## worksheet 23

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#### 1 Worksheet 23

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#### 1.0.1 Topics

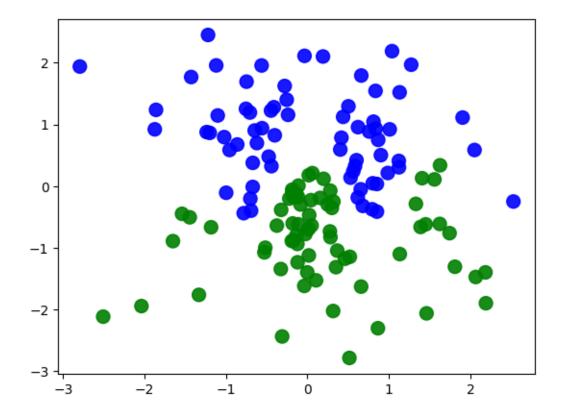
• Tuning Neural Networks

### 1.1 Tuning Neural Networks

Nothing to do in this worksheet except follow along in lecture / use this code to better understand Neural Networks.

```
[]: import math as m
     import numpy as np
     import matplotlib.pyplot as plt
     import sklearn.datasets as datasets
     from tensorflow import keras, math, random, stack
     from tensorflow.keras import layers, initializers
     from tensorflow.keras.activations import relu
     # Set random seed for reproducibility
     np.random.seed(1)
     random.set_seed(1)
     # Data generation - don't modify
     centers = [[0, 0]]
     t, _ = datasets.make_blobs(n_samples=200, centers=centers, cluster_std=1,
                                     random_state=1)
     colors = np.array([x for x in 'bgrcmyk'])
     # CURVE
     def generate_curve_data(t):
         # create some space between the classes
         X = np.array(list(filter(lambda x : m.cos(4*x[0]) - x[1] < -.5 or m.
      cos(4*x[0]) - x[1] > .5, t)))
         Y = np.array([1 if m.cos(4*x[0]) - x[1] >= 0 else 0 for x in X])
```

```
return X, Y
# The model - modify this
model = keras.models.Sequential()
model.add(layers.Dense(3, input_dim=2, activation="sigmoid"))
model.add(layers.Dense(1, activation="sigmoid"))
model.compile(loss="binary_crossentropy")
X, Y = generate_curve_data(t)
# plot the data
plt.scatter(X[:,0],X[:,1],color=colors[Y].tolist(), s=100, alpha=.9)
plt.show()
history = model.fit(X, Y, batch_size=50, epochs=200)
# Plot the decision boundary
# create a mesh to plot in
h = .02 # step size in the mesh
x_{\min}, x_{\max} = X[:, 0].min() - .5, X[:, 0].max() + 1
y_{min}, y_{max} = X[:, 1].min() - .5, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                     np.arange(y_min, y_max, h))
meshData = np.c_[xx.ravel(), yy.ravel()]
fig, ax = plt.subplots()
Z = model.predict(meshData)
Z = np.array([0 if x < .5 else 1 for x in Z])
Z = Z.reshape(xx.shape)
ax.contourf(xx, yy, Z, alpha=.3, cmap=plt.cm.Paired)
ax.axis('off')
# Plot also the training points
ax.scatter(X[:, 0], X[:, 1], color=colors[Y].tolist(), s=100, alpha=.9)
plt.title("Decision Boundary")
plt.show()
```



```
Epoch 1/200
Epoch 2/200
Epoch 3/200
         ========] - Os 9ms/step - loss: 0.6594
3/3 [======
Epoch 4/200
         ==========] - Os 8ms/step - loss: 0.6566
3/3 [=======
Epoch 5/200
3/3 [========== ] - Os 8ms/step - loss: 0.6541
Epoch 6/200
3/3 [=========== ] - Os 9ms/step - loss: 0.6518
Epoch 7/200
Epoch 8/200
Epoch 9/200
          ========] - Os 16ms/step - loss: 0.6455
3/3 [======
Epoch 10/200
         3/3 [======
Epoch 11/200
```

```
Epoch 12/200
Epoch 13/200
3/3 [========== ] - Os 9ms/step - loss: 0.6377
Epoch 14/200
Epoch 15/200
Epoch 16/200
Epoch 17/200
Epoch 18/200
Epoch 19/200
Epoch 20/200
3/3 [============== ] - 0s 16ms/step - loss: 0.6255
Epoch 21/200
3/3 [============== ] - Os 13ms/step - loss: 0.6238
Epoch 22/200
3/3 [============= ] - 0s 6ms/step - loss: 0.6222
Epoch 23/200
3/3 [========== ] - Os 7ms/step - loss: 0.6206
Epoch 24/200
Epoch 25/200
Epoch 26/200
3/3 [============== ] - 0s 10ms/step - loss: 0.6159
Epoch 27/200
Epoch 28/200
Epoch 29/200
3/3 [============= ] - 0s 8ms/step - loss: 0.6112
Epoch 30/200
Epoch 31/200
Epoch 32/200
3/3 [=========== ] - Os 17ms/step - loss: 0.6068
Epoch 33/200
Epoch 34/200
Epoch 35/200
```

```
Epoch 36/200
3/3 [============== ] - 0s 14ms/step - loss: 0.6011
Epoch 37/200
3/3 [=============== ] - Os 19ms/step - loss: 0.5997
Epoch 38/200
Epoch 39/200
Epoch 40/200
Epoch 41/200
Epoch 42/200
Epoch 43/200
Epoch 44/200
Epoch 45/200
3/3 [============== ] - Os 12ms/step - loss: 0.5890
Epoch 46/200
3/3 [=============== ] - Os 12ms/step - loss: 0.5878
Epoch 47/200
Epoch 48/200
Epoch 49/200
Epoch 50/200
Epoch 51/200
Epoch 52/200
Epoch 53/200
3/3 [=============== ] - Os 10ms/step - loss: 0.5792
Epoch 54/200
Epoch 55/200
Epoch 56/200
3/3 [=========== ] - Os 18ms/step - loss: 0.5758
Epoch 57/200
3/3 [============== ] - 0s 14ms/step - loss: 0.5746
Epoch 58/200
Epoch 59/200
```

```
Epoch 60/200
Epoch 61/200
Epoch 62/200
Epoch 63/200
Epoch 64/200
Epoch 65/200
Epoch 66/200
Epoch 67/200
3/3 [============== ] - 0s 15ms/step - loss: 0.5638
Epoch 68/200
Epoch 69/200
Epoch 70/200
3/3 [============== ] - Os 10ms/step - loss: 0.5608
Epoch 71/200
Epoch 72/200
Epoch 73/200
Epoch 74/200
Epoch 75/200
Epoch 76/200
Epoch 77/200
3/3 [=============== ] - Os 20ms/step - loss: 0.5537
Epoch 78/200
Epoch 79/200
Epoch 80/200
3/3 [=========== ] - Os 14ms/step - loss: 0.5508
Epoch 81/200
Epoch 82/200
Epoch 83/200
```

```
Epoch 84/200
Epoch 85/200
Epoch 86/200
Epoch 87/200
3/3 [=============== ] - 0s 11ms/step - loss: 0.5440
Epoch 88/200
Epoch 89/200
3/3 [============== ] - 0s 16ms/step - loss: 0.5421
Epoch 90/200
Epoch 91/200
Epoch 92/200
Epoch 93/200
3/3 [============== ] - Os 13ms/step - loss: 0.5385
Epoch 94/200
3/3 [=============== ] - Os 16ms/step - loss: 0.5376
Epoch 95/200
3/3 [=========== ] - Os 9ms/step - loss: 0.5368
Epoch 96/200
Epoch 97/200
Epoch 98/200
Epoch 99/200
3/3 [============== ] - 0s 13ms/step - loss: 0.5332
Epoch 100/200
Epoch 101/200
3/3 [============== ] - Os 19ms/step - loss: 0.5315
Epoch 102/200
Epoch 103/200
3/3 [============= ] - 0s 8ms/step - loss: 0.5297
Epoch 104/200
3/3 [=========== ] - Os 12ms/step - loss: 0.5289
Epoch 105/200
3/3 [=========== ] - Os 10ms/step - loss: 0.5280
Epoch 106/200
Epoch 107/200
```

```
Epoch 108/200
Epoch 109/200
Epoch 110/200
Epoch 111/200
Epoch 112/200
Epoch 113/200
Epoch 114/200
Epoch 115/200
Epoch 116/200
Epoch 117/200
Epoch 118/200
3/3 [============== ] - Os 15ms/step - loss: 0.5169
Epoch 119/200
3/3 [=========== ] - Os 9ms/step - loss: 0.5162
Epoch 120/200
Epoch 121/200
Epoch 122/200
Epoch 123/200
3/3 [============ ] - Os 8ms/step - loss: 0.5129
Epoch 124/200
Epoch 125/200
3/3 [=============== ] - Os 52ms/step - loss: 0.5112
Epoch 126/200
Epoch 127/200
Epoch 128/200
3/3 [=========== ] - Os 14ms/step - loss: 0.5087
Epoch 129/200
3/3 [============ ] - Os 28ms/step - loss: 0.5079
Epoch 130/200
Epoch 131/200
```

```
Epoch 132/200
3/3 [============== ] - 0s 15ms/step - loss: 0.5054
Epoch 133/200
Epoch 134/200
Epoch 135/200
Epoch 136/200
3/3 [=============== ] - 0s 13ms/step - loss: 0.5021
Epoch 137/200
Epoch 138/200
3/3 [============== ] - 0s 16ms/step - loss: 0.5004
Epoch 139/200
3/3 [============= ] - 0s 14ms/step - loss: 0.4996
Epoch 140/200
3/3 [============== ] - 0s 10ms/step - loss: 0.4988
Epoch 141/200
3/3 [============== ] - Os 10ms/step - loss: 0.4981
Epoch 142/200
3/3 [=============== ] - Os 12ms/step - loss: 0.4971
Epoch 143/200
Epoch 144/200
Epoch 145/200
Epoch 146/200
Epoch 147/200
3/3 [============== ] - 0s 17ms/step - loss: 0.4931
Epoch 148/200
Epoch 149/200
3/3 [=============== ] - Os 18ms/step - loss: 0.4916
Epoch 150/200
Epoch 151/200
3/3 [============= ] - 0s 6ms/step - loss: 0.4899
Epoch 152/200
3/3 [========== ] - Os 7ms/step - loss: 0.4891
Epoch 153/200
Epoch 154/200
Epoch 155/200
```

```
Epoch 156/200
Epoch 157/200
3/3 [=========== ] - Os 9ms/step - loss: 0.4850
Epoch 158/200
Epoch 159/200
Epoch 160/200
3/3 [============= ] - 0s 8ms/step - loss: 0.4827
Epoch 161/200
Epoch 162/200
3/3 [=========== ] - Os 19ms/step - loss: 0.4811
Epoch 163/200
Epoch 164/200
Epoch 165/200
3/3 [=============== ] - Os 11ms/step - loss: 0.4787
Epoch 166/200
3/3 [=============== ] - Os 19ms/step - loss: 0.4780
Epoch 167/200
Epoch 168/200
Epoch 169/200
Epoch 170/200
Epoch 171/200
Epoch 172/200
3/3 [=========== ] - Os 7ms/step - loss: 0.4734
Epoch 173/200
3/3 [=============== ] - Os 10ms/step - loss: 0.4725
Epoch 174/200
Epoch 175/200
3/3 [============== ] - 0s 9ms/step - loss: 0.4709
Epoch 176/200
3/3 [=========== ] - Os 10ms/step - loss: 0.4701
Epoch 177/200
Epoch 178/200
Epoch 179/200
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Epoch 180/200
3/3 [============== ] - Os 10ms/step - loss: 0.4670
Epoch 181/200
Epoch 182/200
Epoch 183/200
Epoch 184/200
Epoch 185/200
Epoch 186/200
Epoch 187/200
Epoch 188/200
Epoch 189/200
Epoch 190/200
Epoch 191/200
Epoch 192/200
Epoch 193/200
3/3 [============== ] - 0s 14ms/step - loss: 0.4570
Epoch 194/200
3/3 [============= ] - 0s 12ms/step - loss: 0.4563
Epoch 195/200
Epoch 196/200
Epoch 197/200
3/3 [============= ] - 0s 9ms/step - loss: 0.4540
Epoch 198/200
3/3 [============== ] - 0s 9ms/step - loss: 0.4533
Epoch 199/200
Epoch 200/200
3602/3602 [========== ] - 6s 2ms/step
```

# **Decision Boundary**

