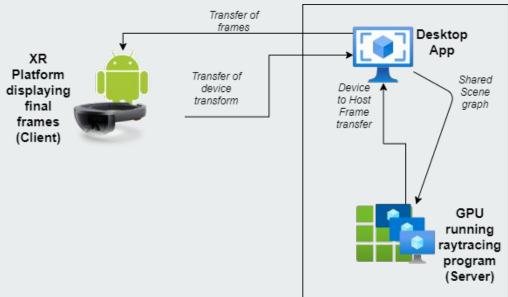
Remote Rendering for XR

By- Gizem Dal, Dayu Li, Tushar Purang



Source: HoloLens 2 Azure Remote Rendering in-action



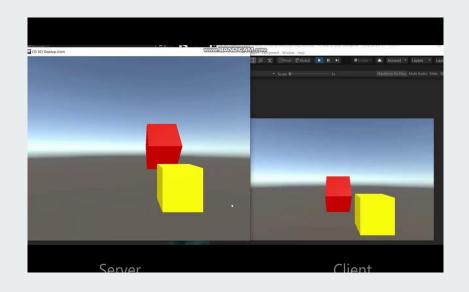
Project Overview

XR Application (Running on Android, Hololens, etc as Client) Desktop App requests frames Nvidia Optix with specified device transform Running on GPU **NVIDIA* OPTIX"** XR Platform sends Device data to Server RAY TRACING ENGINE Nvidia Optix saves frames from device memory to Desktop App sends frames to XR platform host memory for desktop app to access Desktop Application (Running on Laptop as Server)

Review: progress in milestone 1

Basic client/server video streaming & Nvidia optix ray tracing base code.





Overview: Milestone 2

Progress in project

- Obj & Mtl file parser
- OptiX Path Tracer sample enhancement
- Frame Streaming

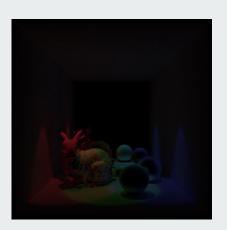
Researches and Studies

- Tiny Obj loader data structure & APIs.
- Mesh loading & Texture mapping in Optix.
- Hololens gesture & spatial mapping APIs.
- <u>Physically Based Rendering: From Theory to Implementation</u>

- Support for area, point and spot lights
- Support for diffuse, perfect specular (mirror), imperfect specular (glossy) and fresnel material
- Support for cube, icosphere and arbitrary meshes
- Russian roulette termination for light paths with less contribution
- Select a random light in scene for MIS







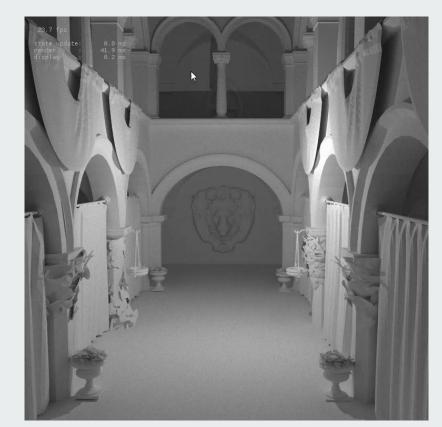
Stanford Bunny Mesh

Area lights

Point lights

Spot lights

- Arbitrary mesh loader for .obj file format based on the tinyOBJ loader.
- The mesh will be rendered as a whole with a specified material.



- Material parser for .mtl format
- The Wavefront Material Template Library (MTL)
 file is a companion file for one or more
 Wavefront OBJ files. It is a "library" that contains
 one or more material definitions, color, texture,
 and reflection characteristics.
- Areas that are in the same material will be rendered as an individual piece with the mtl parser.



- Streaming Raytracer frames via network
- Frames are stored in host memory
- Stored frames are sent from server (Laptop) to client platform (Android, Hololens etc.)
- Current latency (Raytracer to Android):
 1.5 sec (Nvidia Optix to Unity Server)
 + 0.5 sec (Unity Server to Unity Client)



Tasks planned for milestone 3

- Finish up texture mapping
- Synchronizing the camera control in Raytracer with head movement of the Hololens
- Modifying the Raytracer result with hand interaction and gestures.
- Raytracing with the spatial mapping obj
- Optimizing streaming.





Source: <u>Ingo Wald</u> OptiX7 course Source: Azure Remote Rendering + MRTK Demo Hololens 2

Schedule

Milestone 1 - Nov 18th:

Basic Desktop app (Control Panel) + Hololens app

+ GPU networking + basic realtime raytracer

Milestone 2 - Nov 30th:

- (Still in progress) Hybrid Rendering (Scene + UI)
- Real time ray tracing

+ Material parser + Texture mapping

Milestone 3 - Dec 7th:

- Optimizing streaming frame rate
- Late Stage Reprojection for Hololens
- Real time ray tracing in XR

Final - Dec 13:

- Bug fixings and optimizations
- Performance analysis

References

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