

Optimization methods

Lecture 7: Introduction to stochastic gradient methods

Alexandr Katrutsa

Modern State of Artificial Intelligence Masters Program
Moscow Institute of Physics and Technology

Brief reminder of the previous lecture

- ▶ Conjugate gradient method
- ▶ Heavy-ball method
- ▶ Accelerated gradient method

What do we know?

- ▶ Deterministic first-order methods

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Questions

- ▶ How the methods will change if the randomness will be introduced in problems?
- ▶ How to measure convergence in that case?

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- ▶ Stochastic gradient estimate can be sufficient for solving problem at the appropriate level
- ▶ Sometimes given parameters of the problem are inexact

How the randomness can be introduced?

- ▶ The known data in the problem is random variables with known distributions

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- ▶ A particular case

$$\min \frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x})$$

Problem statement

$$\min_{\mathbf{x} \in \mathbb{R}^n} \frac{1}{N} \sum_{i=1}^N f_i(\mathbf{x})$$

- ▶ $f_i(\mathbf{x})$ may be nonconvex
- ▶ n may be of the order 10^6 and higher
- ▶ N is also may be huge

Example 1

- ▶ Hutchinson trace estimator

$$\text{trace}(\mathbf{A}) = \text{trace}(\mathbf{A}\mathbf{I}) = \text{trace}(\mathbf{A}\mathbb{E}_{\mathbf{z}}\mathbf{z}\mathbf{z}^{\top}) = \mathbb{E}_{\mathbf{z}}(\mathbf{z}^{\top}\mathbf{A}\mathbf{z}),$$

where \mathbf{z} is a vector from standard normal distribution or from the Rademacher distribution

- ▶ Expected value is replaced with the unbiased estimate \hat{f}_N
- ▶ Minimize \hat{f}_N for fixed \mathbf{z}_i

Example 2

- ▶ Classification problem
- ▶ Loss function ℓ is additive by the samples of the training set

$$\min_{\mathbf{w}} \frac{1}{N} \sum_{i=1}^N \ell(\mathbf{w} | \mathbf{x}_i)$$

- ▶ Interpretation as the empirical risk minimization or ground truth distribution approximation

Stochastic gradient descent (SGD)

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \alpha_k \mathbf{h}_k,$$

where

- ▶ $\mathbf{h}_k = f'_{i_k}(x_k)$, $i_k \in \{1, \dots, N\}$ is selected randomly
- ▶ $\mathbf{h}_k = \frac{1}{|\mathcal{I}_k|} \sum_{i \in \mathcal{I}_k} f'_i(\mathbf{x}_k)$, $\mathcal{I}_k \subset \{1, \dots, N\}$ is some subset of indices usually of fixed size $|\mathcal{I}_k| = m$

Properties

1. Unbiased gradient estimate

$$\mathbb{E}[\mathbf{h}_k] = f'(\mathbf{x}_k)$$

2. Large variance

Convergence

Theorem

Let f be convex, L -smooth function. Then if SGD generates directions \mathbf{h}_k such that $\text{Var}(\mathbf{h}_k) \leq \sigma^2$ and $\alpha_k \leq \frac{1}{L}$ then

$$\mathbb{E}[f(\bar{\mathbf{x}}_k)] - f^* \leq \frac{\|\mathbf{x}_0 - \mathbf{x}^*\|_2^2}{\alpha_k k} + \frac{\alpha_k \sigma^2}{2}.$$

In particular, after $k = \frac{(\sigma^2 + L\|\mathbf{x}^* - \mathbf{x}_0\|_2^2)^2}{\varepsilon^2}$ iterations if $\alpha_k = \frac{1}{\sqrt{k}}$ we get the solution with accuracy 2ε .

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- ▶ $\text{Var}(Z_\omega) = \text{Var}(X_\omega) + \text{Var}(Y_\omega) - 2\text{Cov}(X_\omega, Y_\omega) \ll \text{Var}(X_\omega)$ if Y_ω highly correlates with X_ω

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The recipe to reduce the variance

Find the estimate Y , such that

1. Its expected value is close to 0
2. It highly correlates with given estimate X

Stochastic average gradient (Schmidt, Le Roux, Bach 2013)

- ▶ Initialization x_0 and $g_i^0 = x_0, i = \{1, \dots, N\}$
- ▶ In the k -th iteration, one selects some index i_k and updates $g_{i_k}^k = f'_{i_k}(x_k)$
- ▶ $x_{k+1} = x_k - \alpha_k \frac{1}{N} \sum_{i=1}^N g_i^k$
- ▶ More convenient notation

$$x_{k+1} = x_k - \alpha_k \left(\frac{1}{N} g_{i_k}^{(k+1)} - \frac{1}{N} g_{i_k}^k + \frac{1}{N} \sum_{i=1}^N g_i^k \right)$$

Variance reduction

- ▶ $X = g_{i_k}^{(k+1)}$ and $\mathbb{E}_\omega[X] = f'(x_k)$
- ▶ $Y = g_{i_k}^k - \sum_{i=1}^N g_i^k$ and $\mathbb{E}_\omega[Y] \neq 0$
- ▶ $\|X - Y\|_2 = \|(g_{i_k}^{(k+1)} - g_{i_k}^k) + \sum_{i=1}^N g_i^k\|_2 \rightarrow 0, k \rightarrow \infty$
- ▶ Variance of the result estimate goes to 0

Convergence for convex and L -smooth function

Theorem

Let f_i be differentiable and L -smooth, $\bar{x}^{(k)} = \frac{1}{k} \sum_{i=0}^{k-1} x_i$, $\alpha_k = \frac{1}{16L}$ and initialization

$$g_i^0 = f'_i(x_0) - f'(x_0), \quad i = 1, \dots, N$$

gives

$$\mathbb{E}[f(\bar{x}^{(k)})] - f(x^*) \leq \frac{48n}{k}(f(x_0) - f^*) + \frac{128L}{k}\|x_0 - x^*\|_2^2$$

Comparison

- ▶ SAG

$$\frac{48n}{k}(f(x_0) - f^*) + \frac{128L}{k}\|x_0 - x^*\|_2^2$$

The first item depends on n !

- ▶ GD

$$\frac{L\|x_0 - x^*\|_2^2}{k}$$

- ▶ SGD

$$\frac{\|x_0 - x^*\|_2^2 + \sigma^2}{2\sqrt{k}}$$

Convergence for L -smooth and μ -strongly convex function

Theorem

If there are the same assumptions that were used in the theorem about convex L -smooth function, then the following estimate holds

$$\mathbb{E}[f(\bar{x}^{(k)})] - f(x^*) \leq \left(1 - \min \left\{ \frac{\mu}{16L}, \frac{1}{8n} \right\}\right)^k \left(\frac{3}{2}(f(x_0) - f^*) + \frac{4L}{n} \|x^* - x_0\|_2^2 \right)$$

- ▶ Adapt to the strong convexity
- ▶ Analogue of the SGD
- ▶ SGD gives only $\mathcal{O}(1/\sqrt{k})$ convergence rate

Remarks

- ▶ SAG requires careful tuning of settings
- ▶ Initial approximation is better to derive from one epoch of SGD and storing g_i^0
- ▶ Choice of α_k

SVRG (Johnson, Zhang 2013)

- ▶ Initialization \bar{x}_0
- ▶ For $k = 1, 2, \dots$

- ▶ $\bar{x} = \bar{x}_0$
- ▶ $\bar{\mu} = f'(\bar{x})$
- ▶ $x_0 = \bar{x}_0$
- ▶ For $m = 1, \dots, l$
 - ▶ Random choice of $i_m \in \{1, \dots, N\}$
 - ▶

$$x_{m+1} = x_m - \alpha(f'_{i_m}(x_m) - f'_{i_m}(\bar{x}) + \bar{\mu})$$

- ▶ $\bar{x}_0 = x_l$

Drawbacks of variance reduction methods

- ▶ They require exact gradient computations
- ▶ They depend on other parameters
- ▶ No universal way to run them

Adaptive stochastic gradient methods

- ▶ Acceleration with step size scaling
- ▶ Scaling based on the gradient norms — AdaGrad method
- ▶ Taking into account moving averaging of gradient values and variance estimate leads to celebrated Adam optimizer
- ▶ In more details these methods will discuss in the webinar

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- ▶ SGD and its properties
- ▶ Variance reduction methods
- ▶ Intro to adaptive step size stochastic methods