entry:

Advanced Z-80 Programming

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48k.ca/advz80.pdf

https://discord.gg/fDyTDAU

The slides of this talk plus my explanatory commentary are at http://48k.ca/advz80.pdf

So don't worry about taking notes or otherwise missing something.

Free free to e-mail me if you want to talk about Z-80 or TRS-80s. Better still, go to that Discord and we can chat interactively.

General Advice

For fast, small code use instructions in the 4 to 11 T-State range.

LDIR, IX, IY make programming much easier but are big and slow.

Keep as much as you can in registers. EXX, EX AF, AF' and IXL/IXH help.

8 bits often faster than 16.

PUSH/POP fastest way to memory by far.

LDIR by itself is not big (but at 21 T-States is slow). It's more than if you use it from a standing start where you end up doing three 16 bit loads. That's 9 bytes; 11 including the LDIR. A lot can happen in 11 bytes.

Clear Carry

The Z-80 has instructions to set the carry and complement it but none to clear it. Most code I've seen uses "OR A", but "AND A" is common in some circles. Nobody uses "CP A" but it'll do the job.

7 8000 FE00

CP 0

4 8001 B7

OR A

4 8002 A7

AND A

Test A == 0 or A < 0 or A > 0

Here's two different ways to test if A is smaller, bigger or equal to zero. Most often just as a test if A equal to 0 or not. Notice that it saves 3 T-States and 1 byte compared to the obvious "CP 0" technique.

7 8000 3E00

LD A,0

4 8001 AF

XOR A

4 8002 97

SUB A

A = 0

Here's a very well known trick for setting A register to 0. I've mostly seen "XOR A" used but "SUB A" is practically identical. Both of them do affect the flags which can be a problem depending on the situation. Otherwise, grab the byte and 3 free T-States.

4	8000	9F	SBC	A,A
4	8001	79	LD	A,C
4	8002	87	ADD	A,A
4	8003	9F	SBC	A,A
4	8004	47	LD	B,A

A = Carry

Here you might start to sense a theme. What happens when we have A operate on itself? "SBC A,A" seems like "SUB A" except that with the carry involved it actually ends up being something like "LD A,carry". If the carry is not set then A = 0, otherwise A = \$FF.

It can have its uses in time sensitive code as a way to use the carry flag without a branch. I've shown an example to take C as an 8 bit signed value and extend it to a 16 bit signed value which just amounts to replicating the sign bit of C into all bits of B.

8 8000 CB27

SLA A

4 8002 87

ADD A,A

A = A * 2

It's smaller and cheaper just to add A to itself rather than use the shift-left-arithmetic "CB" opcode. They are slightly different. "SLA A" sets the parity flag whereas "ADD A,A" sets overflow.

BTW, you can see the bytes difference and the cycle counts are in the first column.

8 8000 CB17 RL A

4 8002 8F ADC A,A

4 8003 17 RLA

Rotate Left A

A few shift and rotate instructions have shorter equivalents due to 8080 compatibility. Here's one, "RL A" and be done as "RLA". However, RLA only sets the Carry flag. The crazy thing is that the 8080 didn't even need RLA since ADC A,A was just sitting right there!

If nothing else I've found that I can remember the difference between RL and RLC by remembering that RL and ADC are the same.

8	8000	CB07	RLC	Α
8	8002	CB1F	RR	Α
8	8004	CB0F	RRC	Α

4	8006	07	RLCA
4	8007	1F	RRA
4	8008	0F	RRCA

Other A Rotates

And there are 3 other rotate instruction with faster variants for just A register. Again, watch out if want to test if A is zero since the shorter ones don't do that. And adding an "OR A" just means the result is the same speed as the "CB" version.

8 8000 CB25 SLA L 8 8002 CB14 RL H **16**

11 8003 29 ADD HL,HL

HL = HL * 2

Generally you'll have to do 16 bit (and larger) shifts 8 bits at a time. But "ADD HL,HL" is much smaller and reasonably faster for a 16 bit shift. Unsurprisingly, it is rather like "SLA HL". On a similar note, "ADC HL,HL" can be thought of as "RL HL" if you have a use for that.

You might wonder about "SBC HL,HL". 15 T-States but you can do it in 12 with "SBC A,A; LD H,A; LD L,A". But if you really need a byte or A is in use then it'd be fine.

10	8000	11E803	LD	DE,1000
4	8003	B7	OR	Α
15	8004	ED52	SBC	HL,DE
29				
10	8006	1118FC	LD	DE,-1000
11	8009	19	ADD	HL,DE
21				

Add Negative To Subtract

Don't underestimate the power of simple arithmetic to save T-States and bytes. We get the same result in HL adding -1000 as we do subtracting but with 8 fewer T-States and 2 fewer bytes.

The flags are different, though so don't do this if you want to see if HL is equal to 1000. However, ADD HL,DE does set carry so you can use the technique to check if HL is bigger or smaller than some number. Just be careful as the sense of the carry will be reversed.

```
; OK if 5 < A < 9
 7 8000 FE05
                                 5
                         CP
                                 C,bad1
12 8002 3815
                         JR
 7 8004 FE09
                         CP
                                 9
12 8006 3011
                                 NC, bad1
                         JR
   8008
                ok1:
                bad1:
   8019
 7 8019 D605
                         SUB
 7 801B FE04
                         CP
                                 9-5
                                 NC, bad2
12 801D 3011
                         JR
                ok2:
   801F
   8030
                bad2:
```

Range Check

So save a bit of time and space in doing ranged comparisons like the one shown, take advantage of modular arithmetic. And note my usage of "9-5". Many programmers will put in "4" but I like to "show my work" and let the assembler take care of it.

```
; HL = HL + A
 4 8000 4F
                                 C,A
                          LD
                                 B,0
 7 8001 0600
                          LD
                                 HL,BC
11 8003 09
                         ADD
22
 4 8004 85
                         ADD
                                 A,L
 4 8005 6F
                                 L,A
                         LD
 4 8006 8C
                                 A,H
                         ADC
 4 8007 95
                                 A,L
                         SUB
                                 H,A
 4 8008 67
                          LD
20
                                 A,L
 4 8009 85
                         ADD
                                 L,A
 4 800A 6F
                          LD
                                 NC, noinc
 7 800B 3001
                          JR
 4 800D 24
                          INC
                                 Н
   800E
                  noinc:
19 (or 20 if JR taken)
```

HL = HL + A

The Z-80 does have 16 bit operations but the instruction set is 8 bit at its heart (and 4 bit on the chip). Doing a hybrid operations like this (adding an 8 bit to a 16 bit value) can be done faster with just 8 bit math. Though it won't have the same flag results at all due to that trick of adjusting H to save a critical 3 T-States.

We can even do a little better by using a conditional branch. This averages to 19.5 T-States saving 0.5 from before. Note that if A is large a carry will happen frequently so using JP is better than JR as the usual case will be 4+4+10 or 18 cycles. But it'll be worse at 24 cycles if A is small and the JP isn't taken.

```
; HL'HL = HL'HL + $00800800
10 8000 110008
                                DE,$0800
                         LD
11 8003 19
                        ADD
                                HL, DE
 4 8004 D9
                         EXX
10 8005 118000
                                DE,$0080
                         LD
15 8008 ED5A
                        ADC
                                HL, DE
 4 800A D9
                         EXX
```

32 Bit Add

The "prime" registers available through EXX are really handy though they can be inconvenient as there isn't a fast facility for passing values between the two register banks. They're great for 32 bit arithmetic as seen in this example.

```
; A = (B \& \$F8) \mid (C \& 7)
 4 8000 78
                         LD
                                 A,B
                                 $F8
 7 8001 E6F8
                         AND
 4 8003 47
                                 B,A
                         LD
 4 8004 79
                                 A,C
                         LD
 7 8005 E607
                                 $7
                         AND
 4 8007 B0
                         OR
                                 В
30
A = ((B ^ C) & F8)
                        ^ C
 4 8008 78
                         LD
                                 A,B
 4 8009 A9
                         XOR
                                 C
 7 800A E6F8
                                 $F8
                         AND
 4 800C A9
                         XOR
                                 C
19
```

High 5 Bits of B Combined with Low 3 of C

A mastery of boolean algebra can speed up code. Consider this operation where we want to take the high 5 bits of B and combine them with the low 3 bits of C. The simpleminded solution masks both source values but we can use the properties of XOR to do the operation much more quickly.

And, as a bonus, the mask value could easily be a parameter in a register. The simple code would get much more complicated having to compute the mask and its inverse.

```
; A = A
4 8000 B0
                          OR
                                   В
; A = A \& \sim B
                                   C,A
4 8001 4F
                          LD
                                   A,B
4 8002 78
                          LD
4 8003 2F
                          CPL
4 8004 A1
                          AND
                                   C
; A = (A \mid B) \land B
4 8005 B0
                          OR
                                   В
4 8006 A8
                          XOR
                                   В
```

Set Bits and Clear Bits

Similar to the previous transformation, consider wanting to set all the bits in A where the corresponding bit is 1 in B register. That's trivial: just OR. But if you want to clear the corresponding bit in A then you might think you need to complement the mask value. Or just use more XOR magic.

7	8000	2605	LD	H,5
4	8002	2D	DEC	L
4	8003	85	ADD	A,L
11	8004	DD2605	LD	IXH,5
8	8007	DD2D	DEC	IXL
8	8009	FD85	ADD	A,IYL

Split IX, IY are OK

A quick word on undocumented instructions. The Z-80 has a number of them including access to the high and low bytes of IX and IY. I consider these well-supported and have no qualms using them. They're all 1 byte and 4 T-States slower then their "HL" counterparts (DD means IX, FD means IY) but they can be very handy as extra registers when you run low.

4	8000	EB	EX	DE,HL
11	8001	09	ADD	HL,BC
7	8002	86	ADD	A,(HL)
4	8003	EB	EX	DE.HL

EX DE, HL most Underrated

I think "EX DE,HL" is the most underrated Z-80 instruction (and its actually an 8080 instruction but let's not quibble). Since you can do so much with HL it is like having a second HL register (or, uh, third and fourth if you consider EXX).

This example shows storing A register into (DE+BC). It's not super compelling but it's hard to come up with a concise example. Probably why the instruction is so often overlooked. But I find it can help get out of tight spots where registers are running out and can avoid having to use IX or IY.

```
A, (var1)
13 8000 3A00A0
                         LD
4 8003 3C
                         INC
13 8004 3200A0
                                 (var1),A
                         LD
30
                                 A,0
 7 8007 3E00
                         LD
                                 $-1
   8008
                var2
                         equ
 4 8009 3C
                         INC
13 800A 320880
                                 (var2),A
                         LD
24
10 800D 2100A0
                         LD
                                 HL, var1
                                 (HL)
11 8010 34
                         INC
21
```

Variable self-modify

The Z-80 is fairly slow to access memory. If you're not writing code for a ROM you can save a good number of cycles by storing the variable value in one of the LD instructions. That's obviously even better if that LD is in a loop. And that kind of thing is one of the chief reasons why self-modifying code can speed things up. 6 cycles vs. 13 if you modify a load rather than using an indirect load.

The Z-80's 8080 heritage shows through in that it really wants you to load HL with the address of a variable. Look at how the last code fragment is faster still despite the self-modifying cleverness.

```
A = A / 3
                                H, high (div3)
 7 8000 2681
                        LD
 4 8002 6F
                                L,A
                        LD
7 8003 7E
                                A,(HL)
                        LD
18
   8100
                                ($+255) \& -256
                        org
                                0/3,1/3,2/3
4 8100 000000 div3:
                        DEFB
                                3/3,4/3,5/3
10 8103 010101
                        DEFB
                                6/3,7/3,8/3
 7 8106 020202
                        DEFB
 6 8109 030303
                                9/3,10/3,11/3
                        DEFB
```

8 Bit Page Aligned Table (div 3)

For more complicated functions, nothing beats page (256 byte) aligned table lookups. A mere 18 T-States to to look up a value or only 11 if H already points to the table. Here we use a lookup table to divide A register by 3.

Fastest way to map an 8 bit input to an 8 bit value. Only one or two instruction functions will be faster.

```
LD
                               H, high (squared)
7 8000 2681
7 8002 56
                        LD
                               D, (HL)
4 8003 24
                        INC
                               Н
7 8004 5E
                               E,(HL); DE=L*L
                        LD
                               ($+255) \& -256
  8100
                        org
  8100
               squared:
  0000
                        x = 0
  8100 00000000
                        rept 256
                          DEFB x * x / 256
  8104 00000000
                          X++
                        endm
  0000
                        x = 0
                        rept 256
  8200
        00010409
                          DEFB x * x % 256
        10192431
                          X++
                        endm
```

16 Bit Page Aligned Table (squares)

For 16 bit result tables you may be tempted to store them as 16 bit values. But in another way the Z-80 is 8 bit at heart you should split the values across into a page of high bytes and a page of low bytes. Then you can handle 256 inputs without 16 bit math (or any math at all). By having the pages adjacent a simple "INC" gets us there faster and shorter than another "LD H,high(squared+1)".

The "x = 0" and "x++" notation are something I added specifically to zmac for making table generation such as this more concise.

Going	Places
-------	--------

,	
<u>!</u>	
;	
Ĺ	

4	8000	37	SCF	
7	8001	30FE	JR	NC,\$
12	8003	38FE	JR	С,\$
12	8005	18FE	JR	\$
10	8007	C30580	JP	\$

Use JR for forward conditional branches. Use JP on all others.

Specifically, conditional JR beats JP if branch is taken less than 60% of the time.

JP vs JR

Obviously using a JR is more compact than a JP. The forward/back advice is based on the idea that backward jumps are typically for loops and forward jumps for exceptional case. Obviously there are many exceptions to this heuristic.

In fact, looping or not, for speed use JR is a branch is taken less than 60% of the time. A JR is faster if not taken so you should "JR" to the uncommon rather than common case.

```
12 8000 2803
                         JR
                                 Z, incd1
 4 8002 15
                         DEC
                                 D
                                 done1
12 8003 1801
                         JR
 4 8005 14
                incd1:
                         INC
                                 D
   8006
                done1:
                                 Z,incd2
12 8000 2802
                         JR
 4 8002 15
                         DEC
                                 D
                                 A,$14
 7 8003 3E14
                         LD
   8004
                                 $-1
                         org
 4 8004 14
                incd2:
                         INC
```

One byte jump

Here's a trick that the BASIC ROM uses to save code bytes. Suppose we want to add 1 to D if zero is set and subtract 1 otherwise. Normally that means having two jumps but if we don't care about the contents of A register we can effectively jump over the "INC D" by hiding it in a "LD A,n" instruction. It's pretty weird. And to be clear the second code segment is only 5 bytes long (look at the address repeating on the left).

The "LD A,n" is kind of a 1 byte jump forward.

The takeway here is to remember how the processor works. You can go ahead and jump into the so-called middle of an instruction and it'll just to what you tell it.

10 8000 11DD23 LD DE,\$23DD - 8002 org \$-1
10 8002 DD23 lp: INC IX
13 8003 10FC DJNZ lp

Two byte jump

LD DE,nn and other 16 bit loads can act as a 2 byte jump forward. Again, with a side effect of "trashing" a register pair. Here in this artificial example we want to add B-1 to IX. The first time through we do nothing. The load of DE skips the INC IX. Subsequent iterations do the INC IX so it happens B - 1 times.

```
(HL)
                         JP
 4 8000 E9
 5 8001 D8
                         RET
                                 C
                                          ;skip
                                 C,$
                                          ;skip
 7 8002 38FE
                         JR
 8 8004 FDE9
                                 (IY)
                         JP
 8 8006 10FE
                                          ;skip
                         DJNZ
                                 $
                                 $
10 8008 C30880
                         JP
10 800B C9
                         RET
10 800C DC1B80
                                 C, PRINT ; skip
                         CALL
11 800F D0
                         RET
                                 NC
11 8010 CF
                         RST
                                 8
                                 $
12 8011 18FE
                         JR
13 8013 10FE
                         DJNZ
17 8015 CD1B80
                         CALL
                                 PRINT
```

Relative Speed of flow change

Here's a quick cheat sheet demonstrating the relative speed of change of flow instructions. Nobody beats JP (HL), conditional return not taken is a bit faster than conditional JR not taken. So while a CALL is expensive it can win back that type if there are many conditional returns not taken in it compared to JR's not taken. JP (IY) or (IX) is just a bit faster than JP so use that to grab a couple extra T-States in a loop.

```
; case of A 0,1,2,3
 4 8000 87
                        ADD
                                A,A
                                (jroff),A
13 8001 320580
                        LD
12 8004 18FE
                        JR
                jroff
   8005
                                $-1
                        equ
12 8006 1826
                        JR
                                case0
41
12 8008 1835
                        JR
                                case1
12 800A 1844
                        JR
                                case2
                case3:
                case0:
                case1:
                case2:
```

Simple Jump Table

Switch statements or "jump tables" where a different bit of code is executed depending on a register value are common. One easy and compact way to approach this is to self-modify the offset of a JR instruction.

Note how we avoid a "JR case3" by staring that case at offset 6.

If you can control the values of a case (say by them being 0, 2, 4, 6) then the "ADD A,A" isn't required.

```
L,A
 4 8000 6F
                         LD
                                 H, high (jump)
 7 8001 2681
                         LD
                                 L,(HL)
 7 8003 6E
                         LD
                                 (HL)
 4 8004 E9
                         JP
22
   8100
                                 ($+255) \& -256
                         org
                                 low(do_1)
 6 8100 03
                jump:
                         defb
 4 8101 14
                         defb
                                 low(do 2)
 4 8102 25
                                 low(do_3)
                         defb
   8103
                do 1:
                do_2:
   8114
                do 3:
   8125
```

Fast Jump Table

For pure speed you can't beat JP (HL) at a mere 4 T-States. As with ordinary table lookup the best approach is to split 16 bit values into two pages. But if the possibilities are small then a single byte can be used as the destination as long as the jump table and the destinations are all on a single page.

Here I've given them the most possible space with full page alignment but that is more than is required.

We could lose a bit of time and have the table not start on a page boundary. And we could even do a full 16 bit add but it'd be slower.

Subroutines

Great way to simplify programming.

Arguments and return values in registers. Otherwise fixed memory locations (not stack).

Zero flag is best for boolean (yes/no) return.

Carry flag is best for single bit return value.

Always have one subroutine named "ME".

Not sure if that's a Blondie or Carly Rae Jepsen joke.

11 8000 29 mul8: ADD HL,HL 11 8001 29 ADD HL,HL 11 8002 29 ADD HL,HL 10 8003 C9 RET

HL = HL * 8

Small subroutines are not good for speed and size reasons. This routine to multiply HL by 8 could be done in-line faster and would reduce the size of the entire program by 4 bytes because the 3 "ADD HL,HL" instructions would fit in the 3 bytes the CALL requires.

```
4 8000 7C
                         LD
                                A, H
                hexHL:
17 8001 CD0E80
                         CALL
                                hexA
 4 8004 7D
                         LD
                                A,L
                                      ;CALL hexA;RET
11 8005 F5
                         PUSH
                                ΑF
                hexA:
 4 8006 0F
                         RRCA
 4 8007 0F
                         RRCA
4 8008 0F
                         RRCA
4 8009 0F
                         RRCA
17 800A CD0E80
                         CALL
                                hex
10 800D F1
                         POP
                                      ;CALL hex;RET
                                AF
 7 800E E60F
                hex:
                         AND
                                15
 7 8010 FE0A
                                10
                         CP
 7 8012 DE69
                         SBC
                                $69
4 8014 27
                                      ;CALL putch;RET
                         DAA
10 8015 C300B0
                         JP
                                putch
```

Fall Though to Tail and DAA Magic

A very common space and time-saving technique it to have subroutines "fall though" rather than having a "CALL to-subroutine; RET" sequence at their end. Here the routine to convert HL to hexadecimal does a call to output H and then falls-through to print L. Similarly, hexA falls through to do the lower nybble of A.

Notice how "hex" converts binary 0 .. 15 to ASCII '0' .. '9', 'A' ... 'F'. I won't go into it (nor do I fully understand it), but considering DAA's job is to take results like 5 + 6 = 11 and convert them to BCD "11" you can kind of see the connection with hexadecimal.

equ 0000 no err 0 0002 2 sn err equ 0004 tm err equ 4 7 8000 3E04 A, tm_err LD 12 8002 1811 JR done 7 8010 3E02 A, sn_err LD 4 8012 B7 done: OR Α 10 8013 C9 **RET**

Set Z flag for Non-zero Error Codes

The Z flag is pretty convenient if A register contains an error code. If any non-zero code is an error then "OR A" suffices to set the flag. This means the caller does not have to do the test themselves but can immediate branch to test for failure. Or conditionally return on not-zero to propagate the error back to their caller.

```
12 8000 1825
                         JR
                                 s_ok
                                 s_fail
12 8013 1811
                         JR
                s_fail: OR
                                 $AF
 7 8026 F6AF
   8027
                                $-1
                         org
 4 8027 AF
                         XOR
                s_ok:
                                 Α
10 8028 C9
                         RET
```

Boolean Tail Overlap

The overlapping instruction technique can be used to create compact good/bad exit points in a subroutine. Since \$AF is non-zero the "OR \$AF" will guarantee Z is not set. But the JR to "s ok" will be "XOR A" which ensures Z is set.

```
print
17 8000 CD1B80
                         CALL
                                'Hello!',0
                        ascii
 4 8003 48656C6C
        6F2100
10 800A 010A00
                                BC, 10
                         LD
                print:
                                (SP),HL
19 801B E3
                        EX
 7 801C 7E
                plp:
                        LD
                                A,(HL)
 6 801D 23
                         INC
                                HL
 4 801E B7
                        OR
                                Α
12 801F 2805
                                Z,pdn
                         JR
17 8021 CD00B0
                                putchar
                         CALL
12 8024 18F6
                                plp
                         JR
                pdn:
                        EX
                                (SP),HL
19 8025 E3
10 8026 C9
                         RET
```

Arguments After CALL

One very convenient trick is to put CALL parameters directly after the CALL instruction. It saves having to load (and use) a register and annoys reverse engineers as a side effect. It also shatters the myth that a Z-80 will return to the next instruction after a CALL.

Here we swap the return address and HL with the EX (SP),HL. Then read over the nul terminated string as we print it and simply return back to the next instruction after the string.

```
; Model I/III
                  BASIC
             RST $0 ; reboot
11 8000 C7
             RST $8 ; JP $4000 syntax check
11 8001 CF
11 8002 D7
             RST $10 ; JP $4003 next char
             RST $18; JP $4006 CP HL, DE
11 8003 DF
             RST $20 ; JP $4009 get type
11 8004 E7
             RST $28; JP $400C break/sys
11 8005 EF
             RST $30; JP $400F unused/debug
11 8006 F7
11 8007 FF
             RST $38 ; JP $4012 IM 1 intr
```

RST is compact but slow (Model I/III)

The Z-80 feaatures a fast call instruction called RST. It is 6 T-States faster and 2 bytes smaller than a CALL. But it can only go to 8 fixed locations which then generally involve an additional JP either because the locations are vectored from ROM or 8 bytes is not sufficient for a subroutine. As a result a RST isn't usually faster than a CALL but it certainly is very compact.

On the Model I/III only one RST vector is completely unused. RST 0 will just warm start the machine and RST \$38 is the interrupt.

```
; Model 4
11 8000 C7
             RST $0 ; reboot
11 8001 CF
             RST $8 ; unused
             RST $10; unused
11 8002 D7
             RST $18; unused
11 8003 DF
11 8004 E7
             RST $20; unused
             RST $28; syscall
11 8005 EF
11 8006 F7
             RST $30; debug
11 8007 FF
             RST $38 ; IM 1 intr
```

RST is compact and maybe fast (Model 4)

The Model 4 has 4 unused RST vectors, one shared by the interrupts and the others available if you don't need TRS-DOS.

```
; Model II
11 8000 C7
            RST $0 ; possible (TRSDOS return)
            RST $8 ; syscall
11 8001 CF
            RST $10; debug
11 8002 D7
11 8003 DF
            RST $18; unused
          RST $20 ; unused
11 8004 E7
          RST $28 ; unused
11 8005 EF
11 8006 F7
          RST $30 ; unused
11 8007 FF
          RST $38; unused
```

RST is compact and maybe fast (Model II)

The Model II uses mode 2 interrupts (IM 2) so RST \$38 is available as are others.

L	ooping

13 8000 10FE \$ DJNZ 4 8002 05 DEC В 12 8003 20FD NZ,\$-1 JR 16 4 8002 15 DEC D NZ,\$-1 10 8003 C20280 JP 14

DJNZ is small but slightly fast

For 8 bit loops you can't beat DJNZ for size and speed. But its speed advantage is surprisingly slim. Just 1 cycle savings over a decrement and JP and you can use other conditions besides != 0.

Use it when you can but if it doesn't fit easily into the code then it may not be saving any time.

```
loop1:
 6 8011 0B
                           DEC
                                   BC
4 8012 78
                                   A,B
                           LD
 4 8013 B1
                           OR
                                   \mathsf{C}
                                   NZ,loop1
10 8014 C20080
                           JP
24
                 loop2:
                           CPI
16 8028 EDA1
10 802A EA1780
                                   V,loop2
                           JP
26
 6 802D 23
                           INC
                                   HL
```

16 bit BC loop using CPI

For loops with 16 bit counters the easy approach is to use a register pair. To make register pairs more convenient as pointers the 16 bit INC/DEC instruction does not set flags. So extra work must be done to test for 0.

There is an instruction, CPI, which will decrement BC and set the overflow flag. It is a byte shorter than the obvious code but slightly slower. It also has the side effect of reading (HL) and incrementing HL so be careful.

However, if your code happens to need HL incremented anyways then it is 4 T-States faster as a bonus.

Because CPI sets the usual flags for other reasons the parity/overflow flag is used to indicate BC != 0. My mnemonic is "overflow means we keep flowing through the loop".

```
; BC to B inner, C outer
 4 8000 AF
                          XOR
                                  Α
                                  \mathsf{C}
 4 8001 B9
                          CP
4 8002 88
                                  A,B
                          ADC
 4 8003 41
                                  B,C
                          LD
4 8004 4F
                                  C,A
                          LD
                 loop3:
                                  loop3
13 8016 10ED
                          DJNZ
13
4 8018 0D
                          DEC
                                  C
10 8019 C20580
                                  NZ,loop3
                          JP
```

Change 16 bit BC loop to two 8 bit Nested

The best way to go faster is to break the loop into an inner loop and outer loop with 8 bit counters. If the loop count is known in advance you can do this by hand. But if the loop count is a parameter then here's a little bit of code to transform the 16 bit loop count into the necessary two 8 bit loop counts. This works for all values of BC include 0 = 65536.

Each iteration only takes 13 rather than the 24 of the straightforward approach. The outer loop iterations are relatively infrequent so don't add much to the total.

The first run through the loop will be the remainder. After that C counts off how many times we do 256 iterations of the loop taking advantage of the fact that B == 0 after the DJNZ completes.

```
; DE to E inner, D outer
 6 8000 1B
                        DEC
                                DE
4 8001 14
                        INC
                                D
 4 8002 1C
                        INC
                                Ε
                loop4:
4 8014 1D
                        DEC
10 8015 C20380
                        JP
                                NZ,loop4
14
4 8018 15
                        DEC
                                D
10 8019 C20380
                                NZ,loop4
                        JP
```

Change any pair to nested

If you don't need that extra T-State per iteration DJNZ gives you then there's an even more compact transformation. It's a good one to sit down and think through how it works.

LD HL,\$3C00 10 8000 21003C 4 8003 AF XOR Α 7 8004 77 loop5: (HL),ALD 6 8005 23 INC HL 8 8006 CB74 6,H BIT Z,loop5 12 8008 28FA JR

Drop Counter and Test Pointer

Another way to speed up loops is to use the pointer to memory as a counter. Thus not having to maintain both a pointer and a counter. This can be difficult and slow in general on a Z-80 as "SBC" is the only 16 bit comparison we have and it is destrutive (though EX DE,HL can help). This example shows clearing the screen on a Model III (\$3C00 .. \$3FFF). It's not actually faster than broken into two 8 bit loops but it is quite compact (and never mind how much slower it is than PUSH).

10	8000	21003C		LD	HL,\$3C00
4	8003	7D		LD	A,L
7	8004	77	loop6:	LD	(HL),A
4	8005	2C		INC	L
10	8006	C20480		JP	NZ,loop6
4	8009	24		INC	Н
8	800A	CB74		BIT	6,H
12	800C	28F6		JR	Z,loop6

Nested Counter Drop

This clear screen is faster yet as it not only uses an 8 bit inner loop but gets rid of the inner counter by using L for both purposes. We're running through memory without using a 16 bit increment!

This is like the previous loop but basically the "INC HL; BIT 6.H" is replaced with an "INC L" dropping 10 T-States out of the loop.

Looping over memory a page at a time like this is a very fast approach. Combined with the split values we say with the table lookups you can see how this can lead to some compact and fast code.

```
; Almost the same as LDIR if BC is even
; (loses 5 cycles in total)
16 8000 EDA0 loop7: LDI
16 8002 EDA0
                      LDI
                      JP V,loop7
10 8004 EA0080
42 (21 / byte)
; faster than LDIR if BC is a multiple of 4
16 8007 EDA0 loop8:
                     LDI
16 8009 EDA0
                      LDI
16 800B EDA0
                      LDI
16 800D EDA0
                      LDI
10 800F EA0780
                      JP V,loop8
74 (18.5 / byte)
```

Unrolling LDIR

A general technique that can be used anywhere is loop unrolling and the Z-80 is no exception.

LDIR is very handy but if BC is even we can unroll LDIR into two LDI instructions and be almost as fast. If we unroll 4 times (BC must be divisible by 4) then the average per byte drops from 21 - epsilon to 18.

If the amount to copy is known then you can unroll fully for 16 T-States/byte.

7	8000	0610		LD	B,64/4
4	8002	AF		XOR	Α
7	8003	86	loop9:	ADD	A,(HL)
4	8004	2C		INC	L
7	8005	86		ADD	A,(HL)
4	8006	2C		INC	L
7	8007	86		ADD	A,(HL)
4	8008	2C		INC	L
7	8009	86		ADD	A,(HL)
6	800A	23		INC	HL
13	800B	10F6		DJNZ	loop9

Unrolling and using 8 bit INC

Since 8 bit increment is two T-States less than 16 bit increment you can also use unrolling to save on the update of the memory pointer. As long as HL 4 byte aligned in this case. And if you know HL doesn't cross a page boundary you can use INC L for all the updates. If we're feeling really clever we could make the page boundary the end of loop condition and drop the counter.

```
(spsave), SP
                        LD
20 8000 ED730C82
 4 8004 F3
                        DI
                                DE,' '*$101
10 8005 112020
                        LD
                                SP, screen+$400
10 8008 310040
                        LD
   800B D5D5D5D5
                        rept 1024/2
11 800F D5D5D5D5
                          PUSH DE
                        endm
                               SP,0
10 820B 310000
                        LD
                                $-2
   820C
                spsave
                        equ
 4 820E FB
                        ΕI
 7 8000 77
                        LD
                                (HL),A
 4 8001 2C
                        INC
```

Unroll All the Way (fast clear)

When it comes to reading a writing memory there is nothing faster on the Z-80 than POP and PUSH. POP can read two bytes in 10 T-States (5 per byte) and PUSH can write two bytes in 11 T-States (5.5 per byte). And you even get to update the destination pointer in that.

Here's a super fast, fully unrolled screen clear. Interrupts must be disabled because we're using the stack. This example is for a TRS-80 Model I, III or 4 but you can do similar things on a Model II but DI won't stop NMI so you'll need to turn that interrupt source off for safety.

Just for comparison the fastest an unrolled conventional loop could manage is 11 cycles/byte.

Exan	1p1	.es
	_	

_	
Three	Useful

Disturbing

ldv reg, var macro REG,(IX+var-varbase) LD endm stv reg, var macro (IX+var-varbase), reg LD endm decv macro var (IX+var-varbase) DEC endm addv macro var A, (IX+var-varbase) ADD endm

Zero Page IX Macros

Programmer convenience isn't nearly as compelling as small and fast programs but it is important. There's a lot of code to write where speed and size are minor concerns but it is complicated enough that juggling registers becomes difficult. These macros allow you to set up 256 byte region in memory of very convenient 8 bit variables. You can pull the variables into any register and even use them as loop counters.

```
defb
10 8000 01
                step
                                 1
   8001
                varbase:
 4 8001 00
                          defb
                count
                                 0
                          defb
 4 8002 00
                pos
                                 0
14 8003 DD210180
                                 IX, varbase
                          LD
19 8018 DD7E00
                          ldv
                                 A, count
 7 801B C605
                                 A,5
                          ADD
19 801D DD86FF
                                 step
                          addv
19 8020 DD7700
                                 A, count
                          stv
                lp:
                           . . .
23 8031 DD3500
                          decv
                                 count
12 8034 20EA
                                 NZ, 1p
                          JR
10 8036 210180
                          LD
                                 HL, count
11 8039 35
                          DEC
                                 (HL)
21
```

Zero Page IX Usage

Here's a quick example of the macros in use. One thing to note is that you can still access the variables directly by their name if that is easier. The cycle counts and byte sizes make it clear that the technique is not winning any speed or size contests. In fact, look how we can decrement a variable using HL as a pointer FASTER than using IX indexing using only one byte extra.

```
Just load A with 0 to start up.
 Use SLA r and RL r for other reg.
4 8000 87
               getbit: ADD
                               A,A
11 8001 C0
                               NZ
                        RET
17 8002 CD0080
                        CALL
                               getbyt
4 8005 37
                        SCF
4 8006 8F
                        ADC
                               A,A
10 8007 C9
                        RET
```

Stream Bits

Oftentimes you need to read data a bit at a time for compression or anything where compact data representation is important. Here's a very efficient approach that doesn't require a register to keep track of the number of bits remaining in the current byte.

The trick is to insure that the bit buffer (A register in this case) will always be non-zero when there are bits remaining. So in the normal case the next bit put into the carry flag and the routine terminates. If not, we get another byte from the input stream, put the top bit into carry and set the lowest bit. That's what guarantees the value will be non-zero as more bits remain. After 7 more calls that bit will end up in the carry but it was just a marker of sorts, A will be all 0's so we'll get another byte.

The whole thing starts out by loading A register with 0. And you can easily use another register besides A if slightly slower.

```
getbyt: INC
 4 8000 2C
 7 8001 7E
                                A,(HL)
                         LD
11 8002 C0
                        RET
                                NΖ
                                fillbuffer
17 8003 CD1980
                        CALL
 7 8006 7E
                                A,(HL)
                         LD
10 8007 C9
                        RET
                fillbuffer:
   8019
10 8029 C9
                         ret
10 802A 21FF81 setup:
                                HL, buffer+255
                        LD
                               ($+255) & -256
   8100
                        org
                buffer: defs
   8100
                                256
```

Stream Bytes

"getbyt" may just step through memory. But if we'd like to stream from floppy then we can use the page-aligned tricks to make another efficient routine for reading another block of 256 bytes at a time. As long as L doesn't "wrap around" to the start of the page.

Initialization is as simple as loading HL with buffer+255 guaranteeing the first call will fill the buffer. If reading from a floppy "fillbuffer" will jump to an error handler if it fails (i.e., an exception). If there is not a full 256 bytes remaining in the file then it only need put them at the end of the buffer and point HL to them.

"INC L" sets the sign bit. By self-modifying the "RET" condition we could have fillbuffer be called after the first or second 128 bytes of the buffer have been consumed. That could give us some parallelism where we kick off a DMA for the consumed part of the buffer so it may be filled while we continue processing.

```
7 8000 1E08
                                 E, od err
                         LD
10 8002 C32F80
                         JP
                                 error
10 8016 C32D80
                                e_syn
                         JP
 7 802A 1E04
                e fc:
                                E,4
                         LD
10 802C 01
                         defb
                                 1
 7 802D 1E02
                                E,2
                         LD
                e syn:
10 802F 213880 error:
                                HL, errtab
                         LD
 7 8032 1600
                         LD
                                D,0
11 8034 19
                         ADD
                                HL, DE
                         JP
10 8035 C31B80
                                 print
                                'NF'
                errtab: ascii
 7 8038 4E46
                               'SN'
 4 803A 534E
                         ascii
 7 803C 4643
                                 'FC'
                         ascii
```

How BASIC Signals Errors

Here's an example of space optimization that might well offend your sensibilities and is something I did whilst fooling around trying to make a smaller version of the Model III BASIC ROM.

BASIC handles errors by loading E register with the error number (always a multiple of two) and jumped to the "error" routine which prints the 2 letter error code and so on.

Each error check can take as much as 5 bytes (load and JP) though common ones are reduced by 3 by jumping to a common "load E" location which can then fall through directly or with "LD BC," jumps.

Short of using RST I couldn't see any way to better this. And even then a "LD E,n; RST" is still 3 bytes so not doing much better than the usual case.

```
10 8000 CD2F80
                                e od
                        CALL
10 8016 CD2C80
                        CALL
                                e_syn
 7 802A 00
               e od:
                        NOP
               e_fc:
10 802B 00
                        NOP
 7 802C 00
                e syn:
                        NOP
; Use return address to find what was
; called and calculate E based on that.
                                HL, errtab
10 802F 213880 error:
                        LD
 7 8032 1600
                        LD
                                D,0
11 8034 19
                                HL, DE
                        ADD
10 8035 C31B80
                        JР
                                print
               errtab: ascii
 7 8038 4E46
                              'NF'
4 803A 534E
                        ascii
                              'SN'
                                'FC'
 7 803C 4643
                        ascii
```

NOP Slide For Errors

So for every error we have an entry in this seriees of NOPs (which won't just 3 but 23 long). To signal an error just call the right routine. We can then pop return return address, look back two bytes to see what the actual entry point of the routine was and then use that to compute E.

I've not shown the actual calculation because I wasn't terribly satisified with the result. It saved some bytes but not a whole lot one the size of the computation code was factored in. After all, the old system handled most error codes with only 3 bytes.

And those NOPs seemed like such a waste. 23 bytes of zeros. Could they at least be doing some work? Well, not especially. You can't stick a subroutine in there because the code has to fall through.

But then I thought, hey, what if we put the error strings where the NOPs are. Could that work?

```
C, (HL)
7 8000 4E
                         LD
                                B,(HL);
                                          'F'
7 8001 46
                         LD
                                D,E
                                          'S'
4 8002 53
                         LD
                                C,(HL)
                                          'N'
7 8003 4E
                         LD
                                          'F'
7 8004 46
                                B,(HL);
                         LD
4 8005 43
                                B,E
                                          'C'
                         LD
```

Executing ASCII!?

However, let's consider the two letter error messages themselves. It's a strange question, but what if we were to run them as code? It turns out that mostly it would mean random registers loaded into other registers. Sometimes it would mean reading (HL) though not writing since those are lower-case letters.

Executing them would be harmless since HL normally points to the BASIC code being interpreted. And H and L load instructions are out of range of the upper-case letters.

```
17 8000 CD1980
                          CALL
                                  err_sn
                          CALL
17 8003 C41780
                                  nz,err_nf
                                   'NF'
 7 8017 4E46
                err nf:
                          ascii
                                  'SN'
 4 8019 534E
                err sn:
                          ascii
                                   'FC'
                err_fc:
 7 801B 4643
                          ascii
10 802E E1
                          POP
                                  HL
                error:
 6 802F 2B
                          DEC
                                  HL
                                  D, (HL)
 7 8030 56
                          LD
 6 8031 2B
                          DEC
                                  HL
 7 8032 5E
                                  E, (HL)
                          LD
 4 8033 7B
                          LD
                                  A,E
 7 8034 D617
                          SUB
                                  low(err nf)
                                  DE, HL
 4 8036 EB
                          EX
 4 8037 5F
                          LD
                                  E,A
10 8038 C31B80
                          JP
                                  print
```

Tighter BASIC Errors

So this insane solution can work. Instead of loading E register anywhere we just CALL the error string. This harmlessly falls through to "error" routine (which is no longer called directly). The CALL isn't because we can return from an error (we can't). Instead, the "error" routine looks at the return address which is just after the CALL to the error string. By backing up two bytes we get the low address of the error string which we can adjust into the error code E. And we were given the address of the string already so that's that.

My actual code was a little more complicated and safer. It had to allow for "/0" and "L3" errors, too, which are less convenient opcodes. There was also more bookkeeping BASIC which I've left out.

Saved 35 bytes!

end entry

End of Class

A small joke here. We have the entry point on the first slide so we must make sure to tell the assembler that we have finished and where to start.