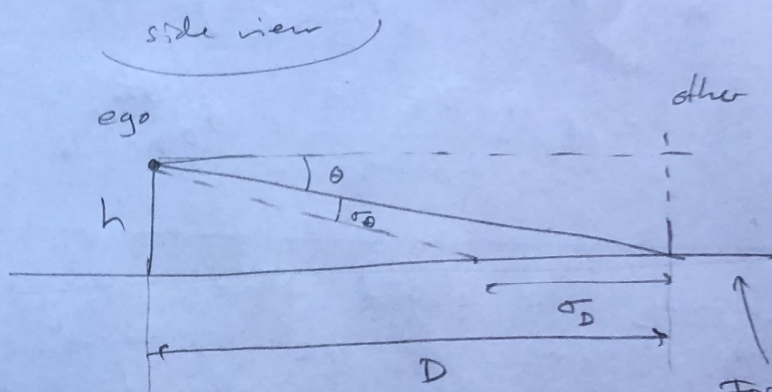
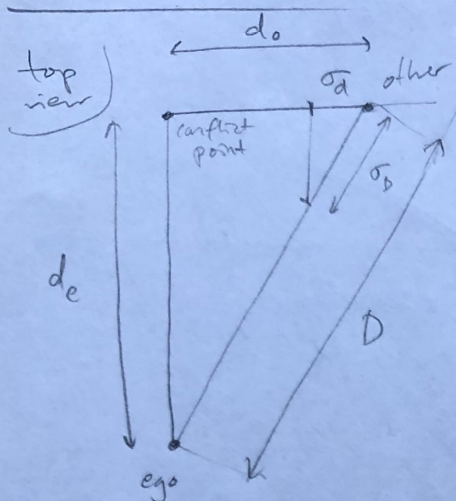


2021-11-02

Uncertainty in distance to conflict point,  
from uncertainty in angle over horizon



For simplicity  
we don't  
consider  
a separate  
 $\sigma_D$  on this  
side.

From the top view:

$$D = \sqrt{d_e^2 + d_o^2} \quad (1)$$

$$\frac{\sigma_d}{\sigma_D} = \frac{d_o}{D} \quad (2)$$

From the side view:

$$\theta = \arctan \frac{h}{D} \quad (3)$$

$$\tan(\theta + \sigma_\theta) = \frac{h}{D - \sigma_D}$$

$$\Leftrightarrow D - \sigma_D = \frac{h}{\tan(\theta + \sigma_\theta)}$$

$$\Leftrightarrow \sigma_D = D - \frac{h}{\tan(\theta + \sigma_\theta)} \quad (4)$$

$$= \{ (3) \} = D - \frac{h}{\tan(\arctan \frac{h}{D} + \sigma_\theta)} \quad (5)$$

$$(2) \Rightarrow \sigma_d = \frac{d_o}{D} \sigma_D = \{ (5) \} = \frac{d_o}{D} \left( D - \frac{h}{\tan(\arctan \frac{h}{D} + \sigma_\theta)} \right)$$

$$= d_o \left( 1 - \frac{h}{D \tan(\arctan \frac{h}{D} + \sigma_\theta)} \right)$$

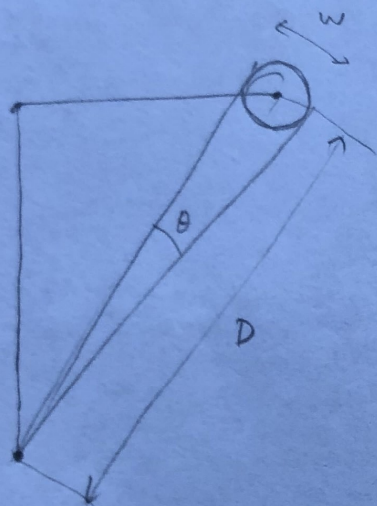


For small angles;  $h \ll D$  and  $\sigma_\theta$  small:

$$\sigma_d \approx d_0 \left( 1 - \frac{h}{D(\frac{h}{D} + \sigma_\theta)} \right) = d_0 \left( 1 - \frac{h}{h + D\sigma_\theta} \right)$$

$$= d_0 \frac{h + D\sigma_\theta - h}{h + D\sigma_\theta} = d_0 \frac{D\sigma_\theta}{h + D\sigma_\theta}$$

It may be noted that we get something very similar if we instead estimate positions based on optical size:



$$\tan \frac{\theta}{2} = \frac{w/2}{D}$$

If we now instead observe an optical angle  $\theta + \sigma_\theta$ , indicative of a smaller distance  $D - \sigma_D$ , we get:

$$\tan \frac{\theta + \sigma_\theta}{2} = \frac{w/2}{D - \sigma_D}$$

$$\Rightarrow D - \sigma_D = \frac{w/2}{\tan \frac{\theta + \sigma_\theta}{2}}$$

$$\Rightarrow \sigma_D = D - \frac{w/2}{\tan \frac{\theta + \sigma_\theta}{2}},$$

which is identical in form to (4) above.