

**A**

Snapshot payoffs

Affordance-based values

Own speed adjustment (a):

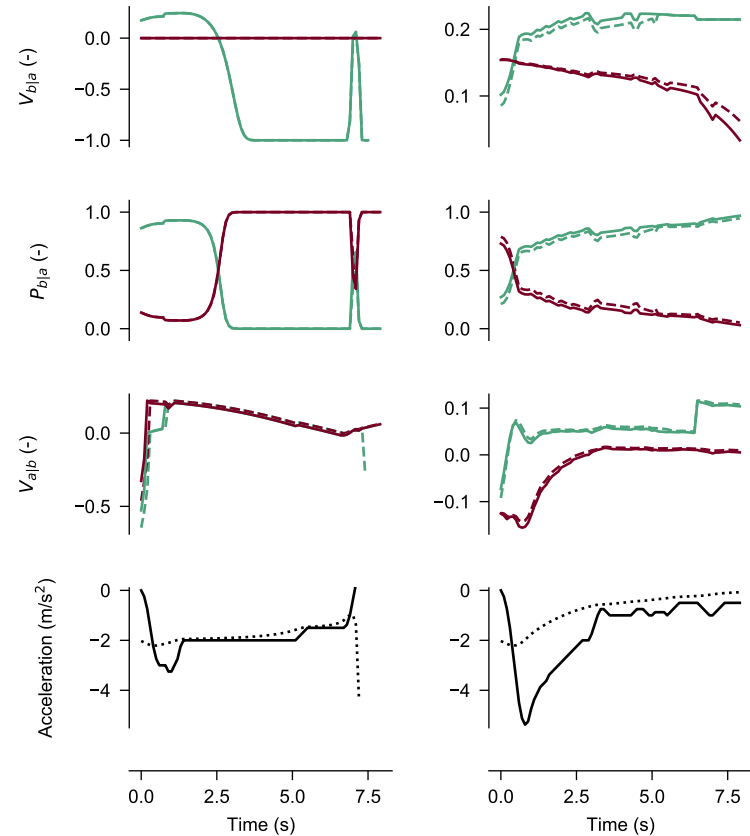
--- None

— Decelerate

Pedestrian's intended behavior (b):

— Pass first

— Pass second

**B**

Passing in front of yielding pedestrian

