

# Optimization methods

## Lecture 8: Introduction to stochastic gradient methods

Alexandr Katrutsa

Modern State of Artificial Intelligence Masters Program  
Moscow Institute of Physics and Technology

# Brief reminder of the previous lecture

- ▶ Conjugate gradient method
- ▶ Heavy-ball method
- ▶ Accelerated gradient method

# What do we know?

- ▶ Deterministic first-order methods

# What do we know?

- ▶ Deterministic first-order methods
- ▶ Fast methods for different classes of problems

# What do we know?

- ▶ Deterministic first-order methods
- ▶ Fast methods for different classes of problems

## Questions

- ▶ How the methods will change if the randomness will be introduced in problems?
- ▶ How to measure convergence in that case?

# Why do we need randomness?

- ▶ If the number of variables is huge, the explicit computing of the gradient can be hard

# Why do we need randomness?

- ▶ If the number of variables is huge, the explicit computing of the gradient can be hard
- ▶ Stochastic gradient estimate can be sufficient for solving problem at the appropriate level

# Why do we need randomness?

- ▶ If the number of variables is huge, the explicit computing of the gradient can be hard
- ▶ Stochastic gradient estimate can be sufficient for solving problem at the appropriate level
- ▶ Sometimes given parameters of the problem are inexact



## How the randomness can be introduced?

- ▶ The known data in the problem is random variables with known distributions

$$\begin{aligned} & \min x_1 + x_2 \\ \text{s.t. } & w_1 x_1 + x_2 \geq 0 \\ & w_2 x_1 + x_2 \geq 0 \\ & x_{1,2} \geq 0, \end{aligned}$$

where  $w_1 \sim \mathcal{U}[0, 4]$ ,  $w_2 \sim \mathcal{U}[2, 3]$

# How the randomness can be introduced?

- ▶ The known data in the problem is random variables with known distributions

$$\begin{aligned} & \min x_1 + x_2 \\ \text{s.t. } & w_1 x_1 + x_2 \geq 0 \\ & w_2 x_1 + x_2 \geq 0 \\ & x_{1,2} \geq 0, \end{aligned}$$

where  $w_1 \sim \mathcal{U}[0, 4]$ ,  $w_2 \sim \mathcal{U}[2, 3]$

- ▶ Objective function is an expected value of some other function

$$\min f(\mathbf{x}) := \mathbb{E}_\omega[F(\mathbf{x}, \omega)]$$

# How the randomness can be introduced?

- ▶ The known data in the problem is random variables with known distributions

$$\begin{aligned} \min \quad & x_1 + x_2 \\ \text{s.t.} \quad & w_1 x_1 + x_2 \geq 0 \\ & w_2 x_1 + x_2 \geq 0 \\ & x_{1,2} \geq 0, \end{aligned}$$

where  $w_1 \sim \mathcal{U}[0, 4]$ ,  $w_2 \sim \mathcal{U}[2, 3]$

- ▶ Objective function is an expected value of some other function

$$\min f(\mathbf{x}) := \mathbb{E}_\omega[F(\mathbf{x}, \omega)]$$

- ▶ A particular case

$$\min \frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x})$$

# SAA vs SA

- ▶ Stochastic approximation (SA)

# SAA vs SA

- ▶ Stochastic approximation (SA)
  - ▶ Generate  $\omega^k$  i.i.d.

# SAA vs SA

- ▶ Stochastic approximation (SA)
  - ▶ Generate  $\omega^k$  i.i.d.
  - ▶ Compute stochastic gradient  $G(\mathbf{x}, \omega^k)$

# SAA vs SA

- ▶ Stochastic approximation (SA)
  - ▶ Generate  $\omega^k$  i.i.d.
  - ▶ Compute stochastic gradient  $G(\mathbf{x}, \omega^k)$
  - ▶ Use it in stochastic gradient descent

# SAA vs SA

- ▶ Stochastic approximation (SA)
  - ▶ Generate  $\omega^k$  i.i.d.
  - ▶ Compute stochastic gradient  $G(\mathbf{x}, \omega^k)$
  - ▶ Use it in stochastic gradient descent
- ▶ Sample average approximation (SAA)



# SAA vs SA

- ▶ Stochastic approximation (SA)
  - ▶ Generate  $\omega^k$  i.i.d.
  - ▶ Compute stochastic gradient  $G(\mathbf{x}, \omega^k)$
  - ▶ Use it in stochastic gradient descent
- ▶ Sample average approximation (SAA)
  - ▶ Generate  $N$  samples  $\omega_1, \dots, \omega_N$

# SAA vs SA

- ▶ Stochastic approximation (SA)
  - ▶ Generate  $\omega^k$  i.i.d.
  - ▶ Compute stochastic gradient  $G(\mathbf{x}, \omega^k)$
  - ▶ Use it in stochastic gradient descent
- ▶ Sample average approximation (SAA)
  - ▶ Generate  $N$  samples  $\omega_1, \dots, \omega_N$
  - ▶ Compute estimate of the objective
$$\hat{f}_N(\mathbf{x}) = \frac{1}{N} \sum_{i=1}^N F(\mathbf{x}, \omega_i)$$

# SAA vs SA

- ▶ Stochastic approximation (SA)
  - ▶ Generate  $\omega^k$  i.i.d.
  - ▶ Compute stochastic gradient  $G(\mathbf{x}, \omega^k)$
  - ▶ Use it in stochastic gradient descent
- ▶ Sample average approximation (SAA)
  - ▶ Generate  $N$  samples  $\omega_1, \dots, \omega_N$
  - ▶ Compute estimate of the objective
$$\hat{f}_N(\mathbf{x}) = \frac{1}{N} \sum_{i=1}^N F(\mathbf{x}, \omega_i)$$
  - ▶ Minimize  $\hat{f}_N$  instead of the original function  $f$

# Problem statement

$$\min_{\mathbf{x} \in \mathbb{R}^n} \frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x})$$

- ▶  $f_i(\mathbf{x})$  may be nonconvex
- ▶  $n$  may be of the order  $10^6$  and higher
- ▶  $N$  is also may be huge

# Example 1

- ▶ Hutchinson trace estimator

$$\text{trace}(\mathbf{A}) = \text{trace}(\mathbf{A}\mathbf{I}) = \text{trace}(\mathbf{A}\mathbb{E}_{\mathbf{z}}\mathbf{z}\mathbf{z}^{\top}) = \mathbb{E}_{\mathbf{z}}(\mathbf{z}^{\top}\mathbf{A}\mathbf{z}),$$

where  $\mathbf{z}$  is a vector from standard normal distribution or from the Rademacher distribution

- ▶ Expected value is replaced with the unbiased estimate  $\hat{f}_N$  similar to SAA approach
- ▶ Minimize  $\hat{f}_N$  for fixed  $\mathbf{z}_i$

## Example 2

- ▶ Classification problem
- ▶ Loss function  $\ell$  is additive by the samples of the training set

$$\min_{\mathbf{w}} \frac{1}{N} \sum_{i=1}^N \ell(\mathbf{w} | \mathbf{x}_i)$$

- ▶ Interpretation as the empirical risk minimization or ground truth distribution approximation

# Stochastic gradient descent (SGD)

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \alpha_k \mathbf{h}_k,$$

where

- ▶  $\mathbf{h}_k = f'_{i_k}(x_k)$ ,  $i_k \in \{1, \dots, N\}$  is selected randomly
- ▶  $\mathbf{h}_k = \frac{1}{|\mathcal{I}_k|} \sum_{i \in \mathcal{I}_k} f'_i(\mathbf{x}_k)$ ,  $\mathcal{I}_k \subset \{1, \dots, N\}$  is some subset of indices usually of fixed size  $|\mathcal{I}_k| = m$

## Properties

1. Unbiased gradient estimate

$$\mathbb{E}[\mathbf{h}_k] = f'(\mathbf{x}_k)$$

2. Large variance

# Convergence

## Theorem

Let  $f$  be convex,  $L$ -smooth function. Then if SGD generates directions  $\mathbf{h}_k$  such that  $\text{Var}(\mathbf{h}_k) \leq \sigma^2$  and  $\alpha_k \leq \frac{1}{L}$  then

$$\mathbb{E}[f(\bar{\mathbf{x}}_k)] - f^* \leq \frac{\|\mathbf{x}_0 - \mathbf{x}^*\|_2^2}{\alpha_k k} + \frac{\alpha_k \sigma^2}{2}.$$

In particular, after  $k = \frac{(\sigma^2 + L\|\mathbf{x}^* - \mathbf{x}_0\|_2^2)^2}{\varepsilon^2}$  iterations if  $\alpha_k = \frac{1}{\sqrt{k}}$  we get the solution with accuracy  $2\varepsilon$ .



# General approach to variance reduction

- ▶ Assume  $X_\omega$  gives unbiased estimate of the parameter  $x$ :  
 $\mathbb{E}_\omega[X_\omega] = x$

# General approach to variance reduction

- ▶ Assume  $X_\omega$  gives unbiased estimate of the parameter  $x$ :  
 $\mathbb{E}_\omega[X_\omega] = x$
- ▶ Assume  $Z_\omega = X_\omega - Y_\omega$  such that  $\mathbb{E}_\omega[Y_\omega] \approx 0$

# General approach to variance reduction

- ▶ Assume  $X_\omega$  gives unbiased estimate of the parameter  $x$ :  
 $\mathbb{E}_\omega[X_\omega] = x$
- ▶ Assume  $Z_\omega = X_\omega - Y_\omega$  such that  $\mathbb{E}_\omega[Y_\omega] \approx 0$
- ▶ Then  $\mathbb{E}_\omega[X_\omega] = \mathbb{E}_\omega[Z_\omega] = x$

# General approach to variance reduction

- ▶ Assume  $X_\omega$  gives unbiased estimate of the parameter  $x$ :  
 $\mathbb{E}_\omega[X_\omega] = x$
- ▶ Assume  $Z_\omega = X_\omega - Y_\omega$  such that  $\mathbb{E}_\omega[Y_\omega] \approx 0$
- ▶ Then  $\mathbb{E}_\omega[X_\omega] = \mathbb{E}_\omega[Z_\omega] = x$
- ▶  $\text{Var}(Z_\omega) = \text{Var}(X_\omega) + \text{Var}(Y_\omega) - 2\text{Cov}(X_\omega, Y_\omega) \ll \text{Var}(X_\omega)$  if  $Y_\omega$  highly correlates with  $X_\omega$

# General approach to variance reduction

- ▶ Assume  $X_\omega$  gives unbiased estimate of the parameter  $x$ :  
 $\mathbb{E}_\omega[X_\omega] = x$
- ▶ Assume  $Z_\omega = X_\omega - Y_\omega$  such that  $\mathbb{E}_\omega[Y_\omega] \approx 0$
- ▶ Then  $\mathbb{E}_\omega[X_\omega] = \mathbb{E}_\omega[Z_\omega] = x$
- ▶  $\text{Var}(Z_\omega) = \text{Var}(X_\omega) + \text{Var}(Y_\omega) - 2\text{Cov}(X_\omega, Y_\omega) \ll \text{Var}(X_\omega)$  if  $Y_\omega$  highly correlates with  $X_\omega$

## The recipe to reduce the variance

Find the estimate  $Y$ , such that

1. Its expected value is close to 0
2. It highly correlates with given estimate  $X$

# Stochastic average gradient (Schmidt, Le Roux, Bach 2013)

- ▶ Initialization  $x_0$  and  $g_i^0 = x_0, i = \{1, \dots, N\}$
- ▶ In the  $k$ -th iteration, one selects some index  $i_k$  and updates  $g_{i_k}^k = f'_{i_k}(x_k)$
- ▶  $x_{k+1} = x_k - \alpha_k \frac{1}{N} \sum_{i=1}^N g_i^k$
- ▶ More convenient notation

$$x_{k+1} = x_k - \alpha_k \left( \frac{1}{N} g_{i_k}^{(k+1)} - \frac{1}{N} g_{i_k}^k + \frac{1}{N} \sum_{i=1}^N g_i^k \right)$$

## Variance reduction

- ▶  $X = g_{i_k}^{(k+1)}$  and  $\mathbb{E}_\omega[X] = f'(x_k)$
- ▶  $Y = g_{i_k}^k - \sum_{i=1}^N g_i^k$  and  $\mathbb{E}_\omega[Y] \neq 0$
- ▶  $\|X - Y\|_2 = \|(g_{i_k}^{(k+1)} - g_{i_k}^k) + \sum_{i=1}^N g_i^k\|_2 \rightarrow 0, k \rightarrow \infty$
- ▶ Variance of the result estimate goes to 0

# Convergence for convex and $L$ -smooth function

## Theorem

Let  $f_i$  be differentiable and  $L$ -smooth,  $\bar{x}^{(k)} = \frac{1}{k} \sum_{i=0}^{k-1} x_i$ ,  $\alpha_k = \frac{1}{16L}$  and initialization

$$g_i^0 = f'_i(x_0) - f'(x_0), \quad i = 1, \dots, N$$

gives

$$\mathbb{E}[f(\bar{x}^{(k)})] - f(x^*) \leq \frac{48n}{k}(f(x_0) - f^*) + \frac{128L}{k}\|x_0 - x^*\|_2^2$$



# Comparison

- ▶ SAG

$$\frac{48n}{k}(f(x_0) - f^*) + \frac{128L}{k}\|x_0 - x^*\|_2^2$$

The first item depends on  $n$ !

- ▶ GD

$$\frac{L\|x_0 - x^*\|_2^2}{k}$$

- ▶ SGD

$$\frac{\|x_0 - x^*\|_2^2 + \sigma^2}{2\sqrt{k}}$$

# Convergence for $L$ -smooth and $\mu$ -strongly convex function

## Theorem

If there are the same assumptions that were used in the theorem about convex  $L$ -smooth function, then the following estimate holds

$$\mathbb{E}[f(\bar{x}^{(k)})] - f(x^*) \leq \left(1 - \min \left\{ \frac{\mu}{16L}, \frac{1}{8n} \right\}\right)^k \left( \frac{3}{2}(f(x_0) - f^*) + \frac{4L}{n} \|x^* - x_0\|_2^2 \right)$$

- ▶ Adapt to the strong convexity
- ▶ Analogue of the SGD
- ▶ SGD gives only  $\mathcal{O}(1/\sqrt{k})$  convergence rate

# Remarks

- ▶ SAG requires careful tuning of settings
- ▶ Initial approximation is better to derive from one epoch of SGD and storing  $g_i^0$
- ▶ Choice of  $\alpha_k$

# SAGA (Defazio, Bach, Lacoste-Julien 2014)

The analogue of SAG, but

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \alpha_k \left( \mathbf{g}_{i_k}^{(k+1)} - \mathbf{g}_{i_k}^k + \frac{1}{N} \sum_{i=1}^N \mathbf{g}_i^k \right)$$

- ▶ Unbiased estimate:  $\mathbb{E}[Y] = 0$
- ▶ Variance is higher than in SAG
- ▶ The analysis of variance reduction is the same
- ▶ Can be generalized in the composite problems
- ▶ Convergence estimates are the same as they are for SAG
- ▶ Implementation details are the same as for SAG

# SVRG (Johnson, Zhang 2013)

- ▶ Initialization  $\bar{x}_0$
- ▶ For  $k = 1, 2, \dots$

- ▶  $\bar{x} = \bar{x}_0$
- ▶  $\bar{\mu} = f'(\bar{x})$
- ▶  $x_0 = \bar{x}_0$
- ▶ For  $m = 1, \dots, l$ 
  - ▶ Random choice of  $i_m \in \{1, \dots, N\}$
  - ▶

$$x_{m+1} = x_m - \alpha(f'_{i_m}(x_m) - f'_{i_m}(\bar{x}) + \bar{\mu})$$

- ▶  $\bar{x}_0 = x_l$

# Features of SVRG

- ▶ Analogue of SAGA
- ▶ The proof is simpler
- ▶ It depends on the number of epoch

# Drawbacks of variance reduction methods

- ▶ They require exact gradient computations
- ▶ They depend on other parameters
- ▶ No universal way to run them

# Summary

- ▶ Stochastic estimate of the gradient helps in many cases



# Summary

- ▶ Stochastic estimate of the gradient helps in many cases
- ▶ SGD and its properties

# Summary

- ▶ Stochastic estimate of the gradient helps in many cases
- ▶ SGD and its properties
- ▶ Variance reduction methods