

STATISTICS CHEAT SHEET

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1. LEAST SQUARES REGRESSION

Trying to estimate the coefficients β in $\mathbf{y} = \mathbf{X}\beta + \epsilon$ is done by

$$(1) \quad \beta = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

This is analogous to finding the projection $\mathbf{y}^* = \beta \hat{\mathbf{x}} + \mathbf{r}$ of the vector \mathbf{y} on the vector \mathbf{x} :

$$(2) \quad \beta = \frac{\mathbf{x} \cdot \mathbf{y}}{\mathbf{x} \cdot \mathbf{x}}$$

If you wish to include a diagonal weight matrix \mathbf{W} this is done by

$$(3) \quad \beta = (\mathbf{X}^T \mathbf{W} \mathbf{X})^{-1} \mathbf{X}^T \mathbf{W} \mathbf{y}$$

and in the case that $\mathbf{W} = \mathbf{I}$ this reduces to (1). One would ordinarily choose the weight matrix to be e.g. $\mathbf{W} = \text{diag}(1/\sigma_i^2)$ if the uncertainties σ_i for each point y_i are known. Alternatively for survey data for example, $\mathbf{W} = \text{diag}(n_i)$ if the population n_i of each district for which the statistic x_i was measured. In the first case, an estimate of the variance is given by the square residuals, divided by the number of points minus the number of parameters, e.g.

$$(4) \quad \hat{\sigma}^2 = \frac{1}{n-p} |\epsilon|^2$$

$$(5) \quad = \frac{1}{n-p} \left| \mathbf{y} - \mathbf{X}\hat{\beta} \right|^2$$

The covariance matrix Σ for β is given by

$$(6) \quad \Sigma = (\mathbf{X}^T \mathbf{W} \mathbf{X})^{-1} \hat{\sigma}^2$$

$$(7) \quad = (\mathbf{X}^T \mathbf{W} \mathbf{X})^{-1} \frac{1}{n-p} \left| \mathbf{y} - \mathbf{X}\hat{\beta} \right|^2$$

where n is the number of data points and p is the number of parameters, i.e. $\nu = n - p$ is the degrees of freedom. An estimate of the variance of each parameter β_i is given by the diagonal entries of Σ ,

$$(8) \quad \text{Var}(\beta_i) = \Sigma_{ii}$$

and assuming they are either normally distributed (for large n) or t -distributed for small n , we can work out confidence intervals for the parameter by using either of the following

$$(9) \quad \beta_i = \hat{\beta}_i \pm z^* \sqrt{\Sigma_{ii}}$$

$$(10) \quad \beta_i = \hat{\beta}_i \pm t^* \sqrt{\Sigma_{ii}}$$

where

$$(11) \quad p = \text{erf} \left(\frac{z_p^*}{\sqrt{2}} \right)$$

$$(12) \quad = \frac{1}{\sqrt{2\pi}} \int_{-\frac{z_p^*}{\sqrt{2}}}^{\frac{z_p^*}{\sqrt{2}}} e^{-t^2} dt$$

$$(13) \quad = \Phi(z_p^*) - \Phi(-z_p^*)$$

is the confidence (probability) that the true value will lie in this range for the normal distribution, and t_p^* is defined similarly but for Student's t -distribution.

The variance of a particular estimated new value of \hat{y} (for input vector \mathbf{x}) is given by

$$(14) \quad \text{Var}(y) = \mathbf{x}^T \cdot \Sigma \cdot \mathbf{x}$$

So, to work out the bounds on a given fit, use the covariance matrix thusly

$$(15) \quad \text{Var}(\hat{y}) = \text{diag}(\mathbf{X}\Sigma\mathbf{X}^T)$$

so the standard deviation is given by

$$(16) \quad \sigma_{\hat{y}} = \sqrt{\text{diag}(\mathbf{X}\Sigma\mathbf{X}^T)}$$

and the 100

$$(17) \quad \hat{y} \pm t_p^* \sigma_{\hat{y}}$$

which is a function of x .

In the case that you have two or more disjoint subsets of points $(\mathbf{X}_a, \mathbf{y}_a)$ and $(\mathbf{X}_b, \mathbf{y}_b)$ each with estimates for parameters β respectively of β_a and β_b - the correct way to combine these to form an overall estimate is the following

$$(18) \quad \mathbf{X}_{\text{tot}}^T \mathbf{X}_{\text{tot}} = \mathbf{X}_a^T \mathbf{X}_a + \mathbf{X}_b^T \mathbf{X}_b$$

$$(19) \quad \beta_{\text{total}} = (\mathbf{X}_{\text{tot}}^T \mathbf{X}_{\text{tot}})^{-1} (\mathbf{X}_a^T \mathbf{X}_a \beta_a + \mathbf{X}_b^T \mathbf{X}_b \beta_b)$$

Or for an arbitrary number

$$(20) \quad \mathbf{X}_{\text{tot}}^T \mathbf{X}_{\text{tot}} = \sum_i \mathbf{X}_i^T \mathbf{X}_i$$

$$(21) \quad \beta_{\text{total}} = (\mathbf{X}_{\text{tot}}^T \mathbf{X}_{\text{tot}})^{-1} \sum_i \mathbf{X}_i^T \mathbf{X}_i \beta_i$$

this has the advantage of saving and or computing with only $p \times p$ symmetric matrices, where p is the number of parameters i.e. the length of β . So you only need to save $(p+2)p$ values. The computation of the inverse matrix will probably be the bottleneck and go as $\mathcal{O}(p^3)$.