spanny: mdspan

```
// Allocate the map
std::array map storage{...};
// Create a 2D view of the map
auto occupancy map = std::mdspan(map storage.data(), 384, 384);
// Update the map
for (std::size t i = 0; i != occupancy map.extent(0); <math>i++) {
    for (std::size t j = 0; j != occupancy map.extent(1); <math>j++) {
        occupancy_map[i, j] = get occupancy from laser scan(...)
```

spanny: policy injection

```
using bin_view =
std::mdspan<class T, class Extents, class LayoutPolicy, class Accessor>;
```

spanny: bin accessor

```
using bin view =
std::mdspan<class T, class Extents, class LayoutPolicy, bin checker>;
struct bin checker {
  using element type = bin state;
  using reference = std::future<bin state>;
  using data handle type = robot arm*;
  reference access(data handle type ptr, std::ptrdiff t offset) const {
    return std::async([=]{
      return bin state{ptr->is bin occupied(static cast<int>(offset)),
                       offset to coord(static cast<int>(offset))};
   });
```

spanny: bin layout

```
using bin view =
std::mdspan<class T, class Extents, bin layout, bin checker>;
struct bin layout {
  template <class Extents>
  struct mapping : stdex::layout right::mapping<Extents> {
    using base t = stdex::layout right::mapping<Extents>;
    using base t::base t;
    std::ptrdiff t operator()(auto... idxs) const {
      [&]<size t... Is>(std::index sequence<Is...>) {
        if (((idxs < 0 || idxs > this->extents().extent(Is)) || ...)) {
          throw std::out of range("Invalid bin index");
      }(std::make index sequence<sizeof...(idxs)>{});
      return this->base t::operator()(idxs...);
```

spanny: beer view

```
using bin view =
std::mdspan<bin_state, six pack, bin layout, bin checker>;
auto arm = robot arm{"/dev/ttyACM0", 9600};
auto bins = bin view(&arm);
while(true) {
 std::vector<std::future<bin state>> futures;
 for (auto i = 0u; i < bins.extent(0); ++i)
   for (auto j = 0u; j < bins.extent(1); ++j)
       futures.push back(bins(i, j));
 for (auto const& future : futures) future.wait();
 for (auto& future : futures) print state(future.get());
```

Demo Time

Thank you!

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