

Using the deforisk QGIS plugin for making and comparing deforestation risk maps



Ghislain VIEILLEDENT¹ Thomas ARSOUZE¹ FAO team²

[1] Cirad UMR AMAP, [2] FAO Rome and Latin America



Outline

1 The deforisk QGIS plugin

- Aim and specificities
- Website and documentation
- Installation

2 Data preparation

- Get variables
- Forest cover change data
- Spatial explanatory variables

3 Models and validation

- Benchmark model
- Forestatrisk models
- Moving window models
- Validation

4 Usage

- Allocating deforestation
- Subnational jurisdictions
- User's data

5 Conclusion

- Workshop agenda
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Aims

- Provide a **tool** to create and compare **deforestation risk maps**.
 - At the **jurisdictional** level.
 - Following **Verra's methodology** for certification.
 - **Allocating deforestation** to projects within the jurisdiction.

Python based

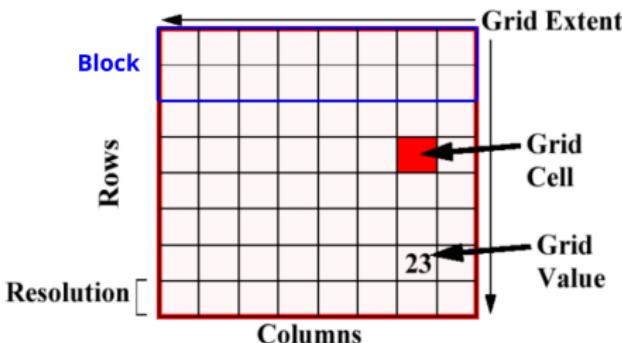
The deforisk plugin relies on four Python packages developed specifically for modelling deforestation :

- `geefcc` : make forest cover change maps from Google Earth Engine (GEE).
 - `pywdpa` : downloading protected areas from the World Database on Protected Areas (WDPA).
 - `forestatrisk` : model deforestation and predict the spatial deforestation.
 - `riskmapjnr` : risk maps following Verra JNR methodologies.



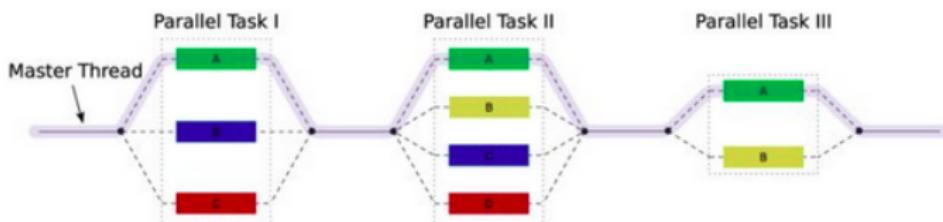
Processing raster by blocks

- Raster files of forest cover change and explanatory variables might occupy a space of several gigabytes on disk.
- Processing such large rasters in memory can be prohibitively intensive on computers with limited RAM.
- Functions used in the deforisk plugin process large rasters by blocks of pixels representing subsets of the raster data.
- This makes computation efficient, with low memory usage.



Running tasks in parallel

- State-of-the-art approach to select the best risk map implies repeating tasks (model, periods).
- To save computation time, the deforisk plugin use the QGIS task manager.
- Allows running several analysis in parallel.



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Website and documentation

The website includes all the documentation to use the plugin :

- **Installation page** : How to install the plugin ?
- **Plugin API page** : What is the meaning of each parameter ?
- **Get started page**. How to start using the plugin on a small area of interest ?
- **Articles' page**. How can I use the plugin for specific cases (subnational jurisdictions, user's data) ?
- **References' page** : A page with reference documents including presentations.

<https://deforisk-qgis-plugin.org>



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Installation

Reduced number of steps for installing the plugin :

- Install QGIS and GDAL on you system (using OSGeo4W on Windows).
- Install the `forestatrisk` and `riskmapjnr` Python packages using pip.
- **Download** and install the `deforisk` plugin from QGIS.
- (Unix-like systems only : install OSM tools).

The screenshot shows the official documentation for the `deforisk` QGIS plugin. At the top, there's a navigation bar with links for Home, Installation (which is underlined, indicating it's the current page), Get started, Articles, Plugin API, and More. To the right of the navigation is a search bar with a placeholder "Search" and a keyboard shortcut "Ctrl + K". There are also icons for GitHub and a green QGIS logo.

The main content area has a title "Installation". Below it is a "Note" box with a blue header containing a note icon and the word "Note". The text inside the box states:

Dependencies: [QGIS](#) and [GDAL](#) must be installed on your system before using the `deforisk` plugin. On Unix-like systems, you must also install [osmconvert](#) and [osmfilter](#). On Windows systems, these dependencies are already included in the plugin as binary `.exe` files so you don't need to install them. Then, the `forestatrisk` and `riskmapjnr` Python packages must be installed on your system. Follow the instructions below to install these dependencies.

To the right of the main content, there's a sidebar with a "On this page" section containing links to "On Windows", "On Unix-like systems (Linux and macOS)", "Access to GEE and WOPA", and "Installing the `deforisk` plugin in QGIS".

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Get variables

- Functions to help prepare the data for modelling deforestation.
- Two different sources for **forest cover change** (GFC or TMF).
- Spatial explanatory variables describing **forest accessibility** and **land tenure** (altitude, slope, distance to roads, protected areas, etc.).



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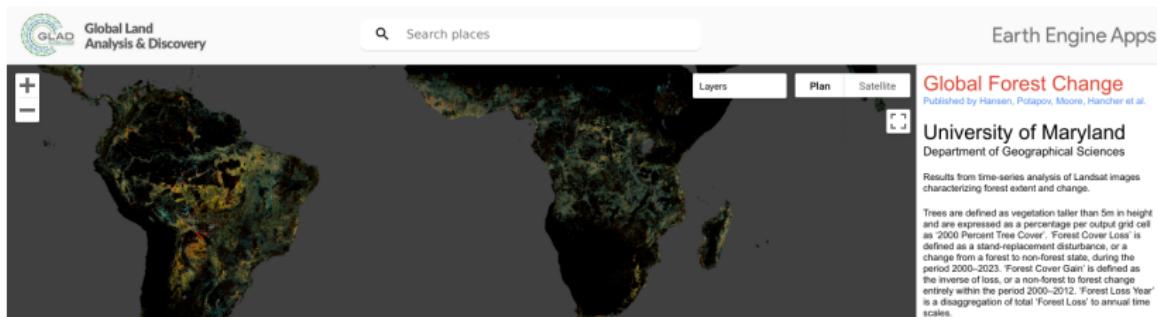
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GFC dataset

- Hansen et al. 2013.
- Global dataset encompassing all forest types.
- Tree cover and annual tree cover loss.
- 30m resolution, from 2000 on.
- Data : <https://glad.earthengine.app/view/global-forest-change>



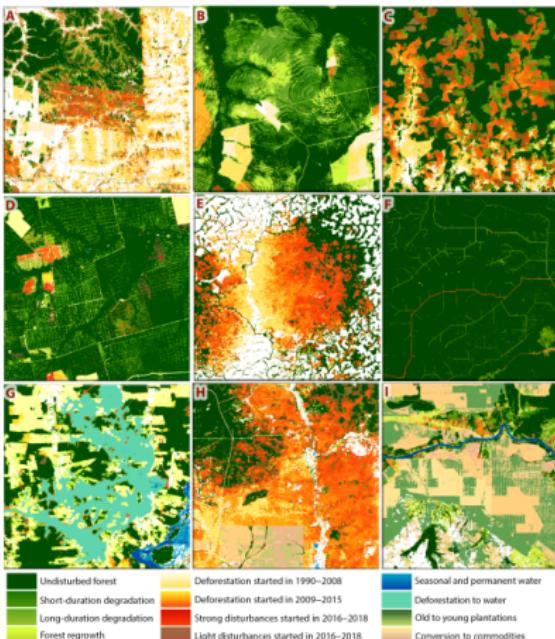
TMF dataset

- Vancutsem et al. 2021. Tropical Moist Forests (evergreen forest, no dry deciduous forests).
- 30m resolution, from 1990 on.
- Tropical deforestation was underestimated (-33% in 2000–2012, Hansen et al. 2013), especially in Africa.
- Data : <https://forobs.jrc.ec.europa.eu/TMF/>.



TMF dataset

- Precise enough to visually identify the causes of deforestation (logging, fires, agriculture)



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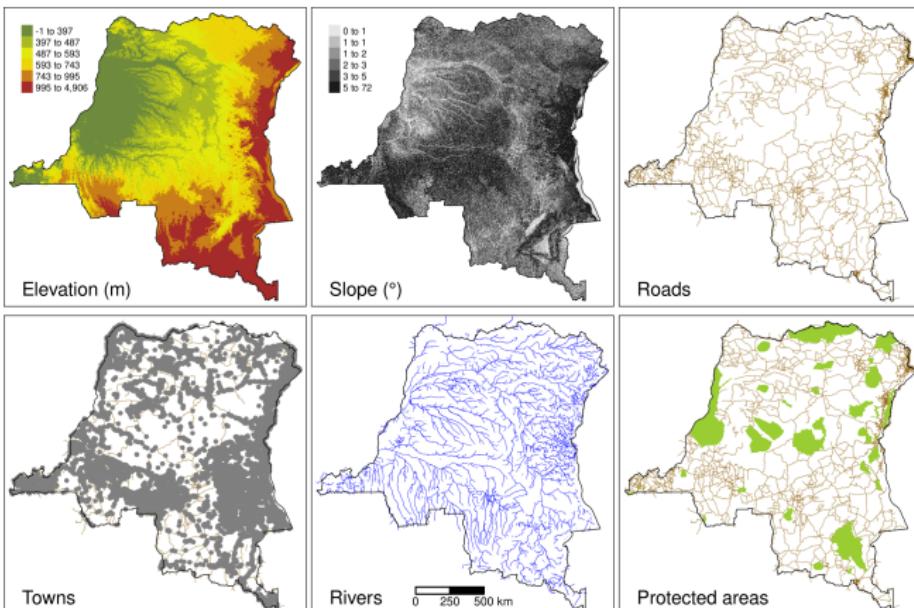
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Spatial variables

The plugin helps computing eight explanatory variables.

Product	Source	Variable derived	Unit	Resolution (m)	Date
Forest maps (2000-2010-2020)	Vancutsem et al. 2021	distance to forest edge	m	30	–
		distance to past deforestation	m	30	–
Digital Elevation Model	SRTM v4.1 CSI-CGIAR	elevation	m	90	–
Highways	OSM-Geofabrik	slope	degree	90	–
Places		distance to road	m	150	March 2021
Waterways	WDPA	distance to town	m	150	March 2021
Protected areas		distance to river	m	150	March 2021
		presence of protected area	–	30	March 2021

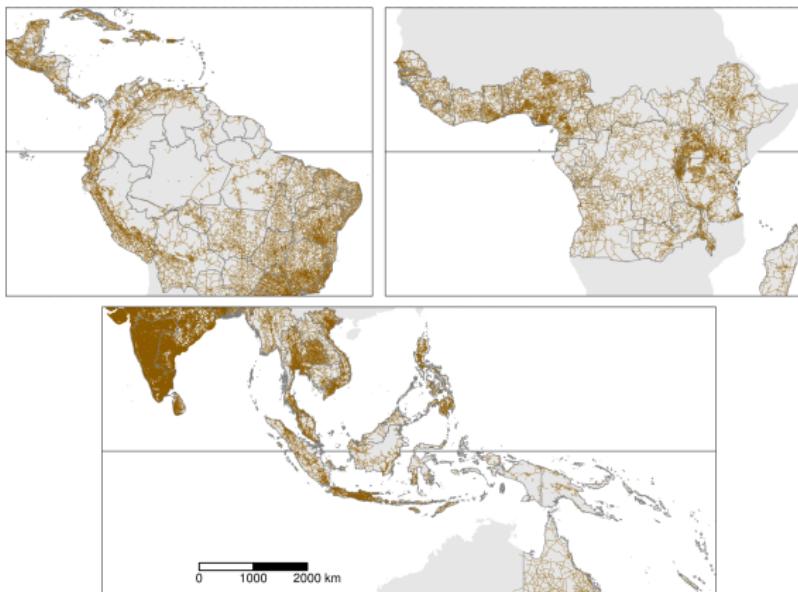
Spatial variables



Spatial explanatory variables in DRC

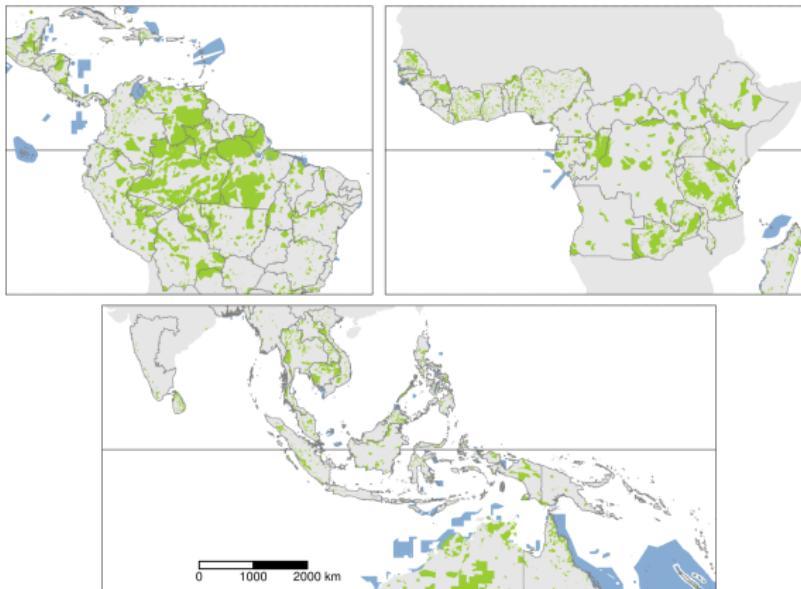
Roads

- OpenStreetMap (OSM)
- “motorway”, “trunk”, “primary”, “secondary” and “tertiary” roads
- 3.6 million roads from OSM



Protected areas

- PA status : “Designated”, “Inscribed”, “Established”, or “Proposed”.
- 85,000 protected areas from WDPA.



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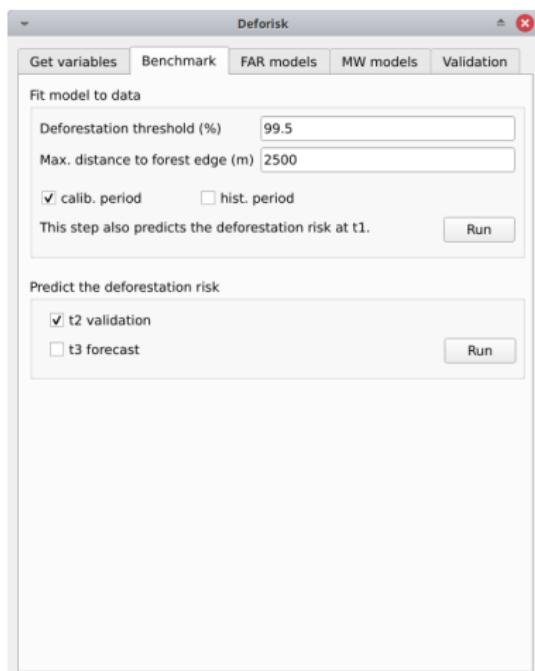
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Benchmark model

- Benchmark model or reference model.
- A reasonably good deforestation model (better than a null model).
- Assuming a *decrease of deforestation with distance to forest edge* (commonly admitted).
- And a *different model between subjurisdictions* (regional variability).
- See presentation **Cirad and FAO**. 2024. Jurisdictional risk maps for allocating deforestation.

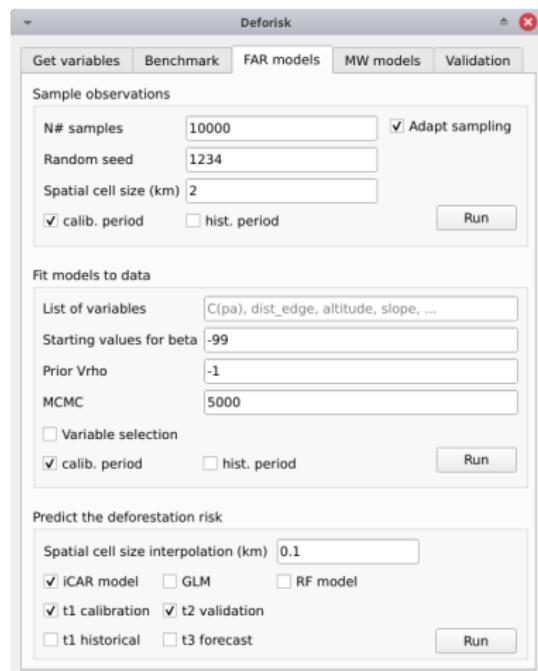


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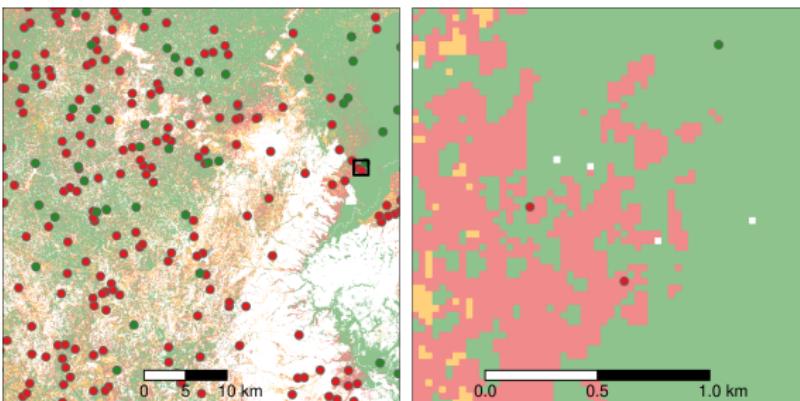
Forestatrisk models

- Three statistical models : iCAR, GLM, RF.
- iCAR : Logistic regression with spatial random effects (iCAR process).
- GLM : Generalized Linear Model, simple logistic regression (no random effects).
- Random Forest model : random regression trees.
- Statistical models based on a sample of the observations.



Sampling for FAR models

- We consider the forest cover change between t and $t + 1$.
- Stratified sampling between deforested/non-deforested pixels.
- Total number of points proportional to the forest cover (from 20,000 to 100,000 points per study area).



iCAR model

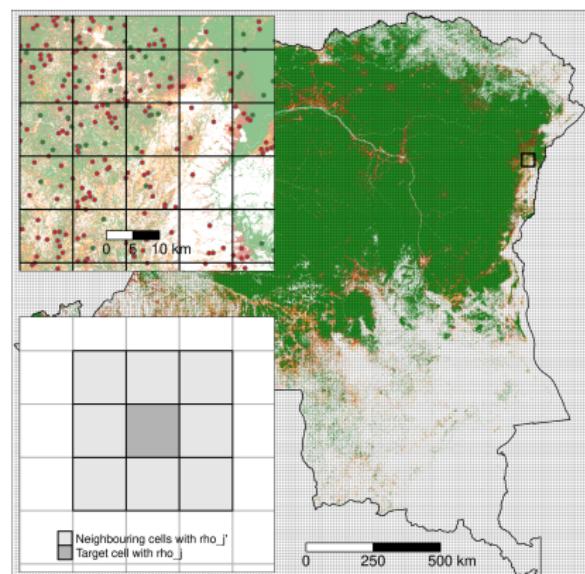
A logistic regression model with iCAR process :

$$y_i \sim \text{Bernoulli}(\theta_i)$$

$$\text{logit}(\theta_i) = \alpha + X_i\beta + \rho_{j(i)}$$

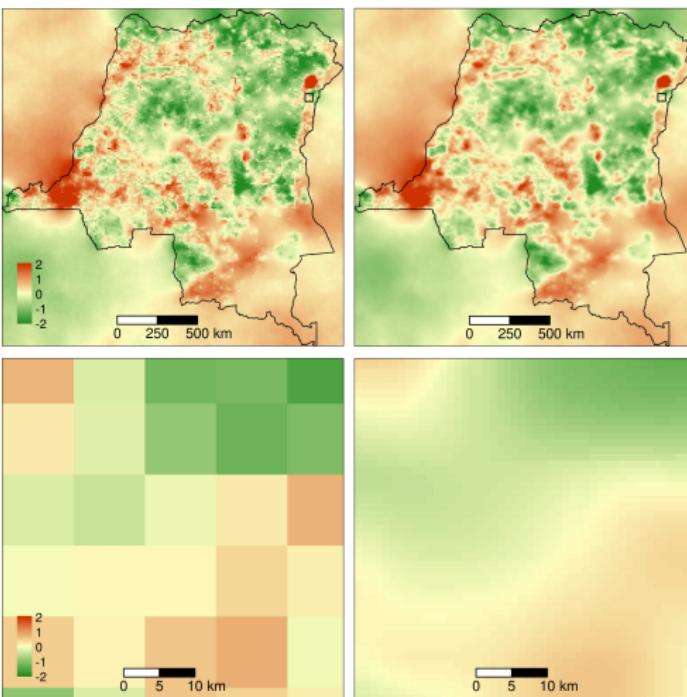
$$\rho_{j(i)} \sim \mathcal{N}ormal\left(\sum_{j'} \rho_{j'}/n_j, V_\rho/n_j\right)$$

Random effects $\rho_{j(i)}$ allows accounting for residual spatial variation not taken into account by model variables X_i .



Square grid of 10km cells over DRC

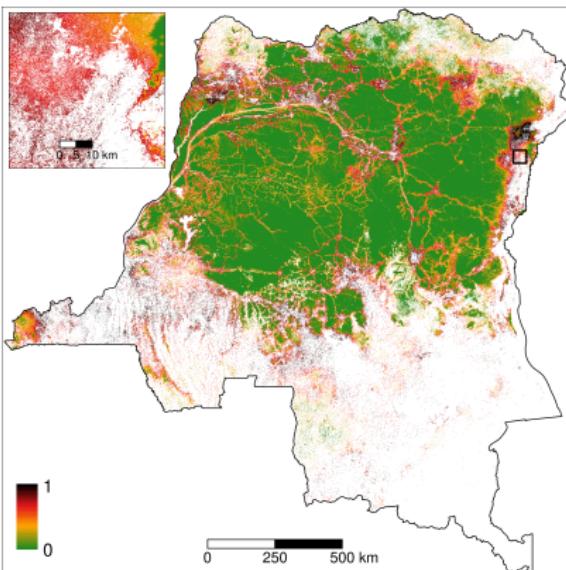
Spatial random effects



Interpolation of spatial random effects at 1km in DRC

Spatial probability of deforestation

- We use the fitted model to compute the spatial probability of deforestation.
- Probabilities in $[0, 1]$ are transformed into classes in $[1, 65535]$.



Relative spatial probability of deforestation in DRC

GLM model

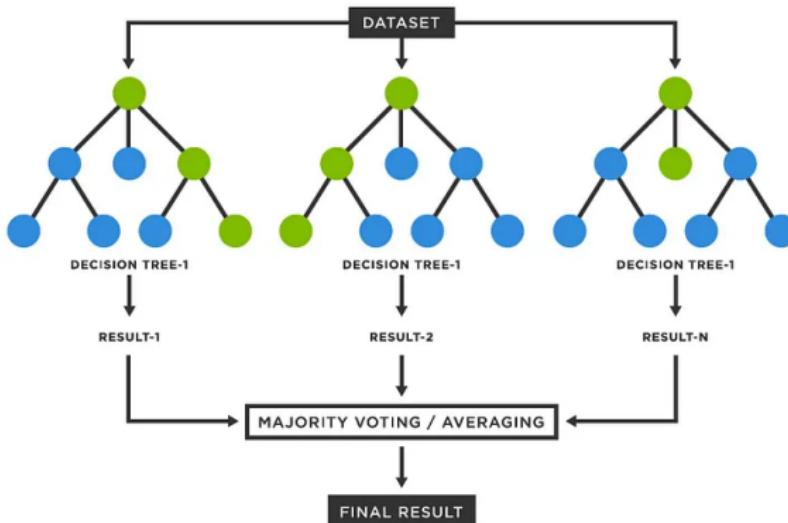
A simple logistic regression model without random effects :

$$\begin{aligned}y_i &\sim \text{Bernoulli}(\theta_i) \\ \text{logit}(\theta_i) &= \alpha + X_i\beta\end{aligned}$$

Easy to compare with iCAR to see the impact of spatial random effects.

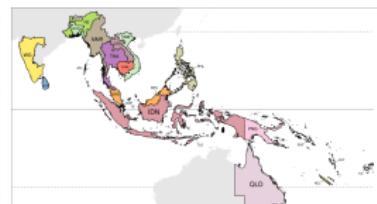
Random Forest model

- Random Forest is an ensemble machine learning algorithm.
- Combines multiple decision trees to create a more robust and accurate predictive model.



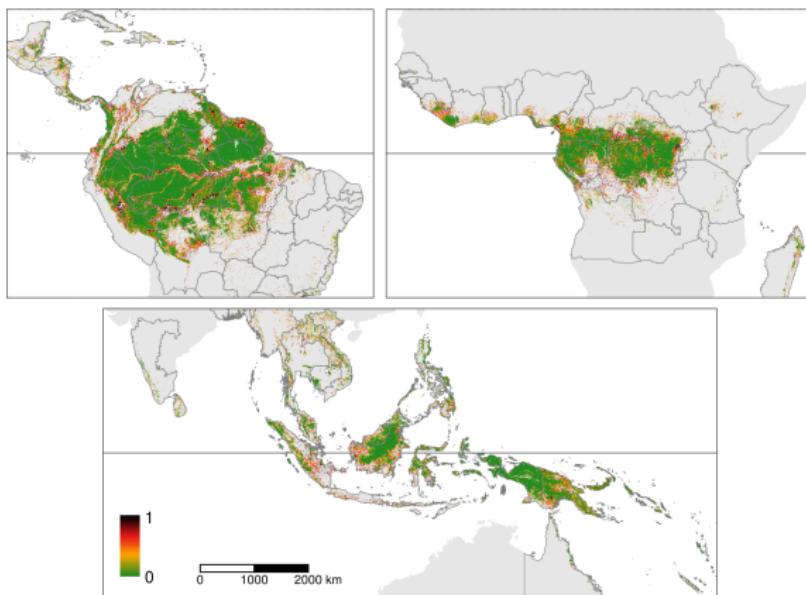
ForestAtRisk in the tropics

- i. Consider tropical moist forest in **92** countries (119 study areas)
- ii. Estimate the current deforestation rate and uncertainty in each country
- iii. Model the spatial risk of deforestation from environmental factors
- iv. Forecast the deforestation assuming a business-as-usual scenario
- v. Consequences in terms of carbon emissions



The 119 study areas in the 3 continents

ForestAtRisk in the tropics



Pantropical map of the spatial probability of deforestation
Article in review : [10.1101/2022.03.22.485306](https://doi.org/10.1101/2022.03.22.485306)
<https://forestatrisk.cirad.fr/maps.html>

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Moving window models

- Model proposed by previous Verra's methodology.
- Find a distance threshold to define class 1 for the deforestation risk (same thing as for the benchmark model).

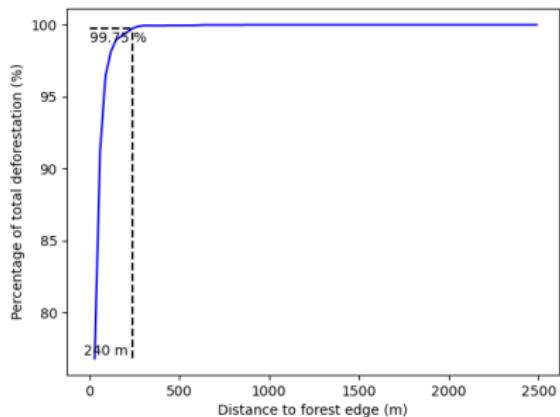


Figure – Cumulative deforestation as a function of the distance to forest edge.

Moving window models

- Compute a local risk of deforestation at the pixel level using a moving window.
- The moving window can be of different sizes.
- Deforestation rates in $[0, 1]$ are converted to $[2, 65535]$.

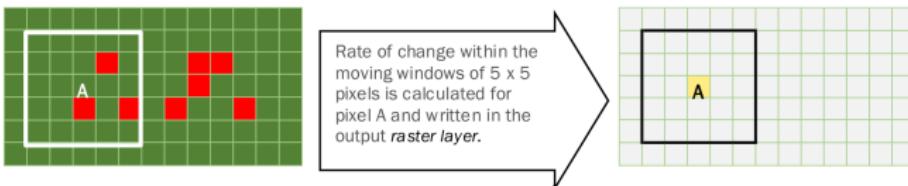


Figure – Moving window.

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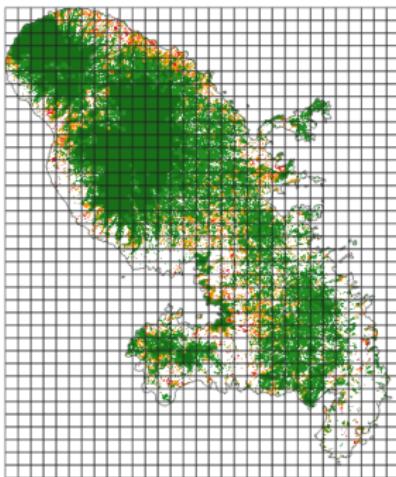
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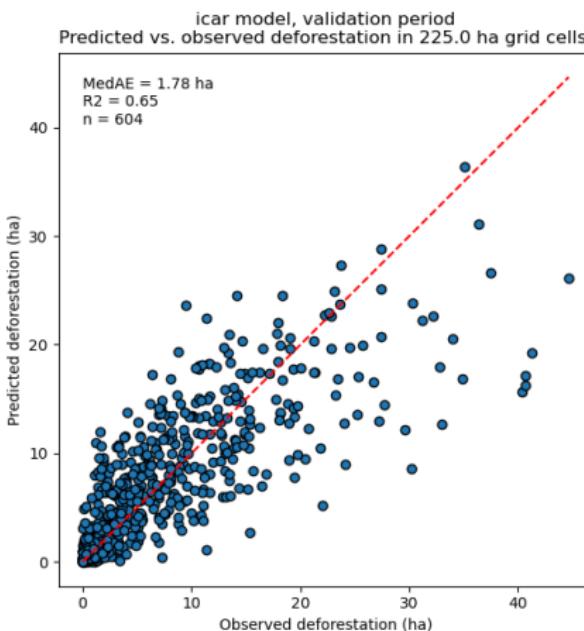
Validation

- Comparing predicted vs. observed deforestation (in ha) for each cell in a coarse grid.
- For a given period of time.



Validation

- Performance indices : R^2 , and median of absolute error (MedAE).
- Computed for each model and each period (calibration, validation, historical).



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Allocating deforestation

For the best model, we obtain at t3 :

- A jurisdictional map with classes of deforestation risk.
- A table with relative deforestation rates for each class.

Table – Deforestation rates at t3 for each class of deforestation risk (numbers truncated to three decimal digits).

cat	n_i	d_i	$\theta_{m,i}$	$\theta_{a,i}$	T	A	δ_i
1	137575	–	1.000e-06	–	–	0.09	–
2	5425	–	1.625e-05	–	–	0.09	–
3	3523	–	3.151e-05	–	–	0.09	–
4	2458	–	4.677e-05	–	–	0.09	–
5	2078	–	6.203	–	–	0.09	–

Allocating deforestation

Table – Deforestation rates at t3 for each class of deforestation risk (numbers truncated to three decimal digits).

cat	n_i	d_i	$\theta_{m,i}$	$\theta_{a,i}$	T	A	δ_i
1	137575	–	1.000e-06	–	–	0.09	–

- Considering a total **deforestation** D (in ha) for the next Y years at the jurisdictional level.
- Adjustment factor** is $\rho = D / (A \sum_i n_i \theta_{m,i})$, with A the pixel area in ha.
- Absolute rate** is $\theta_{a,i} = \rho \theta_{m,i}$: so that total predicted deforestation = expected deforestation.
- Deforestation density** is $\delta_i = \theta_{a,i} \times A / Y$. Used to predict the amount of deforestation (in ha/yr) for each forest pixel.

Allocating deforestation

Deforestation density is δ_i (in ha/yr) is used to predict the amount of deforestation for each forest pixel.

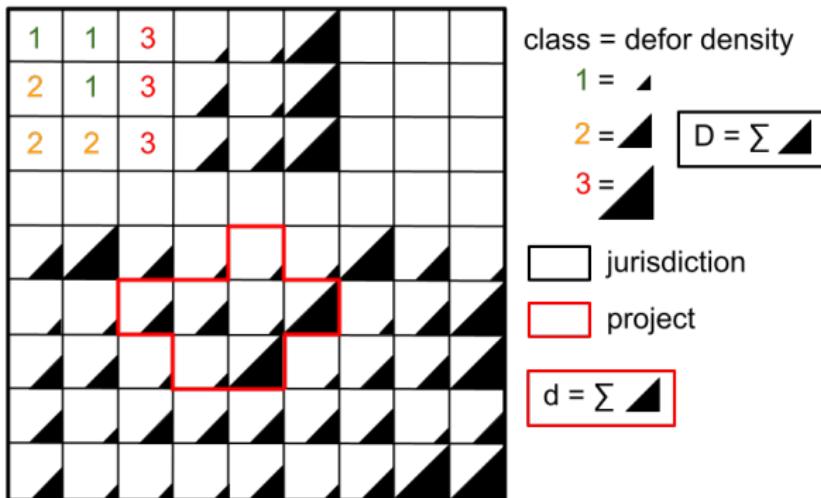


Figure – Allocating deforestation to projects within the jurisdiction.

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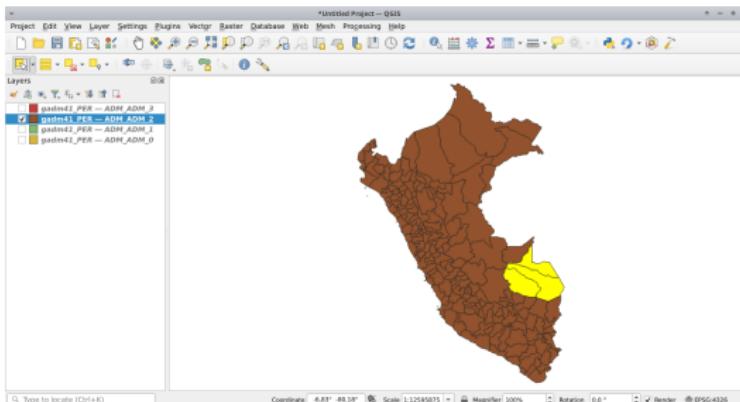
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Subnational jurisdictions

- Possibility to work with subnational jurisdictions.
- GPKG file named `aoi_latlon.gpkg` with two layers named `aoi` for the jurisdiction and `subj` for the subjurisdictions.
- This file can then be used with the `deforisk` plugin to define the area of interest (AOI).
- More details on the website page [Subnational jurisdictions](#).



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User's data

- Possibility to use user's data : national forest cover change map, other explanatory variables (e.g. mining concessions).
- Manual steps at the moment.
- Files in the data folder must be replaced with user's data.
- Additional raster variables can be added to the data folder.
- Symbolic links in `data_*` folders must exist.
- More details on the website page [User's data](#).

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Workshop agenda

Four practical sessions :

- Installing the software and run the Get Started tutorial.
- Choose a small subnational jurisdiction and select the best risk map.
- Derive the best risk map for a large jurisdiction (e.g. country scale).
- Exercises :
 - Change model parameters to see models' behavior (e.g. size of spatial cells for iCAR model).
 - Use country data (e.g. national forest cover change map).
 - Allocate future deforestation to a project.

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Perspectives

- Recent plugin (first version in July 2024).
- Improvements are expected :
 - Increase computational speed (for predictions on large areas).
 - Adding more alternative models (MLP).
- Modifications from users' feedback.



... Thank you for attention ...

<https://deforisk-qgis-plugin.org>

> Articles > References > Presentations



UK Government