

AeroModule::processCommand

HempyModule::processCommand

WaterPump::setSpeed

```
graph LR; A[AeroModule::processCommand] --> C[WaterPump::setSpeed]; B[HempyModule::processCommand] --> C;
```

The diagram illustrates a dependency or call relationship. On the left, two rectangular boxes are stacked vertically. The top box contains the text 'AeroModule::processCommand' and the bottom box contains 'HempyModule::processCommand'. Both boxes have black outlines and white backgrounds. On the right, there is a single rectangular box with a black outline and a light gray fill, containing the text 'WaterPump::setSpeed'. Two blue arrows originate from the right side of the left boxes and point towards the left side of the right box, indicating that both 'AeroModule::processCommand' and 'HempyModule::processCommand' call or depend on 'WaterPump::setSpeed'.