Mek4100 Two-scale perturbation methods

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Motivation

- A number of problems inherit several temporal or spatial scales
- Example: Boundary layer problem; albeit here the rapid scale is only present in the boundary layer
- Several global scales ⇒ a new method is required
- Linear, homogeneous equations: WKB(J) is an alternative

Example 1: damped oscillation

ODE with initial conditions

$$\frac{\mathrm{d}^2 y}{\mathrm{d}t^2} + \epsilon \frac{\mathrm{d}y}{\mathrm{d}t} + y = 0; \quad y(0) = 1, \quad \frac{\mathrm{d}y(0)}{\mathrm{d}t} = 0, \tag{1}$$

 ϵ – small parameter.

Physical interpretation: weak resistance force proportional to the velocity

Direct (naive) perturbation

$$y = y_0 + \epsilon y_1 + \epsilon^2 y_2 + \Rightarrow$$

$O(\epsilon^0)$

$$\frac{\mathrm{d}^2 y_0}{\mathrm{d}t^2} + y_0 = 0,$$

$$\begin{split} \frac{\mathrm{d}^2 y_0}{\mathrm{d}t^2} + y_0 &= 0, \\ y_0(0) &= 1, \quad \frac{\mathrm{d}y_0(0)}{\mathrm{d}t} = 0. \end{split}$$

Solution:

$$y_0 = \cos t$$

$\mathsf{O}(\epsilon^1)$

$$\frac{\mathrm{d}^2 y_1}{\mathrm{d}t^2} + y_1 = -\frac{\mathrm{d}y_0}{\mathrm{d}t} = \sin t,$$

$$y_1(0)=\frac{\mathrm{d}y_1(0)}{\mathrm{d}t}=0.$$

Resonance (secular terms) \Rightarrow

$$y_1 = \frac{1}{2}(\sin t - t\cos t).$$

Breakdown due to

Effect of small resistance accumulates. Exact solution (presented later) implies $y \to 0$ as $t \to \infty$

Hence, $\epsilon y_1 \approx y - y_0$ must be comparable to y_0

Poincare-Lindsted: not applicable, why?



Introduction of a slow time variable

New time

$$\tau = \epsilon t$$
,

is introduced in addition to the fast time t. Hence

$$y=y(t,\tau),$$

which is defined in in the quadrant $[t \ge 0] \times [\tau \ge 0]$ as if t and τ were independent.

Much redundancy: only the line $\tau = \epsilon t$ has direct significance.

Temporal derivatives transform

$$\frac{\mathrm{d}}{\mathrm{d}t} = \frac{\partial}{\partial t} + \epsilon \frac{\partial}{\partial \tau}, \quad \frac{\mathrm{d}^2}{\mathrm{d}t^2} = \frac{\partial^2}{\partial t^2} + 2\epsilon \frac{\partial^2}{\partial t \partial \tau} + \epsilon^2 \frac{\partial^2}{\partial \tau^2}.$$



The transformed problem

Damped oscillation equation in terms of t and au yields PDE

$$\frac{\partial^2 y}{\partial t^2} + y + \epsilon \left(2 \frac{\partial^2 y}{\partial t \partial \tau} + \frac{\partial y}{\partial t}\right) + \epsilon^2 \left(\frac{\partial^2 y}{\partial \tau^2} + \frac{\partial y}{\partial \tau}\right) = 0;$$
$$y(0,0) = 1, \quad \frac{\partial y(0,0)}{\partial t} + \epsilon \frac{\partial y(0,0)}{\partial \tau} = 0.$$

Considerations

- f 0 t and au are not "really" independent, but Solution of the PDE provides solution for ODE Physical effects behind scales may sometimes be conceived as independent
- ② Anyway, an ODE for a PDE; good bargain? Yes, as long as we can solve the PDE



Two-scale perturbation

The series

$$y = y_0(t, \tau) + \epsilon y_1(t, \tau) + ...,$$

$O(\epsilon^0)$

$$\frac{\partial^2 y_0}{\partial t^2} + y_0 = 0; \quad y_0(0,0) = 1, \quad \frac{\partial y_0(0,0)}{\partial t} = 0.$$

The solution for y_0 becomes

$$y_0 = A_0(\tau)\cos t + B_0(\tau)\sin t$$
, $A_0(0) = 1$, $B_0(0) = 0$

 A_0 , B_0 must be determined to the next order.



 (ϵ^1)

$$\frac{\partial^2 y_1}{\partial t^2} + y_1 = -\frac{\partial y_0}{\partial t} - 2\frac{\partial^2 y_0}{\partial t \partial \tau}$$

$$= (A_0 + 2\frac{\mathrm{d}A_0}{\mathrm{d}\tau})\sin t - (B_0 + 2\frac{\mathrm{d}B_0}{\mathrm{d}\tau})\cos t;$$

$$y_1(0,0) = 0$$
, $\frac{\partial y_1(0,0)}{\partial t} = -\frac{\partial y_0(0,0)}{\partial \tau}$.

Avoid secular terms \Rightarrow

$$A_0 + 2\frac{\mathrm{d}A_0}{\mathrm{d}\tau} = B_0 + 2\frac{\mathrm{d}B_0}{\mathrm{d}\tau} = 0.$$

$O(\epsilon^1)$, cont.

Initial conditions for A_0 , $B_0 \Rightarrow$

$$A_0 = e^{-\frac{1}{2}\tau}, \quad B_0 = 0.$$

No particular solution to $O(\epsilon)$:

$$y_1 = A_1(\tau)\cos t + B_1(\tau)\sin t$$
, $A_1(0) = 0$, $B_1(0) = \frac{1}{2}$

Complete solution

$$y = e^{-\frac{1}{2}\epsilon t}\cos t + \epsilon (A_1(\epsilon t)\cos t + B_1(\epsilon t)\sin t) + O(\epsilon^2).$$

! ϵ^2 : secular terms appear; can be eliminated by in troducing $\tau_1 = \epsilon^2 t$.



Comparing with exact solution

Exact

$$y = e^{-\frac{1}{2}\epsilon t} \left(\cos \omega t + \frac{\epsilon}{2\omega} \sin \omega t \right),$$

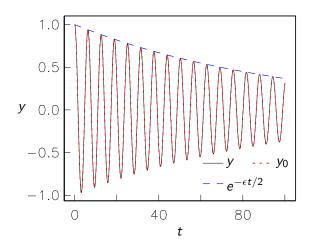
where $\omega = \sqrt{1 - \frac{1}{4}\epsilon^2} = 1 + O(\epsilon)^2$.

Two-scale approximation

$$y = e^{-\frac{1}{2}\epsilon t}\cos t + \epsilon (A_1(\epsilon t)\cos t + B_1(\epsilon t)\sin t) + O(\epsilon^2).$$

The two solutions agree, including the initial condition $B_1(0)=\frac{1}{2}.$

Graphical comparison, $\epsilon = 0.02$.



Example 2: nonlinear oscillations

Scaled equation

$$\frac{\mathrm{d}^2 x}{\mathrm{d}t^2} + x - \frac{\epsilon}{6}x^3 = 0, \quad x(0) = 1, \frac{\mathrm{d}x(0)}{\mathrm{d}t} = 0.$$

Poincare-Lindsted

We seek a periodic solution with frequency $\omega = \omega_0 + \epsilon \omega_1 + ...$

Two-scale method

We regard ϵt a slow time scale that modulates the phase.



Two-scale expansion, nonlinear pendulum

Invoke $\tau = \epsilon t$

$$\frac{\partial^2 x}{\partial t^2} + x + \epsilon \left(2 \frac{\partial^2 x}{\partial t \partial \tau} - \frac{1}{6} x^3 \right) + \epsilon^2 \frac{\partial^2 x}{\partial \tau^2} = 0;$$

$$x(0,0) = 1, \quad \frac{\partial x(0,0)}{\partial t} + \epsilon \frac{\partial x(0,0)}{\partial \tau} = 0.$$

Perturbation series

$$x = x_0(t,\tau) + \epsilon x_1(t,\tau) + ...,$$

 ϵ^0

$$\frac{\partial^2 x_0}{\partial t^2} + x_0 = 0; \quad x_0(0,0) = 1, \quad \frac{\partial x_0(0,0)}{\partial t} = 0.$$

Exponential form \Rightarrow

$$x_0 = A_0(\tau)e^{it} + \overline{A}_0(\tau)e^{-it}, \quad A_0(0) = \frac{1}{2},$$

where $\overline{A_0}$ is the complex conjugate of A_0 .

 ϵ^1

$$\frac{\partial^2 x_1}{\partial t^2} + x_1 = \frac{1}{6} x_0^3 - 2 \frac{\partial^2 x_0}{\partial t \partial \tau}$$
$$= \frac{1}{6} A_0^3 e^{3it} + \left(-2i \frac{\mathrm{d} A_0}{\mathrm{d} \tau} + \frac{1}{2} \overline{A}_0 A_0^2 \right) e^{it} + \mathrm{c.c.},$$

$$x_1(0,0) = 0,$$

$$\frac{\partial x_1(0,0)}{\partial t} = -\frac{\partial x_0(0,0)}{\partial \tau},$$
 (2)

where c.c. indicates the addition of the complex conjugate.

Annihilation of secular terms⇒

$$i\frac{\mathrm{d}A_0}{\mathrm{d}\tau} - \frac{1}{4}\overline{A}_0 A_0^2 = 0.$$

ϵ^1 , cont.

From previous slide

$$i\frac{\mathrm{d}A_0}{\mathrm{d}\tau} - \frac{1}{4}\overline{A}_0 A_0^2 = 0.$$

Insertion of $A_0 = |A_0|e^{i\psi} \Rightarrow$

$$\frac{\mathrm{d}|A_0|}{\mathrm{d}\tau} = 0, \quad \frac{\mathrm{d}\psi}{\mathrm{d}\tau} = -\frac{1}{4}|A_0|^2,$$

Initial condition $A_0(0) = \frac{1}{2} \Rightarrow$

$$A_0 = \frac{1}{2}e^{-\frac{i}{16}\tau}$$

Then, initial conditions \Rightarrow

$$x_1 = -\frac{A_0^3}{48}e^{3it} + A_1(\tau)e^{it} + \text{c.c..}, \quad A_1(0) = \frac{1}{384}$$

The two leading orders combined

$$x = \frac{1}{2}e^{i(1-\frac{\epsilon}{16})t} - \frac{\epsilon}{384}e^{3i(1-\frac{\epsilon}{16})t} + \epsilon A_1(\tau)e^{it} + \text{c.c.} + O(\epsilon^2)$$

$$= \cos(1-\frac{\epsilon}{16})t - \frac{\epsilon}{192}\cos 3(1-\frac{\epsilon}{16})t + \epsilon A_1(\epsilon^2)$$

$$+\epsilon A_1(\epsilon^2)\cos t - \epsilon A_1(\epsilon^2)\sin t + O(\epsilon^2),$$
(3)

where $A_1 = a_1 + ib_1$.

Can be verified by Poincare-Lindsted's method.

Example 3: Pendulum with prescribed length variation

Conservation of angular momentum (around support)

$$\ell\ddot{\phi} + 2\dot{\ell}\dot{\phi} + g\phi = 0,$$

 $\phi{=}\mathrm{excursion},~\ell{=}\mathrm{length}$ and the dot indicates derivation with respect to time.

Scaling

$$t = \sqrt{\frac{g}{\ell(0)}} t^*, \quad \gamma = \frac{\ell}{\ell(0)}, \quad \theta = \frac{\phi}{\phi_c}.$$

Slow scale, $\tau = \epsilon t$, describes change of γ (dimensionless length).

$$\gamma(\tau)\frac{\mathrm{d}^2\theta}{\mathrm{d}t^2} + 2\epsilon \frac{\mathrm{d}\gamma}{\mathrm{d}\tau} \frac{\mathrm{d}\theta}{\mathrm{d}t} + \theta = 0.$$



Attempt: direct application of two-scale method

PDE

$$\gamma(\tau)\frac{\partial^2 \theta}{\partial t^2} + \theta + 2\epsilon \left(\frac{\mathrm{d}\gamma}{\mathrm{d}\tau}\frac{\partial \theta}{\partial t} + \gamma \frac{\partial^2 \theta}{\partial t \partial \tau}\right) + \epsilon^2 \left(2\frac{\mathrm{d}\gamma}{\mathrm{d}\tau}\frac{\partial \theta}{\partial \tau} + \gamma \frac{\partial^2 \theta}{\partial \tau^2}\right) = 0.$$

Initial conditions (choice of ϕ_c)

$$\theta(0,0) = 1, \quad \frac{\partial \theta(0,0)}{\partial t} + \epsilon \frac{\partial \theta(0,0)}{\partial \tau} = 0.$$

Expansion $\theta = \theta_0(t, \tau) + \epsilon \theta_1(t, \tau) + ...$



Direct application..

$$\mathsf{O}(\epsilon^0)$$

$$\gamma \frac{\partial^2 \theta_0}{\partial t^2} + \theta_0 = 0; \quad \theta_0(0) = 1, \quad \frac{\partial \theta_0(0)}{\partial t} = 0.$$

solution

$$\theta_0 = A_0(\tau)e^{i\gamma^{-\frac{1}{2}}t} + \overline{A}_0e^{-i\gamma^{-\frac{1}{2}}t}, \quad A_0(0) = \frac{1}{2},$$

Direct application..

$O(\epsilon^1)$

$$\gamma \frac{\partial^2 \theta_1}{\partial t^2} + \theta_1 = h_s; \quad \theta_1(0,0) = 0, \quad \frac{\partial \theta_1(0,0)}{\partial t} = -\frac{\partial \theta_0}{\partial \tau},$$

where

$$h_{s} = -2\gamma \frac{\partial^{2} \theta_{0}}{\partial t \partial \tau} - 2 \frac{d\gamma}{d\tau} \frac{\partial \theta_{0}}{\partial t}$$

$$= -\left(2i\gamma^{\frac{1}{2}} \frac{dA_{0}}{d\tau} + i\gamma^{-\frac{1}{2}} A_{0} \frac{d\gamma}{d\tau} + 2tA_{0}\gamma^{-1} \frac{\partial\gamma}{\partial\tau}\right) e^{i\gamma^{-\frac{1}{2}}t} + \text{c.c.}$$

Appearance of $t \Rightarrow$ secular terms in θ_1 .

Reason for failure

The fast scale (period) is non-constant; it varies with τ .



Modified two-scale method; variable fast scale

Variable time scale (scale is fast, but it's variation is slow)

$$\frac{\mathrm{d}T}{\mathrm{d}t} = \sigma(\tau).$$

Transformation

$$\frac{\mathrm{d}}{\mathrm{d}t} = \sigma \frac{\partial}{\partial T} + \epsilon \frac{\partial}{\partial \tau},$$

$$\frac{\partial^2}{\partial \tau} = \frac{\mathrm{d}\sigma}{\partial \tau} \frac{\partial}{\partial \tau}$$

$$\frac{\mathrm{d}^2}{\mathrm{d}t^2} = \sigma^2 \frac{\partial^2}{\partial T^2} + \epsilon \left(2\sigma \frac{\partial^2}{\partial T \partial \tau} + \frac{\mathrm{d}\sigma}{\mathrm{d}\tau} \frac{\partial}{\partial T}\right) + \epsilon^2 \frac{\partial^2}{\partial \tau^2}.$$

We must choose (determine) σ as to avoid secular terms. Perturbation series

$$\theta = \theta(T, \tau) + \epsilon \theta_1(T, \tau) + \dots$$



PDE

$$\gamma \sigma^{2} \frac{\partial^{2} \theta}{\partial T^{2}} + \theta + \epsilon \left(2\sigma \frac{d\gamma}{d\tau} \frac{\partial \theta}{\partial T} + 2\sigma \gamma \frac{\partial^{2} \theta}{\partial T \partial \tau} + \gamma \frac{d\sigma}{d\tau} \frac{\partial \theta}{\partial T} \right)$$
$$+ \epsilon^{2} \left(2 \frac{d\gamma}{d\tau} \frac{\partial \theta}{\partial \tau} + \gamma \frac{\partial^{2} \theta}{\partial \tau^{2}} \right) = 0.$$

 $O(\epsilon^0)$

$$\gamma \sigma^2 \frac{\partial^2 \theta_0}{\partial T^2} + \theta_0 = 0; \quad \theta_0(0,0) = 1, \quad \frac{\partial \theta_0(0,0)}{\partial T} = 0.$$

In previous attempt τ appears explicitly in the exponent.

This can be avoided by $\sigma = \gamma^{-\frac{1}{2}} \Rightarrow$

$$\theta_0 = A_0(\tau)e^{iT} + \overline{A}_0(\tau)e^{-iT}, \quad A_0(0) = \frac{1}{2},$$



$\mathsf{O}(\epsilon^1)$

$$\frac{\partial^2 \theta_1}{\partial T^2} + \theta_1 \equiv h_s,$$

where

$$h_{s} = -2\sigma\gamma \frac{\partial^{2}\theta_{0}}{\partial T\partial \tau} - 2\sigma \frac{\mathrm{d}\gamma}{\mathrm{d}\tau} \frac{\partial\theta_{0}}{\partial T} - \gamma \frac{\mathrm{d}\sigma}{\mathrm{d}\tau} \frac{\partial\theta_{0}}{\partial T}$$

$$= -i\left(2\sigma\gamma \frac{\mathrm{d}A_{0}}{\mathrm{d}\tau} + 2\sigma A_{0} \frac{\mathrm{d}\gamma}{\mathrm{d}\tau} + \gamma \frac{\mathrm{d}\sigma}{\mathrm{d}\tau} A_{0}\right) e^{iT} + \mathrm{c.c.}$$

$$= -i\left(2\gamma^{\frac{1}{2}} \frac{\mathrm{d}A_{0}}{\mathrm{d}\tau} + \frac{3}{2}\gamma^{-\frac{1}{2}} A_{0} \frac{\mathrm{d}\gamma}{\mathrm{d}\tau}\right) e^{iT} + \mathrm{c.c.}$$

Annihilation of secular terms \Rightarrow coefficient of e^{iT} is zero \Rightarrow Separable equation (ODE) for A_0 and $A_0(0) = \frac{1}{2}$, $\gamma(0) = 1 \Rightarrow$

$$A_0 = \frac{1}{2} \gamma^{-\frac{3}{4}}$$



Physical note: wave action

Energy in pendulum motion : $E = E_s + E_\ell$

 E_{ℓ} : potential energy due to change in ℓ

 E_s : Energy due to the oscillations

$$E_s = \frac{1}{2}m\ell^2\dot{\phi}^2 + mg\ell(1-\cos\phi),$$

Small amplitude, scaling, invocation of two-scale solution $heta_0 \Rightarrow$

$$E_s = 2mg\ell_0\phi_c^2\gamma A_0^2(1+O(\epsilon)).$$

 E_s is not constant, but

Wave action

$$\frac{E_s}{\omega} \approx \text{const.}, \quad \omega = \sqrt{\frac{g}{\ell}}$$

is constant; general result for oscillations and waves in time dependent medium

