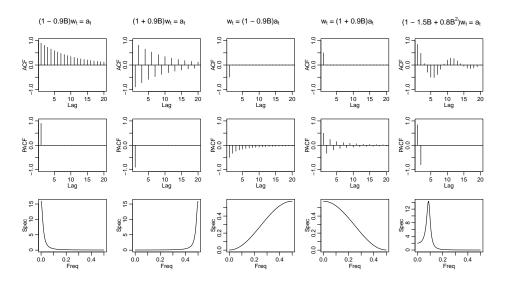


Figure 1: ACF, PACF and spectrum of five UM's.

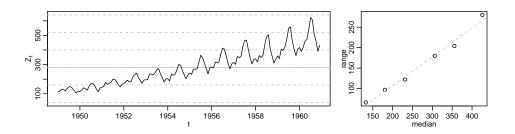


Figure 2: Plot and range-median diagram for the monthly AirPassenger series.

The display() function shows the ACF, PACF and/or spectrum of a list of objects of class um. Other methods of the um class to characterize stochastic processes are pi.weights() and psi.weights(), which show the $AR(\infty)$ and $MA(\infty)$ forms; autocov() and autocorr(), which compute the theoretical autocovariances and (simple/partial) autocorrelations, and roots(), which computes the roots of the different polynomials of the model.

3.2. Model identification

Figure 2 shows the plot and the range-median diagram for the totals of international airline passengers listed as Series G in Box *et al.* (2016). These graphs have been generated with the ide() function of the **tfarima** package:

```
R> Z <- AirPassengers
R> ide(Z, graphs = c("plot", "rm"))
```

where the option rm in the graphs argument means range-median.

The ide() function can also show several graphs for a list of transformations. Figure 3 displays the plot, ACF and PACF for the transformed series: $\log(Z_t)$, $(1+B+\cdots+B^{11})\log(Z_t)$ and $\nabla\nabla_{12}\log(Z_t)$. The transf argument allows us to set a list of lists of transformations such as

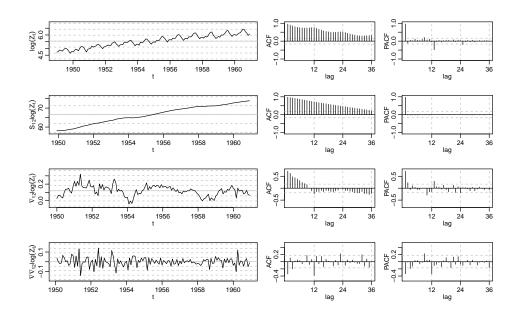


Figure 3: Some identification tools for three data transformations of AirPassengers

the Box-Cox transformation (bc), the number of nonseasonal and seasonal differences (d and D), the annual sum (S) or a list of lagpol objects with the integrated operators (i).

```
R> ide(Z, transf = list(list(bc = T), list(bc = T, S = 1), list(bc = T, D = 1), list(bc = T, D = 1, d = 1))
```

3.3. Model estimation

ARIMA models created with the um function can be estimated by exact or conditional maximum likelihood. We can create and estimate an ARIMA model with the um function by providing a ts object or we can firstly create a um object and then fit to a series with the function fit.

```
R> um1 <- um(AirPassengers, bc = TRUE, i = list(1, c(1, 12)),

+ ma = list(1, c(1, 12)))

R> um2 <- um(i = list(1, c(1, 12)), ma = list(1, c(1, 12)), bc = TRUE)

R> um2 <- fit(um2, AirPassengers)

R> um1
```

Estimate Std. Error theta1 0.4018464 0.07656434 theta2 0.5570393 0.07401700

log likelihood: 244.6965

Residual standard error: 0.03513935

aic: -3.70529

We can compare that these estimatates are very similar to that provided by the arima() function of the stats package

3.4. Model diagnostic checking

Detailed results of the estimation together with diagnostic statistics can be printed with the summary() function:

```
R> summary(um2)
```

```
Model:
```

```
um2 <- um(i = list(1, c(1, 12)), ma = list(1, c(1, 12)), bc = TRUE)
```

 $sigma^2$ estimated as 0.001348: log likelihood = 244.7, aic = -483.4

Time series:

AirPassengers

Maximum likelihood method:

exact

Coefficients:

```
Estimate Gradient Std. Error z Value Pr(>|z|)
theta1 4.018e-01 6.544e-06 7.656e-02 5.248 1.53e-07 ***
theta2 5.570e-01 2.775e-05 7.402e-02 7.526 5.24e-14 ***
---
Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
```

Total nobs	144	Effective nobs	131
log likelihood	244.7	Error variance	0.001348
Mean of residuals	-0.0004231	SD of the residuals	0.03514
z-test for residuals	-0.1445	p-value	0.8851
Ljung-Box Q(1) st.	10.08	p-value	0.001495
Ljung-Box Q(32) st.	47.4	p-value	0.03906
Barlett H(3) stat.	1.138	p-value	0.566
AIC	-3.705	BIC	-3.661

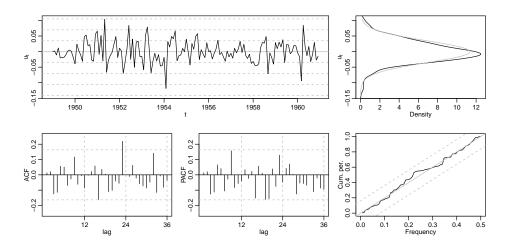


Figure 4: Some diagnostic tools for the residuals of model um1

whose argument is an object of class um. Some diagnostic graphs for this object can be shown with the diagchk() function (see Figure 4):

R> diagchk(um1)

Overfitting is a technique that can be used for diagnostic checking. We can extend our model by adding more AR, I and MA polynomials,

```
R > modify(um1, ar = list(2, c(2, 12)))
```

```
Estimate Std. Error phi1 0.55477214 0.08502302 phi2 0.24975326 0.08322806 phi3 -0.09466045 0.23810134 phi4 -0.03393216 0.14198889 theta1 0.96372038 0.04100168 theta2 0.48331617 0.23071063
```

log likelihood: 246.2311

Residual standard error: 0.03447009

aic: -3.66765

To remove a lag polynomial we indicate its possition with a negative integer. Here we replace the two MA(1) polynomials with two MA(2) polynomials,

```
R> um3 <- modify(um1, ma = list(-1, -2, 2, c(2, 12)))
R> printLagpolList(um3$ma)

[1] 1 - 0.41B - 0.037B^2 [2] 1 - 0.6B^12 + 0.067B^24
```

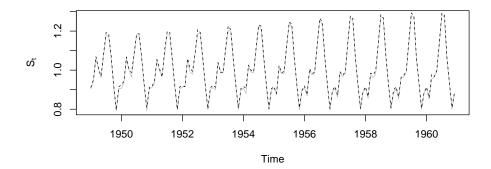


Figure 5: Seasonal components for AirPassengers estimated with **RJDemetra** and **tfarima**.

3.5. Forecasting

Point and interval forecast from a um object can be computed with the predict() function, whose arguments n.ahead and level allow to set the lead time and the confidence levels. The object returned by this function can be displayed with the plot() function, whose n.back argument sets the number of previous observations to be shown.

```
R> p <- predict(um2, n.ahead = 12)
R> #plot(p, n.back = 48)
```

3.6. Unobserved components

The ucomp() function computes unobserved components for a time series based on an object of class um, which can be graphed with the plot command. Figure 5 shows the seasonal component estimated with the tfarima and RJDementra packages. We can see that, for this time series, the results are practically identical.

```
R> uc1 <- ucomp(um2)
R> #plot(uc1)
R> library(RJDemetra)
R> ts1 <- tramoseats(AirPassengers, spec = "RSA5")
R> plot(ts1$final$series[,4], ylab = expression('S'[t]), col = "gray")
R> lines(exp(uc1$seas), lty = 2)
```

4. Customized seasonal ARIMA models

To illustrate the specification and estimation of customized ARIMA models, three alternative representations for seasonal series are considered. Firstly, the lineal regression model for a monthly time series with deterministic trend and seasonality is handled as an non-invertible airline $ARIMA(0,1,1)(0,1,1)_{12}$ model whose two MA parameters are restricted to be equal to

1. Secondly, the additive Holt-Winters method for a monthly series is implemented as an ARIMA(13, 13) model whose 13 MA coefficients are functions of three parameters. Finally, two generalizations of the popular airline model are estimated, which are very close to the structural time series models advocated by Harvey and Durbin (1986).

4.1. Regression models with deterministic components

It is well known that the linear regression model with deterministic trend and seasonality,

$$Y_t = \mu_0 + \mu_1 t + \sum_{j=1}^{s-1} D_{jt} + u_t, \quad t = 1, \dots, n$$
(4)

is equivalent to the non-invertible multiplicative $IMA(1,1)(1,1)_s$ model

$$\nabla \nabla_s Y_t = (1 - B)(1 - B^s)u_t \tag{5}$$

where the seasonal difference ∇_s removes the intercept μ_0 and the set of seasonal dummies D_{jt} and transforms the trend t into a constant $\nabla_s t = s$, which is later removed by the regular difference ∇ . "By equivalent" it is meant that both models provide the same residuals (see, e.g., (Bell 1987)).

The previous code chunk estimates the regression model (4) and the non-invertible IMA model (5) with the um() and arima() functions. In Figure 6, we can see that the least-squares residuals of (4) and the exact residuals of (5) computed by the um functions are the same series, which differ from the innovations provided by the arima() function.

Note that in the um() function we use the argument fit = FALSE because all the parameters are fixed and we don't need to estimate the model. If we extend this model with two AR(2) operators, then to fix the non-invertible MA polynomials we have to create two MA polynomials, MA(1) and $MA(1)_12$, or a MA(13) polynomial with the lagpol() function setting the values of the coefficients in the coef argument. Although it is not necessary, two AR(2) polynomials are also created to highlight the difference when creating a unrestricted and restricted polynomials. Note that the argument ar = list(ar2, AR2) could be replaced by ar = list(2, c(2, 12)).

```
R> #i1 <- lagpol(coef = 1); i12 <- lagpol(coef = 12); i <- list(i1, i12) R> i <- lagpol(lags = c(1, 12, 13), coef = c(1,1,-1))
```

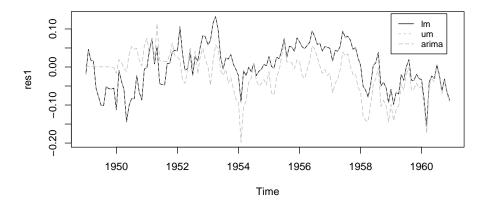


Figure 6: Least-squares residuals, exact ARIMA residuals and innovations.

```
R> ar2 <- lagpol(param = c(phi1 = .1, phi2 = .1))
R> AR2 <- lagpol(param = c(PHI1 = .1, PHI2 = .1), s = 12)
R> um(AirPassengers, bc = TRUE, ar = list(ar2, AR2), i = i, ma = i)
```

Estimate Std. Error phi1 0.5697594 0.07460517 phi2 0.2755773 0.07525051 PHI1 0.4251549 0.07995199 PHI2 0.3131587 0.07636835

log likelihood: 243.8756

Residual standard error: 0.0333997

aic: -3.662224

4.2. Exponential smoothing

Roberts (1982) shown that the Holt-Winters' additive method

$$Y_{t+h} = \mu_t + \beta_t h + S_{t+h-s} + u_{t+h}$$

$$\mu_t = \mu_{t-1} + \beta_{t-1} + \alpha_1 u_t$$

$$\beta_t = \beta_{t-1} + \alpha_2 u_t$$

$$S_t = S_{t-s} + \alpha_3 u_t,$$

can be written as an ARIMA model

$$\nabla \nabla_s Y_t = (1 - \theta_1 B - \theta_2 B^2 - \dots - \theta_{s+1} B^{s+1}) u_t,$$

with $\theta_1 = 1 - \alpha_1 - \alpha_2$, $\theta_2 = \cdots = \theta_{s-1} = -\alpha_2$, $\theta_s = 1 - \alpha_2 - \alpha_3$, $\theta_{s+2} = -(1 - \alpha_1 - \alpha_3)$. For a monthly time series (s = 12), and assigning preestimates to the smoothing parameters, we can create this class of restricted MA(13) polynomials as follows,

```
R> coef <- c("1-a1-a2", rep("-a2", 10), "1-a2-a3", "-(1-a1-a3)")
R> 1p <- lagpol(param = c(a1 = 0.2, a2 = 0.1, a3 = 0.1), coef = coef)
R> 1p

1 - 0.7B + 0.1B^2 + 0.1B^3 + 0.1B^4 + 0.1B^5 + 0.1B^6 + 0.1B^7 + 0.1B^8 + 0.1B^9 + 0.1B^{10} + 0.1B^{11} - 0.8B^{12} + 0.7B^{13}
```

In the following code chunk, the HW-ARIMA model is first estimated with the um function and then the smoothing parameters are estimated with the hw() function of the **forecast** package, choosing both optimal and simple preestimates of the initial states $\mu_0, \beta_0, S_0, \ldots, S_{-11}$.

```
R> library(forecast)
R> um0 <- um(AirPassengers, bc = TRUE, i = list(1, c(1, 12)), ma = lp)
R> hw1 <- hw(log(AirPassengers))
R> hw2 <- hw(log(AirPassengers), initial = "simple")</pre>
```

Given that the values of the likelihood provided by the two packages are not comparable, the estimates of the smoothing parameters obtained with the **forecast** package are used to create the equivalent HW-ARIMA model with the um() function and evaluate its log-likelihood.

```
R> a <- unname(hw1$model$par[1:3])</pre>
R > 1p < -1agpol(param = c(a1 = a[1], a2 = a[2], a3 = a[3]), coef = coef)
R> um1 <- um(log(AirPassengers), i = list(1, c(1, 12)), ma = lp, fit = FALSE)
R> a <- unname(hw2$model$par[1:3])</pre>
R > 1p < -1agpol(param = c(a1 = a[1], a2 = a[2], a3 = a[3]), coef = coef)
R> um2 <- um(log(AirPassengers), i = list(1, c(1, 12)), ma = lp, fit = FALSE)
R> cbind(hw_um = c(coef(um0), lik = logLik(um0)),
         hw_simple = c(coef(um2), logLik(um2)),
         hw_opt = c(coef(um1), logLik(um1))
           hw_um
                    hw_simple
                                     hw_opt
a1 3.502908e-01 3.405976e-01 6.974804e-01
a2 9.648322e-04 1.485999e-04 3.058347e-03
a3 4.966692e-01 5.288037e-01 1.133132e-04
lik 2.379866e+02 2.379169e+02 2.292592e+02
```

4.3. Basic structural model

Harvey and Durbin (1986) consider a basic structural model with a trend μ_t , a seasonal S_t and an irregular u_t component for a seasonal time series Y_t with frequency s observations per unit of time,

$$Y_t = \mu_t + S_t + u_t, \quad u_t \sim iidN(0, \sigma_u^2),$$

where the trend component is specified as

$$\mu_t = \mu_{t-1} + \beta_{t-1} + v_t, \quad v_t \sim iidN(0, \sigma_v^2)$$

 $\beta_t = \beta_{t-1} + \omega_{0t}, \quad \omega_{0t} \sim iidN(0, \sigma_{w_0}^2)$

and the seasonal component $S_t = \sum_{k=1}^{[s/2]}$ is formulated as the sum of [s/2] seasonal cycles with frequencies $2\pi k/s (k=1\ldots,[s/2])$ given by

$$S_{k,t} = c_k S_{k,t-1} + s_k S_{k,t-1}^* + \omega_{kt}, \quad \omega_{kt} \sim iidN(0, \sigma_{w_k}^2)$$

$$S_{k,t}^* = -s_k S_{k,t-1} + c_k S_{k,t-1}^* + \omega_{kt}^*, \quad \omega_{kt}^* \sim iidN(0, \sigma_{w_k}^2)$$

being $c_k = \cos(2\pi k/s)$ and $s_k = \sin(2\pi k/s)$ and $S_{kt} = -S_{kt-1} + \omega_{kt}$ for k = s/2 (s even). The set of shocks u_t , v_t and w_{kt} ($k = 0, \ldots, \lceil s/2 \rceil$) are mutually independent.

The bsm() function of the **tfarima** package estimates this class of models using an algorithm to evaluate the exact likelihood function comparable to that used to estimate the ARIMA models.

R> bsm1 <- bsm(AirPassengers, bc = TRUE)
R> bsm1

```
Var Ratio
irr 2.345541e-04 7.860387e-01
lvl 2.984002e-04 1.000000e+00
slp 1.256384e-10 4.210401e-07
seas 3.560016e-06 1.193034e-02
```

log likelihood: 242.0884

The reduced form of the bsm1 model can be found with the rfom() function,

```
R> rf1 <- rform(bsm1)
R> nabla(rf1)
```

```
1 - B + 6.9e - 16B^2 - 7.2e - 16B^3 - 3.9e - 16B^4 + 1.1e - 17B^5 + 7e - 16B^6 - 9.8e - 16B^7 - 7.2e - 16B^8 + 1.8e - 15B^9 - 3.1e - 16B^10 + 8.2e - 16B^11 - B^12 + B^13
```

R> theta(rf1)

```
1 - 0.52B + 0.024B^2 - 0.047B^3 + 0.025B^4 - 0.041B^5 + 0.021B^6 - 0.039B^7 + 0.012B^8 - 0.046B^9 - 0.012B^10 - 0.08B^11 - 0.46B^12 + 0.17B^13
```

The reduced form rf1 is an object of class um and can be used to compute residuals, as well as to forecast and decompose time series.

4.4. Factored seasonal ARIMA models

As the Holt-Winters method, the ARIMA $(0,1,1)(0,1,1)_s$ model,

$$(1 - B)(1 - B^s)z_t = (1 - \theta B)(1 - \Theta B^s)a_t, \tag{6}$$

doesn't not allow to identify neither series with deterministic linear trend and stochastic seasonality nor series with stochastic linear trend and deterministic seasonality. The first type of series would arise with the cancellation of the two regular differences $(1-B)^2$ on both sides of the equation, while the second one would imply the cancellation of the annual sum operator $1 + B + \cdots + B^{s-1}$. It is not possible either to identify series with mixed deterministic-stochastic seasonality, which would require the cancellation of some, but not all, factors of the seasonal difference. To overcome these restrictions Gallego and Treadway (1995) considered two generalizations of (6): the basic generalization with three parameters

$$(1-B)^{2}(1+B+\cdots+B^{s-1})z_{t} = (1-\theta B)(1-\Theta_{0}^{1/s}B)(1+\Theta_{1}^{1/s}B+\cdots+\Theta_{1}^{(s-1)/s}B^{s-1})a_{t}$$
 (7)

and the full generalization with [s/2] + 1 parameters

$$(1-B)^{2}(1+B) \prod_{k=1}^{[(s-1)/2]} (1-2\cos(2\pi k/s)B + B^{2})z_{t} =$$

$$(1-\theta B)(1-\Theta_{0}^{1/s}B)[(1+\Theta_{s/2}^{1/s}B)] \prod_{k=1}^{[(s-1)/2]} (1-2\cos(2\pi k/s)\Theta_{k}^{1/s}B + \Theta_{k}^{2/s}B^{2})a_{t}.$$
(8)

Note that model (8) reduces to (7) when $\Theta_k = \Theta_1$ for k = 1, ..., [s/2], and (7) reduces to (6) when $\Theta_0 = \Theta_1$. In both equations (7) and (8), the linear trend is deterministic when $\theta = \Theta_0 = 1$, and seasonality is deterministic when $\Theta_1 = \Theta_k = 1$ for k = 1, ..., [s/2]. In (8), mixed deterministic-stochastic seasonality would arise when $\Theta_k = 1$ for some $k \in \{1, ..., [s/2]\}$. Note also that the parameters Θ_k are rised to a power multiple of 1/s to ease the comparisons with the airline model (6), but such powers can be omitted.

The basic generalized airline model with three MA parameters (8) can be created and estimated as follows

log likelihood: 245.7904

Theta1 0.5405008 0.07621691

Residual standard error: 0.0346022

aic: -3.706724

We can see that the basic factorization of the $MA(1)_{12}$ polynomial reveals the presence of a unit MA root that implies a linear trend with a deterministic slope.

The generalized airline model with seven MA parameters (eq:fgam) can be created and estimated as follows

```
R > 1p0 \leftarrow lagpol(param = c(Theta0 = 0.5), coef = "Theta0^(1/12)")
R > 1p6 < -1agpol(param = c(Theta6 = 0.5), coef = "-Theta6^(1/12)")
R> lp15 <- lapply(1:5, function(k) {
     th <- paste("Theta", k, sep = "")
     param <- 0.8
     names(param) <- th
     coef1 \leftarrow paste("2*cos(2*pi*", k, "/12)*", th, "^(1/12)", sep = "")
     coef2 \leftarrow paste("-", th, "^(2/12)", sep = "")
     lagpol(param = param, coef = c(coef1, coef2))
R> gam <- um(AirPassengers, bc = TRUE, i = list(1, c(1,12)),
             ma = list(1, lp0, lp15, lp6))
R> gam
        Estimate Std. Error
theta1 0.4493981 0.09018171
Theta0 0.9991544 0.23126557
Theta1 0.4500810 0.14400633
Theta2 0.4432250 0.12780458
Theta3 0.9914946 0.15453472
Theta4 0.5378578 0.15690862
Theta5 0.6285395 0.12799566
Theta6 0.9958152 0.20530270
log likelihood: 249.2741
Residual standard error: 0.03292445
aic: -3.683575
```

5. Transfer function models

Transfer function models describes the dynamic relationship between an output Y_t and one or several inputs X_{jt} . The impulse response function (IRF) $\nu_j(B) = \nu_{j0} + \nu_{j1}B + \nu_{j2}B^2 + \dots$ for each input X_{jt} can be approximated by the rational transfer function of order (r_j, s_j, b_j)

$$\nu_j(B) = w_{j0} \frac{w_{js_j}(B)}{\delta_{jr_j}(B)} B^{b_j}, \tag{9}$$

where b_j is the delay or dead time, $w_{j0} = \nu_{jb}$ is the first non-null coefficient of the IRF $\nu_j(B)$, and $\delta_{jr_j}(B) = 1 - \delta_{j1}B - \cdots - \delta_{jr_j}B^{r_j}$ and $w_{js_j}(B) = 1 - \omega_{j1}B - \cdots - \omega_{jr_j}B^{r_j}$ are here polynomials of order s_j and r_j that, like the AR and MA operators of (1), can be expressed as the product of multiple normalized polynomials of the class (2)-(3).

Combining (1) and (9) we obtain a rich class of TF models for an output Y_t given by

$$Y_{t} = \sum_{j=1}^{k} w_{j0} \frac{\omega_{js_{j}}(B)}{\delta_{jr_{j}}(B)} B^{b_{j}} X_{jt} + N_{t}$$

$$\delta_{d}(B) N_{t} = \mu + \frac{\vartheta_{q}(B)}{\varphi_{p}(B)} a_{t},$$
(10)

where the noise N_t follows a general ARIMA(p, d, q) model of the class (1). This specification contains as special cases the intervention models used to deal with four common types of outliers: additive outlier (AO), innovative outlier (IO), level shift (LS) and transitory change (TC), see, e.g., Box and Tiao (1975) and Chen and Liu (1993).

5.1. The tfm class: transfer function models

To create TF models defined by equation (10), we have to create previously both the TF for each input and the UM for the noise. The tf() function of the tfarima package specifies the TF for a particular input,

where the input x is an object of class "ts", delay is an integer value for the input lag, w0 a numeric value for the parameter w_0 of the TF, ar and ma are lists of objects of class lagpol in the denominator (AR) and numerator (MA) of the TF, um is an optional object of class um used to back/forecast the input x, and par.prefix is an optional character to set a prefix for the parameters of the TF. Any of the three ways described to provide lag polynomials in the um() function can also be used with the tf() function.

Once we have specified a TF for each input, we can create a TF model with the tfm() function,

```
tfm <- function(output = NULL, xreg = NULL, inputs = NULL, noise, fit = TRUE)
```

where output is an object of class ts, xreg is a vector or matrix of regressors, inputs is a list of objects of class tf, noise is an object of class um with the UM for the noise, fit is a logical value indicating whether or not to fit the TF model. Two comments are in order: (1) if the um object for the output is set to the noise argument, then it is not necessary provide the output argument because it is already contained in this um object; (2) time series for the inputs and regressors must have at least the same length as the output, but they can be extended with backcasts and forecasts to improve the estimation or to forecast the output (more on that later).

The function returns an object of class tfm, whose main data members are xreg, inputs and noise. Some useful methods for these of objects are: noise(), fit(), diagchk(), calendar(), outliers(), predict() and ucomp(), which are illustrated in the following subsections.

5.2. Building transfer function models

To illustrate the Box-Jenkins approach to the identification, fitting and checking of TF models, we replicate the analysis of the gas furnace data by Box *et al.* (2016), Series J. They identify and fit an AR(3) model for the input X_t , which can be also fitted to the output Y_t :

```
R> Y <- seriesJ$Y - mean(seriesJ$Y)
R> X <- seriesJ$X - mean(seriesJ$X)
R> umx <- um(X, ar = 3)
R> umy <- fit(umx, Y)</pre>
```

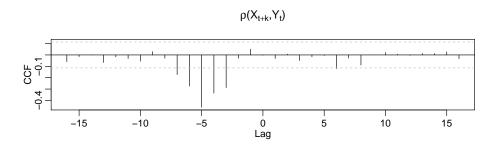


Figure 7: Estimated cross correlation function.

This umx model is used to prewhiten the input X and the output Y. The residuals() function of the **tfarima** package compute the conditional or exact residuals for a time series from an object of class um:

```
R> a <- residuals(umx, Y, method = "cond")
R> b <- residuals(umx, X, method = "cond")</pre>
```

Now we can use the ccf() function of the stats package to display the estimated cross correlation function for the gas furnace data after filtering. Alternatively, we can use the pccf() function of the tfarima defined as

```
R> pccf(X, Y, um.x = umx, um.y = NULL, lag.max = 16)
```

where x and y are the input and the output, um.x and um.y are the univariate models used to prewhiten both series, and lag.max is the number of correlation in each side. If both um.x and um.y arguments are equal to NULL, the ccf is estimated without prewhitening; if only one of these arguments is equal to NULL, the um provided is used to prewhiten both series; otherwise, each series is prewhitened by its own UM.

As in Box et al. (2016) we identify a TF with orders (1,2,3) or (2,2,3), see Figure 7. Preestimates of the parameters of the TF can be computed with the tfest() function

```
R > tfx < -tfest(Y, X, delay = 3, p = 2, q = 2, um.x = umx, um.y = umy)
```

where we provide the output and the input, the delay, the orders of the AR and MA lag polynomials of the TF, and the UMs for the input and the output. The extended lag polynomials of the TF are stored into the data members theta and phi.

```
R> printLagpol(tfx$theta)
```

- 0.51 - 0.32B - 0.48B^2
R> printLagpol(tfx\$phi)

 $1 - 0.65B + 0.087B^2$

Box et al. (2016) fitted the following TF model:

$$Y_{t} = \frac{w_{0} - w_{1}B - w_{2}B^{2}}{1 - \delta_{1}B - \delta_{w}B^{2}}X_{t} + N_{t},$$

$$N_{t} = \frac{1}{1 - \phi_{1}B - \phi_{2}B^{2}}a_{t},$$

which can be estimated as follows:

R> tfmy <- tfm(Y, inputs = tfx, noise = um(ar = 2))
R> printLagpol(tfmy\$inputs[[1]]\$theta)

$$-0.53 - 0.37B - 0.51B^2$$

R> printLagpol(tfmy\$inputs[[1]]\$phi)

$$1 - 0.56B + 0.011B^2$$

R> printLagpol(tfmy\$noise\$phi)

$$1 - 1.5B + 0.63B^2$$

where we can see that the estimates are very close to those reported by Box et al. (2016): $\hat{\omega}_0 = -0.53$, $\hat{\omega}_1 = 0.33$, $\hat{\omega}_2 = 0.51$, $\hat{\delta}_1 = 0.57$, $\hat{\delta}_2 = 0.02$, $\hat{\phi}_1 = 1.54$, $\hat{\phi}_2 = -0.64$.

It is worth mentioning that the tfm() function uses the backcasting method to extend the input using its own UM so that the effect of transients can be minimized. The number of backcasts is set by the n.back argument, which by default is n/4. The UM of the input is also used to compute forecasts when forecasting the output.

As a second illustration, Box *et al.* (2016, p. 409) consider a TF model to predict sales data using a leading indicator. Pankratz (1991, p. 202) estimated this model using the SCA system and the first 140 observations,

$$\nabla Y_t = 0.033 + \frac{4.716}{1 - 0.725B} \nabla X_{t-3} + (1 - 0.620B) \hat{a}_t$$
$$\nabla X_t = (1 - 0.4483B) \hat{b}_t.$$

Before comparing these estimates with those provided by the tfarima package, we can compute the exact value of the concentrated likelihood function of this TF model. To this end, we first create the model without estimating the parameters and then we call the logLik function:

```
R> Y <- window(BJsales, end = 140)
R> X <- window(BJsales.lead, end = 140)
R> umy <- um(Y, i = 1, ma = "1-0.620B", mu = 0.033, fit = FALSE)
R> umx <- um(X, i = 1, ma = "1 - 0.4483B", fit = FALSE)
R> tfx <- tf(X, delay = 3, w0 = 4.716, ar = "1-0.725B", um = umx)
R> tfmy <- tfm(output = Y, inputs = tfx, noise = umy, fit = FALSE)
R> c(logLik(tfmy), logLik(umx))
```

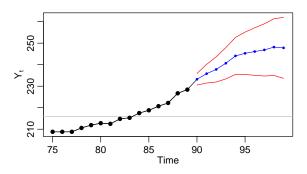


Figure 8: Forecast of sales at origin t = 89.

[1] 7.157349 -23.832730

Without the previous information we would estimate the TF model for the sales data with the following code chunk:

Following the Box-Jenkins textbook example, forecasts from origin 89 for lead times from 1 to 10 are generated and shown in Figure 8.

```
R> p <- predict(tfmy, n.ahead = 10, ori = 89)
R> plot(p, n.back = 15, ylab = expression("Y"["t"]))
```

6. Intervention analysis, outlier detection and calendar effects

Intervention models suggested by Box and Tiao (1975) are special cases of TF models and can be estimated with the tfm() function to take cate of outliers. For example, Box et al. (2016) identify three innovational outliers (IO) at times 58, 59 and 60 in the Series C, the

"uncontrolled" temperature readings every minute in a chemical process. To estimate the effects of these IOs they fit the outlier model:

$$(1 - B)Y_t = \frac{1}{1 - \phi B} (w_1 P_t^{(58)} + w_2 P_t^{(59)} + w_3 P_t^{(60)} + a_t),$$

where $P_t^{(\tau)}$ is a pulse function at τ :

$$P_t^{(\tau)} = \begin{cases} 0 & t \neq \tau \\ 1 & t = \tau \end{cases}$$

They estimated the model by conditional least squares (CLS) and obtained the following results (standard errors in parenthesis): $\hat{\phi} = 0.851(0.035)$, $\hat{\omega}_1 = 0.745(0.116)$, $\hat{\omega}_2 = -0.551(0.120)$, $\hat{\omega}_1 = -0.455(0.116)$, $\hat{\sigma}_a^2 = 0.0132$. This model can be reformulated as a single input transfer function model:

$$Y_{t} = w_{0} \frac{(1 - w_{1}'B - w_{2}'B^{2})}{(1 - \phi B)(1 - B)} P_{t}^{(58)} + N_{t}$$

$$N_{t} = \frac{1}{(1 - \phi B)(1 - B)} a_{t},$$
(11)

where the input and the noise share the same ARI operators. The capabilities of the **tfarima** package to estimate models with multiple operators and parameter restrictions allows us to estimate this model by running the following code:

```
R> Y <- as.ts(seriesC)
R> um1 <- um(Y, ar = 1, i = 1, method = "cond")
R> P58 <- InterventionVar(Y, 58)
R> tf58 <- tf(P58, ma = 2, ar = c(um1$ar, um1$i))
R> tfm1 <- tfm(inputs = tf58, noise = um1)
R> tfm1
```

Estimate Std. Error
P58 0.7447334 0.1183491
P58.w1 0.7405461 0.2053821
P58.w2 0.6110603 0.1869052
phi1 0.8512211 0.0355065

log likelihood: 161.8301

Residual standard error: 0.1180356

aic: -1.402934

R> printLagpol(tfm1\$inputs[[1]]\$theta, digits = 3)

$$0.745 - 0.552B - 0.455B^2$$

Firstly, we load the Series C and fit an ARIMA(1,1,0) model, which is used as noise model. Next, we create a pulse variable at $\tau = 58$ and its transfer function by providing the order of the MA polynomial and the ARI operators of the um1 model. Finally, we create and fit the transfer function model which is made up of a single input and an ARIMA(1,1,0) noise. We can see that the results of the estimation by conditional likelihood maximum are very similar to those of Box *et al.* (2016).

The outliers() function implements a version of the Chen and Liu (1993) procedure to detect and correct the effects of four common types of anomalies: additive outliers, innovational outliers, level shifts and transitory changes. We apply this function to model um1 and use a critical value c = 3.5 to determine if an observation is anomalous:

```
R> tfm2 \leftarrow outliers(um1, c = 3.5)
R> tfm2
```

Estimate Std. Error LS58 0.7037228 0.08971299 IO60 -0.4560648 0.11841531 phi1 0.8535311 0.03524750

log likelihood: 161.6899

Residual standard error: 0.1181278

aic: -1.410577

The function detects two outliers at times 58 and 60 of type LS and IO, respectively. Note that model tfm2 is compatible with model tfm1 since (11) can be reformulated as

$$Y_t = w_0 \frac{(1 - w_1' B)}{(1 - \phi B)} S_t^{(58)} - w_0 * w_2' P_t^{60} + N_t,$$

where $S_t^{50} = (1-B)^{-1} P_t^{58}$ is a step function at T = 58 and $w_1' \simeq \phi$.

The outliers() function can also be used to identify and estimate the effects of possible outliers at known times:

```
R> tfm3 <- outliers(um1, dates = c(58, 59, 60))
R> summary(tfm3)$table
```

```
Gradient Std. Error
                                          z Value
                                                       Pr(>|z|)
      Estimate
LS58 0.8934580
               2.973363e-08 0.10042294
                                        8.896951
                                                   5.740182e-19
                1.186926e-07 0.09221106
TC59 0.3841661
                                        4.166161
                                                   3.097721e-05
A060 0.1240028
               1.280431e-07 0.05601311
                                         2.213818 2.684133e-02
phi1 0.8517213 -2.065117e-07 0.03532254 24.112683 1.840259e-128
```

6.1. Calendar effects

Hillmer (1982) used the telephone data of Thompson and Tiao (1971) to illustrate how to forecast time series with trading day variation. This data refers to outward station movements (disconnections) of the Wisconsin telephone company from January 1951 to October 1968. Clearly the series exhibits increasing seasonality and an upward trend requiring logs and

both types of differences. Besides, it is affected by the number of trading days in a month because there are more disconnections on weekdays than on weekends. Due to these calendar effects, the sample ACF and PACF of $\nabla\nabla \log(Y_t)$ do not have a recognizable pattern. Hence, to identify a tentative ARMA structure for this series, the calendar effects are removed by fitting the regARIMA model

$$\log(Z_t) = \sum_{j=1}^{7} \alpha_j X_{jt} + N_t$$

where X_{jt} , i=1,...,7, are, respectively, the number of Mondays, Tuesdays, and so on in month t and N_t is the noise. Defining $\beta_0 = \sum_{j=1}^7 \alpha_j/7$ and $L_t = X_{1t} + \cdots + X_{7t}$ (length of month t), the regression component $TD_t = \sum_{j=1}^7 \alpha_j X_{jt}$ can be reparametrized as

$$TD_t = \beta_0 L_t + \sum_{j=1}^{6} \beta_1 (X_{jt} - X_{7t})$$

where $\beta_j = \alpha_j - \beta_0$ for $j = 1, \dots, 6$.

The calendar() function enlarges an ARIMA or a TF model by adding calendar variables:

where mdl is an object of class um or tfm, form is a character indicating the type of representation for TD_t , easter is a logical value to include an extra calendar variable for Easter, and n.ahead is an optional integer to extend the regressors with future observations to forecast the output.

To estimate this regARIMA model, we create an ARIMA $(0,1,0)(0,1,0)_{12}$ model without parameters and call the calendar() function:

```
R> Y <- Wtelephone$Y
R > umY < -um(Y, bc = TRUE, i = list(1, c(1,12)))
R> tfmY1 <- calendar(umY, n.ahead = 13)
R> tfmY2 <- calendar(umY, form = "td7", n.ahead = 13)
R > b < -coef(tfmY1); a = coef(tfmY2)
R > cbind(b, cbind(c(a[2:7]-mean(a), mean(a))))
Mon Sun
         0.018741626
                      0.018741626
Tue_Sun
         0.026319985
                      0.026319985
Wed_Sun
         0.013239777
                      0.013239777
         0.001581267
Thu_Sun
                      0.001581267
Fri Sun
        0.011129339
                      0.011129339
Sat Sun -0.045970854 -0.045970854
        -0.025984496 -0.025984496
lom
```

Alternatively, we could estimate this model generating the calendar variables and creating a tfm object:

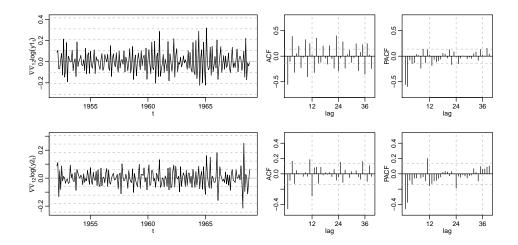


Figure 9: Identification tools for original and corrected telephone data.

```
R> X <- CalendarVar(Y, form = "td7", n.ahead = 13)
R> tfmY <- tfm(xreg = X, noise = umY)</pre>
```

where the Y argument in the CalendarVar() function is used to get the sample period. We can recovery the noise N_t or its transformations $\exp(N_t)$ and $\nabla \nabla_{12} N_t$ with the function

```
noise <- function(tfmY, diff = TRUE, exp = FALSE)</pre>
```

where diff is a logical value indicating if the noise must be differenced and exp is a logical value indicating if the antilog must be applied to the non-differenced noise. Note that these transformations are determined by the noise model.

Now we can identify a pattern in the ACF and PACF of the corrected series compatible with an $ARIMA(0,1,1)(0,1,1)_{12}$:

```
R>y \leftarrow noise(tfmY, diff = FALSE, exp = TRUE)

R>ide(list(Y, y), transf = list(bc = T, d = 1, D = 1))
```

The two MA operators can be added to the tfmY object with the modify() function:

```
R> tfmY <- modify(tfmY, ma = list(1, c(1,12)))
R> tfmY
```

```
Estimate Std. Error
       -0.042666358 0.01809336
Sun
Mon
        0.006352052 0.01706942
        0.005981991 0.01810221
Tue
Wed
        0.002218116 0.01728891
Thu
       -0.019814682 0.01773134
Fri
       -0.003301995 0.01755550
       -0.065388393 0.01736859
Sat
theta1 0.742658333 0.04579664
```

theta2 0.456092445 0.06809570

log likelihood: 338.1755

Residual standard error: 0.04367511

aic: -3.259164

Finally, we could predict future values:

R>
$$p \leftarrow predict(tfmY, n.ahead = 13)$$

R> $print(p, rows = c(1, 13))$

```
Forecast RMSE 95% LB 95% UB dic 1968 18482.13 0.04396946 16956.07 20145.54 dic 1969 20113.80 0.06769674 17614.51 22967.71
```

For the sake of completeness, we estimate the ARIMA model developed by Thompson and Tiao (1971):

$$(1 - \phi_1 B^3)(1 - \phi_2 B^{12})\log(Y_t) = (1 - \theta_9 B^9 - \theta_{12} B^{12} - \theta_{13} B^{13})a_t$$

R> ma <- lagpol(c(theta9 = .2, theta12 = .2, theta13 = .2), + lags = c(9, 12, 13))
R> TT <- um(Y, bc = TRUE, ar = list(c(1, 3), c(1, 12)), ma = ma)
R> TT

Estimate Std. Error phi1 0.94158802 0.030531610 phi2 0.99557584 0.004359192 theta9 -0.23538081 0.064989826 theta12 0.31958805 0.067679083 theta13 0.03334713 0.062176433

log likelihood: 235.9692

Residual standard error: 0.06568544

aic: -2.148551

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