Generic geomorphic Hamiltonian

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Summary

The geomorphic Hamiltonian in Stark & Stark (2022) was derived from and equivalent to the Stream-Power Incision Model (SPIM). However, a more generic form for a geomorphic Hamiltonian can be derived using the same techniques. This notebook demonstrates this generality.

To get from an erosion equation to a geomorphic Hamiltonian, we need to make the following conceptual leaps:

- 1. accept that erosion takes place normal to the erosion surface
 - so the erosion equation should be written as an *erosion speed in the surface-normal direction*:
- 2. accept that the rate of motion of a surface is correctly expressed as a covector, aka a covariant rank-1 tensor, rather than as a vector, aka a contravariant rank-1 tensor
 - so the erosion equation should in fact be written as an *erosion slowness in the surface-normal direction*;
- 3. realize that by writing normal slowness as a function of local properties we actually have an eikonal, or static Hamilton-Jacobi equation
 - which means we have a geomorphic Hamiltonian.

Derivation

In 3-D or 2-D

Let's define a general equation for the speed of surface erosion ξ^{\perp} in the normal direction that is a function of the local surface angle(s) $\{\beta_k\}$ and position \mathbf{r} :

$$\xi^{\perp}(\{\beta_k\}, \mathbf{r}) = f\left(\{\tan \beta_k\}, \{r^i\}\right)$$
(1)

Here the curly brackets $\{\cdot\}$ mean a set of elements (indexed as appropriate), such as the set of local angles $\{\beta_k\}$, indexed by $k \in \{1,2\}$ in 3D and $k \in \{1\}$ in 2D.

Such an erosion model encompasses the SPIM, "granular flow hillslopes" (in the sense of Pauli & Gioia, 2007), and others. It assumes that nonlocal properties such as water volume flux are spatially constant properties that can be parameterized using r alone. It disallows, for example, changes in drainage network pattern or extent. It is essentially a static model, which is why we can convert it into a static Hamiltonian, and can rewrite it as an eikonal equation (a static Hamilton-Jacobi equation).

We recognize that surface erosion rate direction and magnitude are best expressed using the surface-normal erosion *slowness* covector \mathbf{p} . Surface erosion slowness is the reciprocal of surface erosion speed, and since erosion speed scalar is obtained from the erosion velocity vector (in Euclidean space) using the L_2 norm, we also use the L_2 norm (in Euclidean space) to measure the length of the slowness covector:

$$\|\mathbf{p}\|_{L_2} = \frac{1}{\xi^{\perp}} \tag{2}$$

We realize that trigonometric functions of local surface angles can all be written using $\{\tan \beta_i\}$ and that these tangent values can be written as ratios of slowness covector components:

$$\tan \beta_k = p_i/p_j$$
 for $i \neq j, i < j$ (3)

for appropriate choices of i, j, k.

Using Okubo's trick where all the surface erosion slowness covector components are scaled by a positive factor \mathcal{F}_* ,

$$\{p_i\} \to \left\{\frac{p_i}{\mathcal{F}_*}\right\} \tag{4}$$

substituted into the rate equation, the equation rearranged, and \mathcal{F}_* equated with the fundamental function, we get

$$\mathcal{F}_*(\mathbf{p}, \mathbf{r}) = \|\mathbf{p}\|_{L_2} f\left(\left\{\frac{p_i}{p_j}\right\}, \left\{r^k\right\}\right)$$
 (5)

where $\mathcal{F}_* = 1$, obviously. So we have the eikonal equation

$$\|\mathbf{p}\|_{L_2} = \frac{1}{f(\cdot, \cdot)} \tag{6}$$

which we could have obtained simply from the definition of $\|\mathbf{p}\|_{L_2}$ (eqn. 2), and which is equivalent to saying that

observed surface-normal erosion slowness =
$$\frac{1}{\text{required surface-normal erosion speed}}$$
 (7)

From the fundamental function we get the generic geomorphic Hamiltonian

$$\mathcal{H}(\mathbf{p}, \mathbf{r}) := \frac{1}{2} \|\mathbf{p}\|_{L_2}^2 f^2 \left(\left\{ \frac{p_i}{p_i} \right\}, \{r^k\} \right) = \frac{1}{2}$$
 (8)

Given how the Hamiltonian \mathcal{H} is constructed from \mathcal{F}_* , which was obtained by the Okubo substitution, it is inevitable that \mathcal{H} is Euler order-2 homogeneous in \mathbf{p} :

$$\mathcal{H}(\lambda \mathbf{p}, \mathbf{r}) = \frac{1}{2} \|\lambda \mathbf{p}\|_{L_2}^2 f^2 \left(\left\{ \frac{\lambda p_i}{\lambda p_i} \right\}, \left\{ r^k \right\} \right)$$
(9)

$$= \frac{1}{2}\lambda^2 \|\mathbf{p}\|_{L_2}^2 f^2\left(\left\{\frac{p_i}{p_i}\right\}, \left\{r^k\right\}\right)$$
 (10)

$$= \lambda^2 \mathcal{H}(\mathbf{p}, \mathbf{r}) \tag{11}$$

This order-2 homogeneity is *EXTREMELY IMPORTANT* because it's essentially the origin of all the interesting behaviour of the geomorphic Hamiltonian, such as the close correspondence with geometric optics, the conjugacy of slowness covector and velocity vector $\mathbf{p}(\mathbf{v}) = 1$, the amazing utility of the (semi-)metric tensor g, the parametric form of the geomorphic Lagrangian, the geodesic equation form of the Euler-Lagrange equations, and the consequent geodesic spray.

Hamilton's equations are given in the usual way:

$$v^{i} = \dot{r}^{i} = \frac{\mathrm{d}r^{i}}{\mathrm{d}t} = \frac{\partial \mathcal{H}}{\partial p_{i}} \tag{12}$$

$$\dot{p}_i = \frac{\mathrm{d}p_i}{\mathrm{d}t} = -\frac{\partial \mathcal{H}}{\partial r^i} \tag{13}$$

Simpler treatment in 2D (vertical section)

The above explanation is a bit abstract, so to make it more concrete here it is for 2D. Using the same coordinates x-z as Stark & Stark (2022), and having only one local angle to worry about (β), we write the erosion equation as:

$$\xi^{\perp}(\beta, \mathbf{r}) = f(\tan \beta, r^x, r^z) \tag{14}$$

We could just write the eikonal equation directly, given the definition of the surface-normal erosion slowness covector \mathbf{p} :

$$\|\mathbf{p}\|_{L_2} = \frac{1}{f(\tan\beta, \mathbf{r})} \tag{15}$$

or we can use the Okubo trick to obtain the fundamental function

$$\mathcal{F}_*(\mathbf{p}, \mathbf{r}) = \sqrt{p_x^2 + p_z^2} f\left(\frac{p_x}{p_z}, r^x, r^z\right)$$
(16)

where we know that $\mathcal{F}_* = 1$. The generic 2D geomorphic Hamiltonian is then defined in terms of \mathcal{F}_* as

$$\mathcal{H}(\mathbf{p},\mathbf{r}) := \frac{1}{2} \left(p_x^2 + p_z^2 \right) f^2 \left(\frac{p_x}{p_z}, r^x, r^z \right) = \frac{1}{2}$$

$$\tag{17}$$

Euler order-2 homogeneity for \mathcal{H} is inevitable given the manner in which \mathcal{F}_* was obtained

$$\mathcal{H}(\lambda \mathbf{p}, \mathbf{r}) = \frac{1}{2} (\lambda^2 p_x^2 + \lambda^2 p_z^2) f^2 \left(\frac{\lambda p_x}{\lambda p_z}, r^x, r^z\right)$$
(18)

$$= \frac{1}{2}\lambda^2(p_x^2 + p_z^2) f^2\left(\frac{p_x}{p_z}, r^x, r^z\right)$$
 (19)

$$= \lambda^2 \mathcal{H}(\mathbf{p}, \mathbf{r}) \tag{20}$$

Hamilton's equations are then:

$$v^{x} = \frac{\mathrm{d}r^{x}}{\mathrm{d}t} = \frac{\partial \mathcal{H}}{\partial p_{x}} = 2p_{x}f^{2}\left(\frac{p_{x}}{p_{z}}, r^{x}, r^{z}\right) + \left(p_{x}^{2} + p_{z}^{2}\right)f\left(\frac{p_{x}}{p_{z}}, r^{x}, r^{z}\right)\frac{\partial f}{\partial p_{x}}$$
(21)

$$v^{z} = \frac{\mathrm{d}r^{z}}{\mathrm{d}t} = \frac{\partial \mathcal{H}}{\partial p_{z}} = 2p_{z}f^{2}\left(\frac{p_{x}}{p_{z}}, r^{x}, r^{z}\right) + \left(p_{x}^{2} + p_{z}^{2}\right)f\left(\frac{p_{x}}{p_{z}}, r^{x}, r^{z}\right)\frac{\partial f}{\partial p_{z}}$$
(22)

$$\frac{\mathrm{d}p_x}{\mathrm{d}t} = -\frac{\partial \mathcal{H}}{\partial r^x} = -\left(p_x^2 + p_z^2\right) f\left(\frac{p_x}{p_z}, r^x, r^z\right) \frac{\partial f}{\partial r^x} \tag{23}$$

$$\frac{\mathrm{d}p_z}{\mathrm{d}t} = -\frac{\partial \mathcal{H}}{\partial r^z} = -\left(p_x^2 + p_z^2\right) f\left(\frac{p_x}{p_z}, r^x, r^z\right) \frac{\partial f}{\partial r^z} \tag{24}$$