

# Breadth First Search

## 1. Algorithm Design

Def BFS ( $G, s$ )

for all vertices  $u$  in  $V$

$\text{dist}[u] = \infty$  # Initialize dist to  $\infty$

$\text{dist}[s] = 0$  # dist from source is 0.

$Q = \{s\}$  # Queue to keep track of nodes

while  $Q$  is not empty:

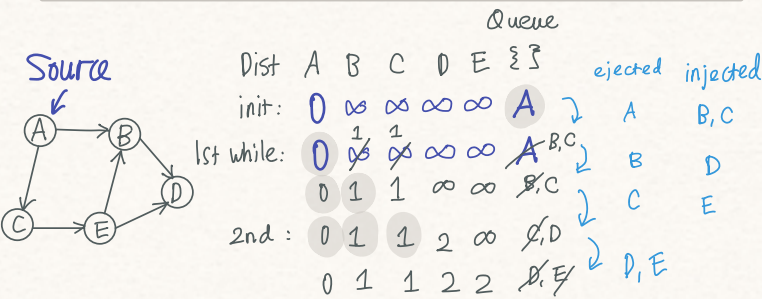
$u = \text{eject}(Q)$  # Assertion 1\*

for all neighbors  $v$  of  $u$

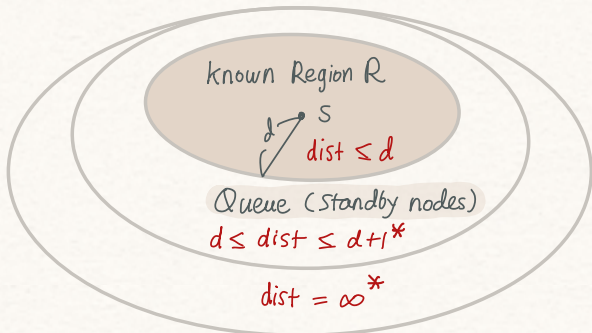
if  $\text{dist}[v] == \infty$

inject( $Q, v$ )

$\text{dist}(v) = \text{dist}(u) + 1$



## 3. Properties of BFS



At initialization,  $\text{dist} = \infty$  except for  $\text{dist}(\text{source}) = 0$

With the (standby) queue, closest nodes from  $s$  are pulled out. Once the distance is updated, it is final & correct value.

$\Rightarrow$  Time Complexity:  $O(n + e)$

## 2. Use Cases

To find shortest paths, DFS is not helpful

$\hookrightarrow$  path length can differ depending on which path to explore first.

$\Rightarrow$  Explore "shallow" nodes before "deeper" ones. Keep track of nodes to explore w/ FIFO queue.

## \* Dijkstra's Shortest Path w/ Edge Weight

Given edge length  $l(u, v)$ ,

keep track of nodes to explore using "Priority Queue"

$\hookrightarrow$  instead of  $\text{dist}(u) = \text{dist}(v) + 1$ , use "Relaxation"

Def DSP ( $G, s$ )

for all vertices  $u$  in  $V$

$\text{dist}[u] = \infty$  # Initialize dist to  $\infty$

$\text{dist}[s] = 0$  # dist from source is 0.

$H = \text{MakeHeap}(V)$  # Min Heap to keep track of nodes

while  $H$  is not empty:  $O(n)$

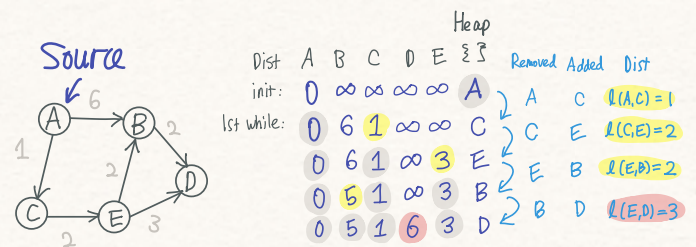
$u = \text{DeleteMin}(H)$   $O(\log n)$

for all neighbors  $v$  of  $u$

if  $\text{dist}[v] > \text{dist}[u] + l[u, v]$   $O(e)$

$\text{dist}[v] = \text{dist}[u] + l[u, v]$

$\text{DecreaseKey}(H, v)$   $O(\log n)$



$\Rightarrow$  Time Complexity:  $O(n \log n + e \log n)$