```
# gerardo Herrera... svm (kernel radial "rbf") con 28k instacias de normal y recovering y
from google.colab import drive
drive.mount('/content/drive')

    Mounted at /content/drive

# This Python 3 environment comes with many helpful analytics libraries installed
# It is defined by the kaggle/python Docker image: https://github.com/kaggle/docker-python
# For example, here's several helpful packages to load
import numpy as np # linear algebra
import pandas as pd # data processing, CSV file I/O (e.g. pd.read_csv)
# Input data files are available in the read-only "../input/" directory
# For example, running this (by clicking run or pressing Shift+Enter) will list all files
import os
for dirname, _, filenames in os.walk('/kaggle/input'):
    for filename in filenames:
        print(os.path.join(dirname, filename))
# You can write up to 5GB to the current directory (/kaggle/working/) that gets preserved
# You can also write temporary files to /kaggle/temp/, but they won't be saved outside of
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
#matplotlib inline
#sensor77 = pd.read_csv('../input/vombas/sensor_procesado.csv')
#sensor77 = pd.read csv('../input/vombas-28955-balanced-25sensor/sensor2-ordenado status s
#sensor77 = pd.read_csv('../input/bombas-sensores-conocidos/sensor2.csv')
#sensor77 = pd.read csv('../input/10ks25/s25balanced10k.csv')
#sensor77 = pd.read_csv('../input/28k-s24-balan-vombas/sensor2-ordenado_status_sin_broken_
sensor77 = pd.read_csv('/content/drive/My Drive/datasets/sensor2-ordenado_status_sin_broke
cleanup nums = {"machine status":
                                      {"NORMAL": 0, "RECOVERING": 1, "BROKEN": 2}}
sensor77.replace(cleanup_nums, inplace=True)
print(sensor77.shape)
sensor77.head()
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```

(28002, 27)

|   | Unnamed:<br>0 | timestamp                  | sensor_00 | sensor_01 | sensor_02 | sensor_03 | sensor_04   | sens |
|---|---------------|----------------------------|-----------|-----------|-----------|-----------|-------------|------|
| 0 | 0             | 2018-04-<br>01<br>00:00:00 | 2.465394  | 47.09201  | 53.2118   | 46.310760 | 634375.0000 | 47   |
| 1 | 1             | 2018-04-<br>01<br>00:01:00 | 2.465394  | 47.09201  | 53.2118   | 46.310760 | 634375.0000 | 47   |
| 2 | 2             | 2018-04-<br>01<br>00:02:00 | 2.444734  | 47.35243  | 53.2118   | 46.397570 | 638.8889    | 48   |
| 3 | 3             | 2018-04-<br>01<br>00:03:00 | 2.460474  | 47.09201  | 53.1684   | 46.397568 | 628125.0000 | 48   |

sensor77.isnull()

| ₽ |       | Unnamed:<br>0 | timestamp | sensor_00 | sensor_01 | sensor_02 | sensor_03 | sensor_04 | S |
|---|-------|---------------|-----------|-----------|-----------|-----------|-----------|-----------|---|
|   | 0     | False         | False     | False     | False     | False     | False     | False     |   |
|   | 1     | False         | False     | False     | False     | False     | False     | False     |   |
|   | 2     | False         | False     | False     | False     | False     | False     | False     |   |
|   | 3     | False         | False     | False     | False     | False     | False     | False     |   |
|   | 4     | False         | False     | False     | False     | False     | False     | False     |   |
|   |       |               | •••       |           |           |           |           |           |   |
|   | 27997 | False         | False     | False     | False     | False     | False     | False     |   |
|   | 27998 | False         | False     | False     | False     | False     | False     | False     |   |
|   | 27999 | False         | False     | False     | False     | False     | False     | False     |   |
|   | 28000 | False         | False     | False     | False     | False     | False     | False     |   |
|   | 28001 | False         | False     | False     | False     | False     | False     | False     |   |

28002 rows × 27 columns

```
# sensor77.dropna()
```

sensor77.fillna(sensor77.mean(), inplace=True)

print(sensor77.shape)
sensor77.head()

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<sup>#</sup> sensor77.fillna(0, inplace=True)

(28002, 27)

|   | Unnamed:<br>0 | timestamp                  | sensor_00 | sensor_01 | sensor_02 | sensor_03 | sensor_04   | sens |
|---|---------------|----------------------------|-----------|-----------|-----------|-----------|-------------|------|
| 0 | 0             | 2018-04-<br>01<br>00:00:00 | 2.465394  | 47.09201  | 53.2118   | 46.310760 | 634375.0000 | 47   |
| 1 | 1             | 2018-04-<br>01<br>00:01:00 | 2.465394  | 47.09201  | 53.2118   | 46.310760 | 634375.0000 | 47   |
| 2 | 2             | 2018-04-<br>01<br>00:02:00 | 2.444734  | 47.35243  | 53.2118   | 46.397570 | 638.8889    | 48   |
| 3 | 3             | 2018-04-<br>01<br>00:03:00 | 2.460474  | 47.09201  | 53.1684   | 46.397568 | 628125.0000 | 48   |
| 4 | 4             | 2018-04-<br>01<br>00:04:00 | 2.445718  | 47.13541  | 53.2118   | 46.397568 | 636.4583    | 49   |

is\_NaN = sensor77.isnull()
row\_has\_NaN = is\_NaN.any(axis=1)
rows\_with\_NaN = sensor77[row\_has\_NaN]

print(rows\_with\_NaN)

Empty DataFrame
Columns: [Unnamed: 0, timestamp, sensor\_00, sensor\_01, sensor\_02, sensor\_03, sensor\_0
Index: []

#Show the number of missing (NAN, NaN, na) data for each column sensor77.isnull().sum()

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```
Unnamed: 0 0 timestamp 0 sensor_00 0 sensor_01 0 sensor_02 sensor_03 0 sensor_04 0 sensor_11 0
```

#sensor77.drop('sensor\_15', axis=1, inplace=True);
#sensor77.drop('sensor\_15', axis=1, inplace=True)

sensor\_19 ช

#sensor77.drop('sensor\_05', axis=1, inplace=True);sensor77.drop('sensor\_06', axis=1, inpla sensor\_22 0

#sensor77.drop('sensor\_07', axis=1, inplace=True);sensor77.drop('sensor\_08', axis=1, inplase=1, inplase=1, inplase=1, inplace=2, inplase=1, inplace=2, inplase=1, inplace=3, inp

#sensor77.drop('sensor\_09', axis=1, inplace=True);sensor77.drop('sensor\_10', axis=1, inpla sensor ש ש

#sensor77.drop('sensor\_12', axis=1, inplace=True);sensor77.drop('sensor\_13', axis=1, inpla sensor\_5ט טכ

#sensor77.drop('timestamp', axis=1, inplace=True)

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#sensor77.drop('Unnamed: 0', axis=1, inplace=True)

print(sensor77.shape)
sensor77.head()

## [→ (28002, 27)

|   | Unnamed:<br>0 | timestamp                  | sensor_00 | sensor_01 | sensor_02 | sensor_03 | sensor_04   | sens |
|---|---------------|----------------------------|-----------|-----------|-----------|-----------|-------------|------|
| 0 | 0             | 2018-04-<br>01<br>00:00:00 | 2.465394  | 47.09201  | 53.2118   | 46.310760 | 634375.0000 | 47   |
| 1 | 1             | 2018-04-<br>01<br>00:01:00 | 2.465394  | 47.09201  | 53.2118   | 46.310760 | 634375.0000 | 47   |
| 2 | 2             | 2018-04-<br>01<br>00:02:00 | 2.444734  | 47.35243  | 53.2118   | 46.397570 | 638.8889    | 48   |
| 3 | 3             | 2018-04-<br>01<br>00:03:00 | 2.460474  | 47.09201  | 53.1684   | 46.397568 | 628125.0000 | 48   |
| 4 | 4             | 2018-04-<br>01<br>00:04:00 | 2.445718  | 47.13541  | 53.2118   | 46.397568 | 636.4583    | 49   |

import time

```
X=sensor77[['sensor_00', 'sensor_01', 'sensor_02', 'sensor_03','sensor_04', 'sensor_11', '
#y=sensor['target'] # Labels
y=sensor77['machine_status'] # Labels
```

print(X.shape)
X.head()

## [→ (28002, 24)

|   | sensor_00 | sensor_01 | sensor_02 | sensor_03 | sensor_04   | sensor_11 | sensor_14   |   |
|---|-----------|-----------|-----------|-----------|-------------|-----------|-------------|---|
| 0 | 2.465394  | 47.09201  | 53.2118   | 46.310760 | 634375.0000 | 47.52422  | 419.5747    |   |
| 1 | 2.465394  | 47.09201  | 53.2118   | 46.310760 | 634375.0000 | 47.52422  | 419.5747    |   |
| 2 | 2.444734  | 47.35243  | 53.2118   | 46.397570 | 638.8889    | 48.17723  | 420848.0000 |   |
| 3 | 2.460474  | 47.09201  | 53.1684   | 46.397568 | 628125.0000 | 48.65607  | 420.7494    | 4 |
| 4 | 2.445718  | 47.13541  | 53.2118   | 46.397568 | 636.4583    | 49.06298  | 419.8926    |   |

```
# Scale the data to be between -1 and 1
from sklearn.preprocessing import StandardScaler
scaler = StandardScaler()
scaler.fit(X)
X = scaler.transform(X)
```

```
# no coorrer
#import time

#X_train=X
#start = time.time()
#X = sensor77.drop('machine_status', axis=1)
#y = sensor77['machine_status']

#from sklearn import preprocessing
#X_train = preprocessing.scale(X_train)
#X_test = preprocessing.scale(X_test)

#from sklearn.model_selection import train_test_split
#X_train, X_test, y_train, y_test = train_test_split(X, y, test_size = 0.20)

#from sklearn.preprocessing import MinMaxScaler
#scaling = MinMaxScaler(feature_range=(-1,1)).fit(X_train)
#X_train = scaling.transform(X_train)
#X_test = scaling.transform(X_test)
```

```
#from sklearn.svm import SVR
#from sklearn.grid_search import GridSearchCV
#svclassifier = SVR(kernel='linear')
#svclassifier.fit(X_train, y_train)
#from sklearn.svm import SVC
#svclassifier = SVC(kernel='linear')
#svclassifier.fit(X_train, y_train)
#stop = time.time()
#print(f"Training time: {stop - start}s")
start = time.time()
#X = sensor77.drop('machine_status', axis=1)
#y = sensor77['machine_status']
from sklearn.model_selection import train_test_split
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size = 0.20)
from sklearn.svm import SVC
svclassifier = SVC(kernel='rbf', random_state=0, gamma=.01, C=1)
svclassifier.fit(X_train, y_train)
stop = time.time()
print(f"Training time: {stop - start}s")
     Training time: 14.533451318740845s
y_pred = svclassifier.predict(X_test)
#Evaluacion
from sklearn.metrics import classification_report, confusion_matrix
print(confusion_matrix(y_test,y_pred))
print(classification_report(y_test,y_pred))
    [[2579 232]
 Гэ
      [ 565 2225]]
                   precision
                                recall f1-score
                                                   support
                        0.82
                                  0.92
                                            0.87
                                                       2811
                1
                        0.91
                                  0.80
                                            0.85
                                                       2790
                                            0.86
                                                       5601
         accuracy
                        0.86
                                  0.86
                                            0.86
                                                       5601
        macro avg
     weighted avg
                        0.86
                                  0.86
                                             0.86
                                                       5601
```

# validacion cruzada

from sklearn.model\_selection import cross\_validate

## # https://scikit-learn.org/stable/modules/cross validation.html

```
#start3 = time.time()
from sklearn import svm
from sklearn.model_selection import cross_val_score
start3 = time.time()
clf = svm.SVC(kernel='rbf', random_state=0, gamma=.01, C=1)
#scores = cross_val_score(clf, X, y, cv=5)
scores = cross_val_score(clf, X, y, cv=10)
scores
print(scores.mean())
stop3 = time.time()
print(f"CV Training time: {stop3 - start3}s")
     0.854941003213138
     CV Training time: 175.27739644050598s
#start3 = time.time()
from sklearn import svm
from sklearn.model_selection import cross_val_score
from sklearn.model_selection import cross_validate
start3 = time.time()
clf = svm.SVC(kernel='rbf', random_state=0, gamma=.1, C=1)
#scores = cross_val_score(clf, X, y, cv=5)
#scores = cross_val_score(clf, X, y, cv=10)
#cv = cross_val_score(clf, X, y, cv=10)
cv = cross_validate(clf, X, y, cv=10)
cv1 = cross_validate(clf, X, y, cv=10,scoring ='accuracy')
#scores
#cv
#print(scores.mean())
#print(cv.mean())
f1=cross_validate(clf, X,y, cv=10, scoring ='f1')
recall_score=cross_validate(clf, X,y, cv=10, scoring ='recall')
pre_score=cross_validate(clf, X,y, cv=10, scoring ='precision_macro')
print(confusion_matrix(y_test,y_pred))
print(f"precision_macro_score:")
print(pre_score['test_score'])
print(pre_score['test_score'].mean())
print(f"test_score:")
print(cv['test score'])
print(cv['test_score'].mean())
print(f"accu:")
print(cv1['test score'])
print(cv1['test_score'].mean())
print(f"recall:")
print(recall_score['test_score'])
print(recall_score['test_score'].mean())
print(f"f1score:")
print(f1['test_score'])
nrint(f1['test score'l_mean())
```

```
P. 1...(.1[ ccsc_sco.c ]....ca..(//
stop3 = time.time()
print(f"CV Training time: {stop3 - start3}s")
 □→ [[2579 232]
     [ 565 2225]]
     precision_macro_score:
     [0.88144615 0.84796086 0.89941654 0.91531037 0.9331989 0.94477786
      0.94581513 0.93750558 0.91862923 0.89742729]
     0.912148790685948
     test score:
     [0.87325955 0.82113531 0.88964286 0.90821429 0.92892857 0.94285714
      0.94428571 0.9375
                        0.91178571 0.89142857]
     0.9049037716121795
     accu:
     [0.87325955 0.82113531 0.88964286 0.90821429 0.92892857 0.94285714
                        0.91178571 0.89142857]
      0.94428571 0.9375
     0.9049037716121795
     recall:
     [0.8
                 0.68236974 0.81142857 0.84285714 0.87928571 0.91
      0.915
               0.93928571 0.84785714 0.83
                                                 ]
     0.8458084021617213
     f1score:
     [0.86319846 0.79237464 0.88027896 0.90179595 0.92521608 0.94091581
      0.94260486 0.93761141 0.90576116 0.88432268]
     0.8974079999777069
     CV Training time: 833.3704061508179s
# print(scores[])
#print(scores.mean())
#stop3 = time.time()
#print(f"CV Training time: {stop3 - start3}s")
```