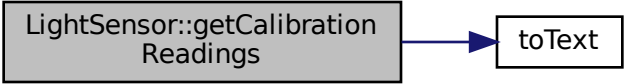


LightSensor::getCalibration
Readings



```
graph LR; A[LightSensor::getCalibrationReadings] --> B[toText]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The first box on the left is light gray with a black border and contains the text 'LightSensor::getCalibrationReadings' in two lines. A dark blue arrow points from the right side of this box to the left side of a second box on the right. The second box is white with a black border and contains the text 'toText'.

toText