

# 清华大学本科生考试试题专用纸

考试课程：操作系统（A 卷）

时间：2011 年 06 月 22 日下午 2:30~4:30

任课教师：\_\_\_\_\_ 系别：\_\_\_\_\_ 班级：\_\_\_\_\_ 学号：\_\_\_\_\_ 姓名：\_\_\_\_\_

答卷注意事项： 1. 在开始答题前，请在试题纸和答卷本上写明系别、班级、学号和姓名。

2. 在答卷本上答题时，要写明题号，不必抄题。

3. 答题时，要书写清楚和整洁。

4. 请注意回答所有试题。本试卷有 7 个题目，共 23 页。

5. 考试完毕，必须将试题纸和答卷本一起交回。

一、（20分）下面是与read()系统调用实现相关源代码。请补全其中所缺的代码，以正确完成从用户态函数read()到内核态函数sysfile\_read()的参数传递和返回过程。提示：每处需要补全的代码只需要一行，一共有10个空要填。

user/libs/file.c

```
-----  
...  
int  
read(int fd, void *base, size_t len) {  
    ...(1)...  
}  
...
```

user/libs/syscall.c

```
-----  
...  
#define MAX_ARGS 5  
  
static inline int  
syscall(int num, ...) {  
    int ret;  
    va_list ap;  
    va_start(ap, num);  
    uint32_t a[MAX_ARGS];  
    int i;  
    for (i = 0; i < MAX_ARGS; i++) {  
        a[i] = va_arg(ap, uint32_t);  
    }  
    va_end(ap);  
  
    asm volatile (  
        "int %1;"  
        : "=a" (ret)
```

```

        : "i" (T_SYSCALL),
        "a" (num),
        "d" (a[0]),
        "c" (a[1]),
        "b" (a[2]),
        "D" (a[3]),
        "S" (a[4])
        : "cc", "memory");

    return ret;
}
...
int
sys_read(int fd, void *base, size_t len) {
    ... (2) ...
}
...
-----
libs/stdlib.h
-----
...
typedef char * va_list;

#define
__va_size(type) \
    ((sizeof(type) + (sizeof(long) - 1)) / sizeof(long) * sizeof(long))

#define va_start(ap, last) \
    ((ap) = (va_list)&(last) + __va_size(last))

#define va_arg(ap, type) \
    (*(type *)((ap) += __va_size(type), (ap) - __va_size(type)))

#define va_end(ap) \
    ((void)0)
...
-----
libs/unistd.h
-----
...
#define T_SYSCALL \
    0x80

/* syscall number */
...
#define SYS_read \
    102
#define SYS_write \
    103
...

```

-----  
**kern/syscall/syscall.c**  
-----

...

```
struct trapframe {
    struct pushregs tf_regs;
    uint16_t tf_es;
    uint16_t tf_padding1;
    uint16_t tf_ds;
    uint16_t tf_padding2;
    uint32_t tf_trapno;
    /* below here defined by x86 hardware */
    uint32_t tf_err;
    uintptr_t tf_eip;
    uint16_t tf_cs;
    uint16_t tf_padding3;
    uint32_t tf_eflags;
    /* below here only when crossing rings, such as from user to kernel */
    uintptr_t tf_esp;
    uint16_t tf_ss;
    uint16_t tf_padding4;
};
...
```

-----  
**kern/trap/trap.c**  
-----

...

```
static void
trap_dispatch(struct trapframe *tf) {
    char c;

    int ret;

    switch (...(3)...) {
    case T_DEBUG:
    case T_BRKPT:
        debug_monitor(tf);
        break;
    case T_PGFLT:
        if ((ret = pgfault_handler(tf)) != 0) {
            print_trapframe(tf);
            if (current == NULL) {
                panic("handle pgfault failed. %e\n", ret);
            }
            else {
                if (trap_in_kernel(tf)) {
```

```

                                                                    panic("handle pgfault failed in
kernel mode. %e\n", ret);
                                                                    }
                                                                    cprintf("killed by kernel.\n");
                                                                    do_exit(-E_KILLED);
                                                                    }
                                                                    }
                                                                    break;
case T_SYSCALL:
    ...(4)...
    break;
case IRQ_OFFSET + IRQ_TIMER:
    ticks ++;
    assert(current != NULL);
    run_timer_list();
    break;
case IRQ_OFFSET + IRQ_COM1:
case IRQ_OFFSET + IRQ_KBD:
    if ((c = cons_getc()) == 13) {
        debug_monitor(tf);
    }
    else {
        extern void dev_stdin_write(char c);
        dev_stdin_write(c);
    }
    break;
case IRQ_OFFSET + IRQ_IDE1:
case IRQ_OFFSET + IRQ_IDE2:
    /* do nothing */
    break;
default:
    print_trapframe(tf);
    if (current != NULL) {
        cprintf("unhandled trap.\n");
        do_exit(-E_KILLED);
    }
    panic("unexpected trap in kernel.\n");
}
}
void
trap(struct trapframe *tf) {
    // used for previous projects
    if (current == NULL) {
        trap_dispatch(tf);
    }
    else {

```

```

        // keep a trapframe chain in stack
        struct trapframe *otf = current->tf;
        current->tf = tf;

        bool in_kernel = trap_in_kernel(tf);

        ...(5)...

        current->tf = otf;
        if (!in_kernel) {
            if (current->flags & PF_EXITING) {
                do_exit(-E_KILLED);
            }
            if (current->need_resched) {
                schedule();
            }
        }
    }
}
...
-----
kern/syscall/syscall.c
-----
...
static int
sys_read(uint32_t arg[]) {
    int fd = (int)arg[0];
    size_t len = (size_t)...(6)...;
    void *base = (void *)...(7)...;
    ...(8a)...
}
...
static int (*syscalls[])(uint32_t arg[]) = {
    ...
        [SYS_read]                sys_read,
        [SYS_write]               sys_write,
    ...
        [SYS_mkfifo]              sys_mkfifo,
};

#define NUM_SYSCALLS      ((sizeof(syscalls)) / (sizeof(syscalls[0])))

void
syscall(void) {
    struct trapframe *tf = current->tf;

```

```

uint32_t arg[5];
int num = tf->...(8b)...;
if (num >= 0 && num < NUM_SYSCALLS) {
    if (syscalls[num] != NULL) {
        arg[0] = tf->tf_regs.reg_edx;
        arg[1] = tf->tf_regs.reg_ecx;
        arg[2] = tf->tf_regs.reg_ebx;
        arg[3] = tf->tf_regs.reg_edi;
        arg[4] = tf->tf_regs.reg_esi;
        tf->tf_regs.reg_eax = ...(9)...;
        return ;
    }
}
print_trapframe(tf);
panic("undefined syscall %d, pid = %d, name = %s.\n",
      num, current->pid, current->name);
}
...

```

#### kern/fs/sysfile.c

```

...
int
sysfile_read(int fd, void *base, size_t len) {
    struct mm_struct *mm = current->mm;
    if (len == 0) {
        return 0;
    }
    if (!file_testfd(fd, 1, 0)) {
        return -E_INVALID;
    }
    void *buffer;
    if ((buffer = kmalloc(IOBUF_SIZE)) == NULL) {
        return -E_NO_MEM;
    }

    int ret = 0;
    size_t copied = 0, alen;
    while (len != 0) {
        if ((alen = IOBUF_SIZE) > len) {
            alen = len;
        }
        ret = ...(10)...;
        if (alen != 0) {
            lock_mm(mm);
            {

```

```

        if (copy_to_user(mm, base, buffer, alen)) {
            assert(len >= alen);
            base += alen, len -= alen, copied
+= alen;
        }
        else if (ret == 0) {
            ret = -E_INVALID;
        }
    }
    unlock_mm(mm);
}
if (ret != 0 || alen == 0) {
    goto out;
}
}

out:
    kfree(buffer);
    if (copied != 0) {
        return copied;
    }
    return ret;
}
...
-----
kern/fs/file.c
-----
...
int
file_read(int fd, void *base, size_t len, size_t *copied_store) {
    int ret;
    struct file *file;
    *copied_store = 0;
    if ((ret = fd2file(fd, &file)) != 0) {
        return ret;
    }
    if (!file->readable) {
        return -E_INVALID;
    }
    filemap_acquire(file);

    struct iobuf __iob, *iob = iobuf_init(&__iob, base, len, file->pos);
    ret = vop_read(file->node, iob);

    size_t copied = iobuf_used(iob);
    if (file->status == FD_OPENED) {

```

```

        file->pos += copied;
    }
    *copied_store = copied;
    filemap_release(file);
    return ret;
}
...

```

二、（10分）给出程序fork.c的输出结果。注：1）getpid()和getppid()是两个系统调用，分别返回本进程标识和父进程标识。2）你可以假定每次新进程创建时生成的进程标识是顺序加1得到的；在进程标识为1000的命令解释程序shell中启动该程序的执行。

```

#include <sys/types.h>
#include <unistd.h>

/* getpid() and fork() are system calls declared in unistd.h. They return */
/* values of type pid_t. This pid_t is a special type for process ids. */
/* It's equivalent to int. */

int main(void)
{
    pid_t childpid;

    int x = 5;
    int i;
    childpid = fork();
    for ( i = 0; i < 2; i++) {
        printf("This is process %d; childpid = %d; The parent of this process has\n", getpid(), childpid, getppid(), i, x);
        sleep(1);
        x++;
    }

    return 0;
}

```

三、（18分）调度器是操作系统内核中依据调度算法进行进程切换选择的模块。1）试描述时间片轮转算法（Round Robin）的基本原理。2）下面代码是ucore中调度器和时间片轮转算法的实现代码。请补全其中所缺代码，以实现调度器和调度算法的功能。提示：每处需要补全的代码只需要一行，一共有7个空要填。

```

sched.h
-----
...
struct proc_struct;

typedef struct {
    unsigned int expires;

```



```

    struct proc_struct *proc;
    list_entry_t timer_link;
} timer_t;

#define le2timer(le, member) \
    to_struct((le), timer_t, member)

static inline timer_t *
timer_init(timer_t *timer, struct proc_struct *proc, int expires) {
    timer->expires = expires;
    timer->proc = proc;
    list_init(&(timer->timer_link));
    return timer;
}

struct run_queue;

struct sched_class {
    const char *name;
    void (*init)(struct run_queue *rq);
    void (*enqueue)(struct run_queue *rq, struct proc_struct *proc);
    void (*dequeue)(struct run_queue *rq, struct proc_struct *proc);
    struct proc_struct *(*pick_next)(struct run_queue *rq);
    void (*proc_tick)(struct run_queue *rq, struct proc_struct *proc);
};

struct run_queue {
    list_entry_t run_list;
    unsigned int proc_num;
    int max_time_slice;
    list_entry_t rq_link;
};

#define le2rq(le, member) \
    to_struct((le), struct run_queue, member)

void sched_init(void);
void wakeup_proc(struct proc_struct *proc);
void schedule(void);
void add_timer(timer_t *timer);
void del_timer(timer_t *timer);
void run_timer_list(void);

extern struct proc_struct *idleproc, *initproc, *current;
extern struct proc_struct *kswapd;
...

```

-----  
**sched.c**  
-----

```
...
static list_entry_t timer_list;

static struct sched_class *sched_class;

static struct run_queue *rq;

static inline void
sched_class_enqueue(struct proc_struct *proc) {
    if (proc != idleproc) {
        sched_class->enqueue(rq, proc);
    }
}

static inline void
sched_class_dequeue(struct proc_struct *proc) {
    sched_class->dequeue(rq, proc);
}

static inline struct proc_struct *
sched_class_pick_next(void) {
    return sched_class->pick_next(rq);
}

static void
sched_class_proc_tick(struct proc_struct *proc) {
    if (proc != idleproc) {
        sched_class->proc_tick(rq, proc);
    }
    else {
        proc->need_resched = 1;
    }
}

static struct run_queue __rq[4];

void
sched_init(void) {
    list_init(&timer_list);

    rq = __rq;
    list_init(&(rq->rq_link));
    rq->max_time_slice = 8;
}
```

```

    int i;
    for (i = 1; i < sizeof(__rq) / sizeof(__rq[0]); i++) {
        list_add_before(&(rq->rq_link), &(__rq[i].rq_link));
        __rq[i].max_time_slice = rq->max_time_slice * (1 << i);
    }

    sched_class = &MLFQ_sched_class;
    sched_class->init(rq);

    cprintf("sched class: %s\n", sched_class->name);
}

void
wakeup_proc(struct proc_struct *proc) {
    assert(proc->state != PROC_ZOMBIE);
    bool intr_flag;
    local_intr_save(intr_flag);
    {
        if (proc->state != PROC_RUNNABLE) {
            proc->state = PROC_RUNNABLE;
            proc->wait_state = 0;
            sched_class_enqueue(proc);
        }
        else {
            warn("wakeup runnable process.\n");
        }
    }
    local_intr_restore(intr_flag);
}

void
schedule(void) {
    bool intr_flag;
    struct proc_struct *next;
    local_intr_save(intr_flag);
    {
        current->need_resched = 0;
        if (current->state == PROC_RUNNABLE) {
            ...(1)...
        }
        if ((next = sched_class_pick_next()) != NULL) {
            ...(2)...
        }
    }
    local_intr_restore(intr_flag);
}

```

```

    if (next == NULL) {
        next = ...(3)...;
    }
    next->runs ++;
    if (next != current) {
        ...(4)...
    }
}
...
-----
sched_RR.c
-----
...
static void
RR_init(struct run_queue *rq) {
    list_init(&(rq->run_list));
    rq->proc_num = 0;
}

static void
RR_enqueue(struct run_queue *rq, struct proc_struct *proc) {
    assert(list_empty(&(proc->run_link)));
    list_add_before(&(rq->run_list), &(proc->run_link));
    if (proc->time_slice == 0 || proc->time_slice > rq->max_time_slice) {
        ...(5)...
    }
    proc->rq = rq;
    rq->proc_num ++;
}

static void
RR_dequeue(struct run_queue *rq, struct proc_struct *proc) {
    assert(!list_empty(&(proc->run_link)) && proc->rq == rq);
    list_del_init(&(proc->run_link));
    rq->proc_num --;
}

static struct proc_struct *
RR_pick_next(struct run_queue *rq) {
    list_entry_t *le = list_next(&(rq->run_list));
    if (le != &(rq->run_list)) {
        return le2proc(le, run_link);
    }
    return NULL;
}

```

```

static void
RR_proc_tick(struct run_queue *rq, struct proc_struct *proc) {
    if (proc->time_slice > 0) {
        ...(6)...
    }
    if (proc->time_slice == 0) {
        ...(7)...
    }
}

struct sched_class RR_sched_class = {
    .name = "RR_scheduler",
    .init = RR_init,
    .enqueue = RR_enqueue,
    .dequeue = RR_dequeue,
    .pick_next = RR_pick_next,
    .proc_tick = RR_proc_tick,
};
-----

proc.c
-----

...
// proc_run - make process "proc" running on cpu
// NOTE: before call switch_to, should load base addr of "proc"'s new PDT
void
proc_run(struct proc_struct *proc) {
    if (proc != current) {
        bool intr_flag;
        struct proc_struct *prev = current, *next = proc;
        local_intr_save(intr_flag);
        {
            current = proc;
            load_esp0(next->kstack + KSTACKSIZE);
            lcr3(next->cr3);
            switch_to(&(prev->context), &(next->context));
        }
        local_intr_restore(intr_flag);
    }
}

...
-----

```

四、（22分）管程是操作系统提供了一种进程同步机制，利用管程可解决进程间通信时遇到的同步互斥问题。读者-写者问题（**Reader-writer problem**）是一个经典的同步问题。写者优先的读者-写者问题是指，假定有多个并发的读进程和写进程都要访问一个共享的数据结构，要求：(1)读写互斥；(2)写写互斥；(3)允许多个读进程同时访问；(4)只要有写进程提出申

请，其后提出申请的读进程就必须等待该写进程完成访问。下面是ucore中管程机制和写者优先的读者-写者问题的实现代码。请尝试补全其中所缺的代码，以正确实现管程机制和读者-写者间的读写操作协调。提示：文件“cdt\_wf.c”中的补全代码可能需要在—处加多行代码，其他需要补全的代码只需要一行，一共有11个空要填。

## condition.h

```
-----
...
typedef struct {
    int numWaiting;
    int valid;
    wait_queue_t wait_queue;
} condition_t;

#define cdtid2cdt(cdt_id) \
    ((condition_t *)((uintptr_t)(cdt_id) + KERNBASE))

#define cdt2cdtid(cdt) \
    ((cdt_t)((uintptr_t)(cdt) - KERNBASE))

void
condition_value_init(condition_t *cdt) {
    ... (1) ...
    cdt->valid=1;
    wait_queue_init(&(cdt->wait_queue));
}

int
condition_init(){
    condition_t *cdt;
    if ((cdt = kmalloc(sizeof(condition_t))) != NULL) {
        condition_value_init( cdt );
    }
    if (cdt != NULL) {
        return cdt2cdtid(cdt);
    }
    return -E_INVAL;
}

int
condition_free(cdt_t cdt_id) {
    condition_t *cdt = cdtid2cdt(cdt_id);
    int ret = -E_INVAL;
    if (cdt != NULL) {
        bool intr_flag;
```

```

        local_intr_save(intr_flag);
        {
            cdt->valid = 0, ret = 0;
            wakeup_queue(&(cdt->wait_queue), WT_INTERRUPTED, 1);
            kfree(cdt);
        }
        local_intr_restore(intr_flag);
    }
    return ret;
}

```

```

int
condition_wait(cdt_t cdt_id, klock_t kl_id){

    condition_t *cdt = cdtid2cdt(cdt_id);
    bool intr_flag;
    local_intr_save(intr_flag);
    ... (2) ...
    wait_t __wait, *wait = &__wait;
    ... (3) ...
    local_intr_restore(intr_flag);

    sys_unlock(kl_id);
    schedule();
    sys_lock(kl_id);

    //local_intr_save(intr_flag);
    //wait_current_del(&(cdt->wait_queue), wait);
    //local_intr_restore(intr_flag);

    if (wait->wakeup_flags != WT_UCONDITION) {
        return wait->wakeup_flags;
    }
    return 0;
}

```

```

int
condition_signal(cdt_t cdt_id){
    condition_t *cdt = cdtid2cdt(cdt_id);
    if (cdt == NULL) {
        return -E_INVAL;
    }

    bool intr_flag;
    local_intr_save(intr_flag);
    if (cdt->numWaiting > 0) {

```

```

        wait_t *wait;
        if ((wait = wait_queue_first(&(cdt->wait_queue))) != NULL) {
            assert(wait->proc->wait_state == WT_UCONDITION);
            ... (4) ...
        }
        ... (5) ...
    }
    local_intr_restore(intr_flag);
    return 0;
}

```

...

---

## ulib.c

---

```

...
cdt_t
cdt_init(){
    return sys_cdt_init();
}

int
cdt_signal(cdt_t cdt_id){
    return sys_cdt_signal(cdt_id);
}

int
cdt_wait(cdt_t cdt_id ,klock_t klock_id){
    return sys_cdt_wait(cdt_id ,klock_id);
}

int
cdt_free(cdt_t cdt_id){
    return sys_cdt_free(cdt_id);
}

klock_t
klock_init(){
    return sys_klock_init();
}

int
klock_acquire(klock_t klock_id){
    return sys_klock_acquire(klock_id);
}

int

```



```

klock_release(klock_t klock_id){
    return sys_klock_release(klock_id);
}

int
klock_free(klock_t klock_id){
    return sys_klock_free(klock_id);
}
...
-----

cdt_wf.c
-----

...
int *active_reader ;    // # count of active readers
int *active_writer ; // # count of active writers
int *waiting_reader ;   // # count of waiting readers
int *waiting_writer ;   // # count of waiting writers
cdt_t cdt_okToRead;
cdt_t cdt_okToWrite;
klock_t lock;

void
failed(void) {
    cprintf("FAIL: T.T\n");
    exit(-1);
}

void
init(void) {
    if ((cdt_okToRead = cdt_init()) < 0 || (cdt_okToWrite = cdt_init()) < 0) {
        failed();
    }
    if ((lock = klock_init()) < 0) {
        failed();
    }
    if ((active_reader = shmem_malloc(sizeof(int))) == NULL || (active_writer =
shmem_malloc(sizeof(int))) == NULL
        || (waiting_reader = shmem_malloc(sizeof(int))) == NULL || (waiting_writer =
shmem_malloc(sizeof(int))) == NULL) {
        failed();
    }
    *active_reader = *active_writer = *waiting_reader = *waiting_writer = 0;
}

void
check_init_value(void) {

```

```

    if (cdt_okToRead < 0 || cdt_okToWrite < 0 ) {
        failed();
    }
    if (lock < 0 ) {
        failed();
    }
    if (*active_reader != 0 || *active_writer != 0 || *waiting_reader != 0 ||
*waiting_writer != 0) {
        failed();
    }
}

void
free_wf(void){
    if ( cdt_free(cdt_okToRead) < 0 || cdt_free(cdt_okToWrite) < 0 ){
        sprintf(" conditon free failed! \n");
        exit(-1);
    }
    if ( klock_free(lock) < 0 ){
        sprintf(" kernal lock free failed! \n");
        exit(-1);
    }
}

void
start_read(void) {
    klock_aquire(lock);
    ...(6)...
    klock_release(lock);
}

void
done_read(void) {
    klock_aquire(lock);
    ...(7)...
    klock_release(lock);
}

void
start_write(void) {
    klock_aquire(lock);
    ...(8)...
    klock_release(lock);
}

void

```

```

done_write(void) {
    klock_acquire(lock);
    ...(9)...
    if ((*waiting_writer) > 0) {
        ...(10)...
    }
    else if ((*waiting_reader) > 0) {
        int wakecount=0;
        while(...(11)...){
            cdt_signal(cdt_okToRead);
            wakecount++;
        }
    }
    klock_release(lock);
}

void
writer(int id, int time) {
    sprintf("writer %d: (pid:%d) arrive \n", id, getpid());
    start_write();
    sprintf("    writer_wf %d: (pid:%d) start %d\n", id, getpid(), time);
    sleep(time);
    sprintf("    writer_wf %d: (pid:%d) end %d\n", id, getpid(), time);
    done_write();
}

void
reader(int id, int time) {
    sprintf("reader %d: (pid:%d) arrive\n", id, getpid());
    start_read();
    sprintf("    reader_wf %d: (pid:%d) start %d\n", id, getpid(), time);
    sleep(time);
    sprintf("    reader_wf %d: (pid:%d) end %d\n", id, getpid(), time);
    done_read();
}

void
read_test_wf(void) {
    ...
}

void
write_test_wf(void) {
    ...
}

```

```

void
read_write_test_wf(void) {
...
}

int
main(void) {
    init();
    read_test_wf();
    write_test_wf();
    read_write_test_wf();
    free_wf();
    cprintf("condition reader_writer_wf_test pass..\n");
    return 0;
}
-----

wait.c
-----

...
void
wait_init(wait_t *wait, struct proc_struct *proc) {
    wait->proc = proc;
    wait->wakeup_flags = WT_INTERRUPTED;
    list_init(&(wait->wait_link));
}

void
wait_queue_init(wait_queue_t *queue) {
    list_init(&(queue->wait_head));
}

void
wait_queue_add(wait_queue_t *queue, wait_t *wait) {
    assert(list_empty(&(wait->wait_link)) && wait->proc != NULL);
    wait->wait_queue = queue;
    list_add_before(&(queue->wait_head), &(wait->wait_link));
}

void
wait_queue_del(wait_queue_t *queue, wait_t *wait) {
    assert(!list_empty(&(wait->wait_link)) && wait->wait_queue == queue);
    list_del_init(&(wait->wait_link));
}

wait_t *

```

```

wait_queue_next(wait_queue_t *queue, wait_t *wait) {
    assert(!list_empty(&(wait->wait_link)) && wait->wait_queue == queue);
    list_entry_t *le = list_next(&(wait->wait_link));
    if (le != &(queue->wait_head)) {
        return le2wait(le, wait_link);
    }
    return NULL;
}

wait_t *
wait_queue_prev(wait_queue_t *queue, wait_t *wait) {
    assert(!list_empty(&(wait->wait_link)) && wait->wait_queue == queue);
    list_entry_t *le = list_prev(&(wait->wait_link));
    if (le != &(queue->wait_head)) {
        return le2wait(le, wait_link);
    }
    return NULL;
}

wait_t *
wait_queue_first(wait_queue_t *queue) {
    list_entry_t *le = list_next(&(queue->wait_head));
    if (le != &(queue->wait_head)) {
        return le2wait(le, wait_link);
    }
    return NULL;
}

wait_t *
wait_queue_last(wait_queue_t *queue) {
    list_entry_t *le = list_prev(&(queue->wait_head));
    if (le != &(queue->wait_head)) {
        return le2wait(le, wait_link);
    }
    return NULL;
}

bool
wait_queue_empty(wait_queue_t *queue) {
    return list_empty(&(queue->wait_head));
}

bool
wait_in_queue(wait_t *wait) {
    return !list_empty(&(wait->wait_link));
}

```

```

void
wakeup_wait(wait_queue_t *queue, wait_t *wait, uint32_t wakeup_flags, bool del)
{
    if (del) {
        wait_queue_del(queue, wait);
    }
    wait->wakeup_flags = wakeup_flags;
    wakeup_proc(wait->proc);
}

void
wakeup_first(wait_queue_t *queue, uint32_t wakeup_flags, bool del) {
    wait_t *wait;
    if ((wait = wait_queue_first(queue)) != NULL) {
        wakeup_wait(queue, wait, wakeup_flags, del);
    }
}

void
wakeup_queue(wait_queue_t *queue, uint32_t wakeup_flags, bool del) {
    wait_t *wait;
    if ((wait = wait_queue_first(queue)) != NULL) {
        if (del) {
            do {
                wakeup_wait(queue, wait, wakeup_flags, 1);
            } while ((wait = wait_queue_first(queue)) != NULL);
        }
        else {
            do {
                wakeup_wait(queue, wait, wakeup_flags, 0);
            } while ((wait = wait_queue_next(queue, wait)) != NULL);
        }
    }
}

void
wait_current_set(wait_queue_t *queue, wait_t *wait, uint32_t wait_state) {
    assert(current != NULL);
    wait_init(wait, current);
    current->state = PROC_SLEEPING;
    current->wait_state = wait_state;
    wait_queue_add(queue, wait);
}

```

-----  
**proc.h**  
 -----

```

...
//the wait state
#define WT_CHILD      (0x00000001 | WT_INTERRUPTED) // wait child process
#define WT_TIMER      (0x00000002 | WT_INTERRUPTED) // wait timer
#define WT_KSWAPD     0x00000003                  // wait kswapd to free page
#define WT_KSEM       0x00000100                  // wait kernel semaphore
#define WT_USEM       (0x00000101 | WT_INTERRUPTED) // wait user semaphore
#define WT_EVENT_SEND (0x00000110 | WT_INTERRUPTED) // wait the sending event
#define WT_EVENT_RECV (0x00000111 | WT_INTERRUPTED) // wait the recving event
#define WT_MBOX_SEND  (0x00000120 | WT_INTERRUPTED) // wait the sending mbox
#define WT_MBOX_RECV  (0x00000121 | WT_INTERRUPTED) // wait the recving mbox
#define WT_UCONDITION (0x00000130 | WT_INTERRUPTED) // wait user condition
--liuruilin
#define WT_INTERRUPTED 0x80000000 // the wait state could be interrupted

...
-----

```

五、（10分）银行家算法(Banker's Algorithm)是一种在资源分配过程中避免出现死锁的算法，资源管理者可以有进程申请资源时，使用银行家算法来判断分配相应资源后是否可能出现死锁。试回答下列问题。

1) 形成死锁的条件是什么？

2) 试用伪代码描述银行家算法。

3) 假设系统中有A、B、C和D这四类资源，有P1、P2和P3这三个进程正在使用这些资源。

下面某次资源申请后的资源占用情况。请问这个状态是否安全？如果是安全的，请给出一个可能的资源分配和回收序列。

当前的可用资源情况：

A B C D

3 1 1 2

当前各进程的已分配资源情况：

A B C D

P1 1 0 3 3

P2 1 2 2 1

P3 1 2 1 0

各进程声称的最大资源申请情况：

A B C D

P1 1 2 3 4

P2 3 3 2 2

P3 1 3 5 0

六、（10分）基本的文件组织方式有哪几种？请用图示方式描述UNIX文件系统UFS的文件组织方式。

七、（10分）磁盘缓存置换算法的作用是什么？试简要描述访问频率置换算法

(Frequency-based Replacement)的基本原理。磁盘调度算法的作用是什么？试简要描述扫描算法(SCAN)的基本原理。

