

DistanceSensor::getDistanceText



```
graph LR; A[DistanceSensor::getDistanceText] --> B[toText]; A --> C[toText_distance];
```

The diagram illustrates a method call. A gray rectangular box on the left contains the text "DistanceSensor::getDistanceText". Two blue arrows originate from the right side of this box. The top arrow points to a white rectangular box containing the text "toText". The bottom arrow points to a white rectangular box containing the text "toText_distance".

toText

toText_distance