worksheet 23

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1 Worksheet 23

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1.0.1 Topics

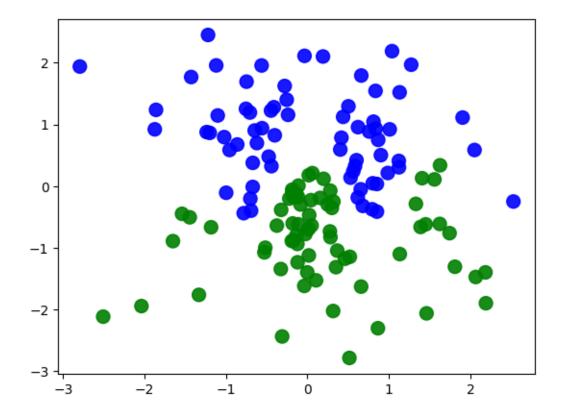
• Tuning Neural Networks

1.1 Tuning Neural Networks

Nothing to do in this worksheet except follow along in lecture / use this code to better understand Neural Networks.

```
[1]: import math as m
     import numpy as np
     import matplotlib.pyplot as plt
     import sklearn.datasets as datasets
     from tensorflow import keras, math, random, stack
     from tensorflow.keras import layers, initializers
     from tensorflow.keras.activations import relu
     # Set random seed for reproducibility
     np.random.seed(1)
     random.set_seed(1)
     # Data generation - don't modify
     centers = [[0, 0]]
     t, _ = datasets.make_blobs(n_samples=200, centers=centers, cluster_std=1,
                                     random_state=1)
     colors = np.array([x for x in 'bgrcmyk'])
     # CURVE
     def generate_curve_data(t):
         # create some space between the classes
         X = np.array(list(filter(lambda x : m.cos(4*x[0]) - x[1] < -.5 or m.
      cos(4*x[0]) - x[1] > .5, t)))
         Y = np.array([1 if m.cos(4*x[0]) - x[1] >= 0 else 0 for x in X])
```

```
return X, Y
# The model - modify this
model = keras.models.Sequential()
model.add(layers.Dense(3, input_dim=2, activation="sigmoid"))
model.add(layers.Dense(1, activation="sigmoid"))
model.compile(loss="binary_crossentropy")
X, Y = generate_curve_data(t)
# plot the data
plt.scatter(X[:,0],X[:,1],color=colors[Y].tolist(), s=100, alpha=.9)
plt.show()
history = model.fit(X, Y, batch_size=50, epochs=200)
# Plot the decision boundary
# create a mesh to plot in
h = .02 # step size in the mesh
x_{\min}, x_{\max} = X[:, 0].min() - .5, X[:, 0].max() + 1
y_{min}, y_{max} = X[:, 1].min() - .5, X[:, 1].max() + 1
xx, yy = np.meshgrid(np.arange(x_min, x_max, h),
                     np.arange(y_min, y_max, h))
meshData = np.c_[xx.ravel(), yy.ravel()]
fig, ax = plt.subplots()
Z = model.predict(meshData)
Z = np.array([0 if x < .5 else 1 for x in Z])
Z = Z.reshape(xx.shape)
ax.contourf(xx, yy, Z, alpha=.3, cmap=plt.cm.Paired)
ax.axis('off')
# Plot also the training points
ax.scatter(X[:, 0], X[:, 1], color=colors[Y].tolist(), s=100, alpha=.9)
plt.title("Decision Boundary")
plt.show()
```



```
Epoch 1/200
Epoch 2/200
Epoch 3/200
           ======== ] - Os 12ms/step - loss: 0.6494
3/3 [======
Epoch 4/200
          ========= ] - Os 10ms/step - loss: 0.6485
3/3 [=======
Epoch 5/200
3/3 [=========== ] - Os 8ms/step - loss: 0.6476
Epoch 6/200
3/3 [=========== ] - Os 18ms/step - loss: 0.6468
Epoch 7/200
Epoch 8/200
3/3 [============ ] - Os 9ms/step - loss: 0.6453
Epoch 9/200
            3/3 [======
Epoch 10/200
          3/3 [======
Epoch 11/200
3/3 [=========== ] - Os 8ms/step - loss: 0.6432
```

```
Epoch 12/200
Epoch 13/200
Epoch 14/200
Epoch 15/200
Epoch 16/200
Epoch 17/200
Epoch 18/200
Epoch 19/200
Epoch 20/200
Epoch 21/200
3/3 [============= ] - 0s 9ms/step - loss: 0.6366
Epoch 22/200
3/3 [============== ] - Os 13ms/step - loss: 0.6360
Epoch 23/200
Epoch 24/200
Epoch 25/200
Epoch 26/200
Epoch 27/200
3/3 [=========== ] - Os 9ms/step - loss: 0.6327
Epoch 28/200
3/3 [========== ] - Os 8ms/step - loss: 0.6320
Epoch 29/200
3/3 [============= ] - 0s 9ms/step - loss: 0.6314
Epoch 30/200
Epoch 31/200
Epoch 32/200
Epoch 33/200
Epoch 34/200
Epoch 35/200
```

```
Epoch 36/200
Epoch 37/200
3/3 [========== ] - Os 8ms/step - loss: 0.6260
Epoch 38/200
Epoch 39/200
3/3 [=============== ] - 0s 13ms/step - loss: 0.6247
Epoch 40/200
Epoch 41/200
Epoch 42/200
Epoch 43/200
Epoch 44/200
Epoch 45/200
3/3 [============== ] - Os 11ms/step - loss: 0.6206
Epoch 46/200
3/3 [============== ] - Os 11ms/step - loss: 0.6200
Epoch 47/200
Epoch 48/200
Epoch 49/200
Epoch 50/200
Epoch 51/200
3/3 [=========== ] - Os 8ms/step - loss: 0.6167
Epoch 52/200
Epoch 53/200
3/3 [============= ] - 0s 8ms/step - loss: 0.6155
Epoch 54/200
Epoch 55/200
Epoch 56/200
3/3 [=========== ] - Os 7ms/step - loss: 0.6135
Epoch 57/200
Epoch 58/200
Epoch 59/200
```

```
Epoch 60/200
Epoch 61/200
3/3 [=========== ] - Os 6ms/step - loss: 0.6104
Epoch 62/200
Epoch 63/200
Epoch 64/200
Epoch 65/200
Epoch 66/200
Epoch 67/200
Epoch 68/200
Epoch 69/200
3/3 [=============== ] - Os 13ms/step - loss: 0.6054
Epoch 70/200
3/3 [============= ] - 0s 9ms/step - loss: 0.6047
Epoch 71/200
3/3 [=========== ] - Os 8ms/step - loss: 0.6042
Epoch 72/200
Epoch 73/200
Epoch 74/200
Epoch 75/200
Epoch 76/200
3/3 [========== ] - Os 6ms/step - loss: 0.6009
Epoch 77/200
3/3 [============= ] - 0s 5ms/step - loss: 0.6002
Epoch 78/200
Epoch 79/200
3/3 [============= ] - 0s 6ms/step - loss: 0.5990
Epoch 80/200
3/3 [=========== ] - Os 8ms/step - loss: 0.5984
Epoch 81/200
Epoch 82/200
3/3 [============== ] - 0s 14ms/step - loss: 0.5971
Epoch 83/200
```

```
Epoch 84/200
Epoch 85/200
3/3 [=============== ] - Os 14ms/step - loss: 0.5951
Epoch 86/200
Epoch 87/200
Epoch 88/200
3/3 [=============== ] - 0s 11ms/step - loss: 0.5931
Epoch 89/200
Epoch 90/200
Epoch 91/200
3/3 [============== ] - 0s 12ms/step - loss: 0.5911
Epoch 92/200
Epoch 93/200
3/3 [============== ] - 0s 8ms/step - loss: 0.5898
Epoch 94/200
3/3 [============== ] - 0s 9ms/step - loss: 0.5892
Epoch 95/200
3/3 [========== ] - Os 8ms/step - loss: 0.5886
Epoch 96/200
Epoch 97/200
3/3 [============== ] - Os 20ms/step - loss: 0.5873
Epoch 98/200
Epoch 99/200
Epoch 100/200
3/3 [=========== ] - Os 8ms/step - loss: 0.5855
Epoch 101/200
3/3 [============== ] - Os 10ms/step - loss: 0.5848
Epoch 102/200
Epoch 103/200
3/3 [=============== ] - Os 19ms/step - loss: 0.5835
Epoch 104/200
3/3 [=========== ] - Os 12ms/step - loss: 0.5829
Epoch 105/200
Epoch 106/200
Epoch 107/200
```

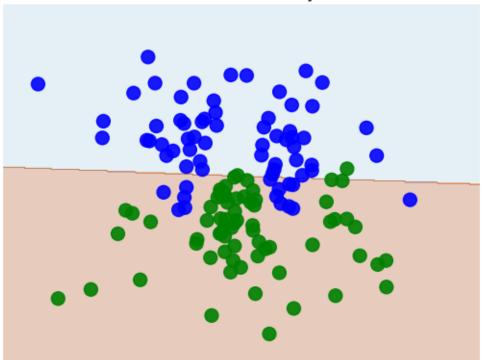
```
Epoch 108/200
Epoch 109/200
Epoch 110/200
Epoch 111/200
Epoch 112/200
Epoch 113/200
Epoch 114/200
Epoch 115/200
Epoch 116/200
Epoch 117/200
3/3 [============= ] - 0s 4ms/step - loss: 0.5744
Epoch 118/200
3/3 [=============== ] - Os 10ms/step - loss: 0.5737
Epoch 119/200
3/3 [=========== ] - Os 9ms/step - loss: 0.5731
Epoch 120/200
Epoch 121/200
Epoch 122/200
Epoch 123/200
Epoch 124/200
Epoch 125/200
3/3 [=============== ] - Os 18ms/step - loss: 0.5692
Epoch 126/200
Epoch 127/200
3/3 [============== ] - 0s 9ms/step - loss: 0.5679
Epoch 128/200
3/3 [=========== ] - Os 8ms/step - loss: 0.5671
Epoch 129/200
Epoch 130/200
Epoch 131/200
```

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Epoch 132/200
Epoch 133/200
Epoch 134/200
Epoch 135/200
Epoch 136/200
Epoch 137/200
Epoch 138/200
Epoch 139/200
Epoch 140/200
Epoch 141/200
3/3 [============= ] - 0s 8ms/step - loss: 0.5582
Epoch 142/200
3/3 [============== ] - 0s 9ms/step - loss: 0.5573
Epoch 143/200
3/3 [========== ] - Os 9ms/step - loss: 0.5567
Epoch 144/200
Epoch 145/200
Epoch 146/200
Epoch 147/200
Epoch 148/200
3/3 [=========== ] - Os 8ms/step - loss: 0.5533
Epoch 149/200
3/3 [=============== ] - 0s 6ms/step - loss: 0.5527
Epoch 150/200
Epoch 151/200
3/3 [============= ] - 0s 7ms/step - loss: 0.5512
Epoch 152/200
3/3 [=========== ] - Os 9ms/step - loss: 0.5506
Epoch 153/200
Epoch 154/200
Epoch 155/200
3/3 [============= ] - 0s 10ms/step - loss: 0.5484
```

```
Epoch 156/200
Epoch 157/200
Epoch 158/200
Epoch 159/200
Epoch 160/200
Epoch 161/200
Epoch 162/200
3/3 [============== ] - 0s 14ms/step - loss: 0.5435
Epoch 163/200
Epoch 164/200
Epoch 165/200
3/3 [=============== ] - Os 12ms/step - loss: 0.5414
Epoch 166/200
3/3 [=============== ] - Os 16ms/step - loss: 0.5407
Epoch 167/200
3/3 [=========== ] - Os 9ms/step - loss: 0.5400
Epoch 168/200
Epoch 169/200
Epoch 170/200
Epoch 171/200
3/3 [============ ] - Os 7ms/step - loss: 0.5373
Epoch 172/200
Epoch 173/200
3/3 [============== ] - Os 14ms/step - loss: 0.5359
Epoch 174/200
Epoch 175/200
Epoch 176/200
Epoch 177/200
3/3 [============== ] - 0s 10ms/step - loss: 0.5331
Epoch 178/200
Epoch 179/200
```

```
Epoch 180/200
3/3 [============== ] - Os 15ms/step - loss: 0.5309
Epoch 181/200
Epoch 182/200
Epoch 183/200
3/3 [=============== ] - 0s 14ms/step - loss: 0.5287
Epoch 184/200
Epoch 185/200
Epoch 186/200
Epoch 187/200
Epoch 188/200
Epoch 189/200
Epoch 190/200
3/3 [=============== ] - Os 16ms/step - loss: 0.5237
Epoch 191/200
Epoch 192/200
Epoch 193/200
3/3 [=============== ] - Os 20ms/step - loss: 0.5215
Epoch 194/200
Epoch 195/200
3/3 [============== ] - Os 10ms/step - loss: 0.5201
Epoch 196/200
3/3 [=========== ] - Os 9ms/step - loss: 0.5194
Epoch 197/200
3/3 [============== ] - 0s 7ms/step - loss: 0.5187
Epoch 198/200
Epoch 199/200
3/3 [============ - - 0s 18ms/step - loss: 0.5173
Epoch 200/200
3602/3602 [========== ] - 10s 3ms/step
```

Decision Boundary



[]: