

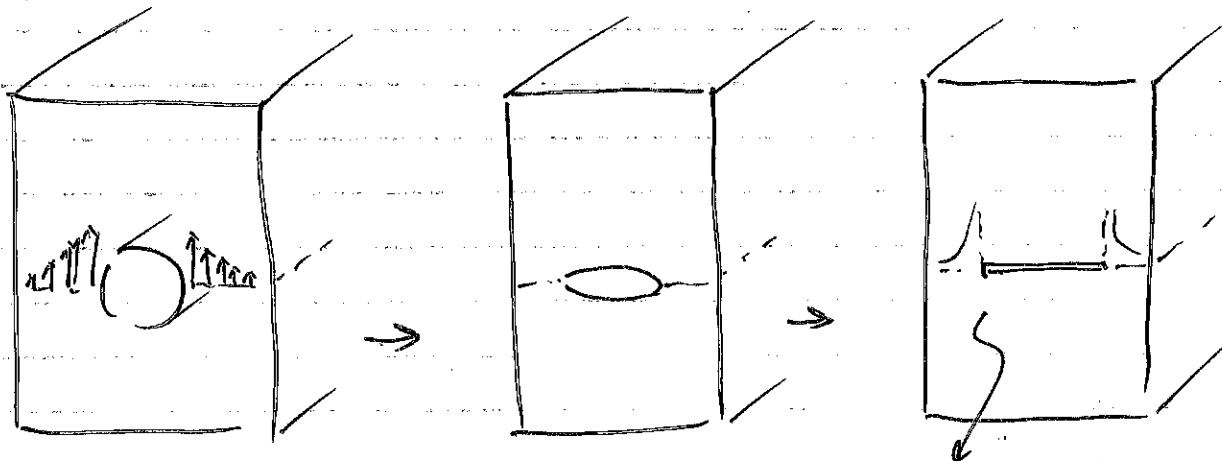
COURSE NOTES

ELASTICITY & INELASTICITY

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Elasticity & Inelasticity. 4/11/2024



~ Soln: 3.

"Singularity"

- Tensor + transform.
- Stress-strain relations

$$\begin{matrix} \text{vector} \\ \underline{u} = u_1 e_1 + u_2 e_2 + u_3 e_3 \\ \downarrow \\ \begin{matrix} e_3 \\ e_1 \\ e_2 \end{matrix} \end{matrix}$$

$$= u_i e_i$$

"not a vector" $\rightarrow u_i = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$

column

vector

$$u_i e_i$$

Einstein notation.

$$u_i = \begin{bmatrix} u'_1 \\ u'_2 \\ u'_3 \end{bmatrix}$$

Define a matrix $\alpha_{ij} = (e_i \cdot e_j)$

Orthogonal matrix: $\alpha^{-1} = \alpha^T$

$$\begin{bmatrix} u'_1 \\ u'_2 \\ u'_3 \end{bmatrix} = \begin{bmatrix} \alpha_{11} & \alpha_{12} & \alpha_{13} \\ \alpha_{21} & \alpha_{22} & \alpha_{23} \\ \alpha_{31} & \alpha_{32} & \alpha_{33} \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$$

$$u'_i = \alpha_{ij} u_j$$

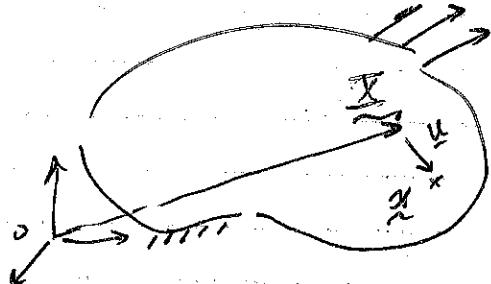
$$a'_i = \alpha_{ij} a_j$$

if index notation.

$$u_i P_{ij} = v_j$$

$$u_i P_{ij} u_j \rightarrow \mathbb{R}$$

unless we specify the element-wise multiplication.



$$u = x - \frac{\tilde{x}}{n}$$

Displacement field.

$$\underline{u}(\tilde{x}) \sim \underline{u}(x) \quad \dots \text{no gradient deformation}$$

tensor here

Strain field.

$$u_{ij} = \frac{\partial u_i}{\partial x_j}$$

Small deformation assumption

$$\text{Strain: } \varepsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i}) = \varepsilon_{ji}$$

assumption

$$\omega_{ij} = \frac{1}{2}(u_{i,j} - u_{j,i}) \leftarrow \text{rotation}$$

No higher-order terms.

$$\varepsilon_{ij} = \text{Dim } \Omega_{jn} \varepsilon_{mn}$$

$$\epsilon_{\text{total}} = \epsilon_0 + \epsilon_{\text{strain}} + \epsilon'$$

$$\epsilon_{\text{strain}} = \text{zeros}(3, 3)$$

for $i = 1:3$

) equivalent.

for $j = 1:3$.

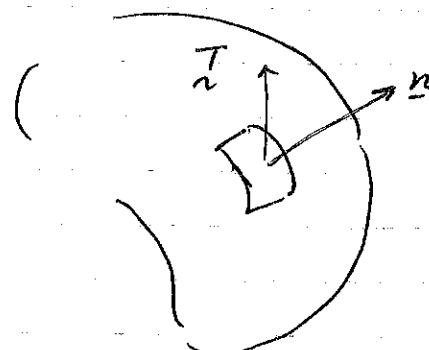
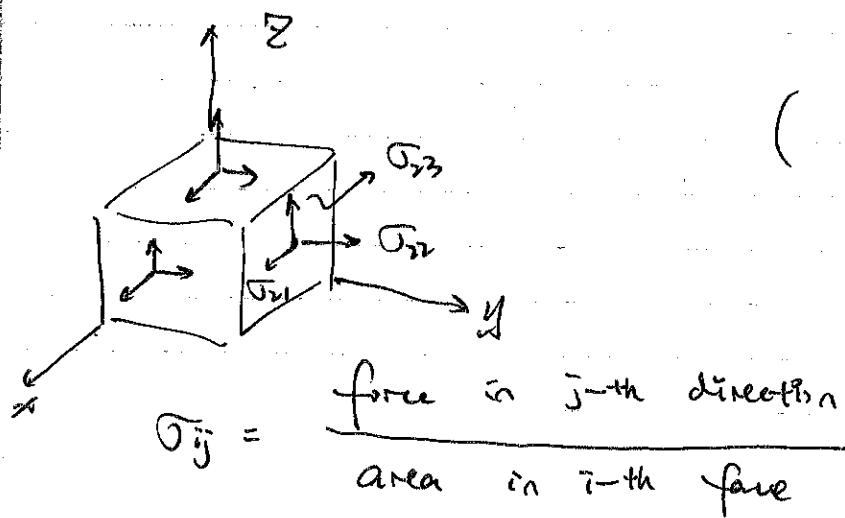
for $m = 1:3$.

for $n = 1:3$.

$$\epsilon_{\text{total}}(i, j) = \epsilon_0 + \epsilon_{\text{strain}}(i, m) + \epsilon'(j, n)$$

$$+ \epsilon_{\text{strain}}(m, n);$$

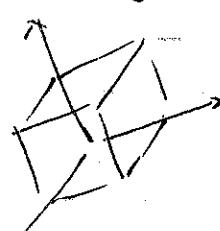
end
end
end
end.



$$\tau_j = \sigma_{ij} n_i$$

symmetric tensors,

$$\sigma_{ij} = \sigma_{ji}$$

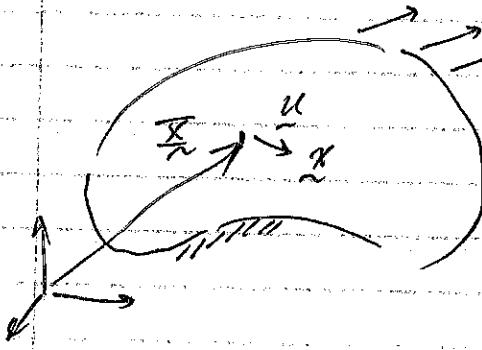


$$\sigma_{ij} = \delta_{ip} \delta_{jq} \sigma_{pq}$$

$$\sigma_{ij} = C_{ijkl} \epsilon_{kl} \rightarrow \sigma_{ijkl} = \delta_{im} \delta_{jn} \delta_{lp} \delta_{kq} C_{mnq}$$

6/13/2024

lecture 2.



Displacement field: $u(x)$

Strain field: $\epsilon_{ij} = \frac{1}{2}(u_{ij} + u_{ji})$

Stress field: σ_{ij}

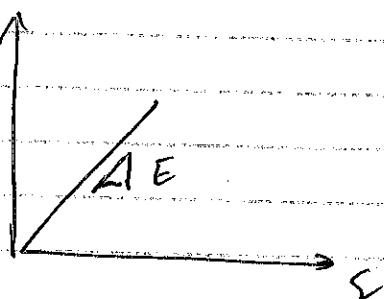
Traction field: $\tau_j = \sigma_{ij} n_i$

Generalized Hooke's law: $\sigma_{ij} = C_{ijkl} \epsilon_{kl}$

Today: { PDE for elasticity.

Attempt to solve it. Anisotropic vs.

Isotropic elasticity.



... generalized Hooke's law.

First relation:

$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \sigma_4 \\ \sigma_5 \\ \sigma_6 \end{bmatrix} \leftarrow \begin{bmatrix} \sigma_{11} & \sigma_{12} & \dots & \sigma_{16} \\ \sigma_{21} & \sigma_{22} & \dots & \sigma_{26} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{61} & \sigma_{62} & \dots & \sigma_{66} \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \epsilon_4 \\ \epsilon_5 \\ \epsilon_6 \end{bmatrix} \rightarrow \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \epsilon_4 \\ \epsilon_5 \\ \epsilon_6 \end{bmatrix}$$

$$\sigma_{ii} = C_{111} \epsilon_{11} + (C_{112} \epsilon_{12}) + \dots + C_{113} \epsilon_{33}$$

$C_{112} \epsilon_{12}$

$$\hookrightarrow C_{1112} \epsilon_{12}$$

↓

$$C_{16} = C_{1112} = C_{1121}$$

$$\sigma_I = C_{IJ} \epsilon_J \quad \Rightarrow J = 1, 2, \dots, 6$$

$$\epsilon_{ij} = S_{ijkl} \sigma_k$$

↑ inverse of C_{ijkl}

$\sigma_{ij} \rightarrow 9$ components, 6 ind. comp.

$C_{ijkl} \rightarrow 81$ components, 21 real. comp.

$$\boxed{\sigma_I = \frac{\partial w}{\partial \epsilon_I}}$$

$$w = \frac{1}{2} \sum \sigma_I \epsilon_I$$

$$\left. \begin{array}{l} 6+5+\dots+1=21 \\ \text{Symmetric } C_{ijkl} \end{array} \right\}$$

$\rightarrow E, v, G$

$\rightarrow S_{ijkl}$

Anisotropic Material

$$\begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ \sigma_{23} \\ \sigma_{31} \\ \tau_{12} \end{bmatrix} = \begin{bmatrix} \frac{1}{E} & -\frac{v}{E} & -\frac{v}{E} & 0 & 0 & 0 \\ \frac{1}{E} & \frac{1}{E} & -\frac{v}{E} & 0 & 0 & 0 \\ -\frac{v}{E} & -\frac{v}{E} & \frac{1}{E} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{G} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{G} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{G} \end{bmatrix} \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \tau_{23} \\ \tau_{31} \\ \tau_{12} \end{bmatrix}$$

sym

Relationship between the material parameters

$$E = 2(1+\nu) \cdot G$$

H.Ws:

$$C_{ij} \rightarrow C_{ijkl} \rightarrow C'_{ijkl}$$

$$S_{ij} \rightarrow S_{ijkl} \rightarrow S'_{ijkl}, \quad E' = \frac{1}{S'_{1111}}$$

If equations for elasticity.

- compatibility condition.

$$\sum \epsilon_{ijkl} + \sum \epsilon_{kl,ij} - (\sum \epsilon_{ik,jl} + \sum \epsilon_{jl,ik}) = 0$$

only for small deformation

- equilibrium condition

$$y \quad [U_{ij,i} + f_j = 0]$$

$$U(x) - 3 \text{ Dof}$$

$$U(x) - 6 \text{ Dof}$$

$$\nabla \cdot \underline{\sigma} + F = 0$$

- constitutive relation.

- B.C.s

For isotropic elasticity:

$$\sigma_{ij} = \lambda \delta_{kk} \sigma_{ij} + 2\mu \epsilon_{ij}$$

$$\epsilon_{ij} = -\frac{\nu}{E} \sigma_{kk} \delta_{ij} + \frac{1+\nu}{E} \sigma_{ij}$$

$$\delta_{ij} = \begin{cases} 1 & , i=j \\ 0 & , i \neq j \end{cases} \quad \text{kroncker delta}$$

$\Sigma_{kk} \rightarrow \Sigma_{\text{trace}}$, i.e., hydrostatic.

$$\epsilon_{11} + \epsilon_{22} + \epsilon_{33}$$

General strategies for soln.

1) $\sigma_{ij} = \lambda u_{kk} \delta_{ij} + \mu(u_{ij} + u_{ji})$.

$$\lambda u_{kk,kk} + (\lambda + \mu) u_{kk,ki} + F_i = 0$$

3 eqs.

$$\mu \nabla^2 u + (\lambda + \mu) \cdot \nabla(\nabla \cdot u) + F = 0$$

2). Write compatibility condition in terms of stress.

(2D)

↳ equilibrium condition

$$\left\{ \begin{array}{l} \sigma_{xx,x} + \sigma_{yy,y} + F_x = 0 \\ \sigma_{xy,x} + \sigma_{yy,y} + F_y = 0 \end{array} \right.$$

2D compatibility: $\epsilon_{xx,yy} + \epsilon_{yy,xx} + 2\epsilon_{xy,xy} = 0$

trial soln / ansatz: $\phi(x, y)$

$$\left. \begin{array}{l} \sigma_{xx} = \phi_{,yy} \\ \sigma_{yy} = \phi_{,xx} \\ \sigma_{xy} = -\phi_{,xy} \end{array} \right\} \text{equilibrium automatically satisfied}$$

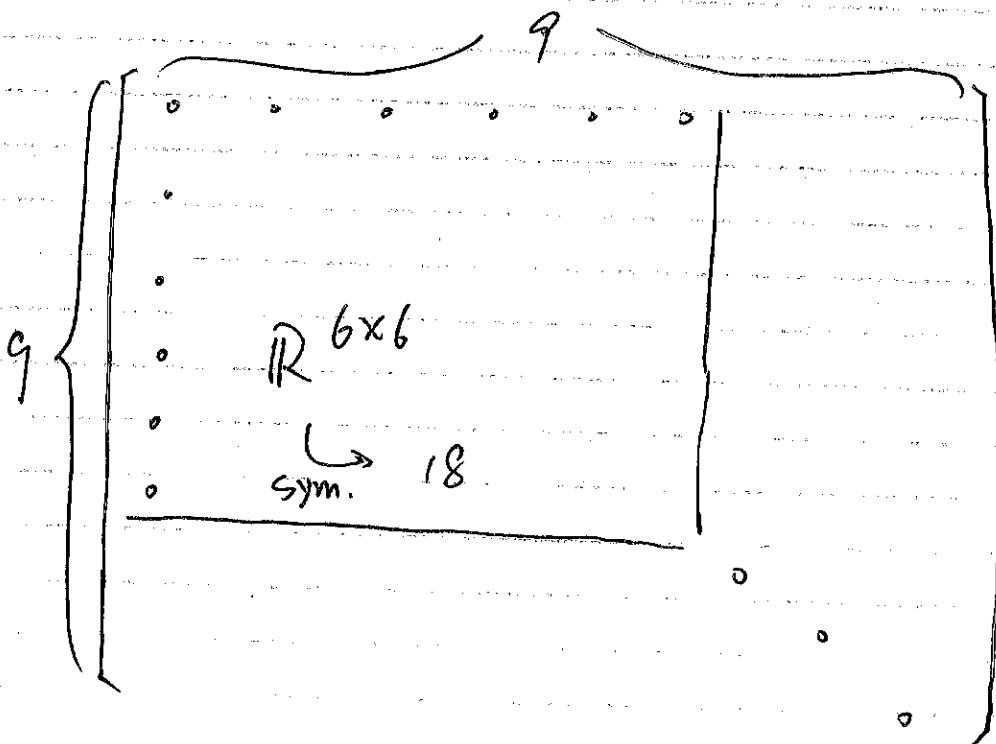
↳ compatibility condition.

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi(x,y) = 0$$

↳ biharmonic eqn.

$$\nabla^2(\nabla^2\phi) = 0$$

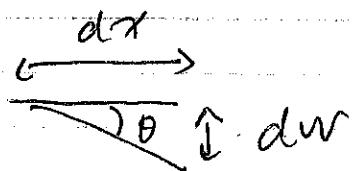
$$81 \rightarrow 21$$



Review of Euler-Bernoulli Beam theory

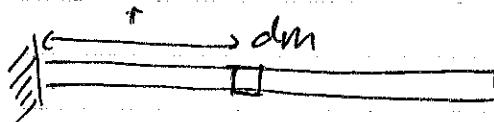
- ① Plane strain
- ② N.A.
- ③ Small deformation
- ④ plane strain \perp N.A.

Assume L

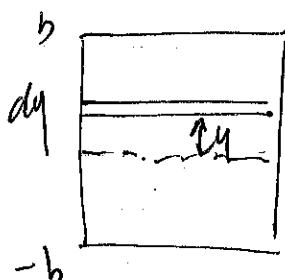


$$\tan \theta = \frac{dw}{dx} \approx \theta$$

$$K = \frac{d\theta}{dx} = \frac{\text{Moment}}{\text{Resistance to bending}}$$



$$I = \int r^2 dm$$

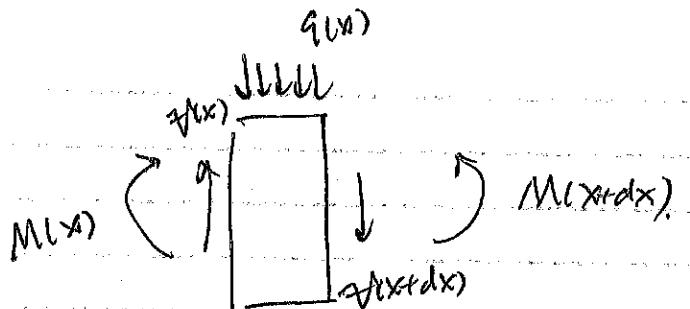


$$E \int_{-b}^b y^2 dy$$

area moment of inertia

$$EI_z = \frac{2Eb^3}{3}$$

$$K = \frac{M}{EI_z} = \frac{dw}{dx^2} \quad \dots \quad (1)$$



$$q(x) dx + \Delta(x+dx) = \Delta(x)$$

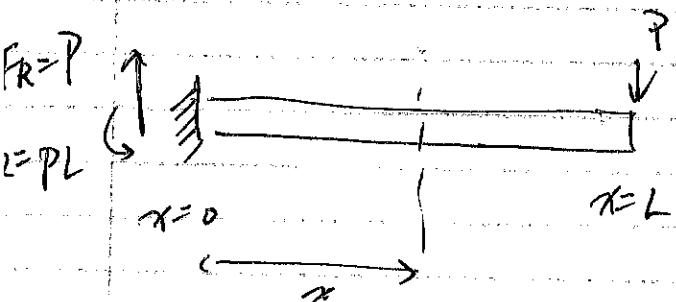
$$q(x) = \frac{d\Delta(x)}{dx} \quad \textcircled{2}$$

$$M(x) + \Delta(x) \frac{dx}{2} + \Delta(x+dx) \frac{dx}{2} = M(x+dx)$$

$$\Delta(x) = \frac{dM(x)}{dx}, \quad \textcircled{3}$$

$$EI_2 \frac{d^4 w}{dx^4} = -q(x).$$

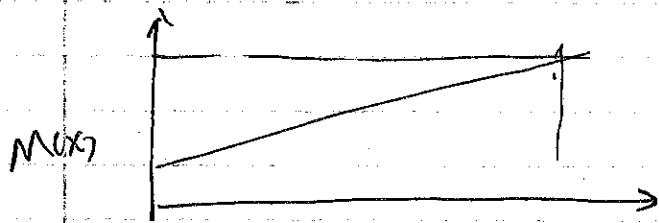
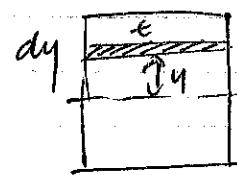
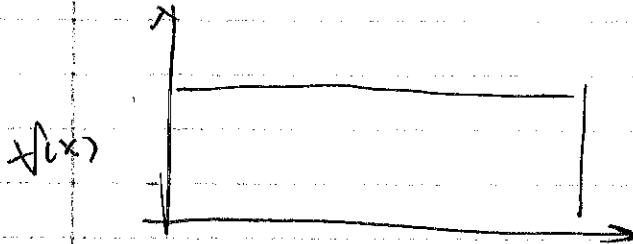
examples



$$\Delta(x) = P$$

$$PL + M = Px.$$

$$M = PLx - L$$



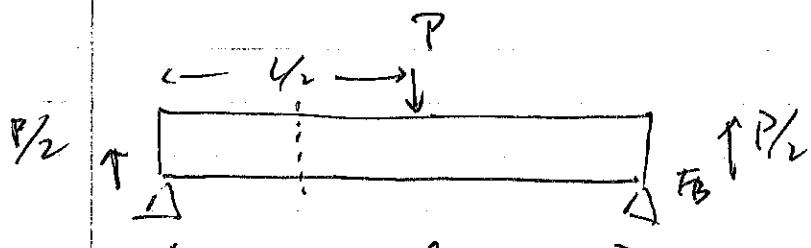
$$M(x) = \int_{-b}^b y T_{xy}(x, y) dy.$$

$$T_{xx} = \frac{-M}{I_2} y$$

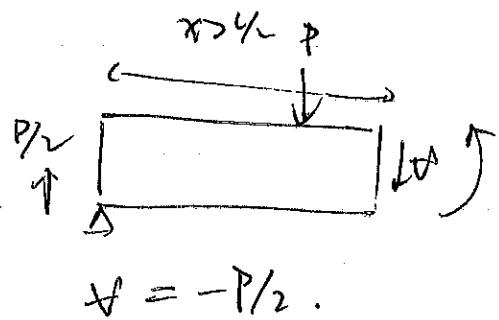
$$T(x) = \int_{-b}^b T_{xy}(x, y) dy.$$

$$T_{xy} = \frac{3T(x)}{2A} \left[1 - \left(\frac{y}{b} \right)^2 \right]$$

$A = 2 + b$

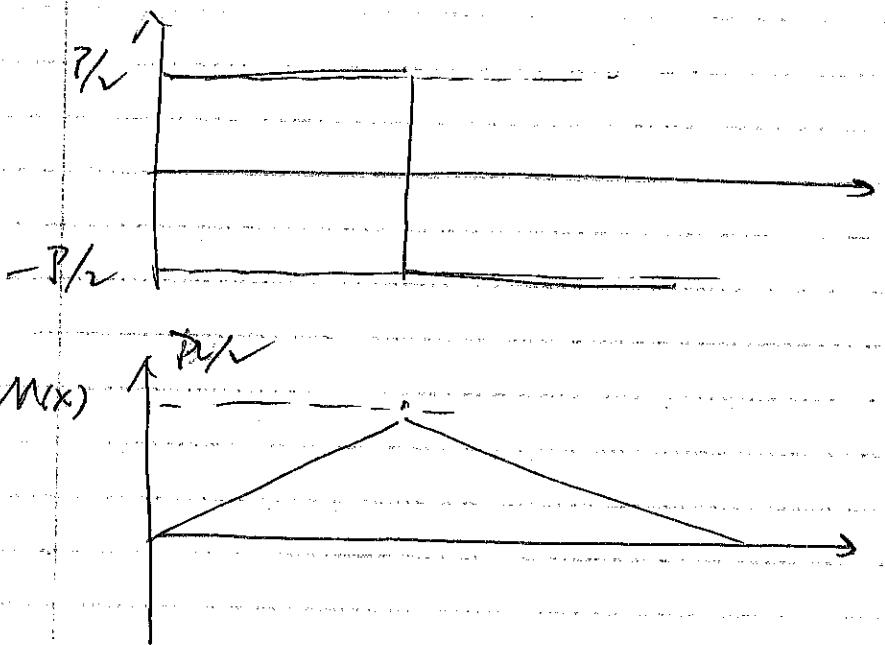


$$M = P x / 2$$

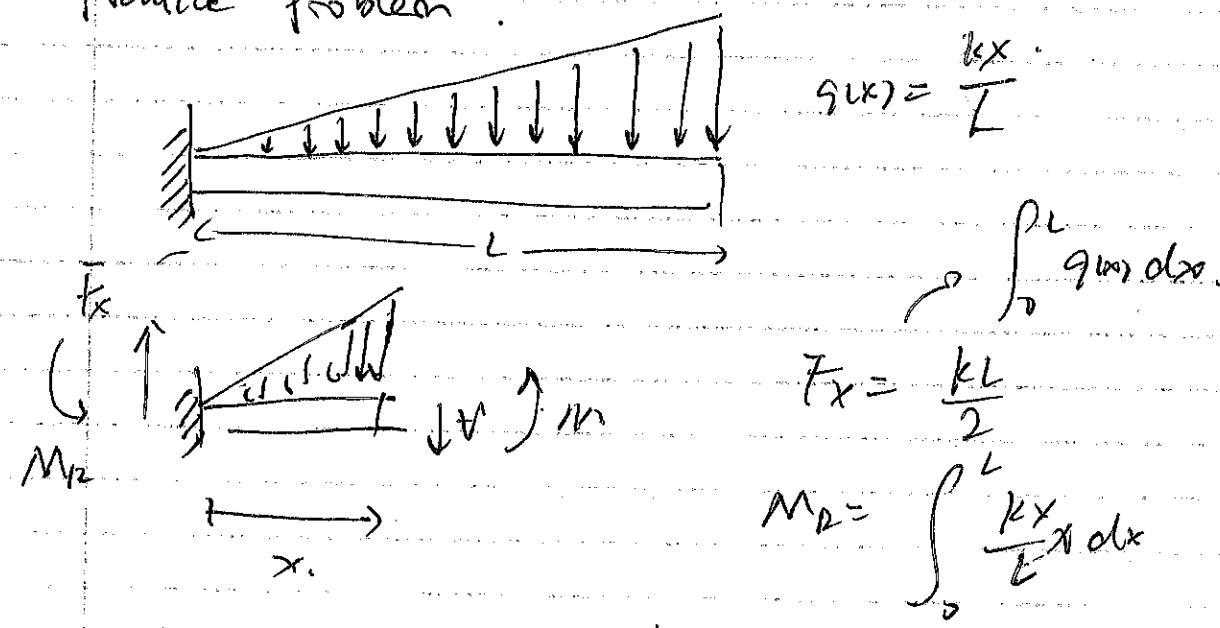


$$M = -P/2$$

$$P/2 - P x/2 = M = \frac{P}{2} (L - x)$$



Practice Problem:



$$F(x) = F_x = \frac{k(l^2 - x^2)}{2l} = \frac{1}{l} \frac{1}{3} kx^3 \Big|_0^l$$

$$M(x) = \frac{k}{2l}(l^2 - x^2)x + \frac{k}{3l}x^3 - \frac{kl^3}{3l}$$

$$\Sigma N \cdot x + \int_0^x q(x) \cdot x dx - M_x = \frac{1}{3} k l^2$$

Stiffness tensor

$$\sigma_{ij} = C_{ijkl} \epsilon_{kl}$$

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{44} \\ \sigma_{55} \\ \sigma_{66} \end{bmatrix} = \begin{bmatrix} C_{11} & \dots & C_{16} \\ ; & ; & ; \\ ; & ; & ; \\ C_{61} & \dots & C_{66} \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \epsilon_4 \\ \epsilon_5 \\ \epsilon_6 \end{bmatrix}$$

4/8/2024.

Lecture 3.

Elasticity equations.

- compatibility. $\epsilon_{ij,kl} + \epsilon_{kl,ij} - \epsilon_{ik,jl} - \epsilon_{jl,ik} = 0$.

- equilibrium. $\sigma_{ij,i} + f_i = 0$

Approach ①: (3D). ← solve displacements.

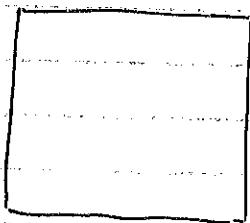
$$\sigma_{ij} = \mu u_{kk} \cdot \delta_{ij} + \mu(u_{i,j} + u_{j,i})$$

$$\mu u_{kk,i} + (\lambda + \mu) u_{k,k,i} - f_i = 0$$

$$i=x \quad \mu \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) u_x + (\lambda + \mu) \frac{\partial}{\partial x} \left(\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} \right) + f_x = 0$$

Approach ②: (2D).

- plane strain.



$$u_x(x,y)$$

$$u_y(x,y)$$

$$u_z = 0 \quad \Rightarrow \quad \frac{\partial}{\partial z} = 0$$

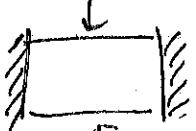
$$\epsilon_{xx}, \epsilon_{yy}, \epsilon_{xy} \rightarrow \epsilon_{zz}=0, \epsilon_{yz}=0, \epsilon_{xz}=0$$

$$\sigma_{xx}, \sigma_{yy}, \sigma_{xy} \rightarrow \sigma_{zz}=0, \sigma_{yz}=0, \sigma_{xz} \neq 0$$

$$\left\{ \begin{array}{l} \epsilon_{xx} = \frac{1}{E} \sigma_{xx} - \frac{\nu}{E} \cdot \sigma_{yy} - \frac{\nu}{E} \sigma_{zz} \\ \epsilon_{yy} = -\frac{\nu}{E} \cdot \sigma_{xx} + \frac{1}{E} \sigma_{yy} - \frac{\nu}{E} \sigma_{zz} \end{array} \right.$$

$$\sigma_{zz} = \nu(\sigma_{xx} + \sigma_{yy})$$

$$\epsilon_{xy} =$$



(under plane strain assumption).

$$\left\{ \frac{1-\nu^2}{E} \sigma_{xx} - \frac{\nu(1+\nu)}{E} \sigma_{yy}, \right.$$

$$\left. -\frac{\nu(1+\nu)}{E} \sigma_{xx} + \frac{1-\nu^2}{E} \sigma_{yy}. \right.$$

equilibrium. $\int \sigma_{xx,x} + \sigma_{yx,y} + F_x = 0$

$$\int \sigma_{xy,x} + \sigma_{yy,y} + F_y = 0$$

compatibility: $\Sigma_{xx,yy} + \Sigma_{yy,xx} - 2 \Sigma_{xy,xy} = 0$

• plane stress.

$$\sigma_{xx}, \sigma_{yy}, \sigma_{xy}, \quad \sigma_{xz}=0, \sigma_{yz}=0, \sigma_{zz}=0.$$

$$\epsilon_{xx}, \epsilon_{yy}, \epsilon_{xy}, \quad \epsilon_{xz}=0, \epsilon_{yz}=0, \epsilon_{zz} \neq 0$$

$$\left\{ \epsilon_{xx} = \frac{1}{E} \sigma_{xx} - \frac{\nu}{E} \sigma_{yy}, \right.$$

$$\left. \epsilon_{yy} = -\frac{\nu}{E} \sigma_{xx} + \frac{1}{E} \sigma_{yy}, \right.$$

$$\epsilon_{xy} = \frac{1}{2\mu} \sigma_{xy}$$



face to expand in z.

Kolosov's constant $K = 3 - 4\nu$
plan strain.)

$$K = \frac{3-\nu}{1+\nu} \rightarrow \text{plane stress.}$$

Ansatz: \rightarrow Airy stress function, $\phi(x, y)$.

$$\left\{ \sigma_{xx} = \phi_{,yy} \right.$$

$$\left. \sigma_{yy} = \phi_{,xx} \right.$$

$$\sigma_{xy} = -\phi_{,xy}$$

\rightarrow equilibrium condition

automatically satisfied

$$\left(\frac{\partial^4}{\partial x^4} + \frac{\partial^4}{\partial y^4} + 2 \frac{\partial^2}{\partial x^2} \frac{\partial^2}{\partial y^2} \right) \phi(x,y) = 0.$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi(x,y) = 0$$

$$\nabla^2 (\nabla^2 \phi) = 0$$

$$\nabla^4 \phi = 0 \quad \leftarrow \text{biharmonic sign.}$$

Examples.

$$\phi(x,y) = \alpha x + \beta y + \delta$$

\rightarrow stresses are zero

$$\phi(x,y) = \frac{1}{2} Ax^2 + \frac{1}{2} By^2 - Cxy$$

$$\rightarrow \sigma_{xx} = B$$

$$\sigma_{yy} = A$$

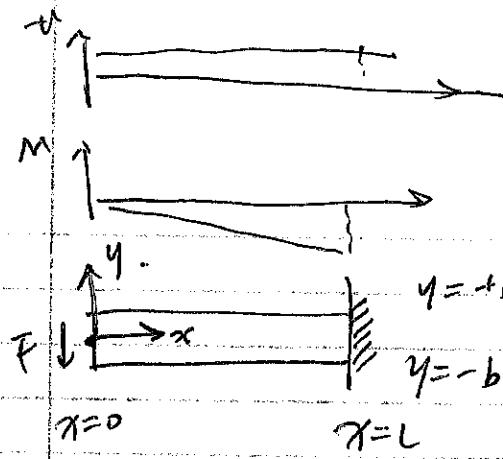
$$\sigma_{xy} = C$$

$$\leftarrow \boxed{x} \rightarrow \pi \rightarrow \theta \quad \phi = \frac{1}{2} \sigma_y y^2$$



$$\phi = -\frac{1}{8} \frac{M}{I} y^6$$

$$\sigma_{xx} = -\frac{M}{I} y$$



Top. Bottom. \rightarrow traction face. $\left\{ \begin{array}{l} \sigma_{xy} = 0 \\ \sigma_{yy} = 0 \end{array} \right. \quad y = \pm b$

J.D⁴

$$\int_a^b (\text{work}) \quad \sigma_{xx} \dots ?$$

"Strong B.C."

Left side $\int_{-b}^b \sigma_{xy} dy = F \quad \dots \text{weak .B.C.s}$

$$\int_{-b}^b \sigma_{xx} y dy = 0 \quad \left. \right|_{x=0}$$

$$\int_{-b}^b \sigma_{yy} dy = 0$$

Right side

\hookrightarrow automatically satisfied. $x=L$
(only for stress).

$$u_x = 0, \quad u_y = 0,$$

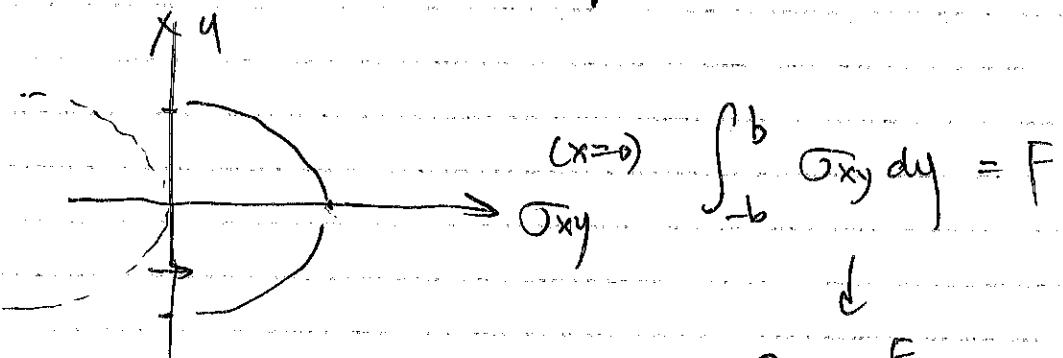
$x=L$. \leftarrow Strong B.C.s.

Guess. $\phi = C_1 xy^3$ -3C_1 b^2 xy
 all the stress field.

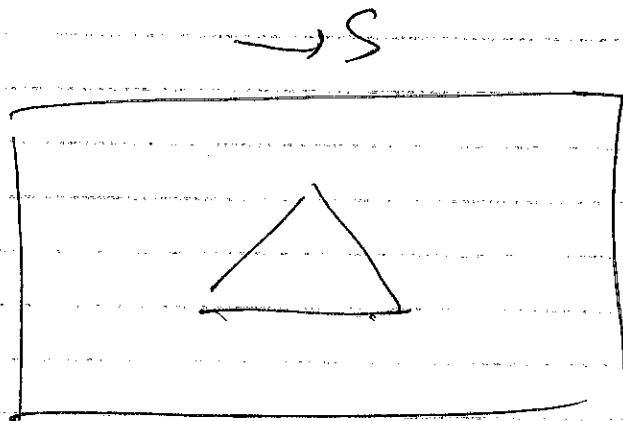
$$\left\{ \begin{array}{l} \sigma_{xx} = 6C_1 xy \\ \sigma_{yy} = 0 \end{array} \right. \rightarrow \frac{3F}{2b^3} xy$$

$$\sigma_{xy} = -3C_1 y^2 \xrightarrow{-3C_1 b^2} \frac{3F}{4b^3} (b^2 - y^2)$$

$$\sigma_{xy} = -3C_1 b^2, \quad y = \pm b$$



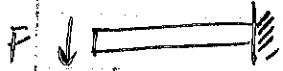
$$C_1 = \frac{F}{4b^3}$$



$$\frac{\sigma_b}{2} = 0.5 \rho b^2 y + 0.b$$

S ←

Lecture 4. 4/10/2024



$\phi(x, y)$.

$\sigma_{xx}, \sigma_{yy}, \sigma_{xy}$.

$$\epsilon_{xx} = \frac{1}{E} \sigma_{xx} - \frac{\nu}{E} \sigma_{yy} = \frac{3F}{2Eb^3} xy$$

$$\epsilon_{yy} = -\frac{\nu}{E} \sigma_{xx} + \frac{1}{E} \sigma_{yy} = -\frac{3F\nu}{2b^3} xy.$$

$$\epsilon_{xy} = \frac{1}{2\nu} \sigma_{xy} = \frac{1}{E} \sigma_{yy} = \frac{3F(1+\nu)}{4Eb^3} (b^2 - y^2).$$

$$u_x = \int \epsilon_{xx} dx = \frac{3F}{4Eb^3} x^2 y + f(y).$$

$$u_y = \int \epsilon_{yy} dy = -\frac{3F\nu}{4Eb^3} xy^2 + g(x)$$

$$u_{xy} = \frac{1}{2} (u_{xy,y} + u_{y,xy}).$$

$$2. \frac{3F(1+\nu)}{4Eb^3} (b^2 - y^2) = \frac{3F}{4Eb^3} x^2 + f(y) - \frac{3F\nu}{4Eb^3} y^2 + g(x)$$

$$\underbrace{\frac{3F}{4Eb^3} x^2 + g(x)}_{\text{function of } x} = \underbrace{\frac{3F(1+\nu)}{2Eb^3} (b^2 - y^2) + \frac{3F\nu}{4Eb^3} y^2 - f(y)}_{\text{function of } y} = C$$

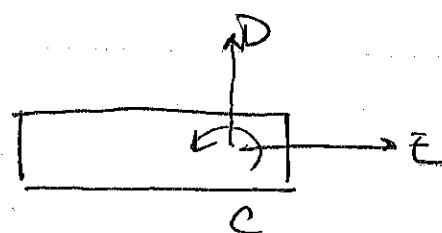
has to be const.

$$g(x) = C - \frac{3F}{4Eb^3} x^2$$

$$g(x) = Cx - \frac{F}{4Eb^3} x^3 + D$$

$$f(y) = \dots$$

$$f(y) = -Cu + \dots + E$$



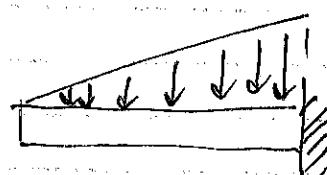
Weak B.C.s \rightarrow St. Venant's principle.

(f)

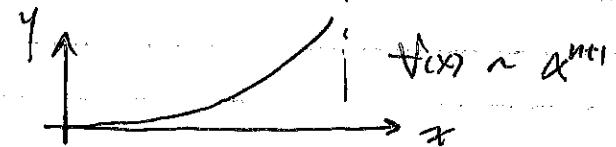
Discussion on exactly

Satisfying the imposed B.C.s

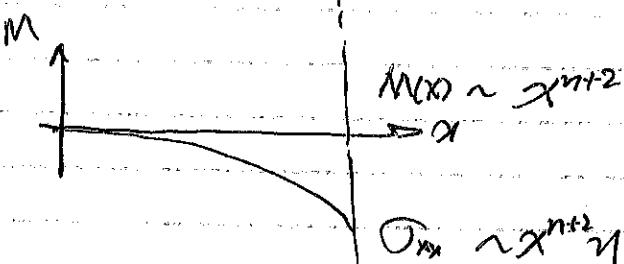
Correction term decays exponentially.



$$q(x) \sim x^n$$



$$f(x) \sim x^{n+1}$$



$$M(x) \sim x^{n+2}$$

$$O_x \sim x^{n+2}$$

B.C.s.

$$\Omega_x(x, y=0) = -q(x)$$

$$\Omega_y(x, y=0) = 0$$

stay BC
has to satisfy

$$\phi \sim x^{n+2} y^3 \quad \phi(x, y) = C_1 x^2 + C_2 xy + C_3 y^2 + C_4 x^3 + \dots$$

Max. order antisymmetric \downarrow biharmonic.

$$\nabla^4 \phi = 0$$

$$x \quad y \quad 1$$

B.C.s

satisfy \rightarrow

determine the coeff.

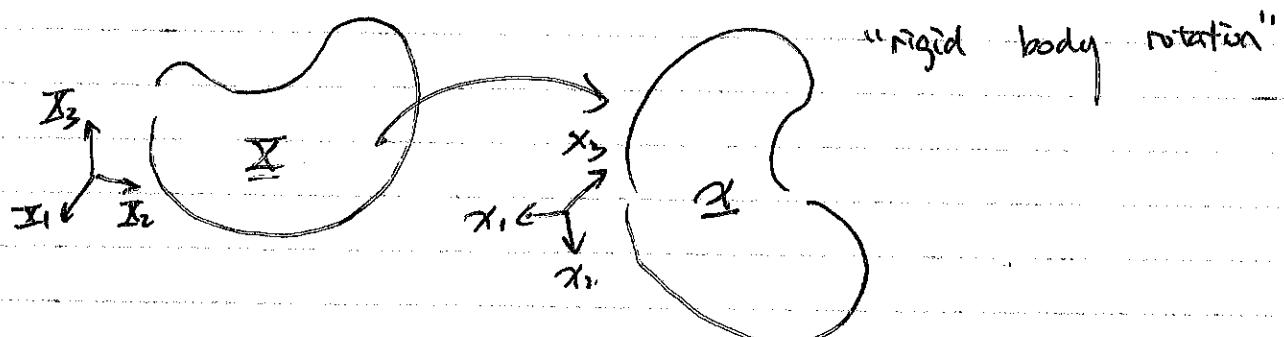
$$x^2 \quad xy \quad y^2 \quad 1$$

$$x^3 \quad x^2 y \quad x y^2 \quad y^3 \quad 2$$

$$x^4 \quad x^3 y \quad x^2 y^2 \quad y^4 \quad 3$$

Derivation of rotational tensor

Begin with the continuum potato:



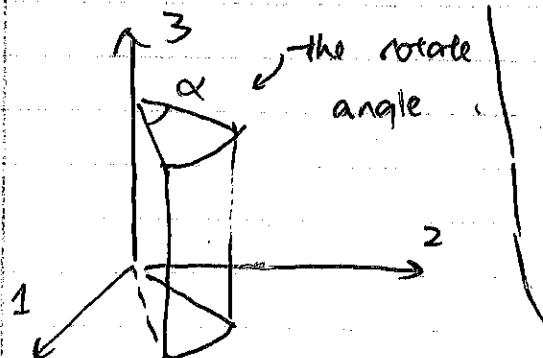
Let's assume there's no deformation in the potato, i.e., pure rigid body rotation. The original coordinate writes $\underline{\underline{\Sigma}} = [I_1, I_2, I_3]^T$, and the rotated coordinate is $\underline{\underline{\Sigma}} = [x_1, x_2, x_3]^T$.

Now let's assume if we just rotate the I_3 axis (or z-axis), the transformation writes

$$x_1 = I_1 \cos \alpha - I_2 \sin \alpha, \quad x_2 = I_1 \sin \alpha + I_2 \cos \alpha$$

$$x_3 = I_3$$

→ it looks something like:



↑ how we introduce the
rotational tensor

Now, this process can be

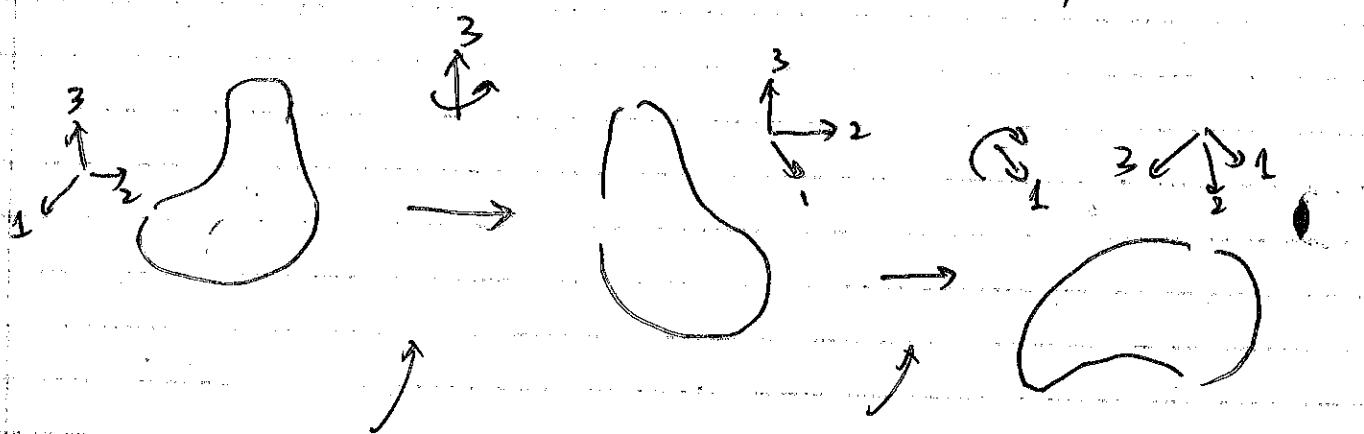
$$\text{written as } \underline{\underline{\Sigma}} = \underline{\underline{Q}} \cdot \underline{\underline{\Sigma}}$$

this $\underline{\underline{Q}}$ is

$\cos \alpha$	$-\sin \alpha$	0
$\sin \alpha$	$\cos \alpha$	0
0	0	1

LINEAR ALGEBRA

from \underline{I} to \underline{x} if we just rotate along the 3-axis, we need 1 $\underline{\Omega}$ tensor, if we want to rotate for both 1, 2, 3 axes, then we will need a bunch of $\underline{\Omega}$ tensors to represent the transformations, something like



needs a $\underline{\Omega}$
here

needs another $\underline{\Omega}$

So this transformation

process can be decomposed

and...

another $\underline{\Omega}$!!

into a bunch of $\underline{\Omega}$'s

→ that's why you'll need to multiply by many $\underline{\Omega}$ s if you want to rotate around many directions.

that example just illustrates how we rotate

a vector $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \rightarrow$ or x_i .

if we want to rotate a tensor,

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \rightarrow \text{or } A_{ij}, \text{ (indicial notation)}$$

we'll need to rotate both the two axes,

we then need two transformation tensors,

because a second-order tensor can be think

of the out. product of 2 vectors (axes in

our example). \rightarrow So, if you want to rotate

a second-order tensor, you'll need 2 R 's.

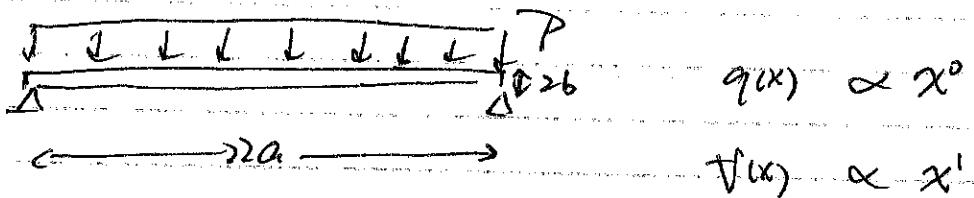
Similarly, if you want to rotate a fourth

order tensor, you then need 4 R 's to

transform (rotate) the 4 axes in that tensor

Problem Session #2

Problem 1 ... using Airy stress function.



$$\phi(x, y) = C_1 x^2 \dots C_{18} \quad M(x) \propto x^2$$

$$t_1 = \sigma_{yy}(x, y = \pm b) = S_1 x^3 + S_2 x^2 \quad \sigma_{xx} \propto M(x) y$$

$$t_2 \quad t_3 \quad t_4 \quad \phi \propto x^{n+5}$$

$$\frac{P}{l^3}$$

4 strong B.C.s \rightarrow 16 coefficients.

$$F_{\text{ax}} = \int_{-b}^b \sigma_{xx} dy = 0$$

Weak B.C.s

$$F_{\text{fy}} = \int_{-b}^b \sigma_{xy} dy = -p_a$$

$$M = \int_{-b}^b \sigma_{xy} y dy = 0 \quad \rightarrow 6 \text{ equations}$$

$$\nabla^4 \phi = 0$$

3 equations
6 coefficients

3 eqns

Obtain the exact form of ϕ

L

get σ_{xx} , σ_{yy} , ...

$$u_x = \int \epsilon_{xx} dx + f_{xy}$$

$$u_y = \int \epsilon_{yy} dy + f_{yx}$$

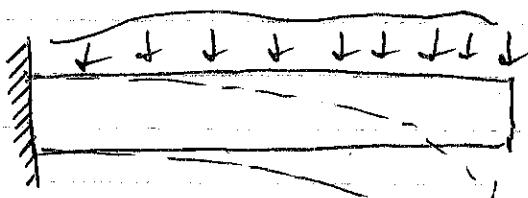
$$\epsilon_{xy} = \frac{1}{2} \left[\frac{\partial u_x}{\partial y} + \frac{\partial u_y}{\partial x} \right]$$

L

$$F(x) = G(y) = C \quad (\text{separate variables})$$

$$C_A + D,$$

$$C_B + E$$



@ $x=0$, $\forall y$.

$$u_x = 0, u_y = 0$$

"not satisfied"

$$\int u_x dy = 0$$

Weak B.C.s

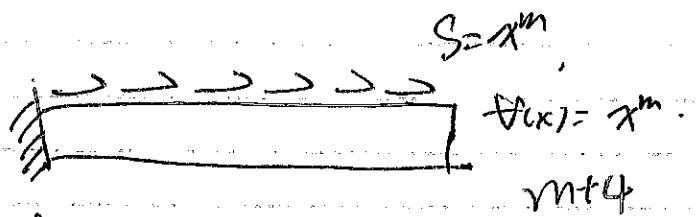
$$x=0, y=0$$

$$\int u_y dx = 0$$

$\frac{\partial u_y}{\partial x} = 0$ ← horizontal.

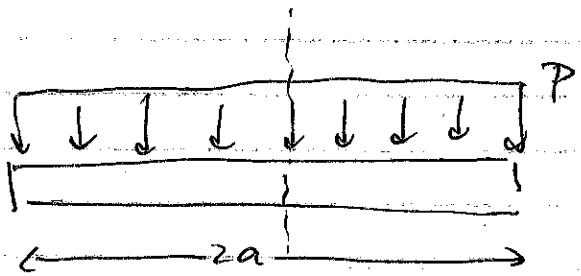
$$\text{moment, } \int u_{xy} dy = 0$$

$$\Rightarrow \partial u_x, y = 0$$



den 2

Using Fourier Series,



$$f(x) = a_0 + \sum_{n=1}^{\infty} a_n \cos(n\pi x/a) + \sum_{n=1}^{\infty} b_n \sin(n\pi x/a)$$

even func. odd func.

$$\lambda_n = \frac{2n\pi}{2a} = \frac{n\pi}{a}$$

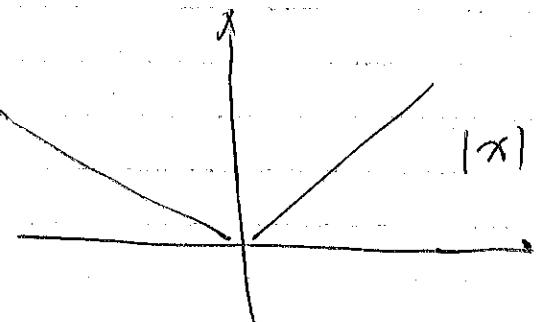
$$P = \sum_{n=1}^{\infty} a_n \cos(n\pi x/a)$$

$$\lambda_n = \frac{(2n-1)\pi}{2a}$$

$$a_n = \frac{2}{2a} \int_{-a}^a P \cdot \cos(n\pi x/a) dx$$

Integration to

determine the
coefficients



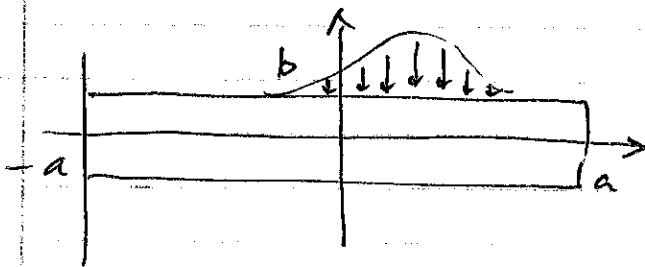
4/15/2024. Lecture 5

Stress function, $\phi(x, y)$. (Recap).

$$\{ \sigma_{xx} = \phi_{yy},$$

$$\sigma_{yy} = \phi_{xx}. \rightarrow \nabla^4 \phi = 0$$

$$\sigma_{xy} = -\phi_{xy}$$



+ trial $\phi(x, y)$ Polynomials.

$$\sigma_{yy}(x, y=\pm b) = \pm t_{y\pm}(x),$$

$$\sigma_{xy}(x, y=\pm b) = \pm t_{xy}(x)$$

trial soln: $\phi(x, y) = e^{\alpha x} e^{\beta y}$

... separation of vars.

$$e^{ikx} = \cos kx + i \sin kx$$

$$\nabla^2 \phi = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) (e^{\alpha x} e^{\beta y}) = (\alpha^2 + \beta^2) (e^{\alpha x} e^{\beta y}).$$

$$\nabla^2 \phi = 0 \quad \dots \text{harmonic eqn} \rightarrow \alpha^2 + \beta^2 = 0$$

General form of the soln:

$$\alpha^2 = -\beta^2$$

$$\phi(x, y) = e^{i\alpha x} e^{i\beta y}$$

$$\alpha = \pm i\beta$$

if not harmonic

$$\nabla^2(\nabla^2\phi) = 0$$

$$\phi(x,y)$$

$$e^{ix}, e^{iy}, e^{ix}, e^{-iy}, e^{ix}e^{iy}, e^{ix}e^{-iy}$$

general expression for ϕ .

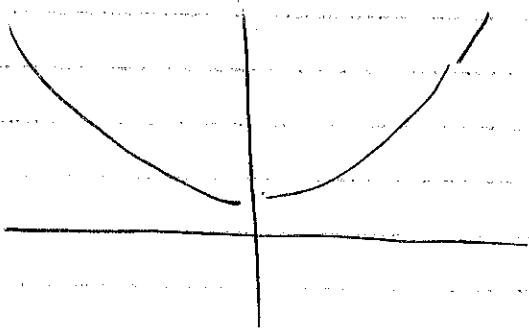
$$\phi(x,y) = e^{ix} [(A + C_2y)e^{iy} + (C_3 + C_4y)e^{-iy}]$$

$$\cosh y = \frac{e^{iy} + e^{-iy}}{2}$$

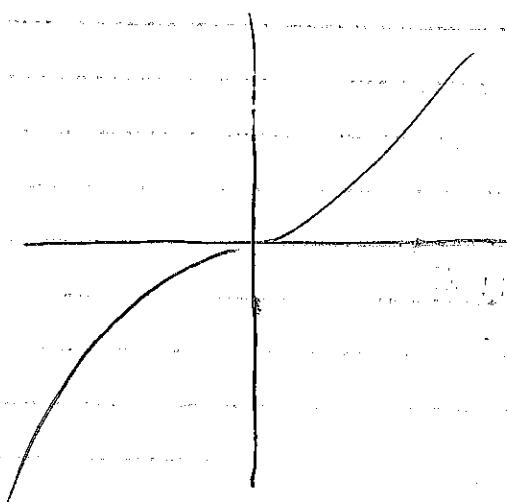
$$\sinh y = \frac{e^{iy} - e^{-iy}}{2}$$

$$\cos kx = \frac{e^{ikx} + e^{-ikx}}{2}$$

$$\sin kx = \frac{e^{ikx} - e^{-ikx}}{2i}$$



$\cosh y$



$\sinh y$

even func. of x .

(prob. even w.r.t. ∞).

$$\phi(x, y) = \cos \pi x \left[\underbrace{A e^{\pi y}}_{\text{sin } \pi x} \quad \underbrace{B y e^{\pi y}}_{\downarrow} \quad \underbrace{C e^{-\pi y}}_{\downarrow} \quad \underbrace{D y e^{-\pi y}}_{\downarrow} \right]$$

$$+ B' y \cosh \pi y + C' \sinh \pi y.$$

$$= \frac{A' (e^{\pi y} + e^{-\pi y})}{2} + \frac{C' (e^{\pi y} - e^{-\pi y})}{2}$$

$$= \frac{A' + C'}{2} e^{\pi y} + \frac{A' - C'}{2} e^{-\pi y}.$$

(try to group term ...)

$$\phi(x, y) = \cos \pi x [A' \cosh \pi y + D' y \sinh \pi y]$$

even in both

even fun.
 ∞ in y .

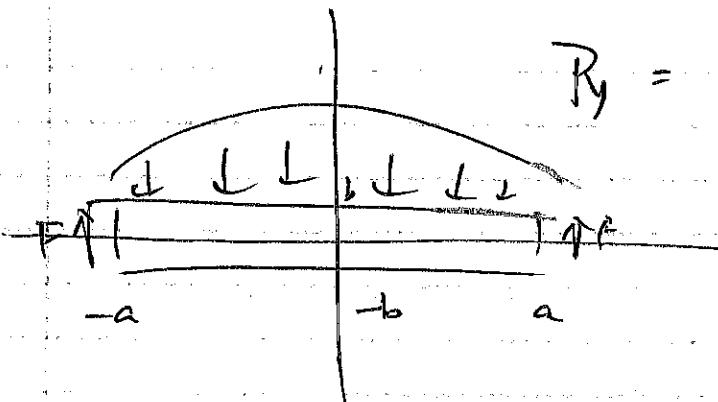
$$\cos \pi x [B' y \cosh \pi y + C' \sinh \pi y]$$

even in y .

odd in y .

$\sin \pi x [\dots]$

$\sin \pi x [\dots]$



$$R_y = P_0 \cos \frac{\pi x}{2a}$$

B.C. $\left\{ \begin{array}{l} \sigma_{yy}(x, y=\pm b) = -P_0 \cos \frac{\pi x}{2a} \\ \sigma_{yy}(x, y=-b) = 0 \end{array} \right.$

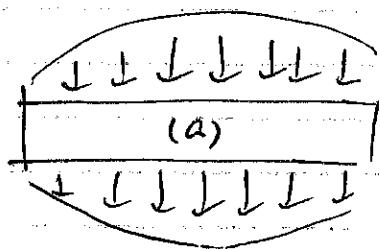
$$\sigma_{yy}(x, y=+b) = 0$$

$$\sigma_{xy}(x, y=-b) = 0$$

$$\sigma_{xy}(x, y=+b) = 0$$

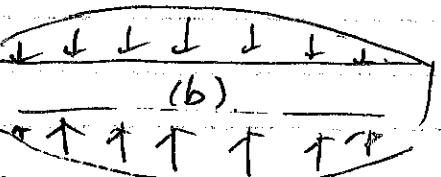
find c_1, c_2, c_3, c_4 (with $\lambda = \frac{\pi}{2a}$)

Principles of superposition.



(a)

+



(b)

$$\frac{1}{2} P_0 \cos \frac{\pi x}{2a}$$

σ_{yy} even in x .
odd in y .

σ_{yy} even in x .
even in y .

ϕ even in x ,
odd in y .

σ_{xy} odd x ,
even y .

ϕ even in x ,
even in y .

σ_{yy} even in x .

$$(a). \phi = \cos \pi x [By \cosh \pi y + C \sinh \pi y]$$

$$B.C. \sigma_{yy}(x, y=b) = -\frac{1}{2}P_0 \cos \frac{\pi x}{2a}$$

$$\sigma_{xy}(x, y=b) = 0$$

$$\lambda = \frac{\pi}{2a}$$

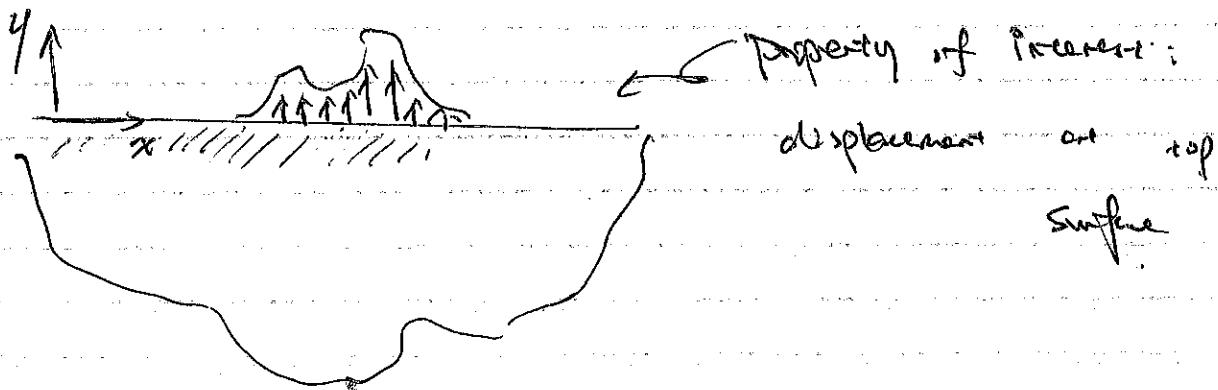
$$\sigma_{yy} = -\lambda^2 \cos \pi x [\dots]$$

$$\sigma_{xy} = \dots$$

plug in $y=b$.

lecture 6 01/17/2024.

Elastic Half Space



① Euler-Bernoulli beam theory

$$w(x) \propto \frac{1}{I}$$

$$\theta(x) \propto \tau_{xy}(x) \propto \frac{1}{I}$$

$$M(x) \propto \tau_{xx}(x) \propto \frac{1}{I}$$

② Army stress function approach $\therefore \phi$

$$\nabla^4 \phi = 0$$

$$\sigma_{xx} = \phi_{yy}$$

$$\sigma_{yy} = -\phi_{xx}$$

$$\tau_{xy} = -\phi_{xy}$$

$$v \rightarrow s \rightarrow u$$

Find my displacement at (on surface)
due to a force at x' .

$$u(x, x') = \underbrace{T(x, x')}_{\downarrow} T_y(x').$$

$$u(x) = \int_{Sx} u(x, x') dx' = \int_{Sx} G_s(x - x') T_y(x') dx'$$

$i \in \{x, y\}$.

$$u_i(x) = \int_{Sx} G_{sij}(x - x') T_j(x') dx'$$

if we just replace by e^{-ikx}

we then get
into Fourier trans.

$$T_y(x) = e^{ikx}$$

$$u_y(x) = \int_{-\infty}^{\infty} G_s(x - x') e^{ikx'} dx'$$

$$x'' = x - x' \rightarrow dx' = -dx''$$

$$u_y(x) = \int_{-\infty}^{\infty} G_s(x'') e^{ikx''} e^{-ikx''} (-dx'')$$

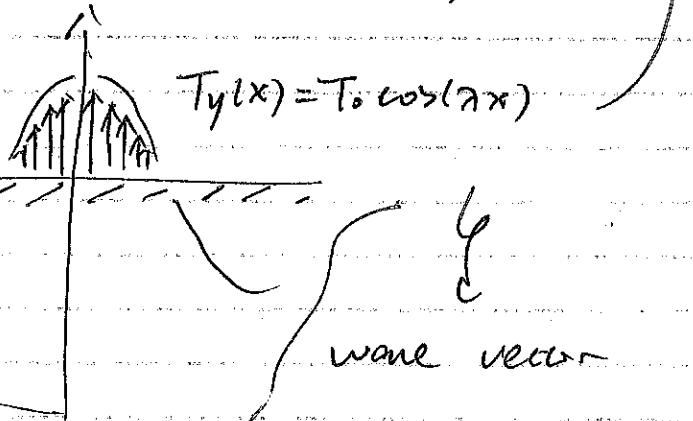
$$= e^{ikx} \underbrace{\int_{-\infty}^{\infty} G_s(x'') e^{-ikx''} dx''}_{\text{Fourier trans.}} + G_s(x)$$

$$u_y(x) = G_s(k) T_y(x)$$

or

$$T_0 \cos(kx)$$

G_s set: $G_{sx}, G_{sy}, G_{syx}, G_{syy}$



B.C.s: $\sigma_{yy}(y=0, x) = T_y(x)$. Stress function:

$$\sigma_{xy}(y=0, x) = 0$$

$$\phi_{xy} = \sin \pi x [A + B y] e^{\gamma y}$$

$$\sigma_{yy} = \phi_{yy} = -\pi \cos \pi x [A + B y] e^{\gamma y} \text{ reject. } e^{-\gamma y}.$$

$$\sigma_{xy} = -\phi_{xy} = \pi \sin \pi x [A + B + B \gamma y] e^{\gamma y}.$$

$$B = -A\pi$$

$$A = -\frac{T_0}{\pi^2}$$

$$B = T_0/\pi$$

$$\sigma_{xx} = \phi_{yy} = \cos \pi x [A\pi^2 + 2B\pi + B\pi^2 y] e^{\gamma y}$$

$$\sigma_{xx} = T_0 \cos \pi x (1 + \gamma y) e^{\gamma y}$$

$$\sigma_{yy} = T_0 \cos \pi x (1 - \gamma y) e^{\gamma y}$$

$$\sigma_{xy} = T_0 \pi \sin \pi x y e^{\gamma y}$$

Under plane-strain assumption

$$\epsilon_{xx} = \frac{1-v^2}{E} \sigma_{xx} - \frac{v(1+v)}{E} \sigma_{yy}$$

$$\epsilon_{yy} = -\frac{v(1+v)}{E} \sigma_{xx} + \frac{1-v^2}{E} \sigma_{yy}$$

$$\epsilon_{xy} = \frac{\sigma_{xy}}{2\mu} = \frac{1+v}{E} \sigma_{xy}$$

$$u_x = \int \epsilon_{xx} dx = \underline{\underline{\underline{\quad}}} + C_{cy}$$

$$u_y = \int \epsilon_{yy} dy = \underline{\underline{\underline{\quad}}} + D(x)$$

$$\frac{1}{2}(u_{xy} + u_{yx}) = \epsilon_{xy} \rightarrow C_{cy} = c \\ D(x) = 0$$

We can then obtain forms

for u_x & u_y :

$$u_x(x, y) = \frac{T_0}{\pi E} \sin \pi x [(1-v-2v^2) + (1+v)\pi y] e^{\pi y} + c$$

$$u_y(x, y) = \frac{T_0}{\pi E} \cos \pi x [(2-2v^2) - (1+v)\pi y] e^{\pi y} + d$$

$$u_x(x, y=0) = \tilde{u}_x(x) = \frac{T_0}{\pi E} \sin \pi x (1-v-2v^2)$$

$$u_y(x, y=0) = \tilde{u}_y(x) = \frac{T_0}{\pi E} \cos \pi x (2-2v^2)$$

$$\hat{U}_y(x) = T_y(x) \frac{(1-\nu)}{\pi E}$$

$$\hat{G}_{sy} (k) = \frac{2(1-\nu)}{kE}$$

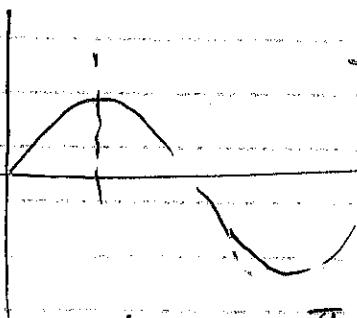
\hookrightarrow can be replaced by $z_{\text{val}}(H^2)$.

$$= \frac{1-\nu}{k\mu}$$

$$\hookrightarrow \frac{1-\nu}{(k)\mu}$$

\hookrightarrow the parentheses does

not really matter here



$$T_y \propto \sin kx \\ \propto \cos(kx)$$

$$x' = x - \frac{\pi}{2k}$$

$$T_y(x) = e^{ikx} = \cos kx + i \sin kx$$

$$\hat{U}_y(x) = T_y(x) \frac{1-\nu}{(k)\mu}$$

\hookrightarrow where:

$$\mathcal{F}^{-1}\left[\frac{1}{(k)}\right] = \frac{-\log(x)}{\pi}$$

$$G_{sy}(x) = \mathcal{F}^{-1}\left[\frac{1}{(k)}\right] \frac{1-\nu}{\mu}$$

$$G_{yy}(x) = \frac{(1-\nu)}{\pi \mu} - \log(x)$$

$$K = 3 - 42$$

$$G_{yy}(x) = -\frac{K_0 + 1}{4\pi \mu} \log(x)$$

$$\tilde{U}_x = \frac{T_0 \sin \pi x}{\pi E} (1 - \nu - 2\nu^2)$$

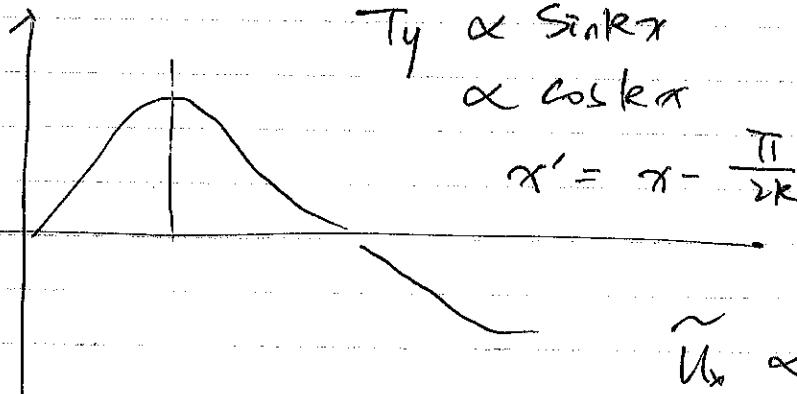
$$= \frac{T_0 \sin \pi x (HD)(1-\nu)}{\pi^2 \mu (1+\nu)}$$

loading of wstr

$$= \frac{T_0 \sin \pi x (1-\nu)}{2\mu}$$

the k & pi's are

interchangeable

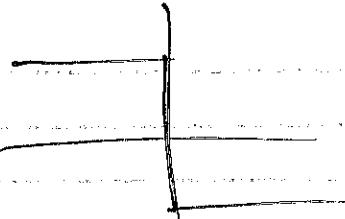


$$\tilde{U}_x \propto \sin(kx - \frac{\pi}{2})$$

$$Ty = e^{-ikx} = \cos kx + i \sin kx \quad \Leftarrow \quad \propto -\cos kx$$

$$\tilde{U}_x = A [\sin kx - i \cos kx]$$

$$\hat{U}_x = -iA \left[\cos kx - \frac{1}{i} \sin kx \right]$$

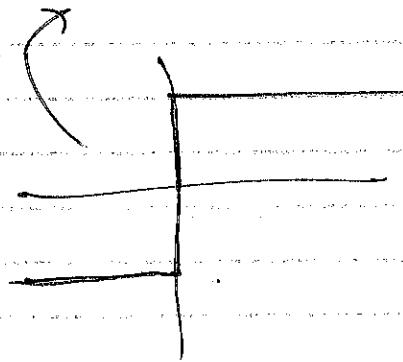


$$-i^{-1} = i$$

$$\tilde{U}_x = -iA e^{ikx}$$

$$= \left[-i(1-2\alpha) / 2\mu k \right] e^{ikx}$$

$$\hat{G}_{sxy}(k)$$



$$\rightarrow \frac{i}{k} \operatorname{sgn}(x)$$

$$\mathcal{F}^{-1}[\hat{G}_{sxy}(k)] = \frac{-(1-2\alpha)}{2\mu} \mathcal{F}^{-1}\left[\frac{i}{k}\right]$$

are strain:

$$K = 3 - 2\alpha \rightarrow \frac{K-1}{2} = 1-2\alpha$$

$$= \frac{-(K-1)}{4\mu} \cdot \frac{\operatorname{sgn}(x)}{2}$$

		Fourier	Real space
y -loading	G_{sy}	$\frac{K\alpha i}{4\mu} \frac{1}{ik}$	$-\frac{K+1}{4\pi\mu} \log(x)$
	G_{sxy}	$-\frac{(K-1)}{4\mu} \left(\frac{i}{k}\right)$	$-\frac{(K-1)}{8\mu} \operatorname{sgn}(x)$
x -loading	G_{sx}	$\frac{K\alpha i}{4\mu} \frac{1}{ik}$	$-\frac{K+1}{4\pi\mu} \log(x)$
	G_{syx}	$\frac{K+1}{4\mu} \left(\frac{i}{k}\right)$	$-\frac{(K-1)}{8\mu} \operatorname{sgn}(x)$

$$T(x) = T_y(x) \hat{e}_y + T_x(x) \hat{e}_x$$

$$\tilde{U}_x = \int_{-\infty}^{\infty} -\frac{k+1}{4\pi n} \log(x-x') T_x(x') dx'$$

$$+ \int_{-\infty}^{\infty} \frac{k+1}{8\pi} \operatorname{sgn}(x-x') T_y(x') dx'$$

Problem Session #3

Generalized Airy Stress function.

$$\phi(x, y) = \sum_i C_i \phi_i(x, y) \quad \begin{array}{l} \text{not universal.} \\ \text{unstable.} \end{array}$$

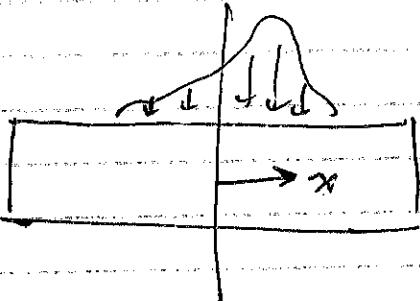
$\nabla^4 \phi = 0$ not guaranteed

$$\phi_1(x, y) = e^{\alpha x} e^{\beta y} \quad \nabla^2 \phi = 0$$

$$= e^{i\alpha x} e^{\beta y} \quad \textcircled{1} \quad \alpha = \pm i\beta \quad \rightarrow \textcircled{1}.$$

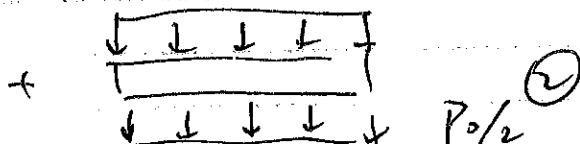
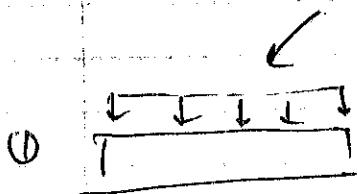
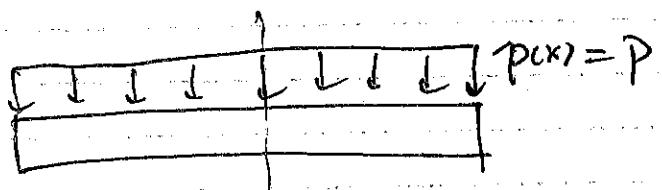
$$e^{i\alpha x} e^{-\beta y} \quad \textcircled{2}$$

$$e^{i\alpha x} y e^{\beta y} \quad \textcircled{3}$$



$$e^{i\alpha x} y e^{-\beta y} \quad \textcircled{4}$$

$$\phi(x, y) = e^{i\alpha x} [(C_1 + C_2 y) e^{\beta y} + (C_3 + C_4 y) e^{-\beta y}]$$



Problem ①.

$$\sigma_{yy}$$

x
even

y.
even

$$\phi$$

Problem ②.

$$\sigma_{yy}$$

x

even

y.

odd.

③

Expand the loading as Fourier series.

$$P(x) = \sum_{n=1}^{\infty} a_n \cos(\pi n x)$$

$$\hookrightarrow \pi_n = \frac{(2n-1)\pi}{2a}$$

$$③ \text{ B.C.s: } \sigma_{yy}(x, y=b) - P/2 = -\sum_{n=1}^{\infty} a_n \cos(\pi n x)$$

$$\sigma_{yx}(x, y=0) = 0$$

$$\left. \sigma_{yy} \right|_{x,y=b} = \sum_{n=1}^{\infty} -\pi_n^2 \cos(\pi n \pi) [B_n \sinh(\pi b) \dots]$$

$$-\frac{\partial u}{\partial x} = -\pi n \left[B_n \sinh(\pi n b) + C_n b \cosh(\pi n b) \right]$$

$$\sigma_{xx}, \sigma_{yy}, \sigma_{xy}$$



$$\epsilon_{xx}, \epsilon_{yy}, \epsilon_{xy}$$

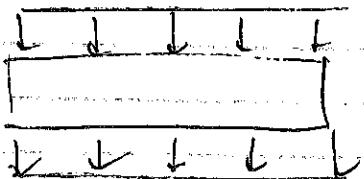
even in x , odd in y .

$$\phi_{yy}$$



$$U_{xx} = U_{x,x}$$

$$\epsilon_{xx} = -\sigma_{xx} + \frac{1}{E} \sigma_{yy}$$



$$U_x = \int \epsilon_{xx} dx$$

even in x ,
odd in y .

odd in y ,

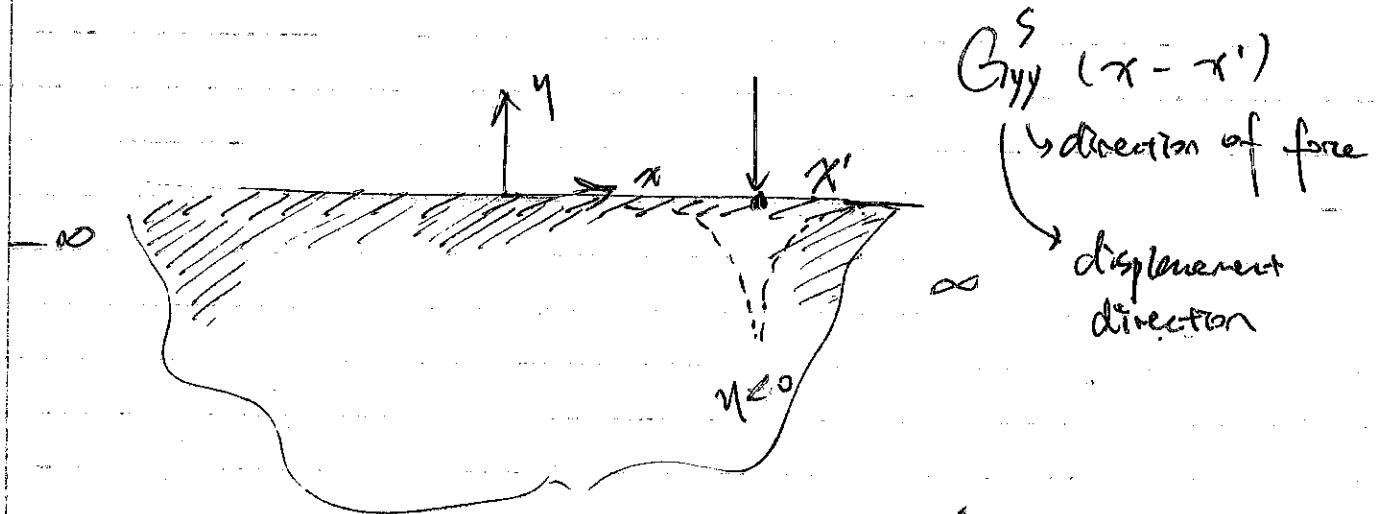
odd in y

$$U_x = \sum_{n=1}^{\infty} \sin(\pi n x) \left[D_n \sinh(\pi n y) + E_n y \cosh(\pi n y) \right]$$

$$U_y =$$

$$U_{x,x} = \epsilon_{xx} = \frac{\sigma_{xx}}{E} - \frac{v' \sigma_{yy}}{E}$$

2) Surface Green's function



$G_{yy}^S(x - x')$
 (↓ direction of force)
 displacement
 direction

Distributed loading

$$\int_{-\infty}^{\infty} G_{yy}^S(x - x') f(x') dx' = f(x)$$

$$\tilde{u}_y = \int_{-\infty}^{\infty} G_{yy}^S(x - x') T_y(x') dx'$$

$$+ \int_{-\infty}^{\infty} G_{yy}^S(x - x') T_x(x') dx'$$

general form of surface displacement.

Reapp. applying loading e^{ikx} .

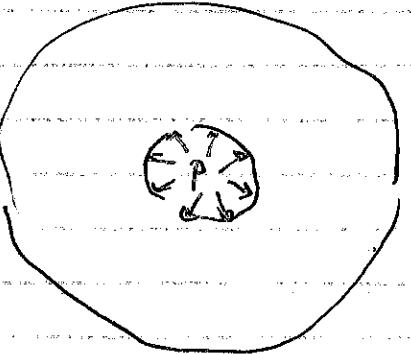
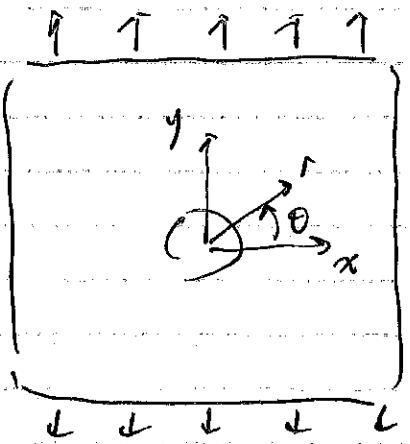
$$\tilde{u}_y = G_{yy}^S(k) \cdot e^{ikx}$$

$$\mathcal{F}(G_{yy}^S(x))$$

lecture 7

4/22/2024.

→ Polar Coordinates



Stress Concentration. ~ 3.

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \rightarrow \begin{cases} r = \sqrt{x^2 + y^2} \\ \theta = \tan^{-1} \frac{y}{x} \end{cases}$$

... Cartesian coordinate.

$$\sigma_{xx} = \phi_{,x}(x, y)$$

$$\sigma_{yy} = \phi_{,xx}(x, y)$$

$$\sigma_{xy} = -\phi_{,xy}(x, y)$$

... Polar Coordinate.

$$\sigma_{rr} = \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

$$\sigma_{\theta\theta} = \phi_{,rr}, \quad \sigma_{r\theta} = -\frac{1}{r} \left(\frac{1}{r} \frac{\partial \phi}{\partial \theta} \right)$$

$\nabla \theta$



$$\phi(r, \theta) = \phi(x, y).$$



$$\sigma_{xx}, \sigma_{yy}, \sigma_{xy}.$$

\downarrow coord. trans.

$$\Omega_x, \Omega_y, \Omega_\theta$$

$$\frac{\partial}{\partial x} \cdot \frac{\partial y}{\partial r} \rightarrow \frac{\partial}{\partial r} \cdot \frac{1}{r} \frac{\partial y}{\partial \theta}$$

chain rule

\Rightarrow Vector calculus

$$\nabla f = e_x f_{,x} + e_y f_{,y}.$$

Gradient operator

$$\nabla = e_x \frac{\partial}{\partial x} + e_y \frac{\partial}{\partial y}.$$

$$= e_x \frac{\partial}{\partial x'} + e_y \frac{\partial}{\partial y'}$$

$$\nabla^2 = \nabla \cdot \nabla = \frac{\partial^2}{\partial x'^2} + \frac{\partial^2}{\partial y'^2}$$

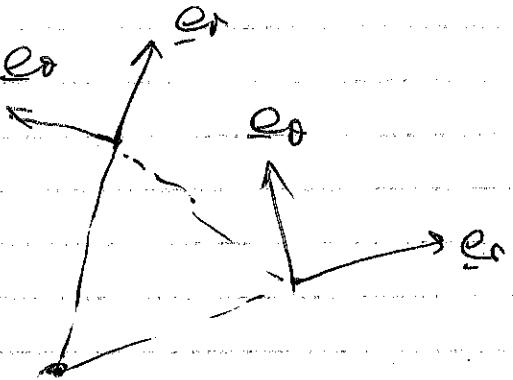
$$= \frac{\partial^2}{\partial x'^2} + \frac{\partial^2}{\partial y'^2}$$

... Laplacian in polar coordinates?

in polar coordinates.

$$\tilde{\nabla} = \underline{e}_r \frac{\partial}{\partial r} + \underline{e}_{\theta} \frac{\partial}{\partial \theta} +$$

(grad).



laplacian.

$$\nabla^2 = \tilde{\nabla} \cdot \tilde{\nabla} = \left(\underline{e}_r \frac{\partial}{\partial r} + \underline{e}_{\theta} \frac{\partial}{\partial \theta} + \underline{e}_{\phi} \frac{\partial}{\partial \phi} \right) \cdot \left(\underline{e}_r \frac{\partial}{\partial r} + \underline{e}_{\theta} \frac{\partial}{\partial \theta} + \underline{e}_{\phi} \frac{\partial}{\partial \phi} \right)$$

Your laplacian:

$$\rightarrow \frac{\partial^2}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2}{\partial \theta^2}$$

One can show that:

$$\left\{ \begin{array}{l} \frac{\partial \underline{e}_r}{\partial \theta} = \underline{e}_{\phi} \\ \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{\partial \underline{e}_{\theta}}{\partial \phi} = -\underline{e}_r \\ \end{array} \right.$$

$$\nabla^2 \neq \tilde{\nabla} \cdot \tilde{\nabla}$$

↑ not true !!

$$\left\{ \begin{array}{l} \frac{\partial \underline{e}_r}{\partial r} = 0 \\ \frac{\partial \underline{e}_{\theta}}{\partial r} = 0 \\ \end{array} \right.$$

$$\tilde{\nabla}^a = \tilde{\nabla} \times \underline{e}_z$$

$$= \left(\underline{e}_x \frac{\partial}{\partial x} + \underline{e}_y \frac{\partial}{\partial y} \right) \times \underline{e}_z$$

$$= \left(-\underline{e}_y \frac{\partial}{\partial x} + \underline{e}_x \frac{\partial}{\partial y} \right)$$

$$\underline{\underline{\epsilon}} = \nabla \phi \otimes \nabla \phi$$

\rightarrow for Question

in Polar coordinates.

$$\nabla^a = \left(\epsilon_r \frac{\partial}{\partial r} + \epsilon_\theta \frac{1}{r} \frac{\partial}{\partial \theta} \right) \times \hat{e}_z$$

$$= \left(-\epsilon_\theta \frac{\partial}{\partial r} + \epsilon_r \frac{1}{r} \frac{\partial}{\partial \theta} \right).$$

$$\nabla^a \otimes \nabla^a = \epsilon_\theta \otimes \epsilon_\theta \frac{\partial^2}{\partial r^2} + \dots$$

Stress function satisfies biharmonic ...

$$\nabla^4 \phi = 0$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \phi = 0$$

\rightarrow in polar coordinate

$$\left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2}{\partial \theta^2} \right) \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right) \phi = 0$$

displacement v.s. strain

$$\epsilon_{ij} = \frac{1}{2} (\epsilon_{ij} + \epsilon_{ji}) \rightarrow \text{Gaussian}$$

$$\underline{\Sigma} = \frac{1}{2} \left[\nabla \otimes \underline{u} + (\nabla \otimes \underline{u})^T \right]$$

$$\underline{u} = \underline{u}_r \underline{e}_r + \underline{u}_0 \underline{e}_0$$

$$\Sigma_{rr} = \frac{\partial u_r}{\partial r}$$

$$\Sigma_{00} = \frac{1}{r} \cdot \frac{\partial u_0}{\partial \theta} + \frac{u_r}{r}.$$

$$\Sigma_{\theta\theta} = \frac{1}{r} \left(\frac{1}{r} \cdot \frac{\partial u_r}{\partial \theta} - \frac{u_0}{r} + \frac{\partial u_0}{\partial r} \right)$$

Generalized Hooke's law.

$$\underline{\Omega} = \Gamma + \alpha [\underline{\Sigma}] I + 2\mu \underline{\Sigma}$$

Traction force vs. Stress.

$$T_j = \sigma_{ij} n_i$$

$$I = \underline{n} \cdot \underline{\Omega}.$$

$$\{ T_r = \sigma_{rr} n_r + \sigma_{0r} n_0$$

$$T_\theta = \sigma_{r\theta} n_r + \sigma_{0\theta} n_0$$

Equilibrium Condition.

$$\sigma_{jj} + F_j = 0$$

$$\nabla \cdot \underline{G} + f = 0$$

"automatically satisfied by stress free approach."

PDE to be solved:

$$\nabla^4 \phi(r, \theta) = 0$$

$$\text{Suggest } \phi(r, \theta) = \phi(r, \theta + 2\pi)$$

$$\phi(r, \theta) = f(r) e^{in\theta} \quad (n=0, 1, 2, \dots)$$

$$\frac{\partial^2}{\partial \theta^2} \phi = n^2 \phi, \quad \frac{\partial^2}{\partial r^2} \phi = -n^2 \phi.$$

$$\left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} - \frac{n^2}{r^2} \right) \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} - \frac{n^2}{r^2} \right) f(r) e^{in\theta} = 0$$

$$\text{try. } f(r) = r^m$$

$$\frac{1}{r} \cdot \frac{\partial}{\partial r} f(r) = m r^{m-1}.$$

$$\frac{\partial^2}{\partial r^2} f(r) = m(m-1) r^{m-2}.$$

$$\left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial}{\partial r} - \frac{n^2}{r^2} \right) r^m = (m^2 - n^2) r^{m-2}$$

$\cancel{f(r)}$
 \uparrow
 deriv. replaced
 by $-n^2$

$$\left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \cdot \frac{\partial}{\partial r} - \frac{n^2}{r^2} \right) r^{m-2} = (m-2)^2 - n^2 \quad r^{m-4}.$$

$$[(m-2)^2 - n^2] (m^2 - n^2) r^{m-4} = 0$$

i.e. four possibilities: $\begin{cases} m = \pm n \\ m = 2 \pm n \end{cases}$

$$\phi(r, \theta) = (A_{n1} r^{n+2} + A_{n2} r^{-n+2} + A_{n3} r^n + A_{n4} r^{-n}) e^{in\theta}$$

$n=0$ > not four solns.

$$r^{n+2} \quad r^{-n+2} \quad r^n \quad r^{-n}$$

$$n=0 \quad m \quad \underbrace{0 \quad 0 \quad 2 \quad 2 \quad 2}$$

only 2 solns for ϕ .

$$n=1 \quad m \quad 1 \quad -1 \quad 3 \quad 1$$

Mitchell Solns. \therefore

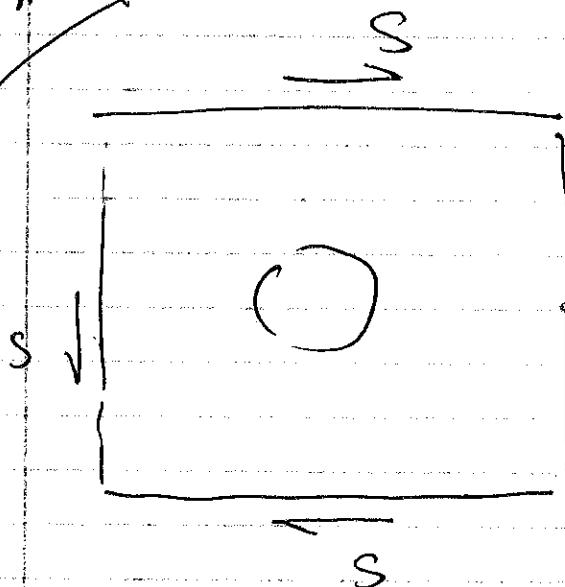
$$f_0(r) = A_{01} r^2 + A_{02} r^2 \ln r + A_{03} r^3 + A_{04} r$$

$\therefore \downarrow$ some much terms.

$$A_{01} r^2 + A_{02} r^2 \ln r + A_{03} r^3 + A_{04}$$

take deriv. w.r.t. parameters

Example 1



$$\left\{ \begin{array}{l} \sigma_{xx} = \sigma_{yy} = 0 \\ \sigma_{xy} = S \end{array} \right. \quad r \rightarrow \infty$$

$$\left\{ \begin{array}{l} \sigma_{xy} = S \\ \sigma_{rr} = 0 \end{array} \right. \quad r \rightarrow \infty$$

on the hole boundary:

$$\left\{ \begin{array}{l} \sigma_{r\theta} = 0 \\ \sigma_{rr} = 0 \end{array} \right. \quad r = a$$

$$\phi = \phi^{(0)} + \phi^{(1)}$$

$$\begin{aligned} \sigma_{xy}^{(0)} &= S, \\ \phi^{(0)} &= -Sxy \end{aligned}$$

In Polar coordinate,

$$\phi^{(0)} = -S r^2 \sin \theta \cos \theta$$

$$= -\frac{1}{2} S r^2 \sin 2\theta$$

$$\left\{ \begin{array}{l} \sigma_{rr}^{(0)} = \frac{1}{r} \cdot \frac{\partial \phi^{(0)}}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2 \phi^{(0)}}{\partial \theta^2} = S \sin 2\theta \end{array} \right.$$

$$\left\{ \begin{array}{l} \sigma_{\theta\theta}^{(0)} = -S \sin \theta \end{array} \right. \rightarrow \text{satisfies infinite for}$$

$$\sigma_{r\theta}^{(0)} = S \cos 2\theta$$

B.C.s

one does not \subset hole B.C.s

We need to come up $\phi^{(1)}$, s.t.

ϕ satisfies hole B.C.s but do not mess up the infinite far B.C.s.

We should pick $n=2$ to cancel the $\sin(2\theta)$ term.

$$\phi^{(1)} = \underbrace{(A_{11}r^4 + A_{22}r^2 + A_{33}r^{-2})}_{\checkmark \quad \checkmark \quad \checkmark} \sin 2\theta$$

Next to cancel these terms

→ terms

survived. (near B.C.)

Divide the stress function:

$\Rightarrow \alpha_1: \alpha_{22}$

$$\phi^{(1)} = (A + B r^2) \sin 2\theta$$

some abs.

$$A = S a^2, B = -\frac{1}{2} S a^2$$

$$\sigma_{rr} = \left(S - \frac{4A}{r^2} - \frac{6B}{r^4} \right) \sin 2\theta$$

$$\sigma_{\theta\theta} = \left(S + \frac{2A}{r^2} + \frac{6B}{r^4} \right) \cos 2\theta$$

$$\sigma_{\theta\theta} = \left(-S + \frac{6B}{r^4} \right) \sin 2\theta$$

Problem Session 4

Polar Coordinates. & Michell Solns.

$$\phi(r, \theta) \rightarrow \text{compatibility} \rightarrow \nabla^4 \phi(r, \theta) = 0.$$

$$\phi(r, \theta) = f(r) e^{in\theta} \rightarrow \phi(r, \theta + 2\pi) = \phi(r, \theta).$$

$$\nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \cdot \frac{\partial^2}{\partial \theta^2} \quad f(r) = r^m.$$

$$\nabla^2 \phi = \left(\dots - \frac{m^2}{r^2} \right) \phi \quad \rightarrow r^m e^{in\theta}$$

$$\nabla^4 = \nabla^2 \cdot \nabla^2 r^m e^{in\theta} = 0$$

\downarrow

not zero everywhere

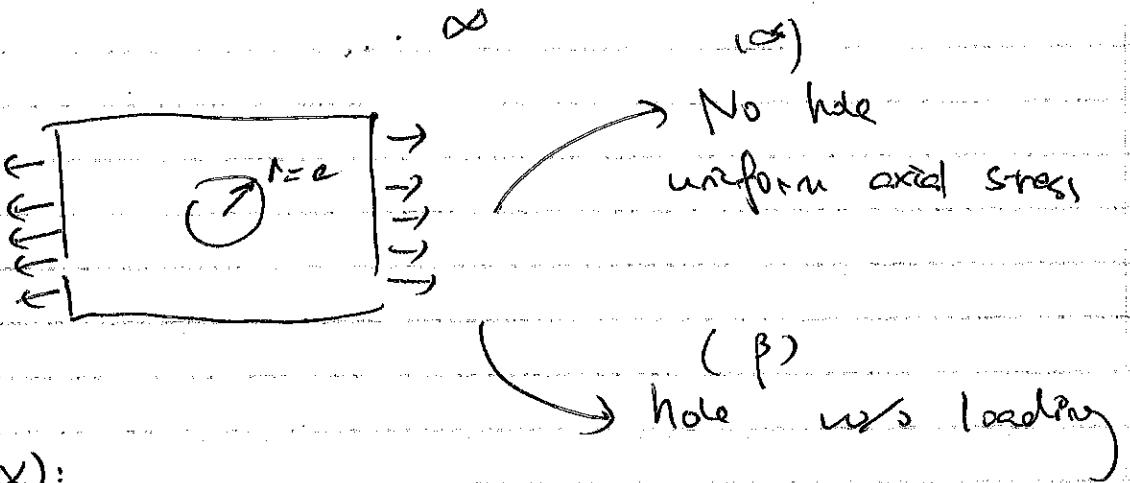
$$m = (2+n, 2-n, +n, -n)$$

... 4 unique solns.

$$\phi(r, \theta) = (A_1 r^{2+n} + A_2 r^{2-n} + A_3 r^n + A_4 r^{-n}) e^{in\theta}$$

Michell solns.

Example



Problem (α):

$$\sigma_{xx} = \sigma$$

$$\sigma_{yy} = \sigma_{xy} = 0$$

[IMPORTANT]

$$\phi^{(0)}(x,y) = \frac{S_1}{2} = \frac{S_0^2 \sin^2 \theta}{2} \left(\frac{1 - \cos 2\theta}{2} \right)$$

$$\phi^{(0)}(x,y) = \frac{S_0^2}{4} - \frac{S_0^2 \cos 2\theta}{4}$$

$n=2$

$n=0$ "base solution".

~~$$\phi^{(1)}(r, \theta) = (A_{01} r + A_{02} r^2 \ln r) + (A_{03} \ln r + A_{04} \theta)$$~~

~~$$+ (A_1 r^4 + A_2 r^2 + A_3 r^2 + \frac{A_4 \theta}{r^2}) w_{20} \dots$$~~

At $r=a$,

B.C.s traction free. $\sigma_{rr} = \sigma_{r\theta} = 0, \tau \neq 0$.

$$\sigma_{rr} = C_1 \cos 2\theta - \frac{S_r^2}{4} \sin 2\theta = 0$$

$$\phi^{(1)}(r, \theta) = A \ln r + B\theta + C \cos 2\theta + \frac{D}{r^2} \cos 2\theta.$$

↓

not periodic

$$\phi^{tot} = \frac{S_r^2}{4} + A \ln r + B\theta + \left(C + \frac{D}{r^2} - \frac{S_r^2}{4}\right) \cos 2\theta$$

$$\sigma_{rr} = \frac{1}{r} \cdot \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

$$= \frac{A}{r} + \frac{1}{r^2} + 0 + \frac{1}{r} \cdot \left(\frac{-D}{r^3} - \frac{2S_r^2}{4}\right) \cos 2\theta$$

$$+ \frac{(-4)}{r^2} \left(C + \frac{D}{r^2} - \frac{S_r^2}{4}\right) \cos 2\theta$$

At $\theta = 90^\circ$ to Midell's table

From Midell's sol'n-table,

$$\sigma_{rr} = \frac{S_r}{4}(2) + A \left(\frac{1}{r^2}\right) + 0 \left(\frac{-4C}{r^2} - \frac{(D - S_r^2)}{r^4} + \frac{S_r^2}{4}\right) \cos 2\theta$$

Get A, B, C, D just as in class.

Given disp. B.C.s

Say $u_r \geq 0$, at $r = a$, $\theta = 0$.

From Michell, tab., $2\rho u_r = \frac{S}{4}(k-1)r + A(-\frac{1}{r})$

$$u_r \Big|_{r=a} = 0$$

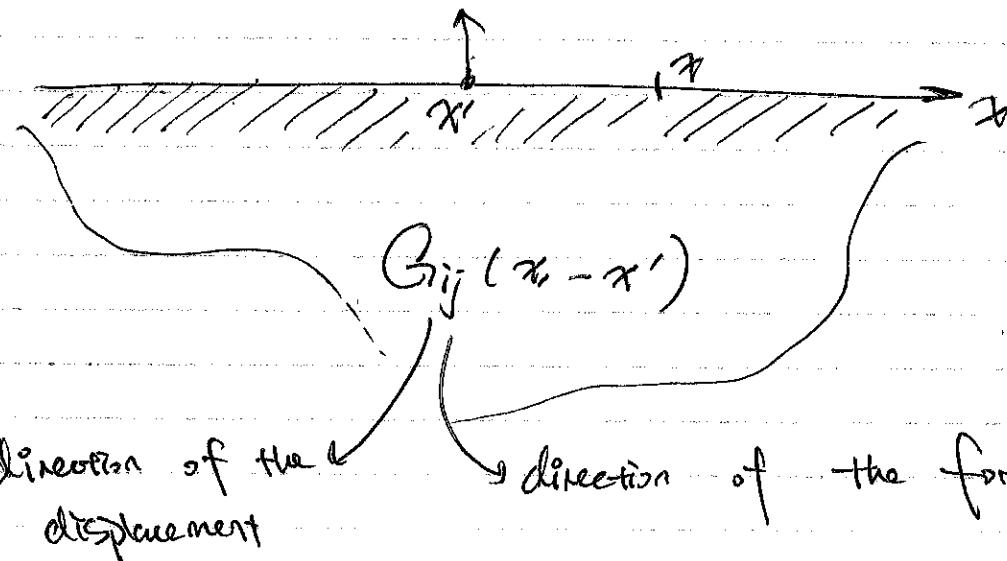
Stress concentration factor

$$\sigma_{rr} = \frac{S}{2} \left(1 + \frac{a^2}{r^2} \right) - S \cos 2\theta \left(\frac{3a^4}{r^4} + 1 \right)$$

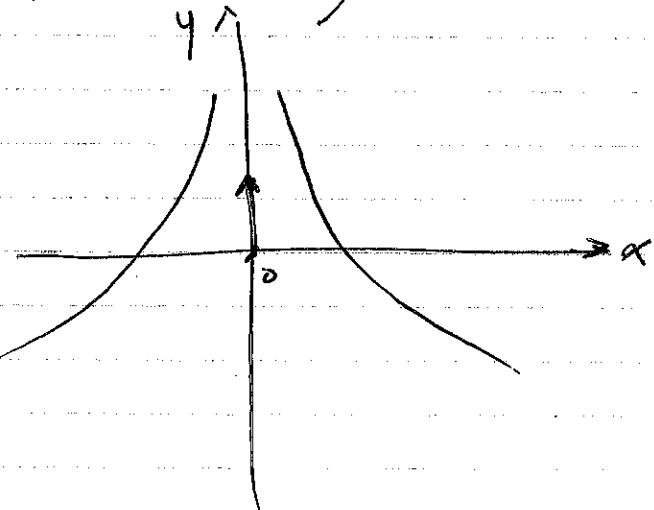
Lecture 9

4/29/2014

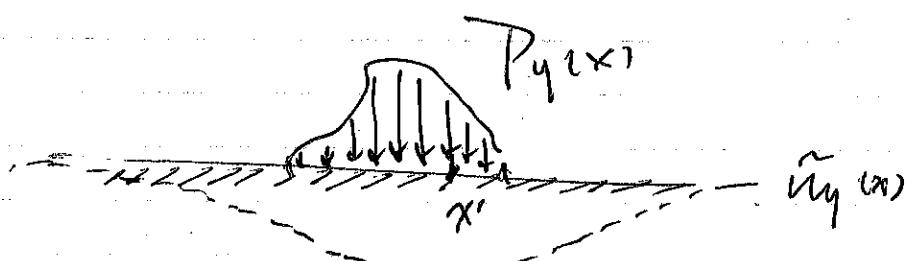
Contact \rightarrow Surface Green function



$$G_{yy}^S(x) = -\frac{K+1}{4\pi\mu} \log(x)$$



$$\tilde{u}_y(x) = \int_{-\infty}^{+\infty} -P_y(x') \quad \text{---}$$

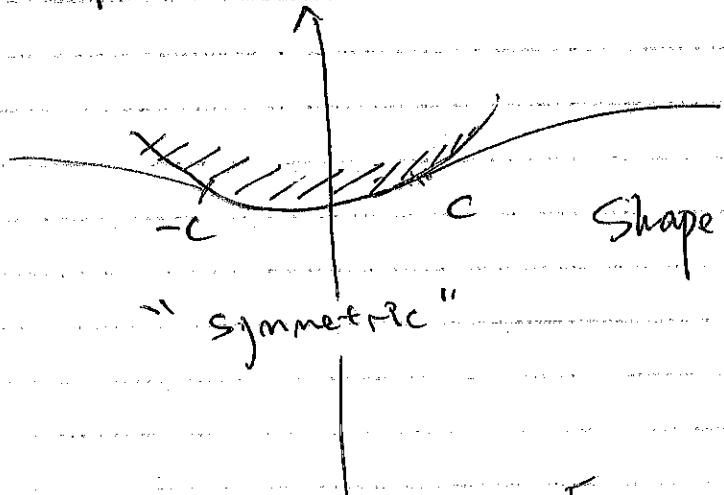
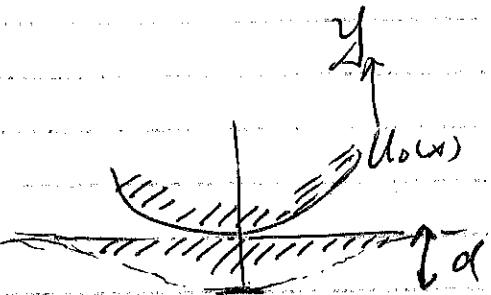


$$G_{yy}^S(x - x') dx'$$

$$\tilde{u}_y(x) = \int_{-\infty}^{+\infty} \frac{K+1}{4\pi\mu} P_y(x') \log|x - x'| dx'$$

Set up frictionless contact problem

- Simplification, rigid indenter



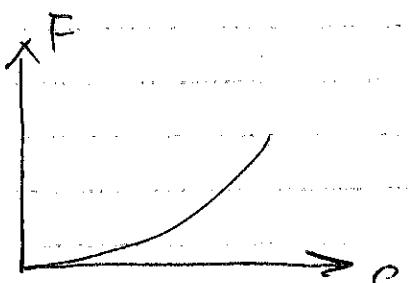
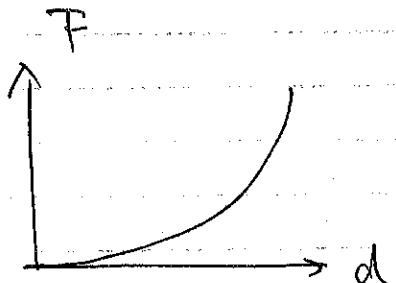
$$u(x) - d = \int_{-\infty}^{+\infty} p_y(x') dx'$$

$$\left[-c < x < c \text{ (contact area)} \right]$$

$$\text{or } \int_{-c}^{+c} \frac{k+1}{4\pi\mu} \log |x - x'| dx'$$

"compact support"

$$\hookrightarrow F = \int_{-c}^{+c} p_y(x') dx'$$



B.C. is \odot contact area.

$$\begin{aligned} -c < x < c, \quad \left\{ \begin{array}{l} \tilde{U}_y(x) = U_0(x) - d \\ (\eta = 0) \end{array} \right. & \quad \tilde{U}_y(x) < U_0(x) - d \\ & \quad \tilde{\sigma}_{yy}(x) = -P_y(x) < 0 \\ & \quad \tilde{\sigma}_{xy}(x) = 0 \end{aligned}$$

② Gap area.

$$|x| > c \quad y=0 \quad \left\{ \begin{array}{l} \tilde{U}_y(x) < U_0(x) - d \\ \tilde{\sigma}_{yy}(x) = 0 \\ \tilde{\sigma}_{xy}(x) = 0 \end{array} \right.$$

try to invert $U_0(x) - d$

Johnson & Berger provided some approaches

$$\frac{dU_0(x)}{dx} = \int_{-c}^c P_y(x') \frac{k+1}{4\pi\mu} \frac{1}{x-x'} dx'$$

$$= \frac{k+1}{4\pi\mu} \int_{-c}^c \frac{P_y(x')}{x-x'} dx' \quad \text{does not have abs. val.}$$

$\dots (-c < x < c)$. (x)

Eqn. (*) is a general relationship

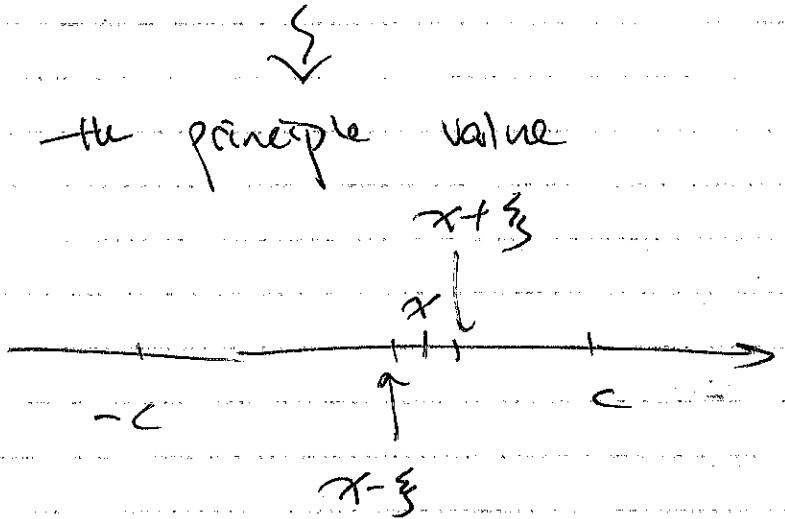
between 2 functions.

$$g(x) = \int_{-c}^c \frac{f(x')}{x - x'} dx'$$

(integral sign)

"the kernel is singular" \leadsto (implicit).

the principle value



$$\int_{-c}^c \rightarrow \int_{-c}^{x-1/2} + \int_{x+1/2}^c$$

Introducing:

$$g(x) = \frac{1}{\pi} \int_{-\infty}^{\infty} \frac{f(x')}{x - x'} dx' \quad \begin{matrix} \leftarrow \text{Hilbert} \\ \text{transform} \end{matrix}$$

"Hilbert transform is its own inverse".

The answer is:

$$f(x) = -\frac{1}{\pi^2 \sqrt{c^2 - x^2}}$$

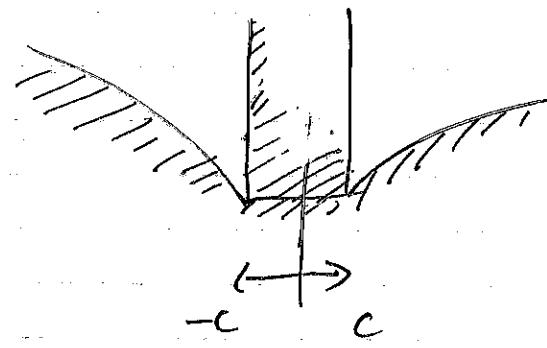
$$\int_{-c}^c \frac{\sqrt{c^2 - x'^2} g(x')}{\pi - x'} dx'$$

$$+ \frac{f}{\pi \sqrt{c^2 - x^2}}$$

Indenter force.

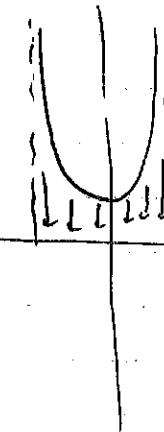
Example 1

Flat punch



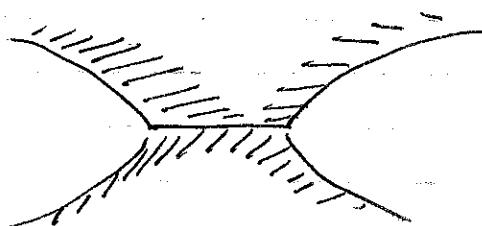
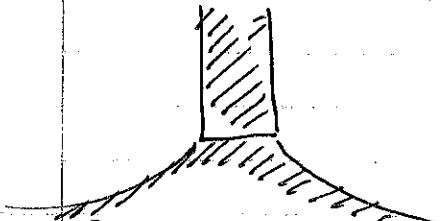
$$x = c - r \rightarrow 0$$

$$\sigma \sim \frac{1}{r}$$

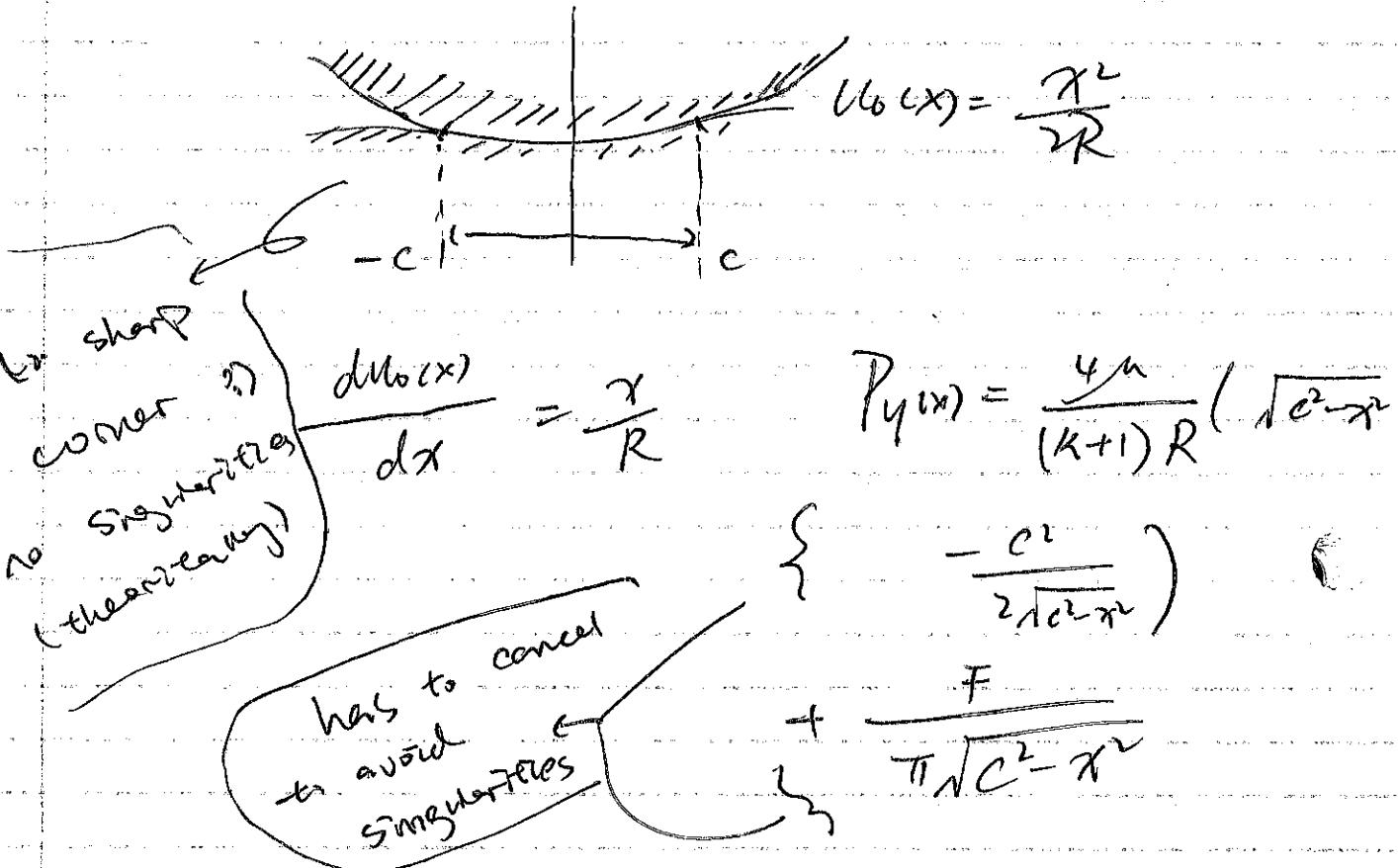


$$P_y(x) = \frac{F}{\pi \sqrt{c^2 - x^2}} \quad \text{Plot: } \rightarrow$$

Other similar samples



Example 2 Cylindrical Punch



Q: what is C ? How does c depend on F ?

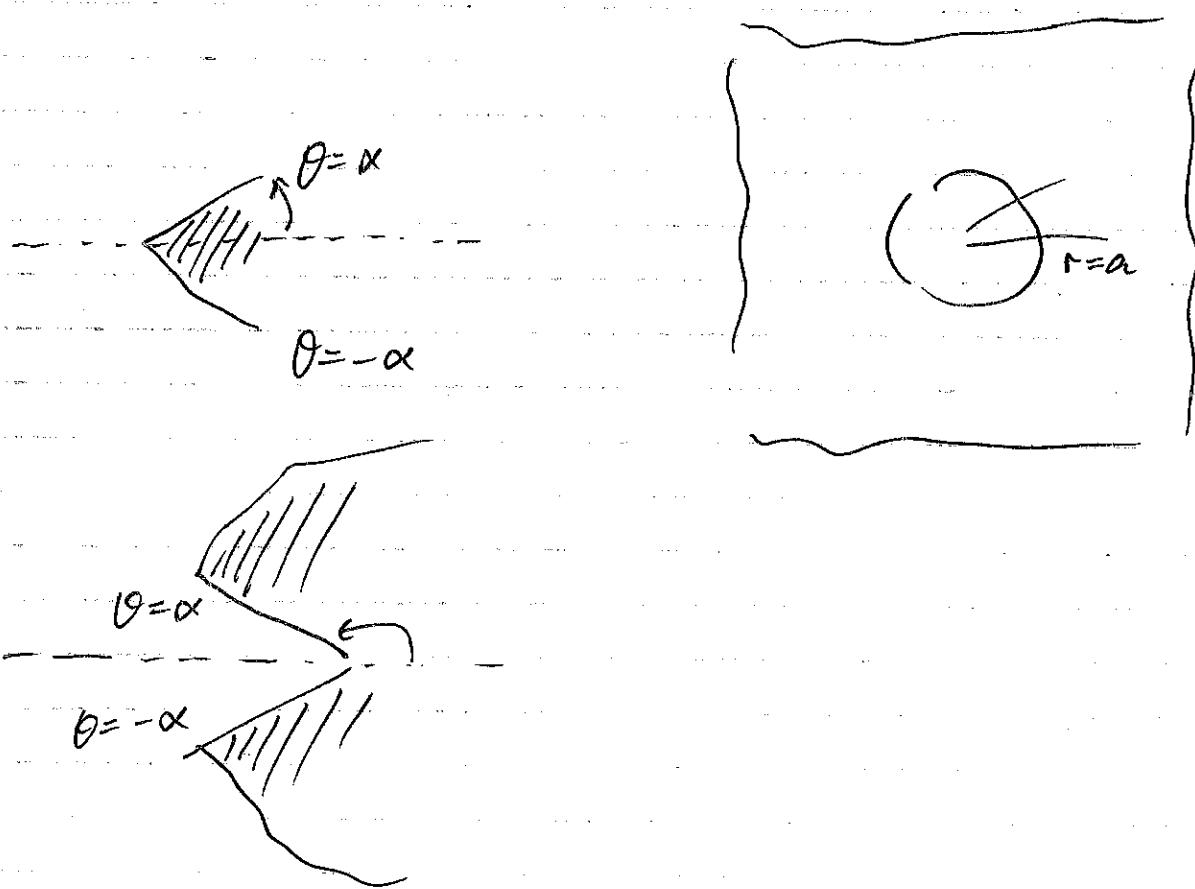
Stress Singularities?

$$\frac{F}{\pi} = \frac{2mc^2}{(K+1)R}$$

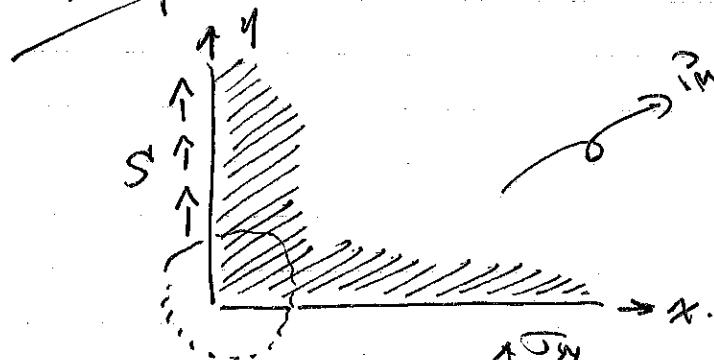
Lecture 10

5/1/2024

Wedge and Notch.

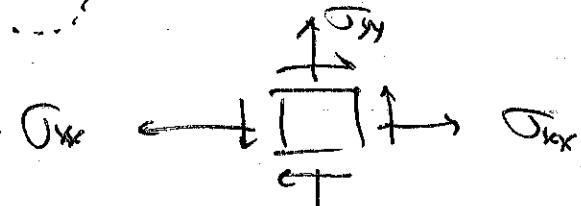


Example 1



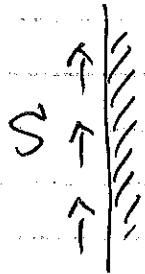
Imagine an infinite large block.

Look at area of interest, i.e., corner



\leftrightarrow traction-free B.C.s

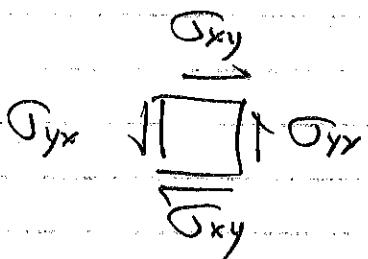
$$\sigma_{xy} = \sigma_{yy} = 0, \quad y=0$$



B.C.s.

$$\sigma_{xx} = 0$$

$$\sigma_{xy} = -S. \quad \left. \right\} x=0$$

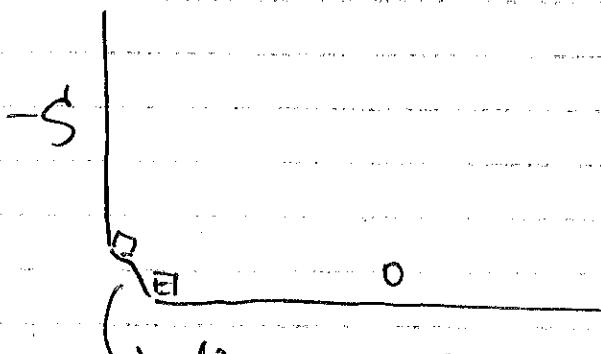


$$\sigma_{xy} \neq \sigma_{yx}$$

$$-S$$

$$\sigma_{xy} = \sigma_{yx} = -\phi_{xy}.$$

we will have:

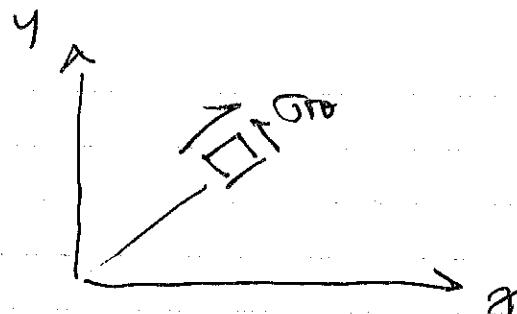


dig a corner to

avoid Singularity

$$\nabla^4 \phi(r, \theta) = 0.$$

$$\phi(r, \theta) = r^m e^{im\theta}$$



$$m = n, -n, 2+n, 2-n.$$

$$\sigma_{rr} \sim r^0, \quad \phi \sim r^2$$

$$m=2, \quad n=2, 0$$

Bacchus. Tab. 8.1.

\rightarrow we create it
manually.

$$\phi = r^2, \quad r^2 \cos 2\theta, \quad r^2 \sin 2\theta, \quad r^2 \theta$$

\downarrow

σ_{rr}

$\sigma_{\theta\theta}$

$\sigma_{\phi\phi}$

\downarrow

satisfies biharmonic eqn.

find corresponding terms in table.

$$\text{for } r^2 \theta \rightarrow 20 \quad -1 \quad 20$$

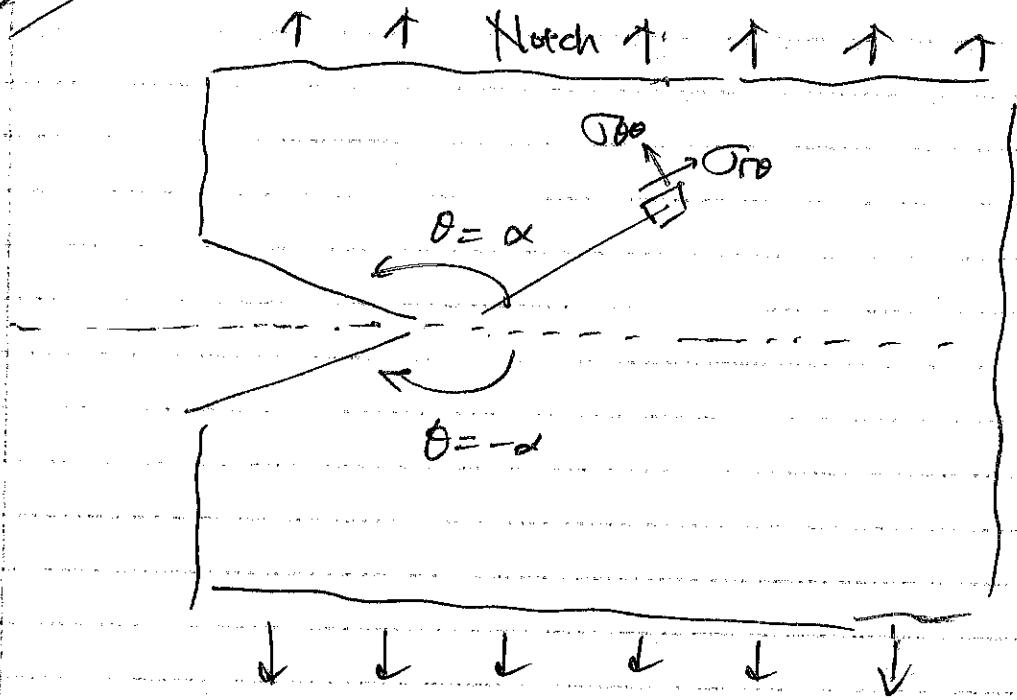
$$(\sigma_{rr}) \quad (\sigma_{\theta\theta}) \quad (\sigma_{\phi\phi})$$

$$\phi = S \left(-\frac{\pi r^2 \cos 2\theta}{8} + \frac{\pi r^2}{8} + \frac{r^2 \sin 2\theta}{4} - \frac{r^2 \theta}{2} \right)$$

$$\rightarrow \phi(x, y) \rightarrow \bar{\sigma}_{xy} = \bar{\sigma}_{yx} = -\frac{\partial^2 \phi}{\partial x \partial y}$$

$$= -\frac{sy^2}{x^2+y^2}$$

Notch problem



\rightarrow William's solution

$$\phi = r^{n+2} \{ A_1 \cos(n+2)\theta + A_2 \cos n\theta + A_3 \sin(n+2)\theta \\ + A_4 \sin n\theta \}$$

$$n = \lambda - 1, \quad n+2 = \lambda + 1.$$

$$\phi = r^{\lambda+1} \{ \dots \}$$

$$\sigma_{rr} = r^{\alpha-1} \{ \dots \}$$

$$\sigma_{\theta\theta} = r^{\alpha-1} \{ \dots \}$$

$$\sigma_{\phi\phi} = r^{\alpha-1} \{ \dots \}$$

If $\alpha < 1$, Stress field is Singular

$$\sigma \sim A \cdot r^{\alpha-1}$$

Substitute $\begin{cases} \theta = \alpha \\ \theta = -\alpha \end{cases}$

$$\sigma_{r\theta} = 0, \quad \theta = \alpha, \quad \theta = -\alpha.$$

$$\sigma_{\theta\theta} = 0 \quad \theta = \alpha, \quad \theta = -\alpha$$

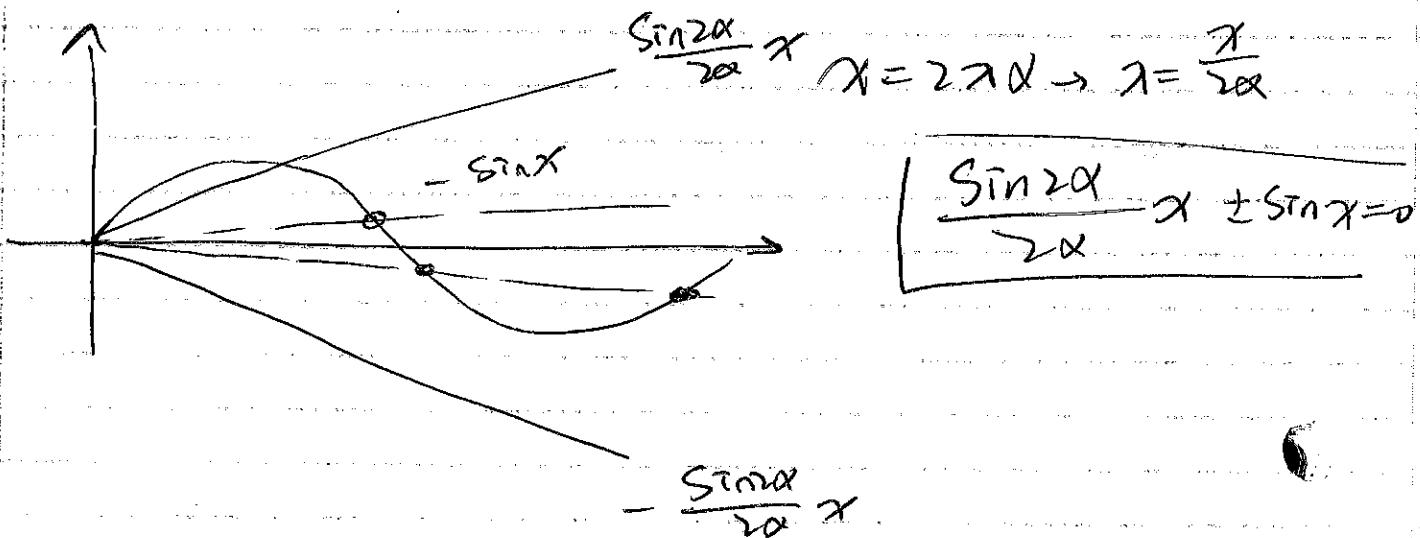
$$\begin{bmatrix} M_1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & M_2 \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ A_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$[M_1] \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad [M_2] \begin{bmatrix} A_3 \\ A_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

In order to have non-trivial soln.

then, $\det(M_1) = 0 \Rightarrow 7\sin 2\alpha + \sin 2\pi\alpha = 0$

or $\det(M_2) = 0 \Rightarrow 7\sin 2\alpha + \sin 2\pi\alpha = 0$

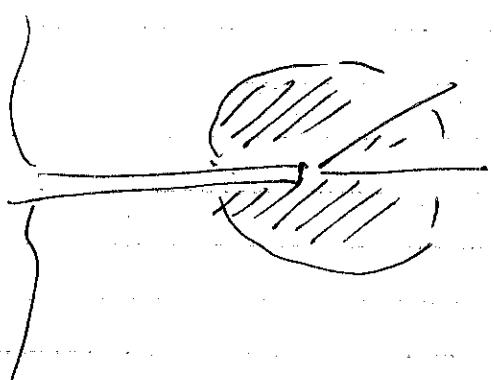


$$\alpha \rightarrow \pi: \alpha = 0, \frac{1}{2}, 1, \frac{3}{2}, \dots$$

$$0 \approx \frac{1}{r}, \frac{1}{\sqrt{r}}, \dots \text{ non-singular}$$

$\cancel{0}$ \checkmark

reject
this soln term.



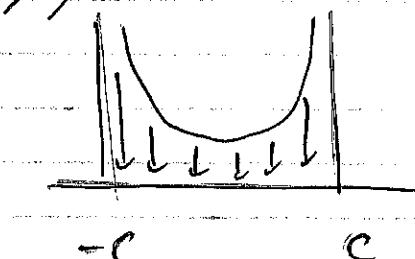
$$0 \approx \frac{1}{\sqrt{r}}, \varepsilon \approx \frac{1}{\sqrt{r}}$$

$$W = \frac{1}{2} \cdot \sigma \varepsilon \approx \frac{1}{r}$$

$$\varepsilon = \int r \omega d\Omega = \int \frac{1}{r} \cdot r dr$$

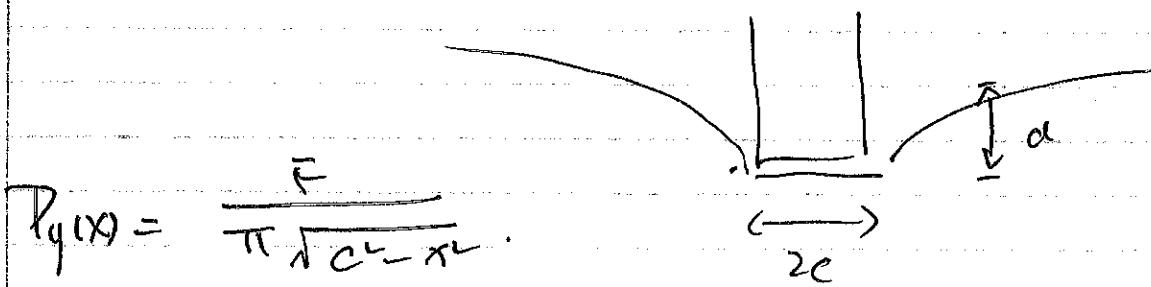
finite

Problem Session #5



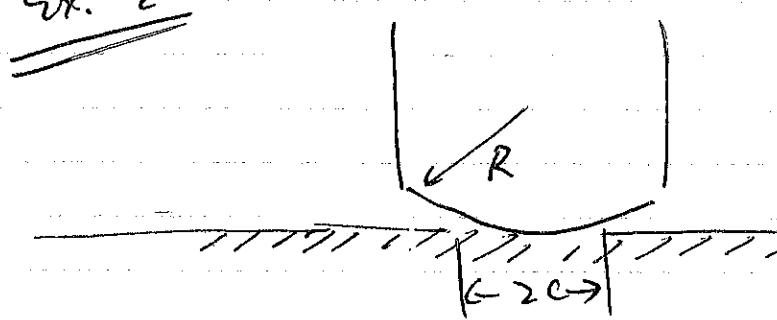
$$u_0(x) = 0$$

$$q(x) \Rightarrow$$



$$P_y(x) = \frac{F}{\pi \sqrt{c^2 - x^2}}$$

Cylindrical
punch



$$d < R, \quad u_0(x) = \frac{x^2}{2P} \quad (\text{parabolic})$$

$$q(x) = \frac{4\pi u}{k+1} \left(\frac{x}{R} \right)$$

$$\hookrightarrow \frac{d u_0(x)}{d x}$$

$$P_y(x) = \frac{-1}{\pi \sqrt{c^2 - x^2}} \text{ P.V.} \int_{-c}^c \frac{\sqrt{c^2 - x'^2}}{k - x'} \frac{4\pi u}{k+1} \left(\frac{x'}{R} \right) dx' + \frac{F}{\pi \sqrt{c^2 - x^2}}$$

$$\text{P.T.} \quad \int_{-1}^1 \frac{\sqrt{1-t^2}}{x-t} t^n dt = \pi \left[x^{n+1} - \frac{x^{n+1}}{2} \dots \right]$$

$$n=1. \quad I_1 = \pi \left(x - \frac{1}{2} \right). \quad I_0 = \pi(x)$$

$$t \rightarrow \frac{x'}{c} \quad \text{transform}$$

Applying change of variables.

$$\int_{-1}^1 \frac{\sqrt{1-t^2}}{\left(\frac{x}{c}-t\right)} c \cdot c dt = c^2 \pi \left(\left(\frac{x}{c}\right)^2 - \frac{1}{2} \right).$$

$$\text{Final expression: } \sqrt{\pi \left(x^2 - \frac{c^2}{4} \right)} = \pi (x^2 - c^2) + \frac{\pi c^2}{2}$$

$$P_g(x) = \frac{4\mu}{(k+1)R} \sqrt{c^2-x^2} + \left(\frac{F}{\pi} - \frac{2\mu c^2}{(k+1)R} \right) \frac{1}{\sqrt{c^2-x^2}}$$

$$f(x) = \frac{-1}{\pi^2 \sqrt{c^2-x^2}} \text{ P.T.} \int_{-c}^c \frac{\sqrt{c^2-x'^2}}{x-x'} g(x') dx' + \frac{F}{\pi \sqrt{c^2-x^2}}$$

the second term has a singularity.

... we went to vanish the $\left(\frac{F}{\pi} - \frac{2mc^2}{(k+1)R} \right) \frac{1}{\sqrt{1-x^2}}$

\rightarrow we set it to zero.

$$F = \frac{2\pi mc^2}{(k+1)R}$$

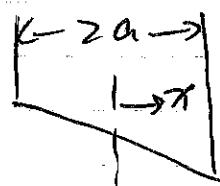
\uparrow total indentation force

$$F = \int_{-c}^c P_y(x) dx.$$

$$\hookrightarrow P_y(x) = \frac{4m}{(k+1)R} \sqrt{c^2 - x^2}$$

$$\frac{F}{\pi} - \frac{2mc^2}{(k+1)R} = 0$$

Ex. 3



$$u_0(x) = \beta(a-x)$$

$$\frac{du_0(x)}{dx} = -\beta.$$

$$P_y(x) = \frac{-1}{\pi^2 \sqrt{c^2 - x^2}} \text{ P.V.} \left[\int_{-c}^c \dots \frac{4m}{k+1} (-\beta) dx' + \dots \right]$$

$-c \quad c$
 x'

transformed coordinate.

$$\tilde{x} = x - (a - c)$$

Subs. \tilde{x} into the eqn.

$$P_1(x) = \frac{-1}{\pi \sqrt{c^2 - x^2}} \text{ P.t. } \left[\int_{-c}^c \dots \frac{4\pi u}{k+1} (-\beta) d\tilde{x}' + \right]$$

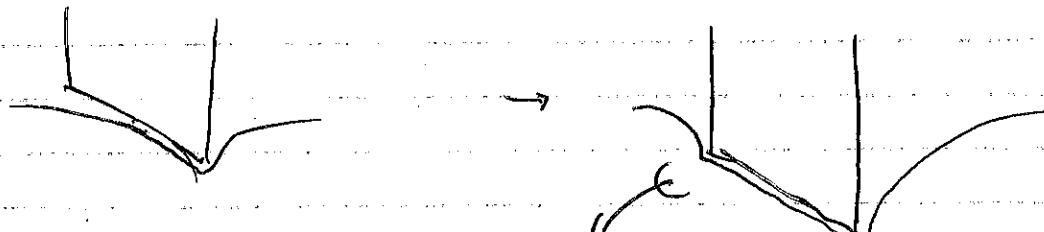
$$I_0 = C \frac{\pi x}{c}$$

$$\pi(x) \leftarrow t^\circ$$

$$= \frac{4\pi \cdot \eta \beta}{\pi \sqrt{c^2 - x^2}} \frac{C \pi x}{c} + \frac{F}{\pi \sqrt{c^2 - x^2}} \quad t = \frac{x'}{c}$$

We know $P_1(-c) = 0$

$$\frac{F}{\pi} = \frac{4\eta \beta c}{(k+1)} \Rightarrow F = \frac{4\eta \beta c}{(k+1)}$$

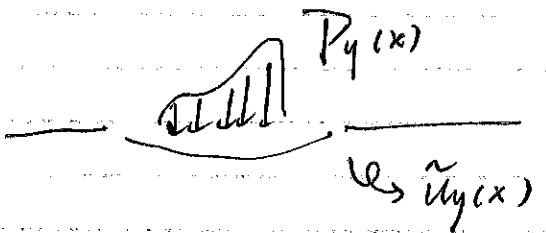


$$c \leq a$$

Critical point.

$$F_{\text{attract}} = \frac{4\pi \mu \beta q}{(k+1)}$$

Review notes for contact problems.



Surface displacement.

$$\tilde{u}_x(x) = \int_{-\infty}^{+\infty} -p_y(x') \cdot G_{xy}^S(x-x') dx'$$

$$\tilde{u}_y(x) = \int_{-\infty}^{+\infty} -p_y(x') \cdot G_{yy}^S(x-x') dx' \quad (*)$$

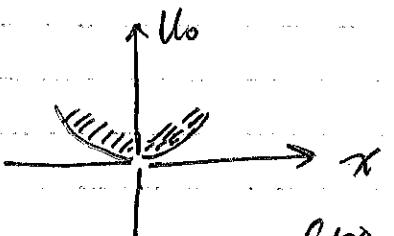
compressive

Green's function for 2D plane strain

$$G_{xy}^S(x) = \frac{k-1}{8\pi a} \operatorname{sgn}(x).$$

$$G_{yy}^S(x) = -\frac{k+1}{4\pi a} \log|x|.$$

Motionless contact. $T_x(x) = 0$ | integrating Green's function ...

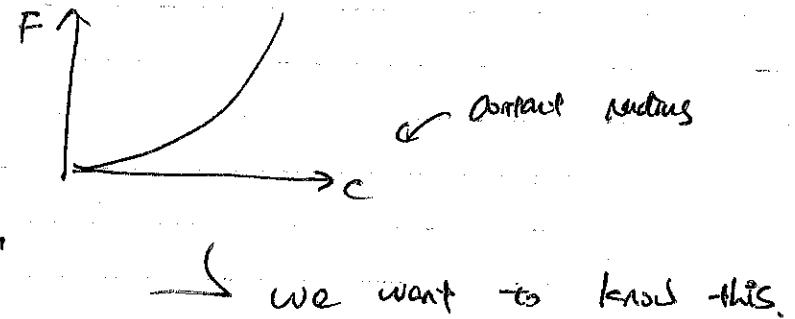
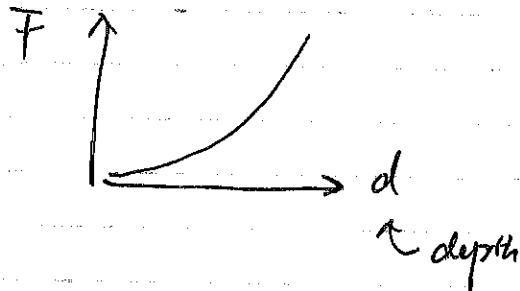


Eqn. (*) gives us:

$$u_0(x) - d = \int_{-\infty}^{+\infty} p_y(x') \cdot \frac{k+1}{4\pi a} \log|x-x'| dx' \quad (**)$$

total indenting force is the integral of the load:

$$F = \int_{-c}^c P_y(x) dx$$



→ we want to know this.

IMPORTANT: in $-c < x < c$ area:

$$\begin{cases} u_y(x) = u_o(x) - d & \text{indenter shape} \\ \sigma_{yy}(x) \leq 0 & \text{compressive} \\ \sigma_{xy}(x) = 0 & \text{frictionless.} \end{cases}$$

outside contact region.

$$\begin{cases} u_y(x) < u_o(x) - d & \text{no overlap} \\ \sigma_{yy}(x) = 0 & \rightarrow \text{traction free} \\ \sigma_{xy}(x) = 0 \end{cases}$$

Direct inversion of integral eqn. (differentiating w.r.t.)

$$\frac{du_o(x)}{dx} = \frac{k+1}{4\pi\mu} \cdot \int_{-c}^c \frac{P_y(x')}{x - x'} dx'$$

of the form: $g(x) = \int_{-c}^c \frac{f(x')}{x - x'} dx'$

General form to the integral equation

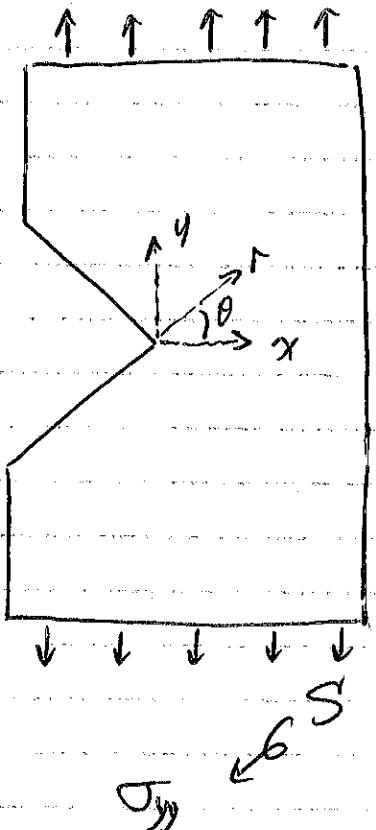
indirect
force

$$f(x) = -\frac{1}{\pi^2 \sqrt{c^2 - x^2}} \int_{-c}^c \frac{\sqrt{c^2 - x'^2} \cdot g(x')}{x - x'} dx' + \frac{F}{\pi \sqrt{c^2 - x^2}}$$

Since $\int_{-c}^c \frac{f(x')}{x - x'} dx'$ is singular, we need to

interpret its singular values, i.e., P.H.

Practice midterm.



Without notch.

$$\Omega = \begin{bmatrix} 0 & 0 & 0 \\ 0 & S & 0 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow 2D$$

$$\text{from } \sigma_{yy} = S, \Rightarrow \phi = \frac{1}{2} S x^2$$

$$\phi_{xx} \quad \phi(r, \theta) = \frac{1}{2} S r^2 \cos^2 \theta$$

$$\phi = \frac{1}{2} S r^2 \left(\frac{1}{2} + \cos 2\theta \right) \quad n=2$$

$$n=0 \quad = \frac{1}{4} S r^2 + \frac{1}{2} S r^2 \cos 2\theta$$

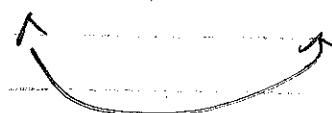
IMPORTANT RELATIONSHIPS.

$$\cos^2\theta = \frac{1+2\cos 2\theta}{2}$$

$$\sin 2\theta = 2 \sin \theta \cos \theta$$

$$\sin^2\theta = \frac{1-2\cos 2\theta}{2}$$

$$\sigma_{rr} = S' \quad \sigma_{\theta\theta} = S'$$



uniform stress field.

$$\left[-\frac{1}{2} S r^2 \right] \cos 2\theta$$

$$\frac{1}{4} S r^2 + \frac{1}{2} S r^2 \cos 2\theta + \dots$$

uniform.

$$\text{Resultant stress: } \begin{cases} -2\cos 2\theta & (\sigma_{rr}) \\ +2\cos 2\theta & (\sigma_{\theta\theta}) \\ +2\sin 2\theta & (\tau_{r\theta}) \end{cases}$$

We need to create $+2\cos 2\theta$ (σ_{rr})

$$\text{Can be applied } \begin{cases} -2\cos 2\theta (\sigma_{\theta\theta}) \\ -2\cos 2\theta (\tau_{r\theta}) \end{cases}$$

to cancel the angle variation θ terms in stress.

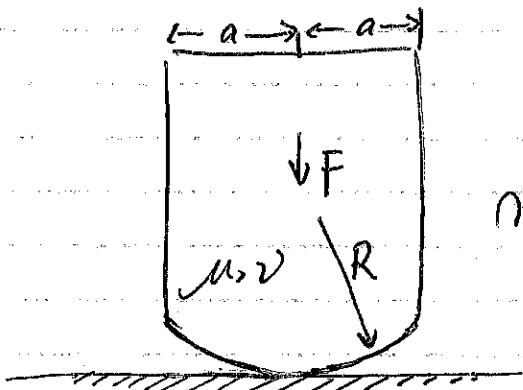
@ $\theta = \pm 135^\circ$: apply shear $\tau_{r\theta} = -2\cos 2\theta$

$$\phi = \frac{1}{2} S x^2 + A y + B$$

$$\phi' = \frac{1}{2} S x^2 + \frac{1}{2} S y^2 - S x y$$

$$\rightarrow \text{goal: } \sigma_{xy} = S \quad \sigma_{yy} = S \quad \frac{1}{2} S \cos 2\theta + \frac{1}{2} S \sin 2\theta - \frac{1}{2} S \sin 2\theta$$

3#2



normal load dist. $P_y(x)$

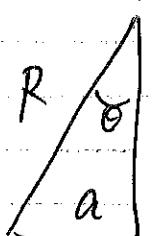
elastic half space

$$P_y(x) = \frac{2F}{\pi C^2} \sqrt{C^2 - x^2} \quad \text{where } C = \sqrt{\frac{2F(1-\nu)}{\pi \mu}}$$

↙
non-truncated cylindrical punch

$$f(x) = - \frac{1}{\pi \sqrt{C^2 - x^2}} \int_{-c}^c \frac{\sqrt{C^2 - z^2} g(z)}{x - z} dz$$

$$+ \frac{F}{\pi \sqrt{C^2 - x^2}}$$

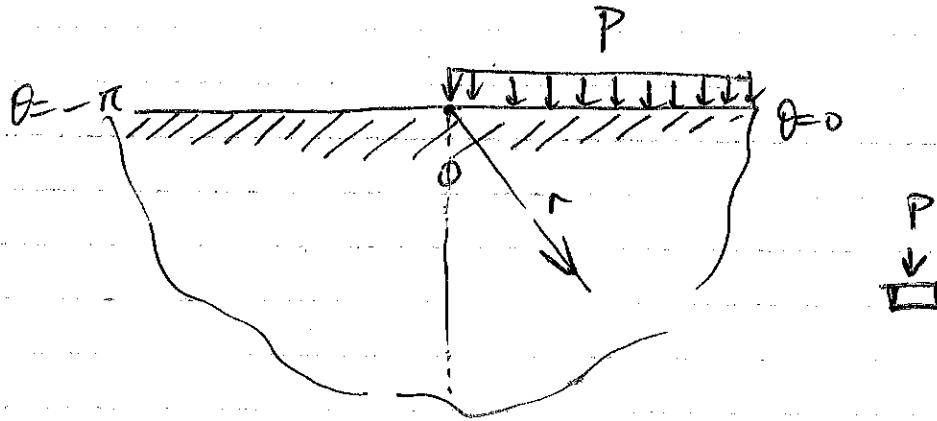


$$\sin \theta = \frac{a}{R}$$

$$\theta = \arcsin\left(\frac{a}{R}\right)$$

$$P_y(x) = \begin{cases} \frac{2F}{\pi C^2} \sqrt{C^2 - x^2} & \theta < \arcsin\left(\frac{a}{R}\right) \\ \frac{2F}{\pi C^2} \sqrt{C^2 - x^2} + \frac{F}{\pi \sqrt{C^2 - x^2}} \theta > \arcsin\left(\frac{a}{R}\right) \end{cases}$$

Pb #3



(a) $\left\{ \begin{array}{l} \sigma_{\theta\theta} = -P \\ \sigma_{rr} = 0 \end{array} \right. \quad @ \quad \theta = 0$

$$\left\{ \begin{array}{l} \sigma_{\theta\theta} = 0 \\ \sigma_{rr} = 0 \end{array} \right. \quad @ \quad \theta = -\pi$$

(b) From the problem, we know that $\sigma_{\theta\theta}$ has θ dependence.

$$@ \quad \theta = 0 \rightarrow \sigma_{rr} = 0$$

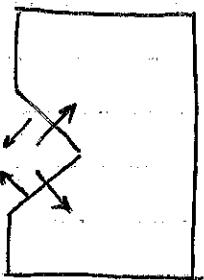
$$@ \quad \theta = -\pi \rightarrow \sigma_{\theta\theta} = 0 \quad \sigma_{rr} = 0 \quad \rightarrow 2\theta \text{ term gone}$$

$$\phi = A r^2 + B r^2 \cos 2\theta$$

A

$$\sigma_{\theta\theta} = 2A + B 2r \cos 2\theta \rightarrow \begin{aligned} 2A + B &= P \\ 2A - 2B &= 0 \end{aligned}$$

$$\sigma_{rr} = B 2r \sin 2\theta$$



$$\left\{ \begin{array}{l} \underline{n}_1 = \left[-\frac{\sqrt{2}}{2} \quad -\frac{\sqrt{2}}{2} \right] \\ \underline{n}_2 = \left[-\frac{\sqrt{2}}{2} \quad \frac{\sqrt{2}}{2} \right] \end{array} \right.$$

$$\underline{\Omega} = \begin{bmatrix} 0 & 0 \\ 0 & S \end{bmatrix}$$

Rotation matrix

$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

transform from Cartesian
to Polar word.

Notes on beam theory.

Euler-Bernoulli

$$EI \downarrow V \quad \frac{d}{dx} f(x) = -q(x)$$

$$(EI) \quad \frac{d}{dx} M(x) = f(x).$$

$$(C) \quad K(x) = \frac{M(x)}{EI}$$

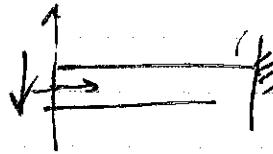
Solving beam problem using Airy Stress function.

Strong B.C.s on top & bottom surfaces.

$$\left\{ \begin{array}{l} \sigma_{xy} = 0 \\ \sigma_{yy} = 0 \end{array} \right. \quad y = \pm b.$$

On two edges, apply the weak B.C.s

$$\int_{-b}^b \sigma_{xy} dy = F$$



→ collection of weak B.C.s.

$$\int_{-b}^b \sigma_{xy} dy = F. \quad \left. \begin{array}{l} \\ \end{array} \right\} x=0$$

$$\int_{-b}^b \sigma_{xy} dy = F \quad \left. \begin{array}{l} \\ \end{array} \right\} x=a$$

$$\int_{-b}^b \sigma_{xx} dy = 0$$

$$\int_{-b}^b \sigma_{xy} dy = 0$$

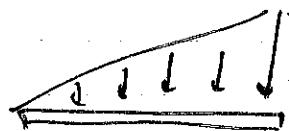
left

Polynomial stress function (analytic)

$$\phi = C_1 xy^3 \rightarrow \left\{ \begin{array}{l} \sigma_{xx} = 6C_1 xy, \\ \sigma_{xy} = -3C_1 y^2 \\ \sigma_{yy} = 0 \end{array} \right.$$

General Solution Strategies for beam Problem.

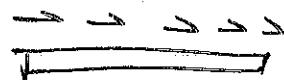
1. Determine the maximum order of polynomials.



normal loading $\sim x^n$

$$\text{Shear } \sim x^{n+1} \rightarrow \text{moment } \sim x^{n+2}$$

$$\rightarrow \phi \sim x^{n+2} y^3$$



loading $\sim x^m$

$$\text{shear } x^m \rightarrow \text{moment } x^{m+1}$$

$$\rightarrow \phi \sim x^{m+1} y^3$$

2. Polynomial trial function.

$$\phi(x, y) = C_1 x^2 + C_2 xy + C_3 y^3 + \dots$$

3. Impose compatibility condition $\nabla^4 \phi = 0$

4. Apply strong & weak B.C.s.

5. Determine the constants.

Fourier expansion

$$f(x) = \sum_{i=0}^{\infty} C_i \varphi_i(x) = \frac{1}{2} a_0 + \sum_{n=1}^{\infty} a_n \cos n\pi x + b_n \sin n\pi x$$

Expansion coefficients:

$$\begin{cases} a_0 = \frac{1}{a} \int_{-a}^a f(x) dx, \\ a_n = \frac{1}{a} \int_{-a}^a f(x) \cos n\pi x dx, \\ b_n = \frac{1}{a} \int_{-a}^a f(x) \sin n\pi x dx \end{cases}$$

If even function:

$$f(x) = \frac{1}{2} a_0 + \sum_{n=1}^{\infty} a_n \cos \frac{n\pi}{a} x.$$

Or $f(x) = \sum_{n=1}^{\infty} a_n \cos n\pi x, \quad \lambda_n = \frac{(2n-1)\pi}{2a}$

Fourier transform.

$$e^{ikx} = \cos kx + i \sin kx.$$

Expansion of $f(x)$ in terms of e^{ikx} .

$$f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{f}(k) e^{ikx} dk.$$

(inverse Fourier transform)

→ little confusing?

Source: Image sampling & reconstruction

frank @ princeton.edu, CS426.7.

• Fourier transform:

$$\hat{f}(k) = \int_{-\infty}^{\infty} f(x) e^{-i2\pi kx} dx.$$

• Inverse Fourier transform:

$$f(x) = \int_{-\infty}^{\infty} \hat{f}(k) e^{i2\pi kx} dk$$

• Fourier solution (beam problem).

- how to construct stress function based on sym.

$$\phi(x, y) = \begin{cases} \cos \pi x [A \cosh \pi y + D y \sinh \pi y] & \text{even } x, y \\ \cos \pi x [B y \cosh \pi y + C \sinh \pi y] & \text{even } x \text{ odd } y \\ \sin \pi x [A \cosh \pi y + D y \sinh \pi y] & \text{odd } x \text{ even } y \\ \sin \pi x [B y \cosh \pi y + C \sinh \pi y] & \text{odd } x \text{ odd } y \end{cases}$$

~~NOT~~ IMPORTANT.

> Generalized Hooke's law for 2D

$$\epsilon_{xx} = \frac{k+1}{2\mu} \sigma_{xx} - \frac{3-k}{2\mu} \sigma_{yy}$$

$$\epsilon_{yy} = -\frac{3-k}{2\mu} \sigma_{xx} + \frac{k+1}{2\mu} \sigma_{yy}$$

$$\epsilon_{xy} = \frac{1}{2\mu} \sigma_{xy}$$

plane strain: $K = 3 - 4\nu$

plane stress: $\nu = \frac{3-\nu}{1+2\nu}$

> Weak B.C.s applied at the beam end.

$$\left\{ \begin{array}{l} u_x = 0 \\ u_y = 0 \\ \frac{\partial u_y}{\partial x} = 0 \end{array} \right. \quad \text{at beam end (subs. pos.)}$$

$$\left\{ \begin{array}{l} u_x = 0 \\ u_y = 0 \\ \frac{\partial u_x}{\partial y} = 0 \end{array} \right.$$

or

$$\left\{ \begin{array}{l} \int_{-b}^b u_y dy = 0 \\ \int_{-b}^b u_y dy = 0 \\ \int_{-b}^b u_x dy = 0 \end{array} \right.$$

~ Additional Notes for Contact.

$$g(x) = \frac{4\pi \mu}{(k+1)} \frac{dU_0(x)}{dx}, \quad f(x) = P_y(x)$$

$$f(x) = -\frac{1}{\pi \sqrt{C^2 - x^2}} \int_{-C}^C \frac{\sqrt{C^2 - x'^2} g(x')}{x - x'} dx' + \frac{F}{\pi \sqrt{C^2 - x^2}}$$

$$f(x') = -\frac{q_n}{(k+1)\sqrt{C^2 - x'^2}} \sum_{n=1}^{\infty} n a_n \cos n \theta + \frac{P_0 C}{2\sqrt{C^2 - x'^2}}$$

▷ # Flat punch.

$$P_y = \frac{F}{\pi \sqrt{C^2 - x^2}}$$

$$\rightarrow P_y \sim \frac{F}{2\pi C} \frac{1}{\sqrt{r}} \rightarrow \sigma_{yy} \propto \frac{1}{\sqrt{r}}$$

▷ # Cylindrical punch.

$$U_0(x) = \frac{x^2}{2R}, \quad \frac{dU_0(x)}{dx} = \frac{x}{R}$$

$$C = \sqrt{\frac{(k+1)R}{2\pi \mu}} F \rightarrow P_y(x) = \frac{2F}{\pi C^2} \sqrt{C^2 - x^2}$$

\sim Polar coordinates.

$$\sigma_{rr} = \frac{1}{r} \cdot \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

$$\sigma_{\theta\theta} = \frac{\partial^2 \phi}{\partial r^2}$$

$$\sigma_{r\theta} = \frac{1}{r} \frac{\partial \phi}{\partial \theta} - \frac{1}{r} \frac{\partial^2 \phi}{\partial r \partial \theta}$$

$$= -\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial \phi}{\partial \theta} \right)$$

$$\sigma_{rr} = (\lambda + 2\mu) \epsilon_{rr} + \lambda \epsilon_{\theta\theta} + \lambda \epsilon_{zz}$$

$$\sigma_{\theta\theta} = \lambda \epsilon_{rr} + (\lambda + 2\mu) \epsilon_{\theta\theta} + \lambda \epsilon_{zz}$$

$$\sigma_{zz} = \lambda \epsilon_{rr} + \lambda \epsilon_{\theta\theta} + (\lambda + 2\mu) \epsilon_{zz}$$

$$\sigma_{r\theta} = 2\mu \epsilon_{r\theta}$$

$$\sigma_{r\theta} = 2\mu \epsilon_{r\theta}$$

$$\sigma_{r\theta} = 2\mu \epsilon_{r\theta}$$

$$\epsilon_{rr} = \frac{\partial u_r}{\partial r}$$

$$\epsilon_{\theta\theta} = \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r}$$

$$\epsilon_{\phi\phi} = \frac{1}{r} \left(\frac{1}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r} + \frac{\partial u_\theta}{\partial r} \right)$$

⇒ $\sin 3\theta = 3\sin\theta - 4\sin^3\theta \quad \sin 2\theta = 2\sin\theta \cos\theta$



$$\cos 2\theta = \cos^2\theta - \sin^2\theta$$

$$\sin^3\theta = \frac{3\sin\theta - \sin 3\theta}{4}$$

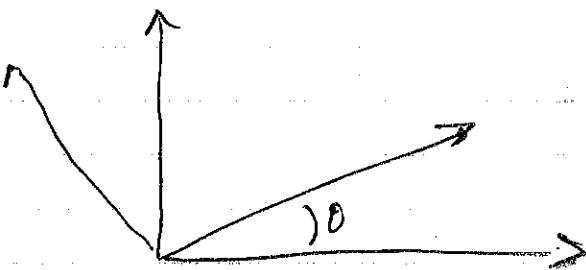
$$= 1 - 2\sin^2\theta$$

$$\cos 3\theta = 4\cos^3\theta - 3\cos\theta$$

$$= 2\cos^2\theta - 1$$

Rotation tensor

$$\underline{\underline{\Omega}} = \begin{bmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



$$\underline{\underline{\Omega}}' = \underline{\underline{\Omega}} \quad \underline{\underline{\Omega}} \equiv \underline{\underline{\Omega}}^T$$

⇒ Beam free end weak B.C.s.

$$\int_{-b}^b \sigma_{xy} dy = F$$



$$\int_{-b}^b \sigma_{xx} y dy = 0$$

$$\int_{-b}^b \sigma_{yy} dy = 0$$

One integral / differentiation will change the
odd / evenness of the function in that specific
direction.

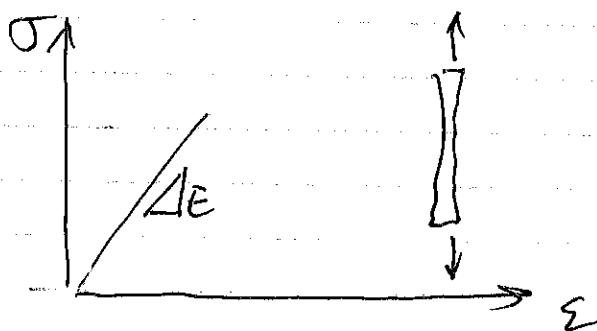
HW example: $\varepsilon_{xx} \rightarrow$ even in x , even in y
 \downarrow
 $u_x = \int \varepsilon_{xx} dx$ odd in x , even in y

lecture 12 5/8/2014

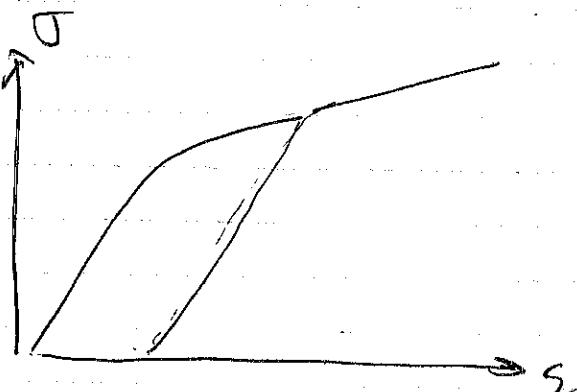
Inelasticity

Plasticity

tensile test.

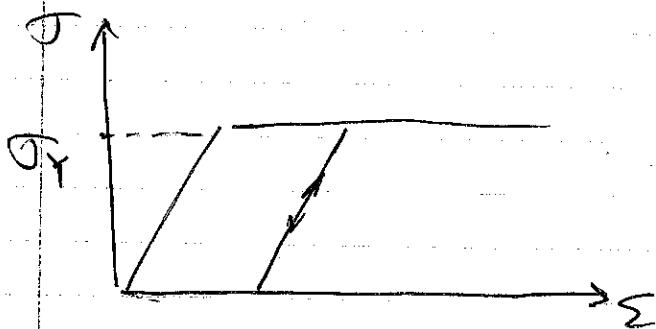


linear plasticity



"real material"

Simpliest model.



perfectly plastic

Displacement field.

$$\underline{u} = \underline{x} - \underline{\xi} \quad u_i(x_i)$$

Strain field

$$\epsilon_{ij} = \frac{1}{2} (u_{ij} + u_{ji})$$

▷ Stress field, traction.

$$T_j = \sigma_{ij} n_i$$

▷ Equilibrium condition.

$$\sigma_{j,i} + f_j = 0$$

▷ Compatibility condition.

$$\epsilon_{ijkl} + \epsilon_{kl,ij} = \epsilon_{de,jl} - \epsilon_{jl,de} = 0$$

Strain decomposition,

$$\epsilon_{ij} = \epsilon_{ij}^{el} + \epsilon_{ij}^{pl}$$

↳ Satisfy the compatibility.

(continuous body assumption)

⇒ Constitutive equation.

~ Generalized Hooke's law.

$$\sigma_{ij} = C_{ijkl} \epsilon_{kl}^{el}$$

isotropic elasticity -

$$\sigma_{ij} = \lambda \epsilon^{el} \delta_{ij} + 2\mu \epsilon^{el}_{ij}$$

where $\lambda = \frac{2\mu v}{1-2v}$

$$\sigma_{xx} = (\lambda + 2\mu) \epsilon_{xx}^{el} + \lambda \epsilon_{yy}^{el} + \lambda \epsilon_{zz}^{el}$$

$$\sigma_{yy} = \lambda \epsilon_{xx}^{el} + (\lambda + 2\mu) \epsilon_{yy}^{el} + \lambda \epsilon_{zz}^{el}$$

$$\sigma_{zz} = \lambda \epsilon_{xx}^{el} + \lambda \epsilon_{yy}^{el} + (\lambda + 2\mu) \epsilon_{zz}^{el}$$

$$\sigma_{xy} = 2\mu \epsilon_{xy}^{el}, \quad \sigma_{yz} = 2\mu \epsilon_{yz}^{el}, \quad \sigma_{xz} = 2\mu \epsilon_{xz}^{el}$$

$$\sigma_{ij} = \begin{bmatrix} \sigma_{xx} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & \sigma_{yy} & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & \sigma_{zz} \end{bmatrix}$$

$$\bar{\sigma} = \frac{1}{3} \sigma_{ii} \quad \text{or Stress invariant.}$$

i.e., hydrostatic stress.

\Rightarrow hydrostatic strain. $\bar{\epsilon} = \frac{1}{3} \epsilon_{ii}$

$$\bar{\sigma} = 3K \bar{\epsilon}^{el}$$

... characterizes the vol. change

bulk modulus

deviatoric Stress

$$S_{ij} = \sigma_{ij} - \bar{\sigma} \delta_{ij}$$

$$\begin{bmatrix} \sigma_{xx} - \bar{\sigma} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & \sigma_{yy} - \bar{\sigma} & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & \sigma_{zz} - \bar{\sigma} \end{bmatrix}$$

deviatoric Strain

$$\epsilon_{ij} = \varepsilon_{ij} - \bar{\varepsilon} \delta_{ij}$$

$$\hookrightarrow S_{ij} = 2\mu \epsilon_{ij}^{\text{el}}$$

shear modulus

Given the strain, one can decompose it

into the hydrostatic part & deviatoric part.

$$\text{i.e., } \epsilon_{ij}^{\text{el}} = \bar{\varepsilon}^{\text{el}} \delta_{ij} + \epsilon_{ij}^{\text{el}} \quad \leftarrow \text{shape change}$$

↓ bulk mod.

Volume
change const.

$$3K \bar{\varepsilon}^{\text{el}} \delta_{ij} + 2\mu \epsilon_{ij}^{\text{el}} = \sigma_{ij}$$

↓
deviatoric stress

Yield condition & flow rule

$$f(\{\sigma_{ij}\}) = 0$$

f(.) takes all the six stress components
and $\rightarrow R$.

f_{in} in the surface,

f_{out} outside surface

assumption: rate-independent $\therefore \textcircled{1}$

Isotropic $\therefore \textcircled{2}$

Coordinate transformation

$$\sigma'_{ij} = Q_{ip} Q_{jq} \sigma_{pq}$$

$$f(\{\sigma'_{ij}\}) = 0$$

$\sigma'_{ij} \rightarrow$ invariants \rightarrow plasticity model.

Stress invariants

$$I_1 = \text{tr}(\sigma_{ij}) \quad | \quad [J_{ij}] \rightarrow \sigma_1, \sigma_2, \sigma_3$$

Principal stresses

$$= \sigma_1 + \sigma_2 + \sigma_3 = \sum_i \sigma_i \quad \text{not easy to compute}$$

$$-I_2 = \frac{1}{2} (\sigma_{ii}\sigma_{jj} - \sigma_{ij}\sigma_{ji}) = (\sigma_{xx}\sigma_{yy} + \sigma_{yy}\sigma_{zz} + \sigma_{zz}\sigma_{xx}) \\ - (\sigma_{xy}^2 + \sigma_{yz}^2 + \sigma_{xz}^2)$$

$$I_3 = \det(\sigma_{ij}) = I_1 I_2$$

$$= \sigma_1\sigma_2 + \sigma_2\sigma_3 + \sigma_3\sigma_1$$

$$f^{(1)} = f(I_1, I_2, I_3) = 0$$

| Bilgehorn.

$$f(I_2, I_3) \rightarrow f(J_2, J_3) = 0$$

$$J_1 = \text{tr}(S_{ij}) = 0$$

$$f(J_2) = 0$$

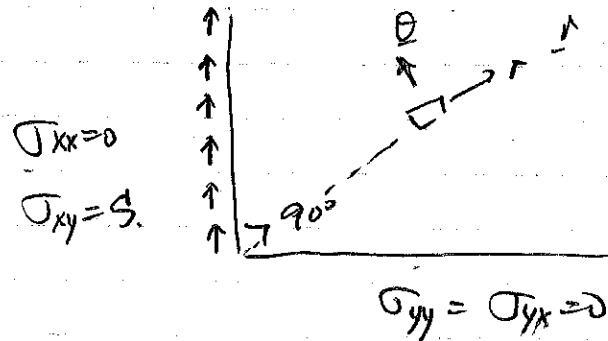
$$J_2 = \frac{1}{2} S_{ij} S_{ij} \rightarrow L^2 \text{-norm.}$$

$$J_3 = \det(S_{ij})$$

Problem Session #6

5/10/2024.

Notches.



We use
polar coord

(a) $\theta = 0$, $\sigma_{\theta\theta} = \sigma_{r\theta} = 0$.

(b) $\theta = \frac{\pi}{2}$, $\sigma_{\theta\theta} = 0$, $\sigma_{rr} = S$.



$$\sigma_{rr} \propto r^0 \rightarrow \phi(r, \theta) \propto r^2$$

$$\phi = f(r) \cdot e^{in\theta}$$

$$= r^m e^{in\theta}$$

$$m = 2 ; n = 0, 2$$

William soln: $\phi(r, \theta) = r^{n+2} [A_2 \cos(n+2)\theta + A_3 \cos(n\theta)] + A_4 \sin(n+1)\theta + A_5 \sin(n\theta)]$

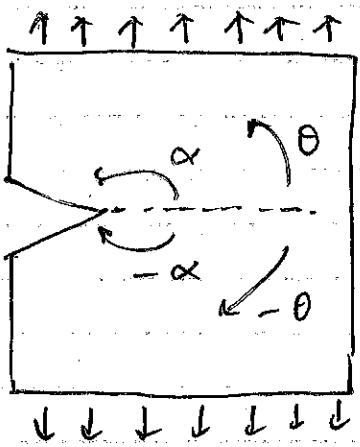
General soln
for notch problem.

$$\lambda = n-1, \quad \phi(r, \theta) = r^{\lambda+1} [A_1 \cos(\lambda+1)\theta + A_2 \cos(\lambda-1)\theta - A_3 \sin(\lambda+1)\theta + A_4 \sin(\lambda-1)\theta]$$

$$\sigma_{rx} = \frac{1}{r^m} [A_1 \pi(\pi+1) \sin(\pi+1)\theta +$$

$$A_2 \pi(\pi-1) \sin(\pi-1)\theta - A_3 \pi(\pi+1) \cos(\pi+1)\theta \\ - A_4 \pi(\pi-1) \cos(\pi-1)\theta]$$

Notch



σ_{rx}, σ_{yy} same symmetry

(from σ_{rx} & σ_{yy})

B.C.s @ $\theta = \pm \alpha$, traction free.

$$\sigma_{rx} = 0, \sigma_{yy} = 0.$$

$$\sigma_{rx} \rightarrow \theta = +\alpha, -\alpha,$$

$$① A_1 (\pi+1) \sin(\pi+1)\alpha + A_2 (\pi-1) \sin(\pi-1)\alpha$$

$$- A_3 (\pi+1) \cos(\pi+1)\alpha - A_4 (\pi-1) \cos(\pi-1)\alpha = 0$$

$$② -A_1 (\pi+1) \sin(\pi+1)\alpha - A_2 (\pi-1) \sin(\pi-1)\alpha$$

$$-A_3 (\pi+1) \cos(\pi+1)\alpha - A_4 (\pi-1) \cos(\pi-1)\alpha = 0$$

Solve for independent eqns for

$[A_1, A_2]$ & $[A_3, A_4]$.

$$\begin{bmatrix} M_{1(2 \times 2)} & 0 \\ 0 & M_{2(2 \times 2)} \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ A_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

③ & ④ from $\partial_{\theta\theta} = 0$,

we now want to solve:

$$M_1 \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = 0. \quad M_1 \text{ is singular.}$$

$$\det(M_1) = 0$$

$$\cdots \begin{bmatrix} (\pi+1) \sin(\pi+1)\alpha & (\pi-1) \sin(\pi-1)\alpha \\ (\pi+1) \cos(\pi+1)\alpha & (\pi-1) \cos(\pi-1)\alpha \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = 0$$

Solve this.

$$\det \left(\begin{bmatrix} (\pi+1) \sin(\pi+1)\alpha & (\pi-1) \sin(\pi-1)\alpha \\ (\pi+1) \cos(\pi+1)\alpha & (\pi-1) \cos(\pi-1)\alpha \end{bmatrix} \right) = 0$$

$$A_1, A_2 \rightarrow \pi \sin(2\alpha) + \sin(2\pi\alpha) = 0$$

2

$$\pi = 2\pi\alpha$$

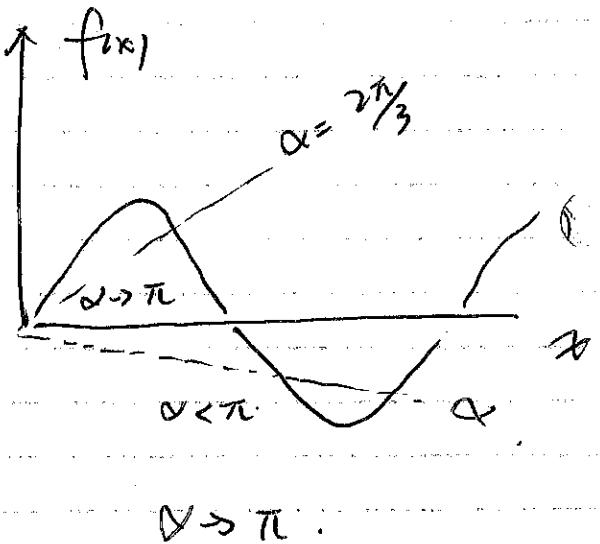
$$-\frac{\pi}{2\alpha} \sin(2\alpha) = \sin(\pi)$$

$$A_3, A_4 \rightarrow \pi \sin(2\alpha) - \sin(2\pi\alpha) = 0$$

$$\text{if } \alpha = \frac{2\pi}{3},$$

Slope of line

$$= -\sin\left(2 \times \frac{2\pi}{3}\right)$$



Solve for A_1, A_2

$$x = 0, \pi, 2\pi, 3\pi, \dots$$

$$\begin{bmatrix} \dots \\ \vdots \\ 1 \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$\lambda = 0, \frac{1}{2}, 1, \frac{3}{2}, \dots$
 ↳ non-singular
 ↳ not possible

$$A_1 = A(\pi-1) \sin((\pi-1)\alpha) \quad \sigma \propto r^{\pi-1} \quad \{ \lambda = \frac{1}{2} \}$$

$$A_2 = A(\pi+1) \sin(\pi+1)\alpha$$

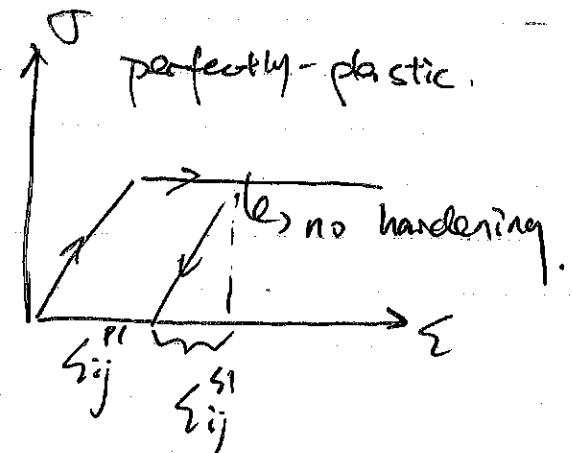
Plasticity

Strain: $\epsilon_{ij} = \epsilon_{ij}^{el} + \epsilon_{ij}^{pl}$.

Stress: $\sigma_{ij} = C_{ijkl} \epsilon_{kl}^{el}$

Compatibility condition.

\Rightarrow total strain ϵ_{ij} .



1). hydrostatic stress. $\rightarrow \bar{\sigma} = \sigma_{ii}/3$.

$$\rightarrow \bar{\sigma}_{xx} + \bar{\sigma}_{yy} + \bar{\sigma}_{zz}$$

2) Deviatoric Stress. $\epsilon_{ij} = \sigma_{ij} - \bar{\sigma}\delta_{ij}$.

hydrostatic stress + Deviatoric.

yield criteria: $f(\{\epsilon_{ij}\}) = 0$.

... depends on stress invariants.

$$\left[\begin{array}{ccc} \bar{\sigma} & & \\ & \bar{\sigma} & \\ & & \bar{\sigma} \end{array} \right] \rightarrow \text{not cause yield}$$

$$\text{on } f(J_2) = 0$$

Stress invariants

→ Stress tensor →

$$\begin{cases} I_1 \dots -(\sigma_{ij}) \\ I_2 \dots -\frac{1}{2}(\sigma_i \sigma_j - \sigma_i \sigma_j) \\ I_3 \end{cases}$$

$$\sigma_{ij} N_i = J_1.$$

eigen val. problem

$$\det(\sigma_{ij} - \lambda I) = 0$$

$$\lambda^3 - I_1 \lambda^2 - I_2 \lambda - I_3 = 0 \quad \curvearrowright$$

detektore:

$$\rightarrow \begin{cases} J_1 : S_{11} + S_{22} + S_{33} = 0 \\ J_2 : \frac{1}{2} S_{ij} S_{ij} = \frac{1}{2} (S_{11}^2 + S_{22}^2 + S_{33}^2) \\ J_3 : S_1 S_2 S_3 \end{cases}$$

$$\begin{bmatrix} S_1 \\ S_2 \\ S_3 \end{bmatrix}$$

lecture 13. 5/13/2024.

plasticity: $\varepsilon_{ij} = \varepsilon_{ij}^e + \varepsilon_{ij}^p$

Generalized Hooke's law: $\sigma_{ij} = 2\mu \varepsilon_{ij}^{ee}$

$$\sigma_{ij} = \bar{\sigma} \delta_{ij} + S_{ij} \quad \begin{matrix} \rightarrow \text{deviatoric} \\ \text{hydrostatic (spherical)} \end{matrix}$$

$$\bar{\sigma} = \frac{1}{3} \sigma_{kk} = \frac{1}{3} \operatorname{tr}(\sigma_{ij})$$

$$\varepsilon_{ij} = \bar{\varepsilon} \delta_{ij} + e_{ij} \quad \begin{matrix} \rightarrow \bar{\varepsilon} = \frac{1}{3} \varepsilon_{kk} = \frac{1}{3} \operatorname{tr}(\varepsilon_{ij}) \end{matrix}$$

$$\bar{\sigma} = 3K \bar{\varepsilon}, \quad S_{ij} = 2\mu e_{ij}$$

\hookrightarrow non-p. elasticity part.

Yield condition.

$$f(\sigma_{ij}) = 0$$

assumption: - isotropic.

$$\hookrightarrow f(\sigma_1, \sigma_2, \sigma_3) = 0$$

... Stress invariants:

$$I_1 = \operatorname{tr}(\sigma_{ij}) = \sigma_{11} + \sigma_{22} + \sigma_{33}$$

\hookrightarrow principal stresses

$$- I_2 = \frac{1}{2} (\sigma_{ii}\sigma_{jj} - \sigma_{ij}\sigma_{ji})$$

(takes a lot of work)

$$I_3 = \det(\sigma_{ij}) = \sigma_1 \cdot \sigma_2 \cdot \sigma_3$$

\rightarrow find them, avoid it...

according to Besdysenov.

equivalently: $f(I_1, I_2, I_3) = 0$ (yield)

$f(S_{ij}) = 0 \leftarrow$ transform I_1, I_2, I_3

$\hookrightarrow f(J_2, J_3) = 0 \quad J_1, J_2, J_3$

$J_1 = \text{tr}(S_{ij}) =$

$J_2 = \frac{1}{2} S_{ij} S_{ij}$ 2-norm of the deviatoric stress

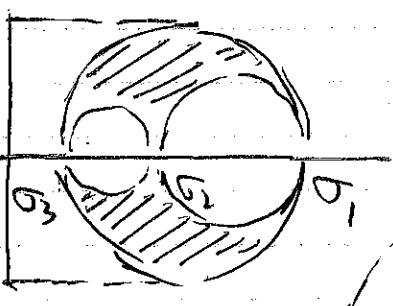
$J_3 = \dots$

Von Mises yield criteria

$$f(J_2) = J_2 - k^2 = 0 \quad J_2 = k^2$$

yield is satisfied when J_2 equals to some const.

Tresca yield condition



$$O_1 - O_3 = 2k$$

Von Mises

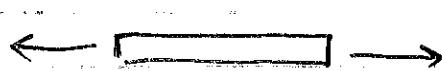
→ different k from

or the maximum difference between three principal stresses.

you can rewrite it as

$$\text{in terms of } f = J(J_2, J_3) = 0 \quad (\text{messy})$$

σ_y : uniaxial tension.



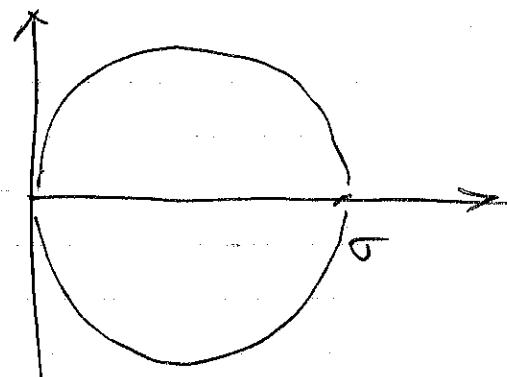
$$\sigma_y^2 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\bar{\sigma} = \frac{1}{3}\sigma \rightarrow S_{ij} = \begin{bmatrix} \frac{2}{3}\sigma & 0 & 0 \\ 0 & -\frac{1}{3}\sigma & 0 \\ 0 & 0 & -\frac{1}{3}\sigma \end{bmatrix}$$

$$J_2 = \frac{1}{2} \left(\frac{4}{3}\sigma^2 + \frac{1}{3}\sigma^2 + \frac{1}{3}\sigma^2 \right) = \frac{1}{2} \cdot \frac{6}{3}\sigma^2 = \frac{1}{3}\sigma^2$$

$$\frac{1}{3}\sigma^2 = k^2 \therefore k = \frac{\sigma_y}{\sqrt{3}}$$

σ_y : uniaxial tension



$$\sigma_1 - \sigma_3 = 0$$

$$\sigma_y = 2k_T$$

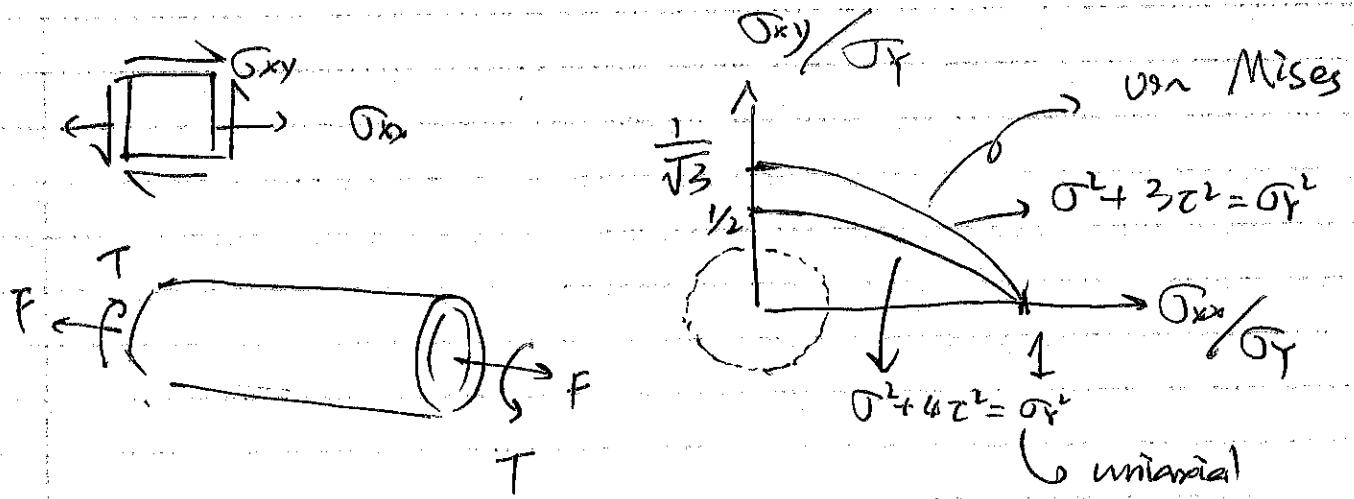
$$k_T = \frac{\sigma_y}{2}$$

k & k_T are calibrated s.t. both v.M.

& Tresca predicts the same yield under uniaxial tension

Taylor & Quinney (1931).

tensor & shear.



"New" stress tensor $\rightarrow \sigma_{ij} = \begin{bmatrix} \sigma_{xx} & \sigma_{xy} & 0 \\ \sigma_{xy} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

$$\bar{\sigma} = \frac{1}{3} \sigma_{xx}$$

$$S_{ij} = \begin{bmatrix} \frac{2}{3} \sigma_{xx} & \sigma_{xy} & 0 \\ \sigma_{xy} & -\frac{1}{3} \sigma_{xx} & 0 \\ 0 & 0 & -\frac{1}{3} \sigma_{xx} \end{bmatrix}$$

Now, let's calc. J_2 :

$$J_2 = \frac{1}{2} \left(\frac{6}{9} \sigma_{xx}^2 + 2 \sigma_{xy}^2 \right) = \frac{1}{3} \sigma_{xx}^2 + \sigma_{xy}^2$$

Same as in pre-tension

$$\frac{1}{3} \sigma_{xx}^2 + \sigma_{xy}^2 = k^2 = \frac{\sigma_y^2}{3}.$$

pure shear: $\sigma_{xy}^2 = \frac{\sigma_y^2}{3}$.

\therefore von Mises

$$\sigma_{xy} = \frac{\sigma_y}{\sqrt{3}}.$$

flow rule.

Elastic perfectly-plastic material.

$$J_2 = k^2, \quad j_2 = 0 \quad \leftarrow \text{von Mises, case 1}$$

$$J_2 = \frac{1}{2} S_{ij} S_{ij}, \quad j_2 = S_{ij} \dot{S}_{ij} = 0$$

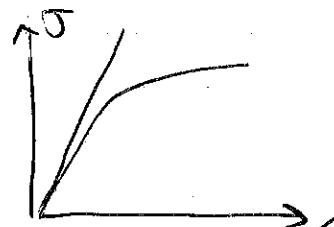
$$\sigma_{ij} = \bar{\sigma} \delta_{ij} + S_{ij}.$$

τ realistic case.

$$\bar{\sigma} = 3K \bar{\epsilon}^{el} \quad S_{ij} = 2\mu \cdot \dot{\epsilon}_{ij}^{el}$$

$$\dot{\epsilon}_{ij}^{pl}$$

$$\dot{\epsilon}_{ij}^{pl} = \int \dot{\epsilon}_{ij}^{pl}(t) dt.$$



\leftarrow the "accepted" theory

$$\dot{\varepsilon}_{ij}^{pl} = \frac{1}{2\mu} S_{ij} \quad \dots \text{Associated flow rule.}$$

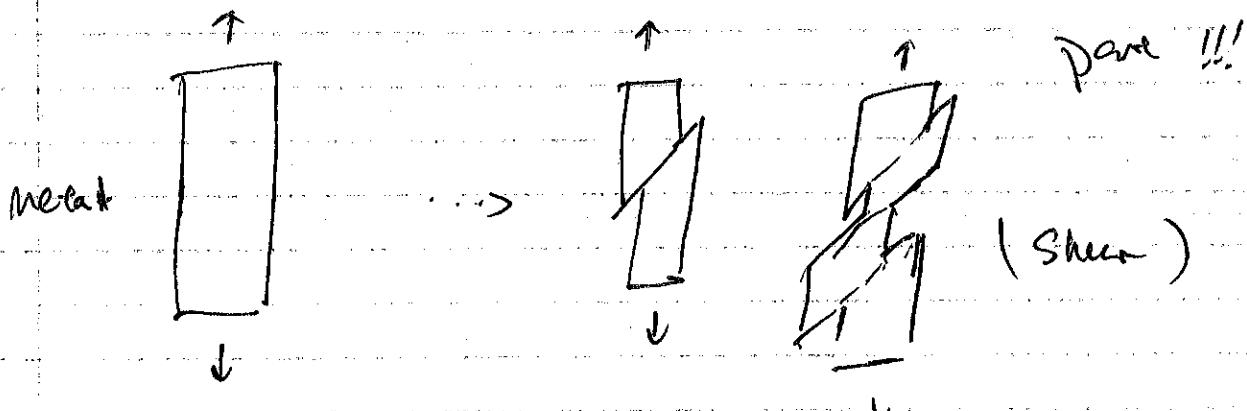
↑ looks like a fluid
... satisfies objective.

$$\dot{\varepsilon}_{ij}^{el} = \frac{1}{2\mu} S_{ij} \quad \text{from}$$

$$+ \text{tr} [\dot{\varepsilon}_{ij}] = 0 \rightarrow \boxed{\dot{\varepsilon}_{ij}} = 0 \Rightarrow \text{Bridgeman.}$$

$$\boxed{\dot{\varepsilon}_{ij}^{pl}} = \cancel{\dot{\varepsilon}_{ij}^{pl} \delta_{ij}} + \boxed{\dot{\varepsilon}_{ij}^{el}}$$

$$\dot{\varepsilon}_{ij} = \dot{\varepsilon}_{ij}^{el} \delta_{ij} + \dot{\varepsilon}_{ij}^{el} \leftarrow \text{plastic strain has no volumetric}$$



$$\therefore \text{therefore: } \dot{\varepsilon}_{ij}^{pl} = \frac{1}{2\mu} S_{ij}$$

lecture 14. 5/15/2024.

Plasticity

yield criterion

von Mises $J_2 - k^2 = 0$.

$$J_2 = \frac{1}{2} S_{ij} S_{ij} \quad k = \frac{\sigma_y}{\sqrt{3}}$$

\Rightarrow flow rule $\rightarrow \dot{\varepsilon}_{ij}^{pl} = 0$

$$3K \bar{\varepsilon}^{el} = \bar{\varepsilon}$$

$$2\mu \dot{\varepsilon}_{ij}^{pl} = \tilde{\lambda} S_{ij} \quad (2\mu e_{ij}^{el} = S_{ij})$$

$$\tilde{\lambda} = \frac{2\mu}{2K^2} \dot{w}$$

$$\dot{w} = S_{ij} \dot{e}_{ij} = S_{ij} (\dot{e}_{ij}^{el} + \dot{\varepsilon}_{ij}^{pl})$$

total strain rate (deviatoric)

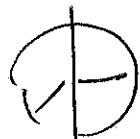
(because in the experiment we can impose the loading)

$$2\mu \dot{w} = S_{ij} (2\mu \dot{e}_{ij}^{el} + 2\mu \dot{\varepsilon}_{ij}^{pl})$$

$$= S_{ij} (\dot{S}_{ij} + \tilde{\lambda} S_{ij}) \quad \dots \text{(TBC)}$$

EPP: elastic perfectly-plastic if J_2 remains const.

for app.



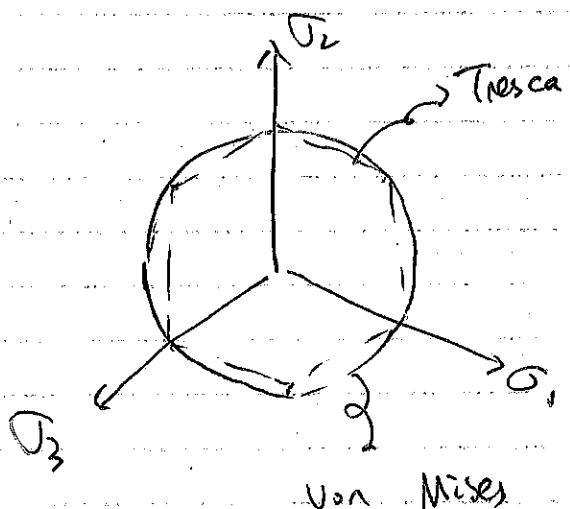
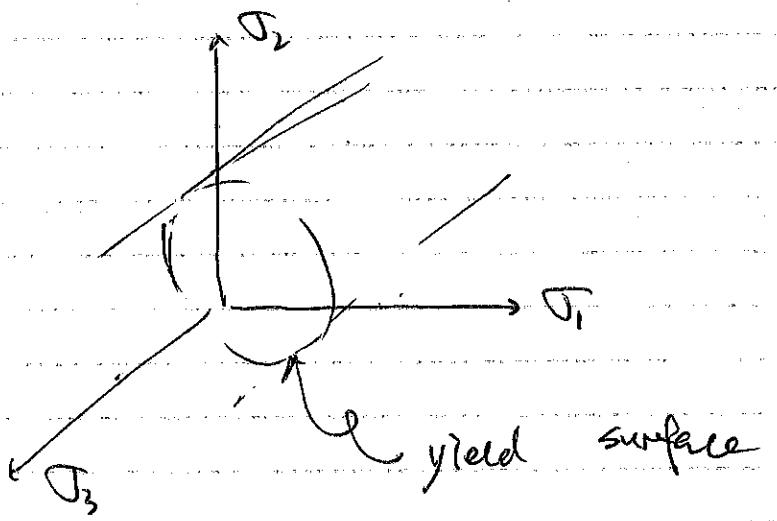
$i \perp \Sigma$

$$\dot{J}_2 = S_{ij} \dot{S}_{ij} = 0$$

$$\dots \tilde{\sigma} S_{ij} S_{ij} = \tilde{\sigma}^2 k^2$$

$$W^{\text{tot}} = \bar{\sigma} \dot{\varepsilon} + W$$

if the material is isotropic we can visualize it based on the principle stresses

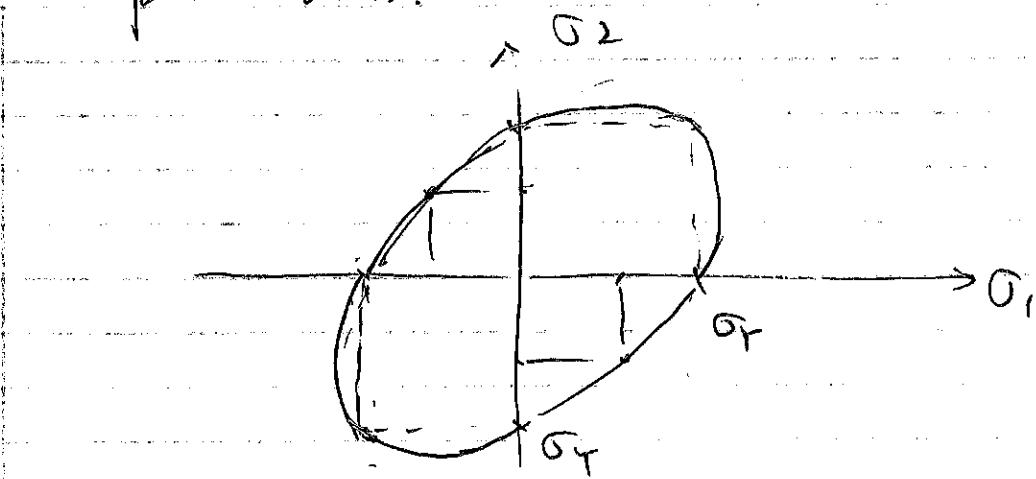


$$\sigma_2 = \frac{1}{2} (\sigma_1^2 + \sigma_2^2 + \sigma_3^2)$$

$$= \frac{1}{2} [(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]$$

in term of
principle stresses

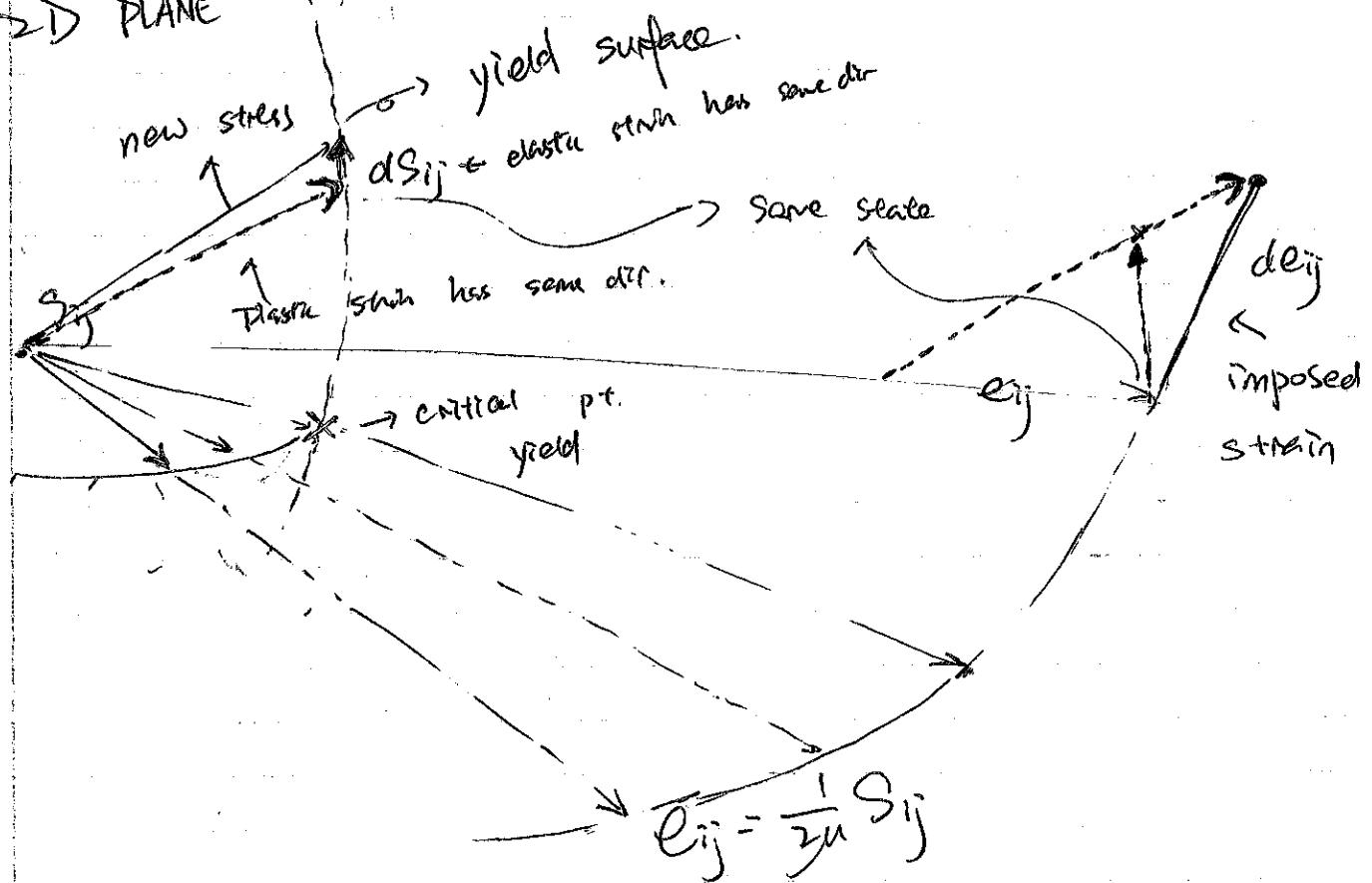
In Plane Stress.



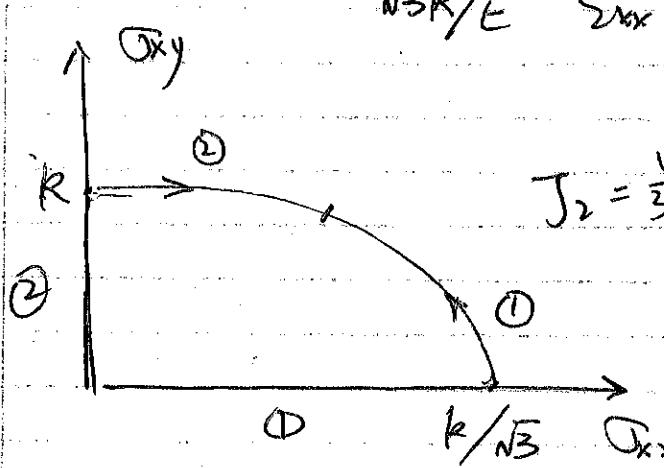
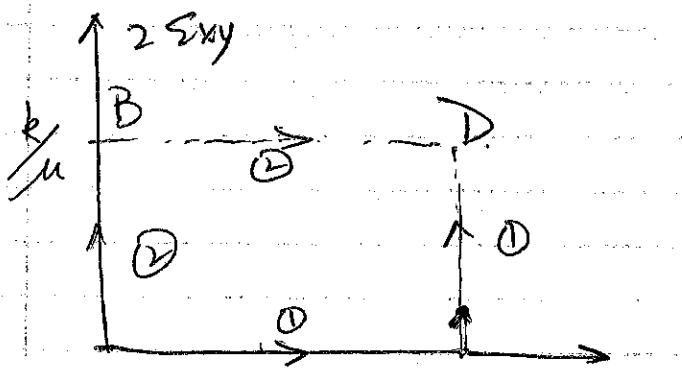
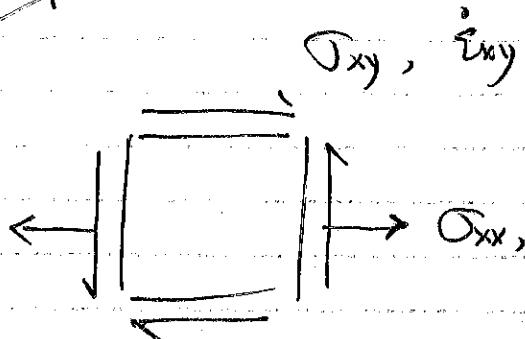
i.e.: cutting a cylinder thru a perpendicular plane

Flow Rule

2D PLANE



Example



$$J_2 = \frac{1}{3} \sigma_{xx}^2 + \sigma_{xy}^2 = k^2$$

$$\dot{\epsilon}_{xy} = \dot{\epsilon}_{xy}^e + \dot{\epsilon}_{xy}^p$$

$$= \frac{\sigma_{xy}}{2\mu} + \frac{w}{2k^2} \sigma_{xy}$$

$$= \frac{\sigma_{xy}}{2\mu} - \frac{\sigma_{xy} 2 \dot{\epsilon}_{xy}}{2k^2}$$

Incompressible $\left\{ \begin{array}{l} V=0.5 \\ E=3/\mu \end{array} \right.$

$$\dot{\epsilon}_{ij}^p = \frac{w}{2k^2} S_{ij}$$

$$w = S_{ij} \dot{\epsilon}_{ij}$$

$$= \sigma_{ij} \dot{\epsilon}_{ij} = \sigma_{xy} 2 \dot{\epsilon}_{xy}$$

$$\rightarrow \dot{\epsilon}_{xy} = \frac{\dot{\sigma}_{xy}}{2\mu} + \frac{\dot{\epsilon}_{xy}}{k^2} \cdot \sigma_{xy}^2$$

Final expression.

$$\left(1 - \frac{\sigma_{xy}^2}{k^2}\right) \dot{\epsilon}_{xy} = \frac{\dot{\sigma}_{xy}}{2\mu}$$

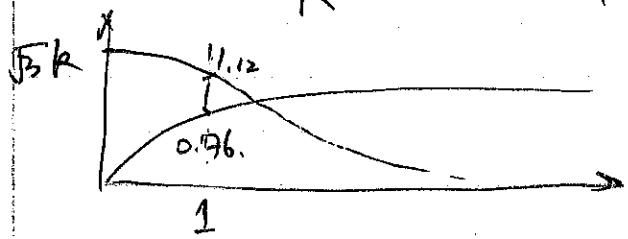
$$\frac{2\mu \dot{\epsilon}_{xy}}{k} = \frac{\dot{\sigma}_{xy}/k}{1 - \frac{\sigma_{xy}^2}{k^2}}$$

$$2\mu \frac{\dot{\epsilon}_{xy}}{k} = \frac{\dot{\sigma}_{xy}/k}{1 - \left(\frac{\sigma_{xy}}{k}\right)^2}$$

$\int dt$ on both sides.

$$2\mu \frac{\epsilon_{xy}(t)}{k} = \text{erf}^{-1} \left[\frac{\sigma_{xy}(t)}{k} \right]$$

$$\frac{\sigma_{xy}(t)}{k} = \tanh \left(2\mu \cdot \frac{\epsilon_{xy}(t)}{k} \right)$$



$$2\mu \frac{\epsilon_{xy}}{k}$$

$$\tanh = \frac{\sinh}{\cosh} = \frac{\frac{e^x - e^{-x}}{2}}{\frac{e^x + e^{-x}}{2}}$$

Problem Session #7

5/17/2014

Problem: first apply shear up to yield point

$$\sigma_{xy} = \sigma_y$$

then apply tension to some strain ϵ_{xx} .

Assumptions: No strain hardening.

$$v=0.5 \text{ (incompress)}$$

Von Mises criteria: $J_2 = k^2$

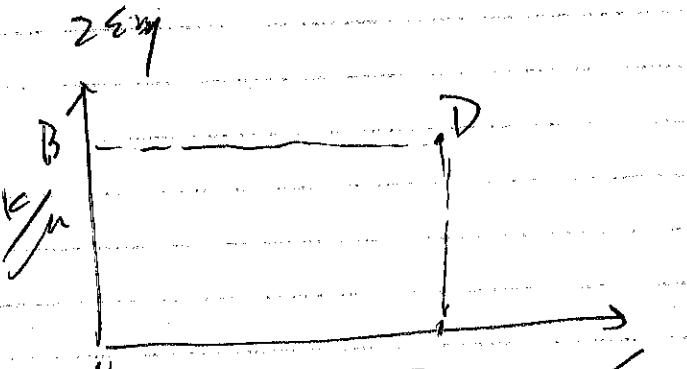
$$\text{VM criteria: } J_2 = k^2 = \frac{\sigma_y^2}{3}$$

$$J_2 = \frac{1}{2} \sum_{ij} S_{ij} S_{ij} \quad \text{EPP: } J_2 = 0 \rightarrow S_{ij} S_{ij} = 0$$

$$\text{Plastic strain rate: } \dot{\epsilon}_{ij}^P = \frac{\dot{\gamma}}{2\mu} S_{ij} = \frac{\dot{\gamma}}{2\mu} \cdot S_{ij}$$

Shear criterion Plasticity

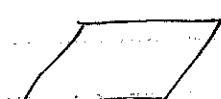
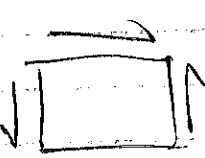
$$J_2 = \frac{\sigma_{xx}^2}{3} + \frac{\sigma_{yy}^2}{3} = k^2$$



$$\epsilon_{xy} = \epsilon_{xy}^{el} + \epsilon_{xy}^{pl}$$

$$\frac{\sigma_y}{E} > \frac{\tau_x}{E} \quad \epsilon_{xy}$$

$$v=0.5 \rightarrow E=2(1+v)\mu$$



① Along path OB. \rightarrow pure plastic strain.

$$\sigma_{xy} = 2\mu \epsilon_{xy} \quad (\text{goes from } o \rightarrow R).$$

$$\sigma_{xx} = \sigma_{yy} = \sigma_{zz} = \sigma_{xz} = \sigma_{yz} = 0$$

$$\epsilon_{xx} = \epsilon_{yy} = \epsilon_{zz} = \epsilon_{xy} = \epsilon_{yz} = 0$$

② Along path BD

$$J_2 = \frac{\sigma_{xx}}{3} + \sigma_{xy}^2 = k^2$$

$$\dot{\epsilon}_{ij}^{pl} = \frac{w}{2k^2} S_{ij}$$

$$W = S_{xx} \dot{\epsilon}_{xx} = S_{xx} \dot{\epsilon}_{xx} \rightarrow \dot{\epsilon}_{xy} = \text{const.}, \dot{\epsilon}_{yy} = 0$$

shape change

role of work

$$W = S_{xx} \dot{\epsilon}_{xx} = \frac{2}{3} \sigma_{xx} \dot{\epsilon}_{xx}$$

$$\rightarrow \dot{\epsilon}_{xx}^{pl} = \frac{W}{2k^2} \cdot S_{xx} = \frac{W}{3k^2} \sigma_{xx}$$

$$\dot{\epsilon}_{xx} = \dot{\epsilon}_{xx}^{el} + \dot{\epsilon}_{xx}^{pl}$$

$$\dot{\epsilon} + \dot{\epsilon}_{xx}^{el}$$

$$\left(\frac{\dot{\sigma}_{xx}}{E} \right)$$

$$\dot{\epsilon} = \frac{\dot{\sigma}_{xx}}{E} + \frac{w}{3k^2} J_{xx}$$

$$= \frac{\dot{\sigma}_{xx}}{E} + \frac{\dot{\epsilon}_{xx}}{3k^2} (\sigma_{xx})^2$$

$$\dot{\epsilon}_{xx} \left(1 - \frac{\sigma_{xx}}{3k^2} \right) = \frac{\dot{\sigma}_{xx}}{E}$$

$$\frac{E \dot{\epsilon}_{xx}}{J_3 k} = \frac{\dot{\sigma}_{xx}}{1 - \left(\frac{\sigma_{xx}}{J_3 k} \right)^2} \quad \text{some algebra}$$

$$\operatorname{atan}'(x) = \frac{1}{1-x^2}$$

Integrate both sides:

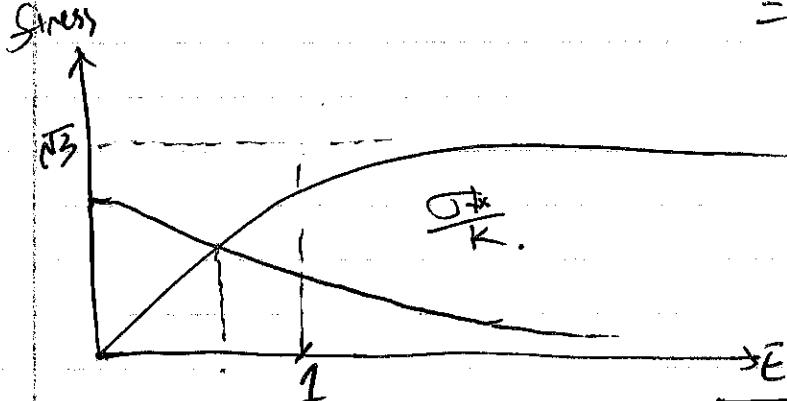
$$\frac{E \dot{\epsilon}_{xx}(t)}{\sqrt{2} k} = \operatorname{arctanh} \left(\frac{\sigma_{xx}(t)}{J_3 k} \right)$$

$$\frac{\sigma_{xx}(t)}{\sqrt{2} k} = \tanh \left(\frac{E \dot{\epsilon}_{xx}(t)}{J_3 k} \right)$$

Using $J_2 = k^2$

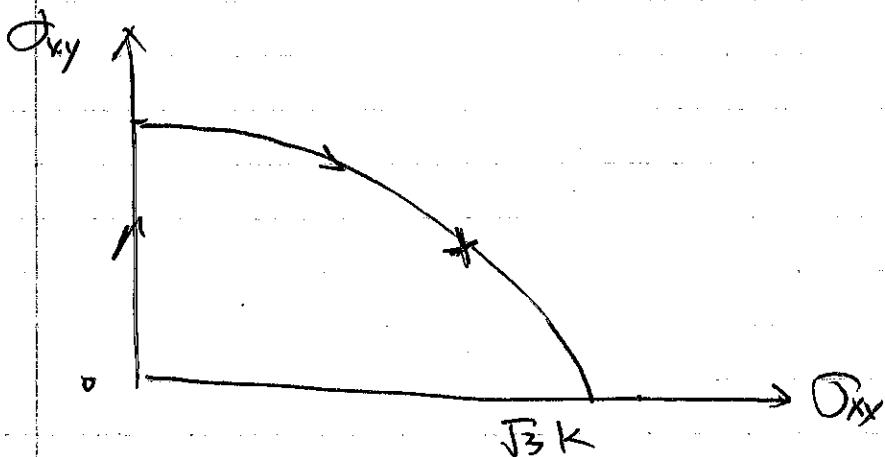
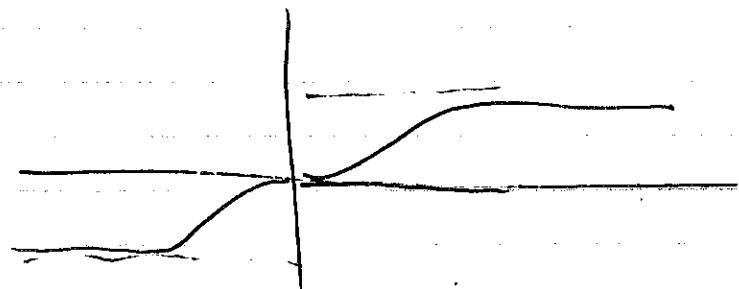
$$\frac{\sigma_{xx}^2}{3} + \sigma_{xy}^2 = k^2 \Rightarrow \frac{\sigma_{xy}}{k} = \sqrt{1 - \left(\frac{\sigma_{xx}}{\sqrt{3}k}\right)^2}$$

$$4 \tanh h^2$$



$$= \frac{1}{\cosh\left(\frac{E\sigma_{xx}(t)}{\sqrt{3}k}\right)}$$

$$\frac{E\sigma_{xx}(t)}{\sqrt{3}k} \rightarrow \frac{E\sigma_y}{E\sqrt{3}k}$$

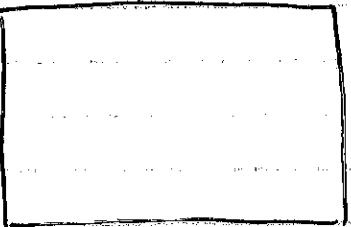


If $\nu < 0.5$ (not incompressible).

↓
no analytical soln

↓
numerical methods.

$$\sigma_{yy} = 0$$



$$\rightarrow \sigma_{xx}, \epsilon_{xx}$$

Plane strain prob.

$$J_2 = k^2 = \frac{\sigma_y^2}{3}$$

$$\sigma_{zz} = \nu \sigma_{xx}$$

$$= \frac{1}{3} (S_{xx}^2 + S_{yy}^2 + S_{zz}^2)$$

$$\sigma_{xx} = \frac{\sigma_y}{\sqrt{1 - \nu^2}} \rightarrow \sigma_y$$

Finite time steps.

$$\sigma_{xx}(t), \sigma_{zz}(t), \epsilon_{xx}(t), S_{zz}(t)$$

$$\epsilon_{xx}(t+\Delta t), \epsilon_{zz}(t+\Delta t)$$

Unknowns: $\sigma_{xx}(t+\Delta t), \sigma_{zz}(t+\Delta t)$
 $(\sigma_y / \rho A)$

$$\Delta \bar{\sigma} = \bar{\sigma}(t + \Delta t) - \bar{\sigma}(t)$$

$$\Delta S_{xx} = S_{xx}(t + \Delta t) - S_{xx}(t).$$

$$\Delta S_{yy} = S_{yy}(t + \Delta t) - S_{yy}(t).$$

Total strains. elastic

$$\Delta \varepsilon_{xx}^{el} = \Delta \bar{\sigma} + \Delta \varepsilon_{xx}^{pl}$$

$$= \frac{\Delta \bar{\sigma}}{3K} + \frac{\Delta S_{xx}}{2\mu}$$

$$\Delta \varepsilon_{yy}^{el} = \dots$$

Plastic strain

$$\Delta \varepsilon_{xx}^{pl(t)} = \frac{\gamma \Delta e}{2\mu} \cdot \left(\frac{S_{xx}(t) + S_{xx}(t + \Delta t)}{2} \right)$$

$$\dot{\varepsilon}_{xx}^{pl} = \frac{\gamma}{2\mu} S_{xx}$$

↓

$$\frac{\Delta \varepsilon_{xx}^{pl}}{\Delta e} -$$

$$\Delta \varepsilon_{yy}^{pl} = \dots$$

Final eqns.

$$\varepsilon_{xx}(t) + \Delta \varepsilon_{xx}^{el} + \Delta \varepsilon_{xx}^{pl} - \varepsilon_{xx}(t + \Delta e) = 0$$

$$\varepsilon_{yy}(t) + \Delta \varepsilon_{yy}^{el} + \Delta \varepsilon_{yy}^{pl} - \varepsilon_{yy}(t + \Delta e) = 0$$

$$\rightarrow \frac{1}{2} [S_{xx}(\epsilon + \Delta\epsilon)^2 + S_{yy}(\epsilon + \Delta\epsilon)^2 + S_{xy}(\epsilon + \Delta\epsilon)^2] = k^2$$

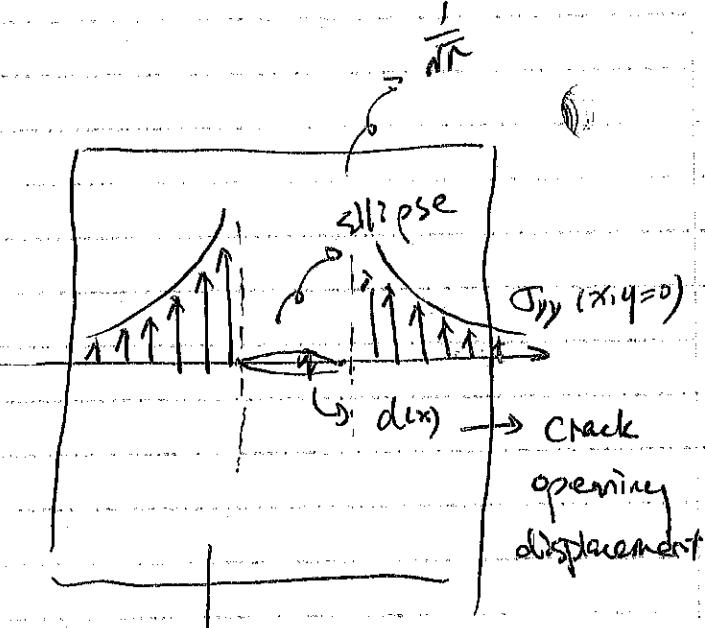
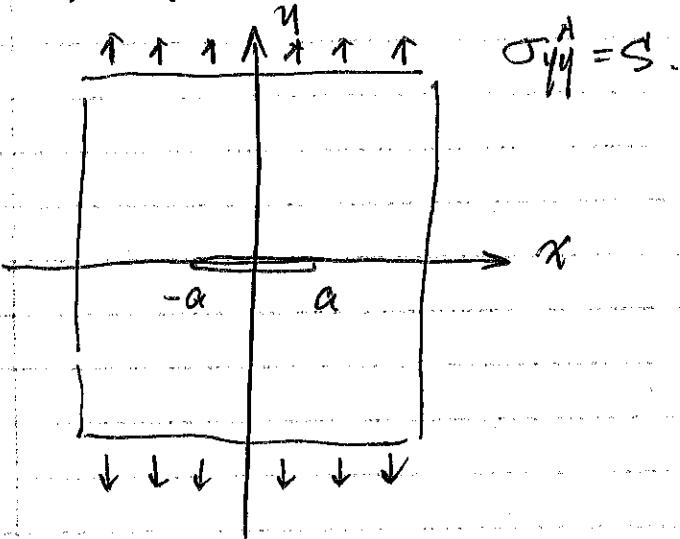
$$J_2 = k^2$$

5/20/24 Lecture 15

LEFM \rightarrow EPFM

"recall previous lecture".

Slit-like crack



undeformed config.

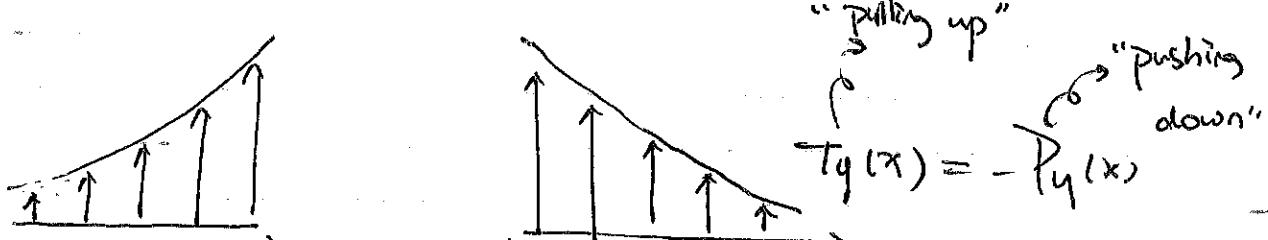
Defn: stress intensity factor:

$$\sqrt{\frac{K_I}{2\pi r}} \rightarrow r = x - a$$

We want to know K_I

\rightarrow smooth

View the crack problem as the half-space



surface displacement.

half-space

$$\tilde{U}_y(x) = \int_{-\infty}^{+\infty} T_y(x') \left(-\frac{k+1}{4\pi\mu} \right) \log|x-x'| dx'$$

from surface Green's function.

Invert it to solve for T_y

$$T_y(x) = \left[\int \frac{u'_y(x')}{\dots} \right] + \frac{Ax+B}{(\pi+a)^{1/2} (\pi-a)^{1/2}} \xrightarrow{\text{even func. of } x} = 0$$

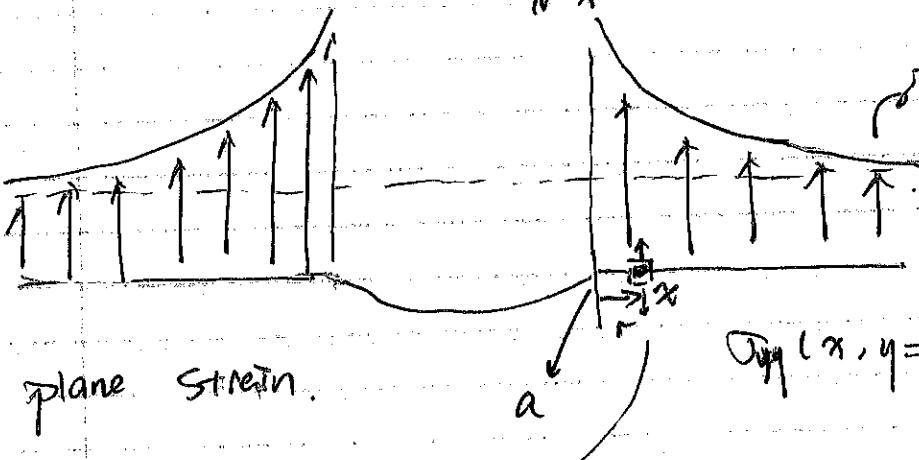
$$T_y(x) = \frac{Ax+B}{(\pi+a)^{1/2} (\pi-a)^{1/2}} = \frac{A + B/x}{\sqrt{1 - (a/x)^2}}$$

$$T_y(x) = \frac{A}{\sqrt{1 - (a/x)^2}} = \frac{S}{\sqrt{1 - (a/x)^2}}$$

"elegant sol'n"

$$\sigma_{yy}(x, y=0) = \frac{S \cdot |x|}{\sqrt{x^2 - a^2}}$$

to make sure the loading is still an even function



"converging to S when $x \rightarrow \infty$ ".

$$\sigma_{yy}(x, y=0) = T_y(x).$$

plane strain.

look at point "x"
Analogous to the flat punch

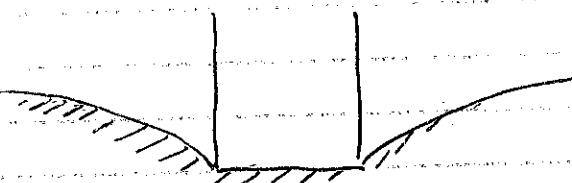
$$x = a + r$$

$$\sigma_{yy}(x, y=0)$$

$$= \sigma_{\theta\theta}(\tau, \theta=0)$$

$$= \frac{S(a+r)}{\sqrt{(a+r)^2 - a^2}} \quad \left| \begin{array}{l} y \lim \\ r \rightarrow 0 \end{array} \right.$$

$$= \frac{Sa}{\sqrt{2ar}}$$



~ Stress Intensity factor

$$= S \sqrt{\frac{a}{2}} \cdot \frac{1}{\sqrt{r}} = \frac{K_I}{\sqrt{2ar}}$$

for Mode-I

fracture

unit: $[Pa \cdot m^{1/2}]$

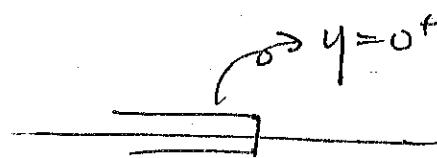
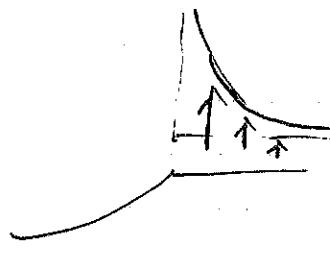
$$\therefore K_I = S \sqrt{a\tau} \quad \left| \begin{array}{l} \text{IMPORTANT} \end{array} \right.$$

Q: why $[Pa \cdot \sqrt{m}]$

... K divide by \sqrt{F} to get stress.

$$\tilde{u}_y(x) = -\frac{K+1}{4\mu} Sa \sqrt{1 - \left(\frac{x}{a}\right)^2}$$

$$|x| < a, y = 0^-$$

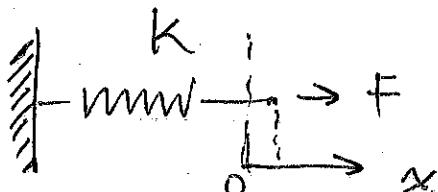


$$d(x) = -2 \tilde{u}_y(x)$$

$$\boxed{= \frac{2(1-\nu)}{\mu} Sa \sqrt{1 - \left(\frac{x}{a}\right)^2}} \quad \text{# IMPORTANT RESULT}$$

Enthalpy

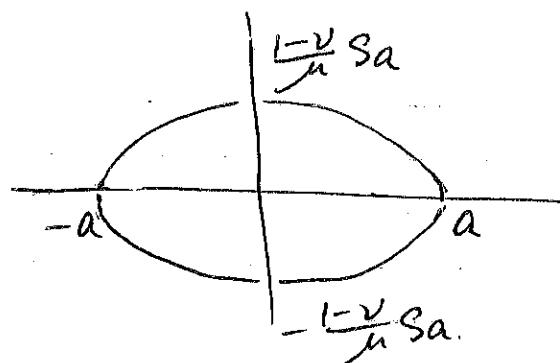
Example



$$\text{enthalpy: } H = E - \Delta W_{lm}.$$

$$F = Kx$$

$$E = \frac{1}{2} Kx^2$$



$$\downarrow \\ \Delta W_{lm} = Fx$$

Principle: under load mechanism, system goes

to the state where H is minimized

)

"when equilibrium is reached"

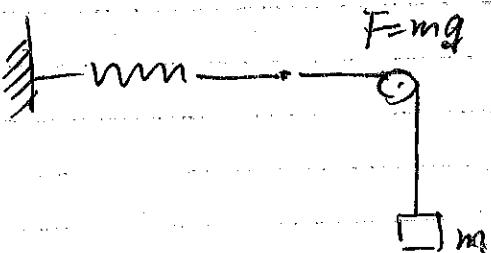
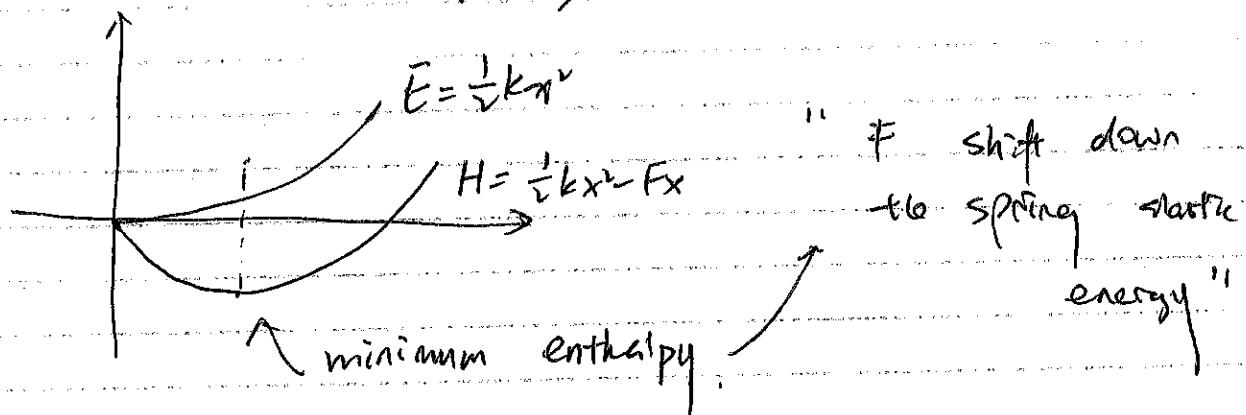
)

H is minimized.

formulate optimization problem

$$\min_x \left(\frac{1}{2} kx^2 - Fx \right).$$

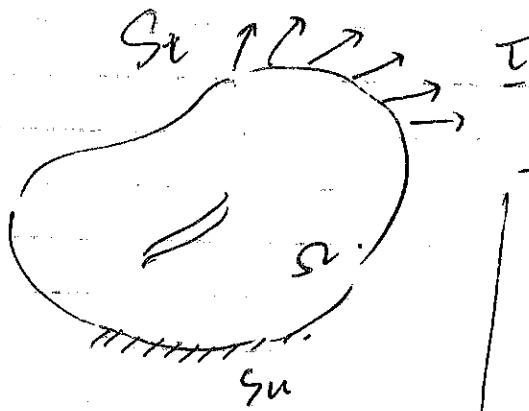
$$x = F/k.$$



$$E^{\text{tot}} = \frac{1}{2} kx - mgx$$

Goal: minimize $H = E - \Delta W_{\text{in}}$

Via some traction B.C.s



$$H = E - \Delta W_{\text{int}}$$

$$= \int_S \frac{1}{2} \sigma_{ij} \epsilon_{ij} dA.$$

$$- \int_{S_t} T_j u_j dS.$$

hypothesis: the system
is minimizing H .

Q: what is the enthalpy of the crack?

→ we may derive the enthalpy of the whole system.

... "enthalpy of crack".

System w/o crack	System w/ crack
$E_0 = \frac{1}{2} \sigma_{ij}^A \epsilon_{ij}^A A$	E_{2a} $\rightarrow \Delta E = (E_{2a} - E_0)$
H_0	H_{2a}

$$\Delta E = \frac{1-\nu}{2\mu} S^2 \pi a^2$$

Conclusion:

$$\Delta H = - \frac{1-\nu}{2\mu} S^2 \pi a^2$$

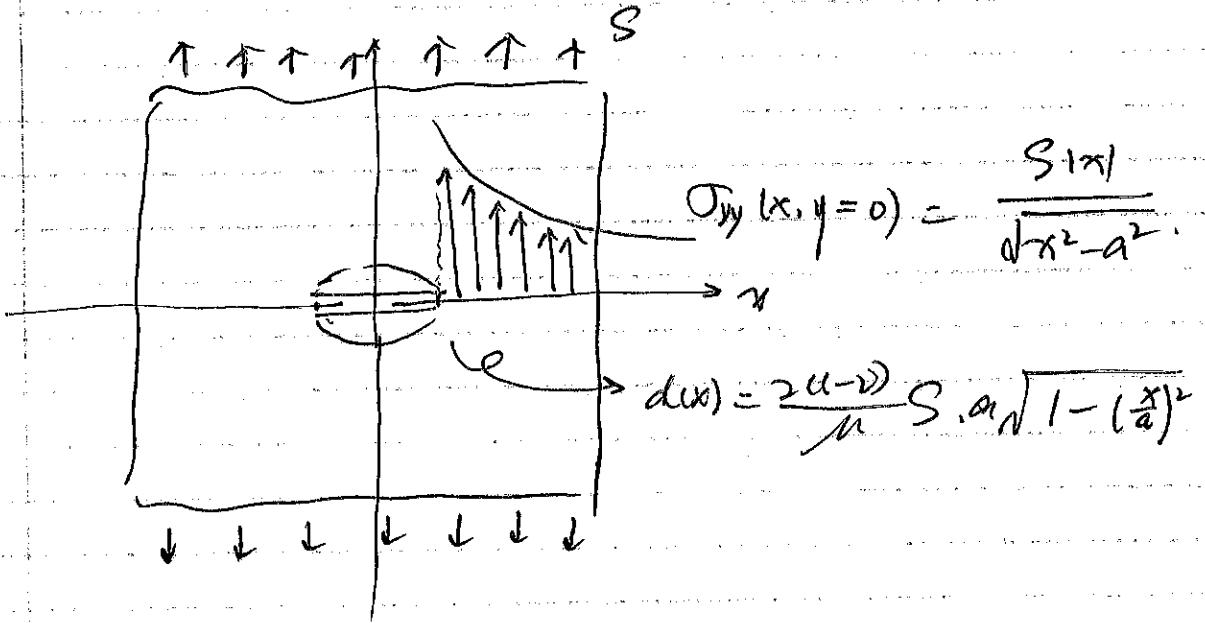
plane strain

$$\Delta H = H_{2a} - H_0$$

lecture 16.

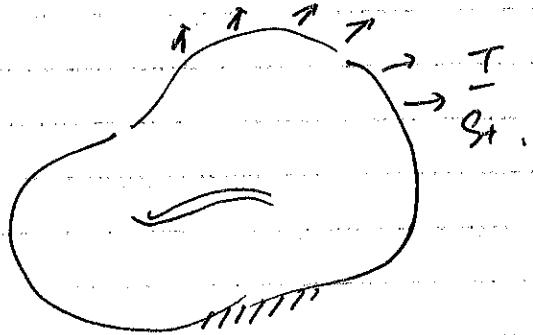
5/22/2024.

Stress-like crack



Q: What is the enthalpy of the crack?

$$H = E - \Delta W_m.$$



$$H = \int \frac{1}{2} \sigma_{ij} \epsilon_{ij} dV.$$

the system is trying to minimize $H = - \int_T T_i u_j dS$.

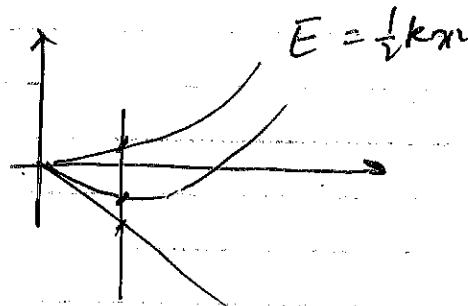
to minimize H .

... body with no pre-existing internal stress.

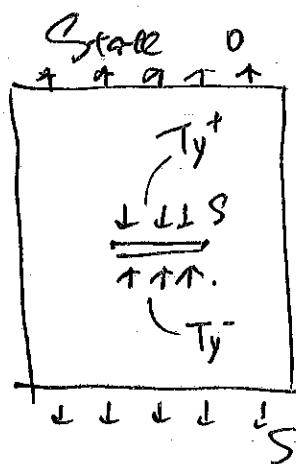
$$\text{then } H = -E$$

toy example

from \rightarrow



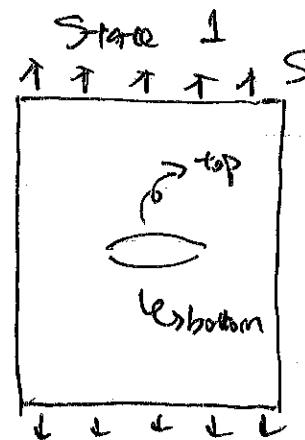
... thought experiment



$$E_0, H_0 = -E_0$$

$$\bar{t}_0 = \frac{1}{2} \sigma_{yy}^A \cdot \epsilon_{yy}^A \ddot{\ell}$$

$$H_0 = -\frac{1}{2} \sigma_{yy}^A \cdot \epsilon_{yy}^A \ddot{\ell}$$

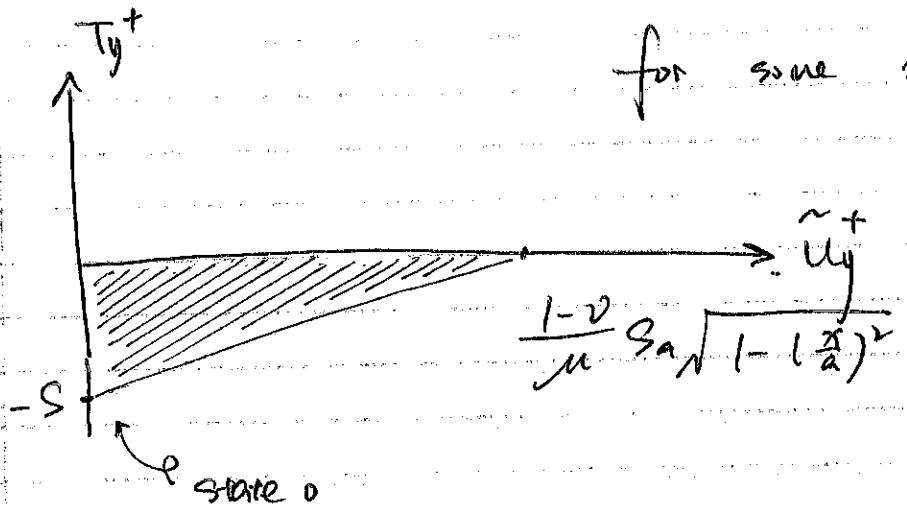


$$E_1, H_1 = -E_1$$

$$\Delta E = E_1 - E_0$$

$$\Delta H = H_1 - H_0 = -\Delta E$$

Calculate the work done along the path from the "closed crack" to the "opened crack".



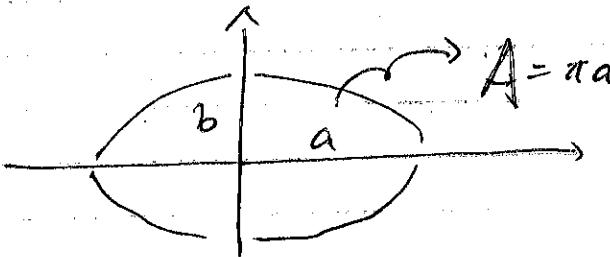
$$\Delta W^+ = \int_{-a}^a \frac{1}{2} S \frac{1-\nu}{\mu} S a \sqrt{1 - \left(\frac{x}{a}\right)^2} dx.$$

$$\Delta H = 2\Delta W^+ = \int_{-a}^a \frac{1-\nu}{\mu} S^2 a \sqrt{1 - \left(\frac{x}{a}\right)^2} dx.$$

$$\Delta H = -\frac{1-\nu}{2\mu} S^2 \pi a^2$$

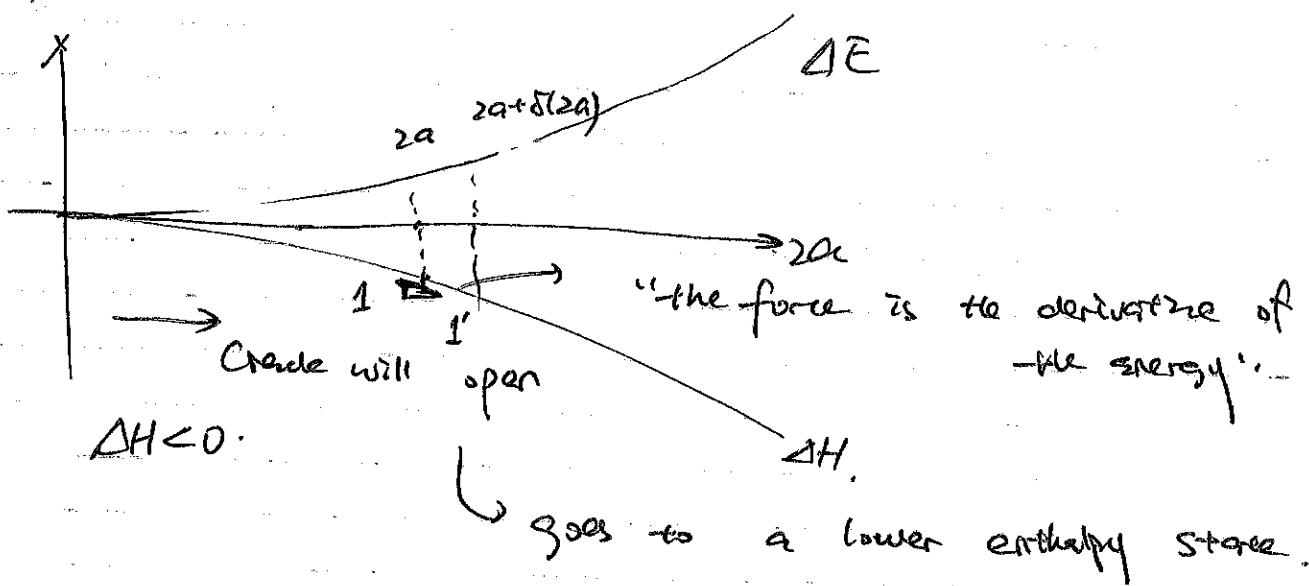
Physically: the enthalpy of crack is

$-\frac{1}{2} S$ multiplies the area of the crack opening.



$$\Delta H < 0$$

$$\Delta H = -\frac{1}{2} S A.$$



Driving force for crack extension,

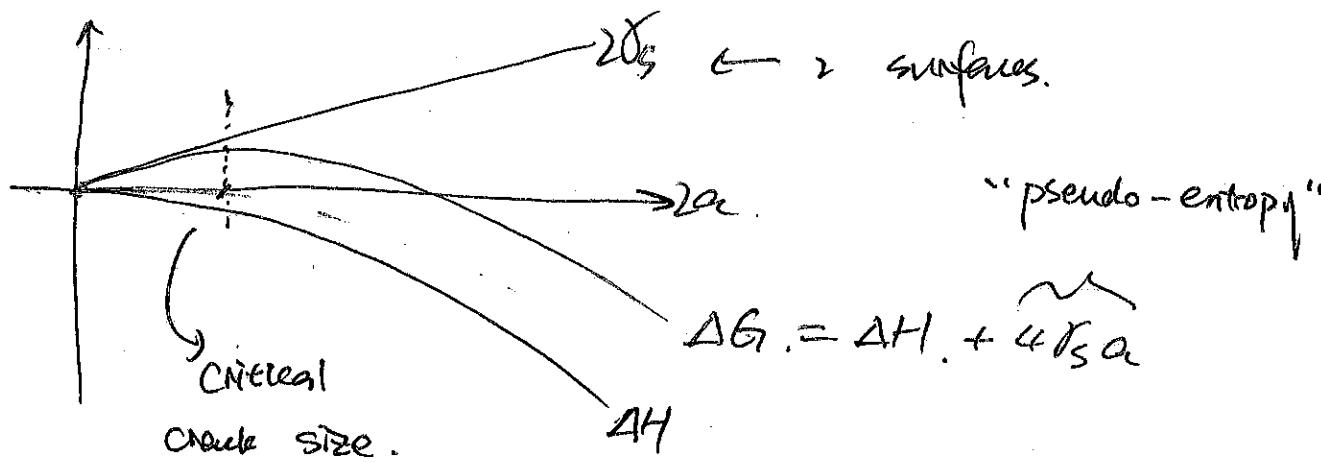
$$f_{el} = - \frac{\partial(\Delta H)}{\partial(2a)} = \frac{\pi(1-\nu)}{2\mu} S^2 a$$

$$K_I = S\sqrt{\pi a}, \quad f_{el} = \frac{1-\nu}{2\mu} K_I^2$$

brace

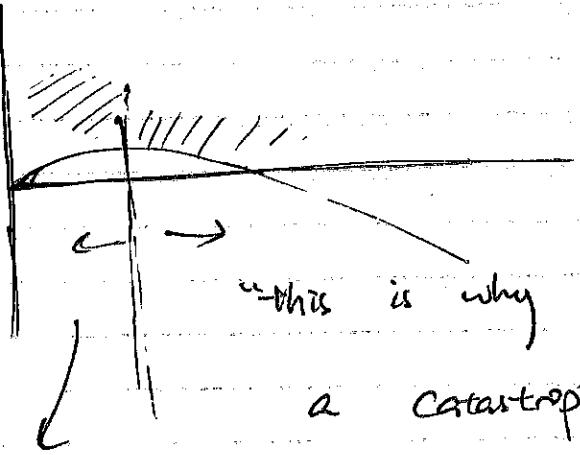
Explicit relationship.

Ell-Greenly Criteria. (1921).



$$2a_c = \frac{8\mu}{\pi(1-\nu)} \left| \frac{\sigma_s}{s^2} \right|$$

\hookrightarrow critical crack size for fracture.



"this is why crack is usually
a catastrophic process"

"stable crack size"

$$S_c = \sqrt{\frac{8\mu \sigma_s}{\pi(1-\nu)(2a)}}$$

\hookrightarrow plane strain

$$\frac{f_{cr}}{f_{ei}} = 2\sigma_s$$

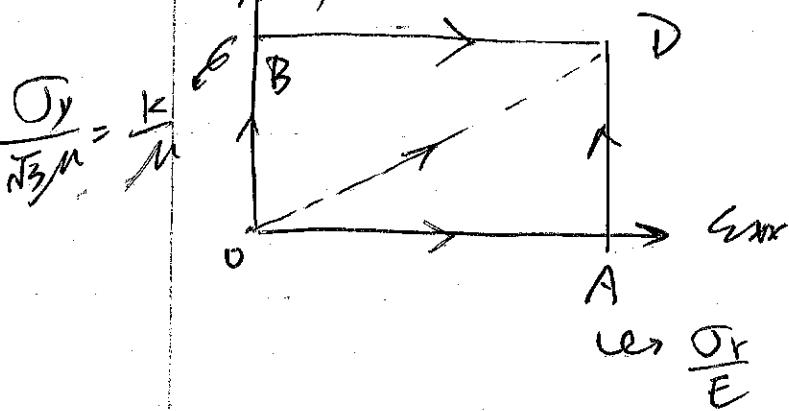
\hookrightarrow surface energy

Crack - driving force

Problem Session 8

Plasticity code for numerical soln

$$2\epsilon_{xy} \rightarrow \delta_{xy}$$



$$\sigma_{ij} = C_{ijkl} \cdot \epsilon_{kl}$$

Differential \rightarrow algebraic

Numerical methods

At any time t ... known: $\sigma_{xx}(t)$, $\sigma_{xy}(t)$

yield point

$\epsilon_{xx}(t)$, $\epsilon_{xy}(t)$.

$\sigma_{xx}(t+\Delta t)$,

$\epsilon_{xy}(t+\Delta t)$.

Up to yield \rightarrow Hooke's law is valid.

Unknowns: $\sigma_{xx}(t+\Delta t)$, $\sigma_{xy}(t+\Delta t)$.

$$\frac{x}{y\mu}$$

Equations:

① change in stress . finite time steps

$$\Delta \bar{\sigma} = \bar{\sigma}(t+\Delta t) - \bar{\sigma}(t)$$

$\Delta t \rightarrow \Delta \sigma_x, \Delta \sigma_y, \text{etc.}$

$$\bar{\sigma}(t+\Delta t) = \frac{\sigma_{xx}(t+\Delta t)}{3}$$

$$\sigma_{xx}(t+\Delta t) = \sigma_{xx}(t+\Delta t) - \bar{\sigma}(t+\Delta t)$$

$$\bar{\sigma}(t) = \frac{\sigma_{xx}(t)}{3}$$

$$S_{xy}(t + \Delta t) = S_{xy}(t) + \Delta S_{xy}$$

① → change in elastic strain.

$$\Delta \bar{\varepsilon}_{xx}^{el} = \Delta \bar{\varepsilon}^{el} + \Delta \varepsilon_{xx}^{el}$$

$$\Delta \varepsilon_{xx}^{el} = \frac{\Delta S_{xx}}{2\mu}$$

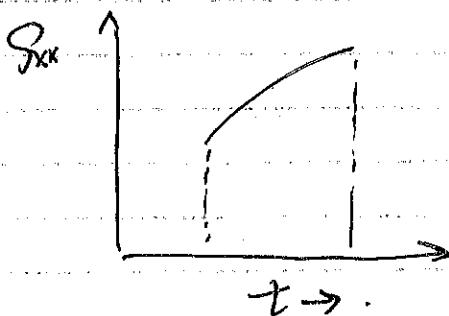
$$\Delta \bar{\varepsilon} = \frac{\Delta \sigma}{3K}$$

$$\Delta S_{xy}^{el} = \frac{\Delta S_{xy}}{2\mu}$$

② - change in plastic strain.

$$\dot{\varepsilon}_{xx}^{pl} = \frac{\dot{\sigma}}{2\mu} S_{xx} \rightarrow \text{analytical}$$

$$\frac{\Delta \dot{\varepsilon}_{xx}^{pl}}{\Delta t}$$



From $t \rightarrow t + \Delta t$:

$$\int_t^{t+\Delta t} \dot{\varepsilon}_{xx}^{pl} dt = \frac{\dot{\sigma}}{2\mu} \int_t^{t+\Delta t} S_{xx}(t) dt \sim \Delta \varepsilon_{xx}^{pl}$$

Assume $\dot{\sigma}$ is const.

from $t \rightarrow t + \Delta t$.

$$= \frac{\dot{\sigma}}{2\mu} \left(\frac{S_{xx}(t) + S_{xx}(t+\Delta t)}{2} \right)$$

Similarly for

$$\Delta \epsilon_{xy}^e = \frac{1}{2\mu} \left(\frac{\sigma_{xy}(t) + \sigma_{xy}(t+\Delta t)}{2} \right)$$

Find 3 eqns

$$1). \epsilon_{xx}(t) + \Delta \epsilon_{xx}^{el} + \Delta \epsilon_{xx}^{pl} = \epsilon_{xx}(t+\Delta t)$$

$$2). \epsilon_{xy}(t) + \Delta \epsilon_{xy}^{el} + \Delta \epsilon_{xy}^{pl} = \epsilon_{xy}(t+\Delta t)$$

$$3) J_2 = k^2$$

$$\frac{1}{2}(\sigma_{xx}^2 + \sigma_{yy}^2 + \sigma_{zz}^2) + \sigma_{xy}^2 = k^2$$

$$(or) \frac{\sigma_{xx}^2}{3} + \left(\frac{\sigma_{xy}^2}{3} \right) = k^2 \quad \text{and solve: } \frac{\tilde{\sigma}}{\mu}$$

$(t+\Delta t) \quad (t+\Delta t).$

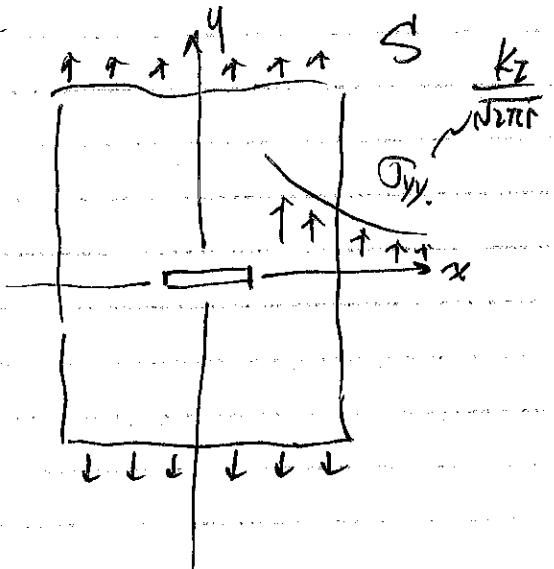
MATLAB
use `fsove (fun, Ftrial, param ...)`.

→ current stress store, σ
 σ_{xx}, σ_{yy}

5/29/2024.

Lecture 17.

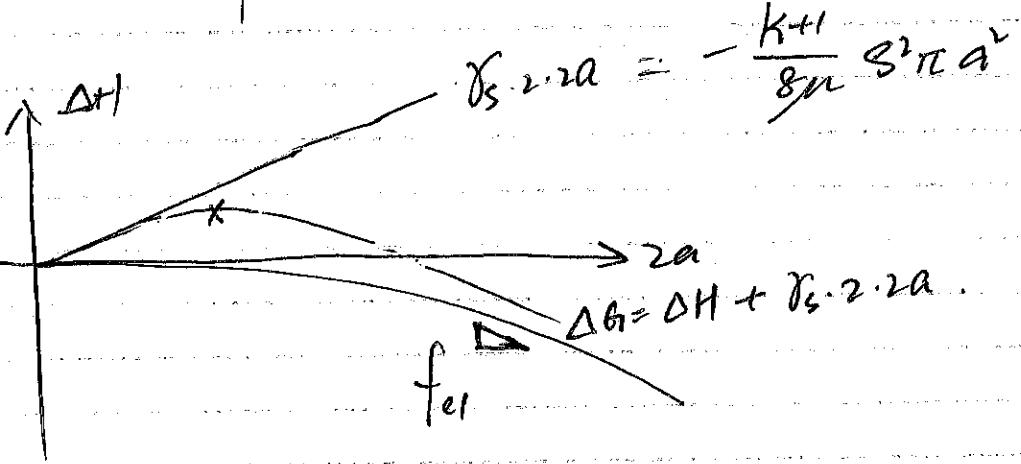
Recap



$$\Delta H = H_1 - H_0$$

$$= -\frac{1-v}{2\mu} S^2 \pi a^2$$

(plane strain)



$$f_{el} = -\frac{\partial \Delta H}{\partial (2a)} = \frac{\pi(1-v)}{2\mu} S^2 a \quad (\text{plane strain})$$

$$\Delta G_t = -\frac{1-v}{2\mu} S^2 a^2 + 4\gamma_S a$$

$$f_{tot} = \frac{\partial \Delta G_t}{\partial (2a)} = \frac{\pi(1-v)}{2\mu} S^2 a - 2\gamma_S$$

... Griffith criteria: $\frac{\pi(1-v)}{2\mu} S^2 a \geq 2\gamma_S \dots (*)$

energy release rate G

LHS of (*) \nearrow

i.e., $G = \frac{\pi(1-\nu)}{2\mu} (\sigma_{yy}^A)^2 a$... (**)

\downarrow

replace S

RHS: critical energy release rate

$$G_c = 2\delta_s \quad \dots (***)$$

Eqn. (**) can be rewritten as:

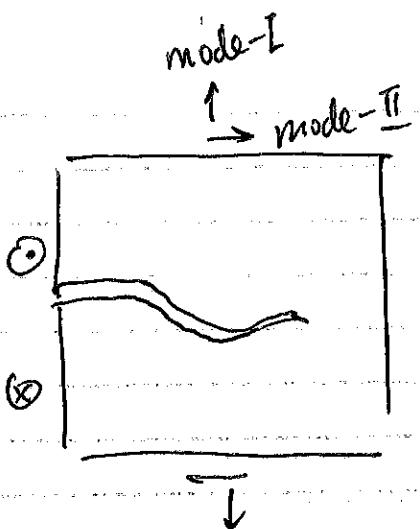
$$G = \frac{\pi(1-\nu)(1+\nu)}{E} (\sigma_{yy}^A)^2 a \quad (\text{plane strain})$$

define $E' = \frac{E}{1-\nu^2} \quad \hookrightarrow \frac{\pi}{E'}$

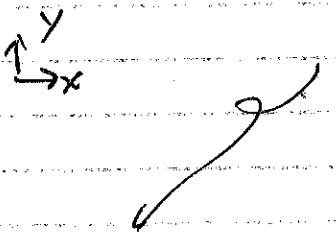
$K_I = \sigma_{yy}^A \sqrt{\pi a}$ stress intensity factor

$$G = \frac{K_I^2}{E'}$$

\hookrightarrow for mode-I loading



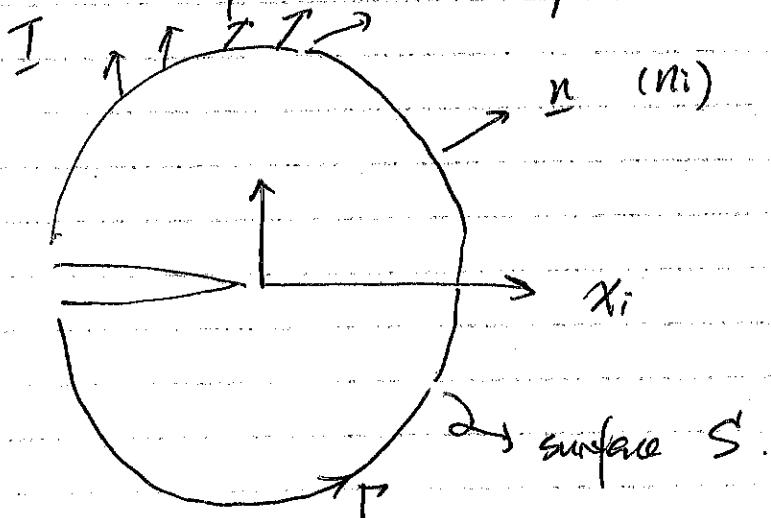
$$G = \frac{K_I^2}{E'} + \frac{K_{II}^2}{E'} + \frac{K_{III}^2}{2\mu}$$



fracture criteria: $G \geq G_c$.

J- Integral

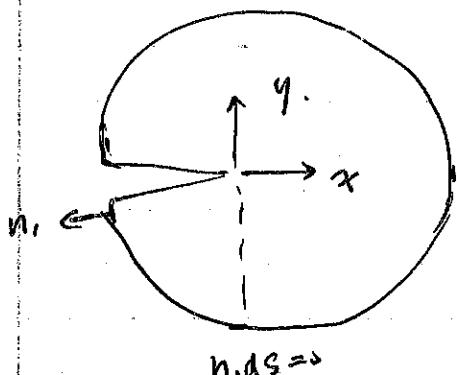
Q: what is the generalized force for any kinds of singularity?



$$J_i = \int_S (w n_i - T_j u_{j,i}) dS$$

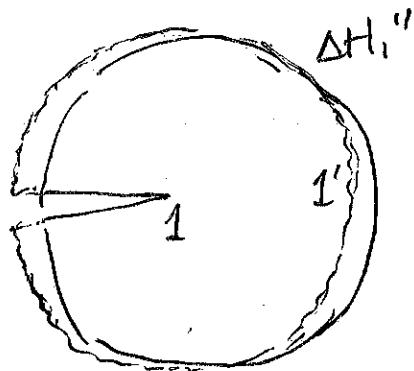
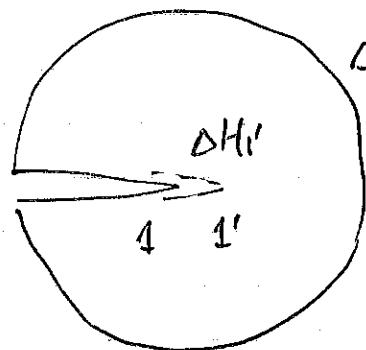
general force surface energy density $\frac{1}{2} \sigma_{ij} \epsilon_{ij}$

$$J_1 = \int_P w dy - T \frac{\partial u}{\partial x} dS$$

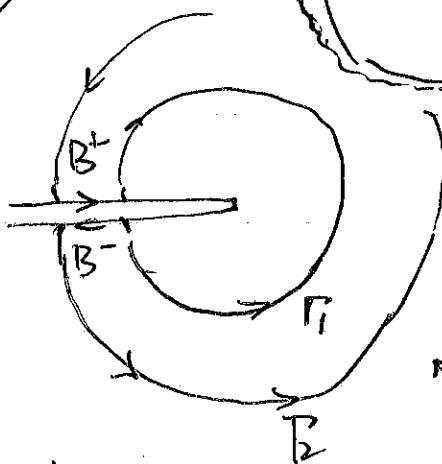


$$G = J$$

does not have to
be a perfect circle.



Example 1



contour integral along
the crack surface

to take any contour
you want.

(Very nice!!)

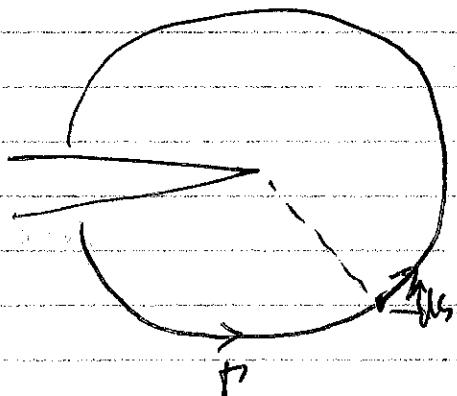
5/31/2014. Lecture 19.

Some review on fracture mechanics.

$$G \geq G_c$$

J-integral

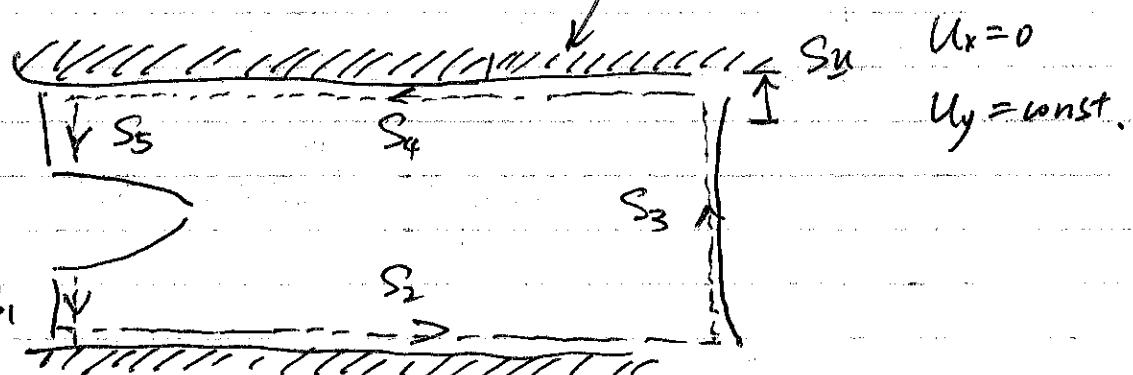
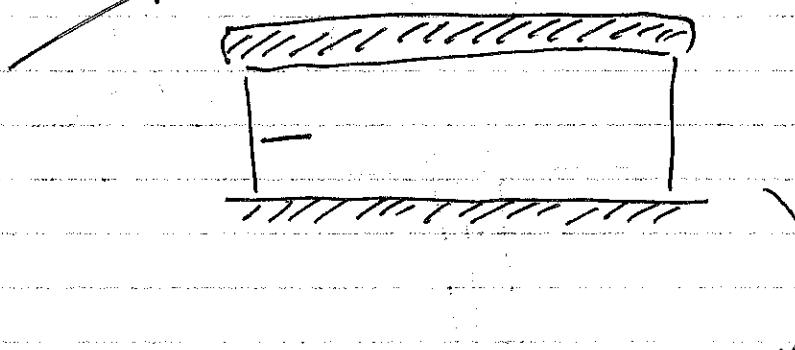
2D



$$J = \int w dy$$

$$= T \frac{\partial u}{\partial s} ds$$

Example 2



$$J(S_2) = \int w dy - T \frac{\partial u}{\partial x} ds = 0 \quad \text{almost zero}$$

$$J(S_4) = 0, \quad J(S_1) = \int w dy - T \frac{\partial u}{\partial x} ds, \quad J(S_3) = 0$$

the only J survived.

$$J(S_3) = \int w dy - I \cancel{\frac{\partial u}{\partial x} ds^0} = wh$$

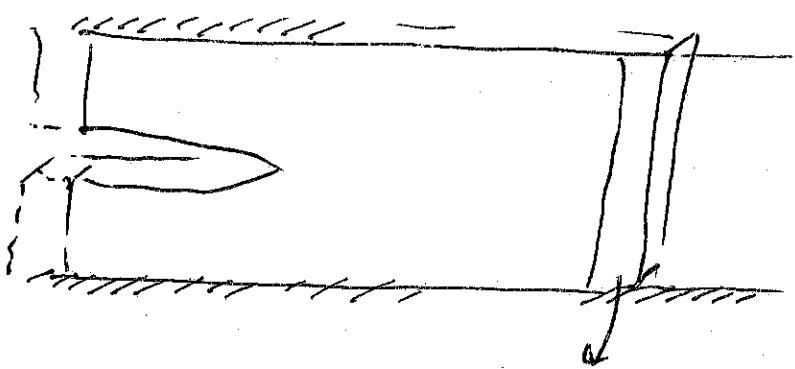
strain energy.

$$G = J = wh$$

$$G \geq G_c$$

Not the material properties

↑
we are just solving for the force
(LHS).

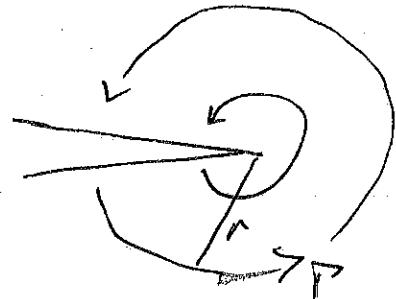


physics intuition behind $G = wh$.

if this 3D. if

should consider the
whole place

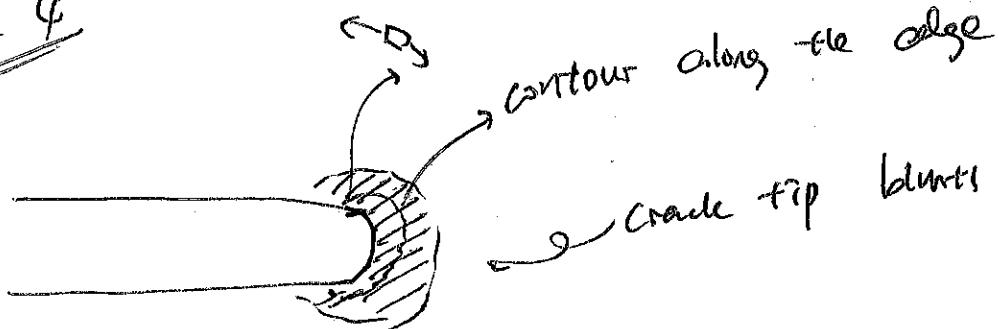
Example 3



$$\sigma_{rr} = \frac{k_i}{2\pi r} \left(\frac{5}{4} \cos \frac{\theta}{2} - \frac{1}{2} \cos \frac{3\theta}{2} \right)$$

$$J = \frac{k_i}{E} \quad \downarrow \quad (\text{shrink the contour})$$

Example 4



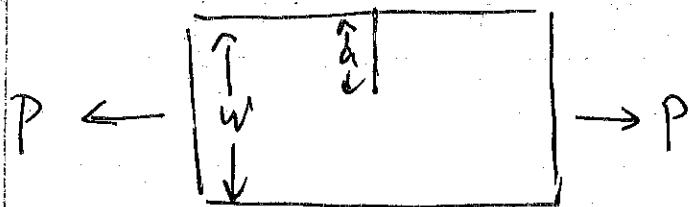
$$J = \int_P w dy - I \frac{\partial u}{\partial x} ds$$

$$= \int_P w dy \quad \left(w = \frac{\sigma^2}{2E} \right)$$

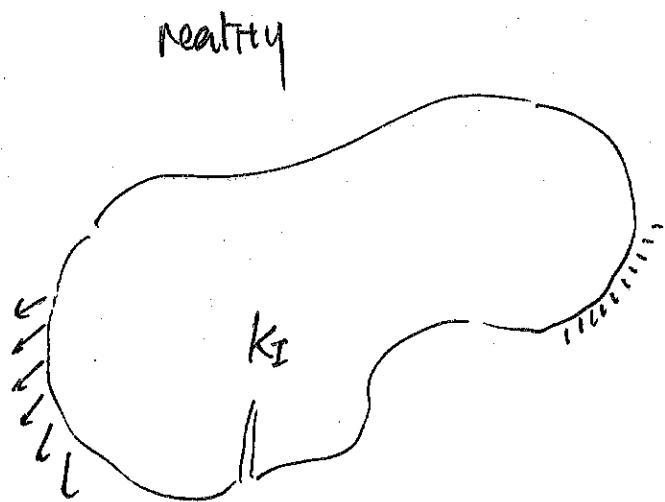
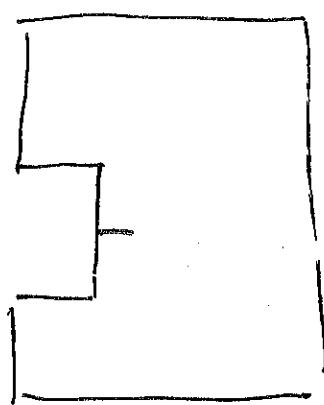
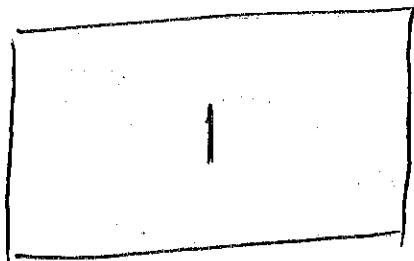
LEFM.

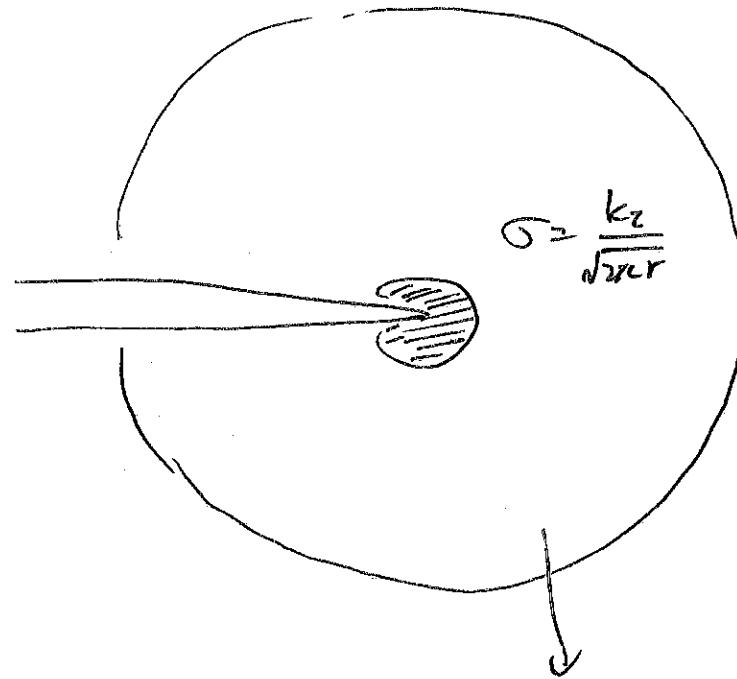
Recap. $G = \frac{k_I^2}{E'}$, $K_I = \sqrt{GE'}$, $K_{Ic} = \sqrt{G_c E'}$

$$\therefore K_I \geq K_{Ic}$$



$$K_I = \frac{P}{B\sqrt{w}}$$



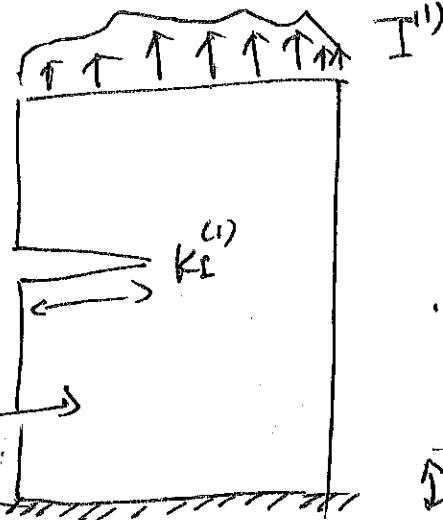


K -field
(zone)

Rice (1972).

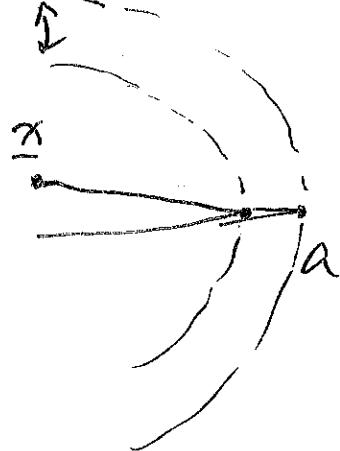
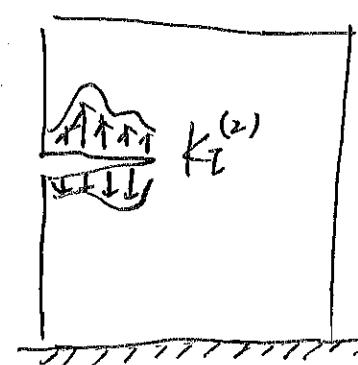
LEFM - K_I .

assume I have
the solution.

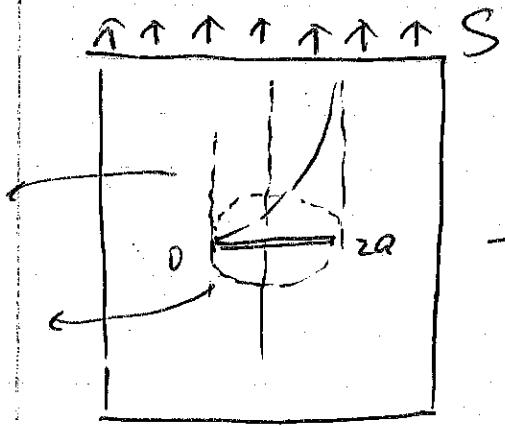


"coupling between
motion of crack
and loading"

$$K_I^{(2)} = \frac{E'}{2K_I^{(1)}} \int T_i^{(2)} \frac{\partial K_i^{(1)}}{\partial a} dP$$



loading (1)



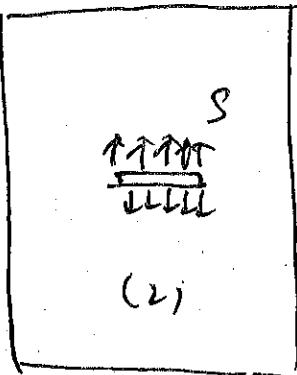
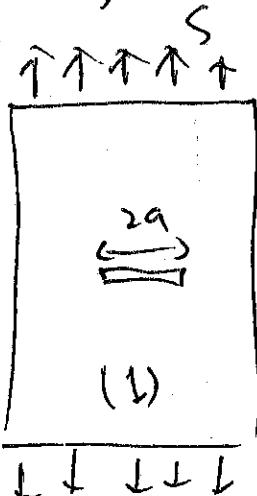
$$\frac{\partial u_i^{(1)}}{\partial a} = \sqrt{\frac{x}{2a-x}}.$$

$$K_I^{(1)} = \frac{E'}{2K_I^{(1)}} \int_S \sqrt{\frac{x}{2a-x}} dP$$

$$= S\sqrt{\pi a}$$

... results are the same.

loading (1)



$$k_I = S\sqrt{\pi a}$$

$$k_I = S\sqrt{\pi a}$$

lecture 19

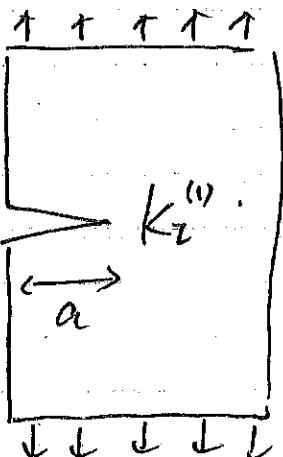
6/3/2024

EPFM.

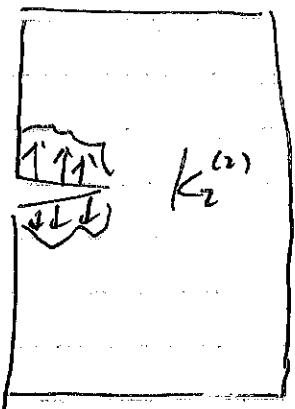
Recap

LEFM.

$$K_I \geq K_{IC}$$



$$T^{(1)}$$



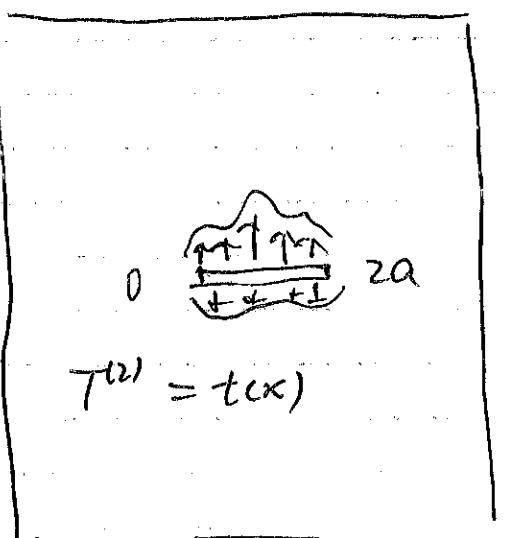
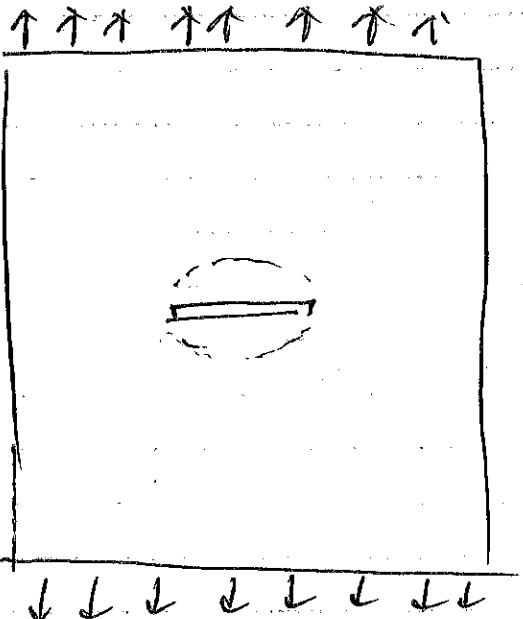
loading (1)

loading (2)

$$K_I^{(1)} = \frac{E'}{2K_I^{(1)}} \int_T^{(1)} \frac{\partial K_I^{(1)}}{\partial \alpha} dP$$

Slit-like crack

s



$$T^{(2)} = t cx$$

$$K_I^{(2)} = \frac{1}{\sqrt{\pi a}} \int_0^{2a} t(x) \sqrt{\frac{x}{2a-x}} dx$$

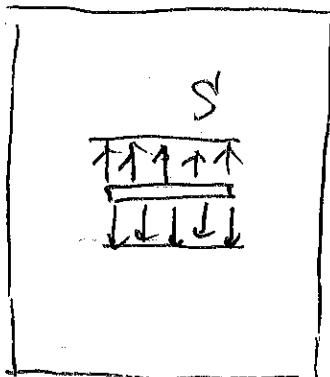
(for $x=2a$)

if we shift the coordinate:

$$K_I^{(2)} = \frac{1}{\sqrt{\pi a}} \int_{-a}^a t(x) \sqrt{\frac{a+x}{a-x}} dx \quad \text{es elasticity theory.}$$

Crack: $-a \leq x \leq a$ for $x=a$

Example 1



$$K_I^{(2)} = \frac{1}{\sqrt{\pi a}} \int_{-a}^a S \sqrt{\frac{a+x}{a-x}} dx$$

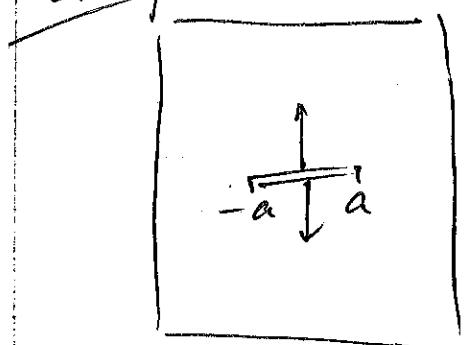
$$= \frac{1}{\sqrt{\pi a}} \cdot S \cdot \pi a$$

$$= S \sqrt{\pi a}$$

$$K_I^{(2)} = \frac{E'}{\sqrt{\pi a}} \int_{-a}^a F \delta(x) \int \frac{a+x}{a-x} dx$$

$$= \frac{E' f}{\sqrt{\pi a}}$$

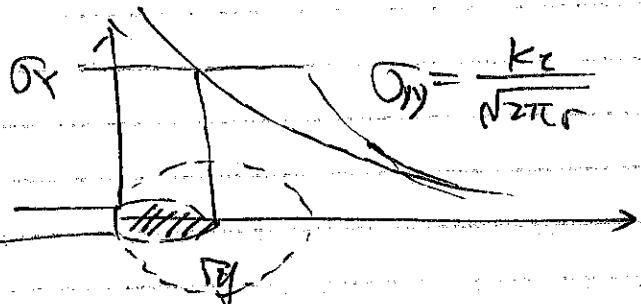
Example 2



EPFM

Irons' approach

w/o plasticity

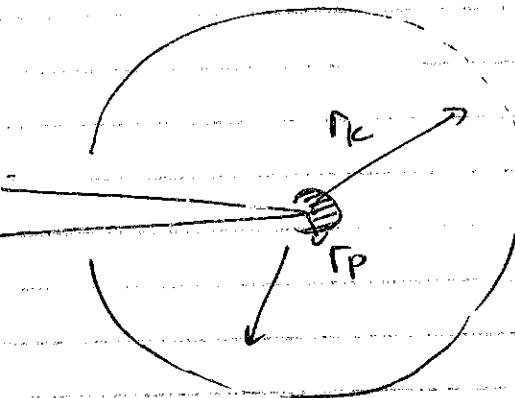


$$\sigma_y = \frac{k_z}{2\pi r_y}$$

$$r_y = \frac{1}{2\pi} \left(\frac{k_z}{\sigma_y} \right)^2$$

Irons did some "debug"

$$r_p = 2r_y = \frac{1}{\pi} \left(\frac{k_z}{\sigma_y} \right)^2$$



K-field

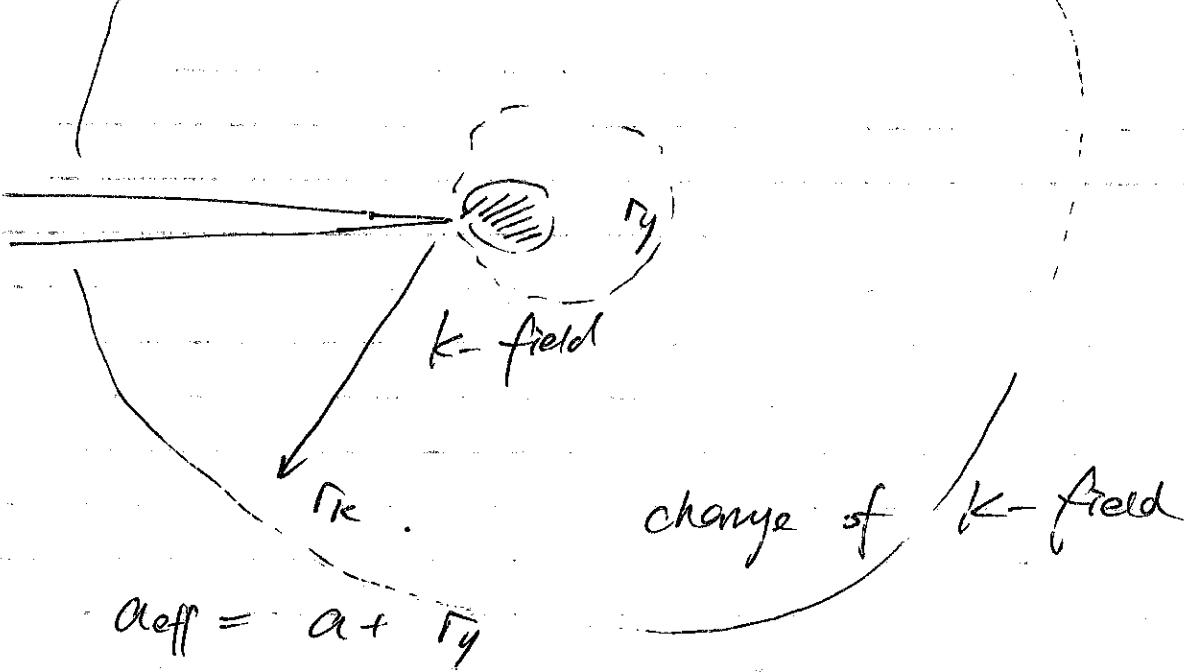
$$\sigma_y \approx \frac{k_z}{2\pi r_p} f(\theta)$$

$$k_z \geq k_{ic}$$

? how does plasticity change this criteria?

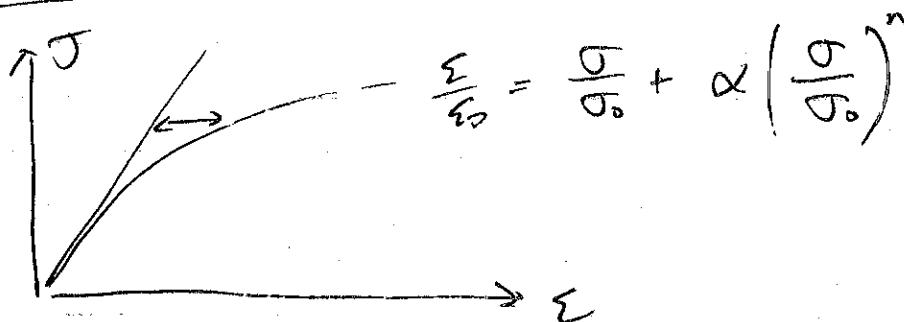
σ_y

yield increases k_{ic} (met. param.)



$$K_{\text{eff}} = \frac{P}{B\sqrt{w}} f\left(\frac{\alpha_{\text{eff}}}{w}\right)$$

HRR Solution 1968



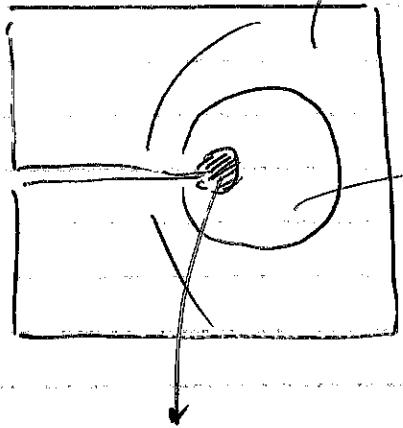
Closer to the crack tip,

$$\sigma_{ij} = K_i \left(\frac{J}{r} \right)^{\frac{1}{m+1}}$$

$$J \cdot \epsilon \propto \frac{1}{r}$$

$$\epsilon_{ij} = K_r \left(\frac{J}{r} \right)^{\frac{n}{m+1}}$$

... HRR singularity



linear elastic region.

find a boundary = K -dominated

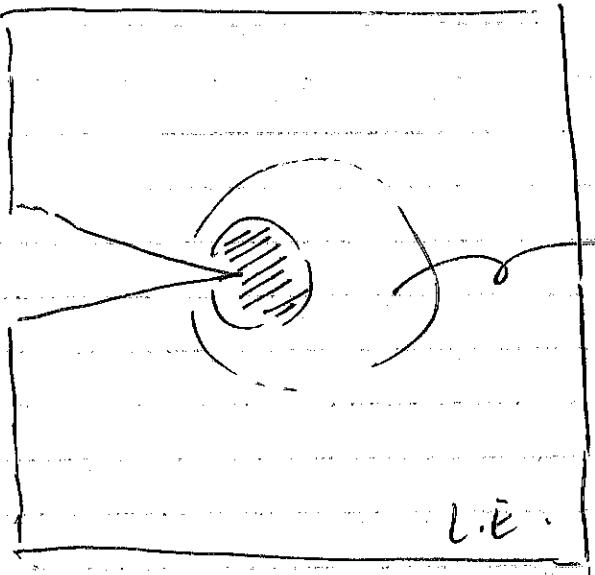
\rightarrow J -dominated region

large strain

\rightarrow LEFM works

J -integral works.

increasing the load.



zone expand

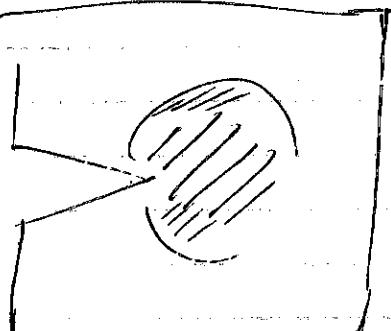
" K -dominated zone
vanishes..."

i.e.

\rightarrow LEFM not works

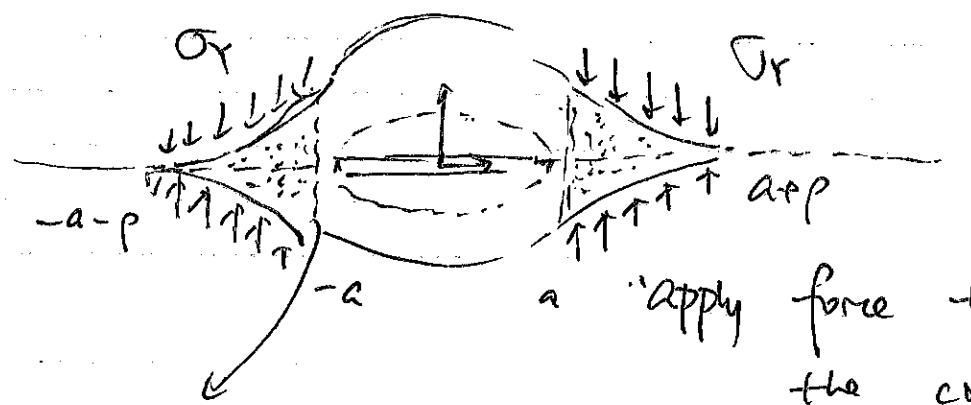
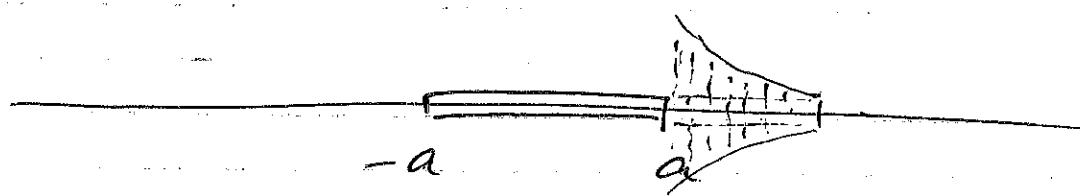
J -integral works

... keep loading



LEFM & J -integral
all done work!

Strip-yield model



plastic flow.

blunts the crack tip.

$$K_I^{\text{tot}} = \sqrt{\pi(a+p)} - 2\sigma_r \sqrt{\frac{a+p}{\pi}} \arccos\left(\frac{a}{a+p}\right)$$

$$\frac{d}{dp} \left(\sqrt{\pi(a+p)} - 2\sigma_r \sqrt{\frac{a+p}{\pi}} \arccos\left(\frac{a}{a+p}\right) \right) = 0$$

Solve for the correct p .

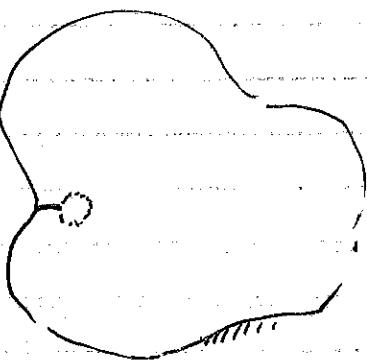
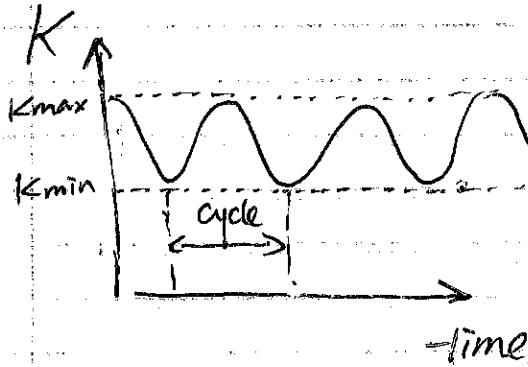
$$p = \frac{\pi}{8} \left(\frac{K_I^{\text{old}}}{\sigma_r} \right)^2 \approx 0.393$$

lecture 20 6/5/2014.

Fatigue

Example, airplane, vehicles, etc. ...

Paris law.



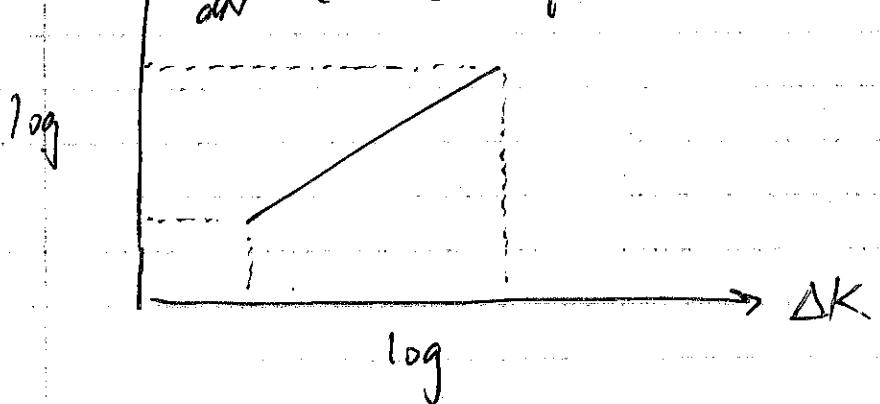
(e) not a time-dependent problem
in this approximation.

$$\Delta K = K_{\max} - K_{\min}.$$

$$R = \frac{K_{\min}}{K_{\max}}$$

If you just focus on ΔK ,

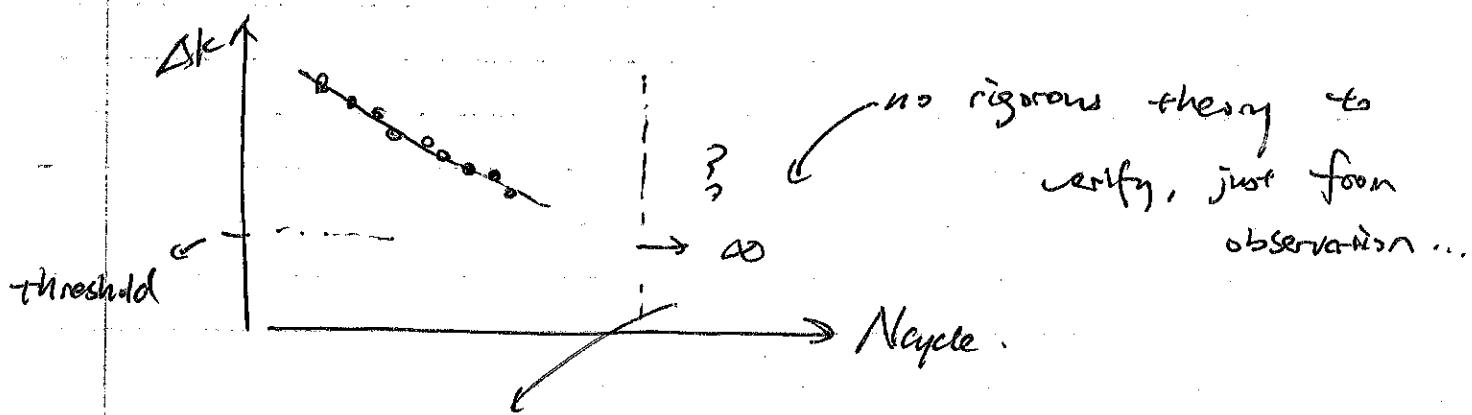
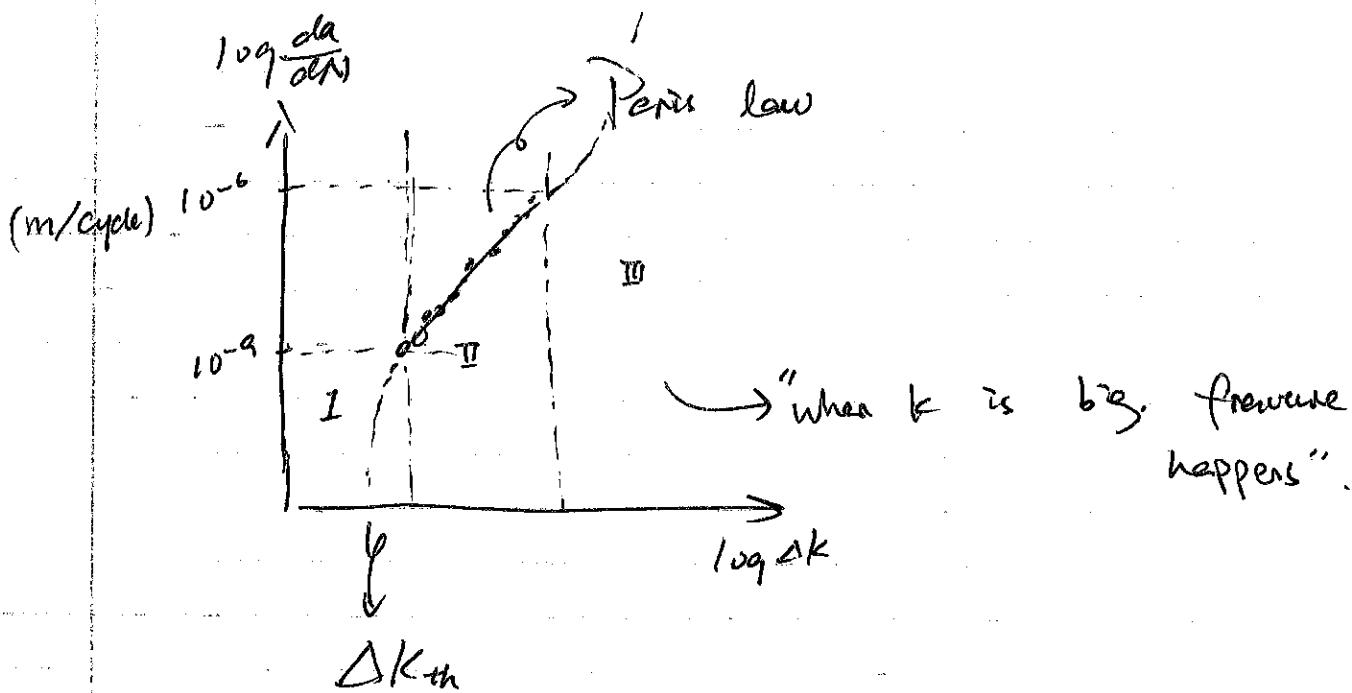
$\frac{da}{dN}$ is defined as the "speed".



$$\frac{da}{dN} = f(\Delta K, R)$$

$$\approx C (\Delta K)^m$$

$$2 \leq m \leq 4 \quad m \sim 3$$



We don't know if there's a limit

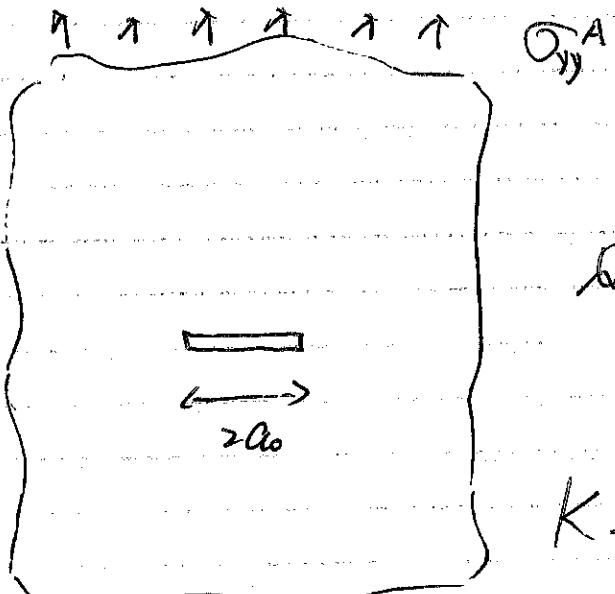
$$\frac{da}{dN} = C (\Delta K)^m \cdot \frac{\left(1 - \frac{\Delta K_m}{\Delta K}\right)^p}{\left(1 - \frac{K_{max}}{K_c}\right)^q}$$

Material constants:

$C, m, \Delta K_m, K_c, p, q$.

{ a modified theory
for fatigue

Example



Q: How many cycles
until fracture?

$$K = \sigma_{yy}^A \sqrt{\pi a}$$

$$K_{max} = S \sqrt{\pi a} = \Delta K$$

$$K_{min} = 0$$

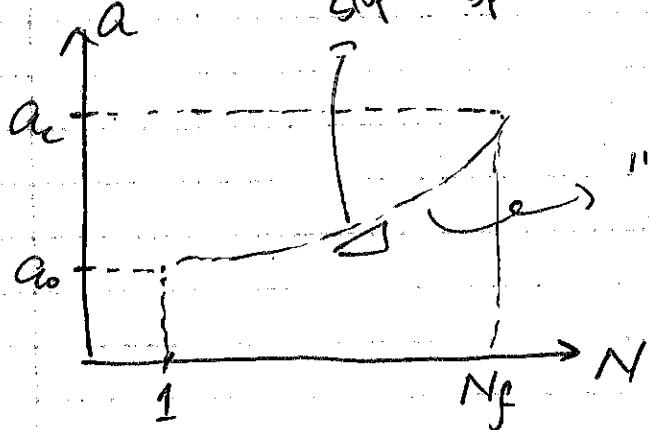
$$\text{assume } \frac{da}{dN} = C(\Delta K)^m$$

we need to find
critical size a_c

1 cycle

when $K = K_{rc}$

$$\sigma_{yy}^A \sqrt{\pi a_c} = K_{rc} \Rightarrow a_c = \frac{1}{\pi} \left(\frac{K_{rc}}{S} \right)^2$$



$$\Delta K = S \sqrt{\pi a}$$

$$\frac{da}{dN} = C(\Delta k)^m = CS^m (\pi a)^{\frac{m}{2}}$$

$$\frac{dN}{da} = \frac{1}{CS^m \pi^{\frac{m}{2}}} a^{-\frac{m}{2}}$$

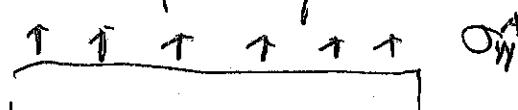
$$N = \int_{a_0}^{a_c} \frac{1}{CS^m \pi^{\frac{m}{2}}} a^{-\frac{m}{2}} da$$

$$N_f = \frac{1}{(-\frac{m}{2}+1) CS^m \pi^{\frac{m}{2}}} \left(a_c^{-\frac{m}{2}+1} - a_0^{-\frac{m}{2}+1} \right)$$

$$N_f = \frac{a_0^{-\frac{m}{2}+1} - a_c^{-\frac{m}{2}+1}}{(\frac{m}{2}-1) C.S. \pi^{\frac{m}{2}}}$$

Example 2

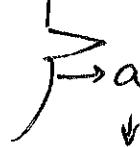
infinite plate



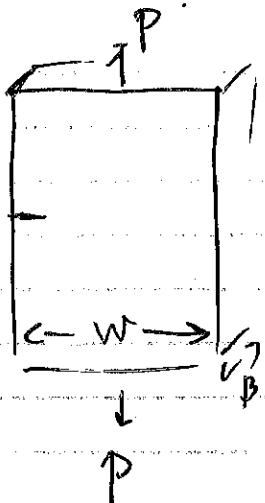
pure white, stress concn. factor 3.

locally

} 1 1 1 3 S.



1 1 1



$$K_I = \frac{P}{B\sqrt{w}} \left[\frac{\sqrt{2+\tan(\frac{\pi a}{2w})}}{\cos(\frac{\pi a}{2w})} \left(0.752 + 2.02 \frac{a}{w} \right) \right]$$

from table

$$\xrightarrow{w \rightarrow \infty} \frac{P}{B\sqrt{w}} \sqrt{\frac{\pi a}{w}} \left(0.752 + 0.37 \right)$$

$$= \frac{P}{Bw} \quad \leftarrow \text{just the stress}$$

$$\cdot \sqrt{\pi a} \cdot 1.122$$

$$= 1.122 \frac{\sigma_y^{\text{app}}}{w} \sqrt{\pi a}$$

3S

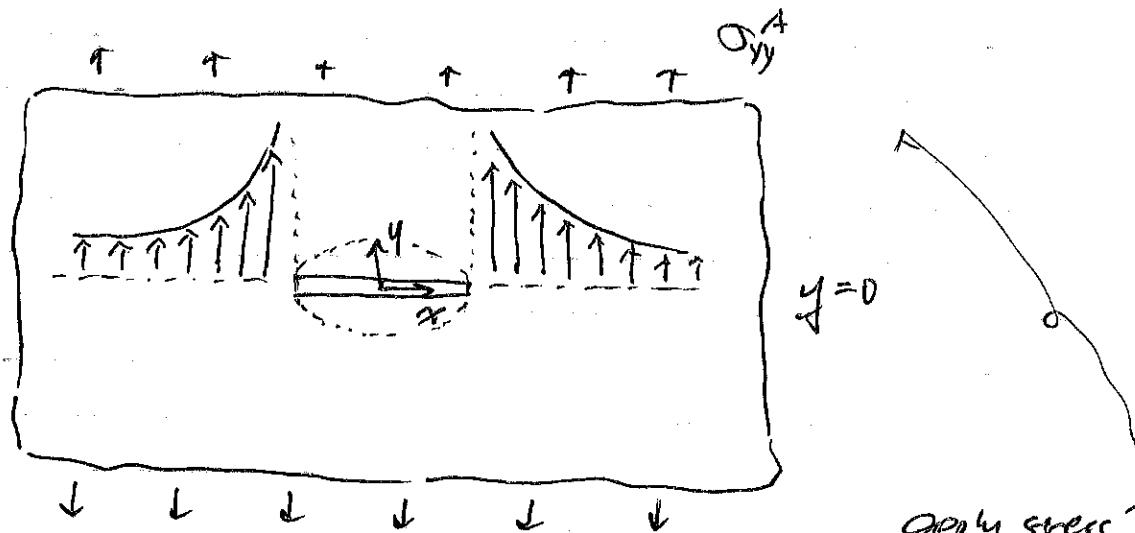
from the hole

solution.

Problem Session 10

6/9/2014

LEFM \rightarrow Slit-like crack.



$$g(x) = \int_{-\infty}^{\infty} \frac{p(x')}{x-x'}, dx' \quad , \quad p(x) = \frac{s|x|}{\sqrt{x^2 - a^2}} \quad \text{apply stress } S$$

$$\frac{du(x)}{dx}$$

$$\text{let } x = a + r, \quad \lim_{r \rightarrow 0} \sigma_{yy}(x) = \frac{k_1}{2\pi r} \quad @ x, y=0.$$

$$d(x) = \frac{2(1-\nu)}{\pi} \sqrt{1 - \left(\frac{x}{a}\right)^2} \quad -a \leq x \leq a.$$

\hookrightarrow enthalpy: $H = E - W_m = \underbrace{-E}_{\text{linear elastic medium}}$

should decrease during loading.

$$\cancel{\frac{\partial u}{\partial n} \rightarrow F} \quad W = Fx$$

κ n. pre-existing

this kind of system: $W_m = 2E$ \leftarrow Stress.

internal energy

State 0.

↓
no crack

State 1.

↓
With crack & opened.

E_0, H_0 .

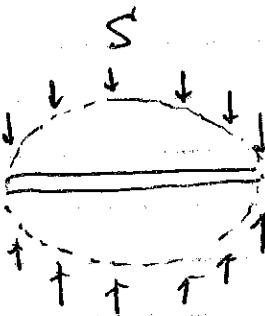
$$\rightarrow H_0 = -E_0$$

E_1, H_1

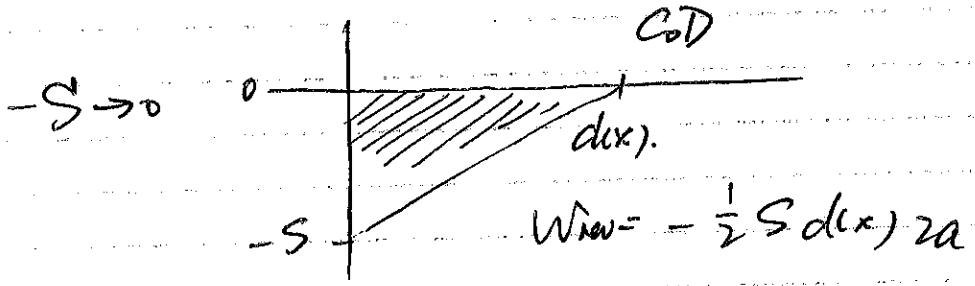
$$\Delta H = -\Delta E$$

$$g \rightarrow \Delta E > 0$$

neg.



apply $S \rightarrow$ state 0

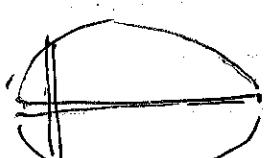


if stress is changing: $\int_a^0 \left[\frac{1}{2} dF \cdot dx \right]$

a.

$S dx$

$$\text{we obtain: } \Delta H = -\frac{(1-\nu)}{2\mu} S^2 \pi a^2$$



semi-circular crack

Griffith Criteria

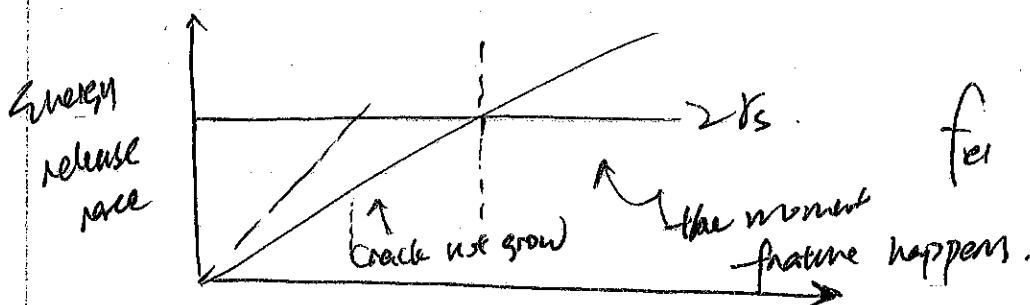
Slit-like.

$$f_{el} = - \frac{\partial (\Delta H)}{\partial (\text{Crack length})} = - \frac{\partial (\Delta H)}{\partial (2a)}$$

$$f_{tot} = - \frac{\partial (\overbrace{\Delta H + 2 \cdot \gamma_s \cdot 2a}^{\Delta G})}{\partial (2a)} \rightarrow \text{two surfaces.}$$

Griffith

$$= - \frac{\partial (\Delta H)}{\partial (2a)} - 2 \gamma_s \quad \text{material property}$$



$$\Delta H = - \frac{(1-\nu)}{2\mu} S^2 a \alpha^2 \rightarrow f_{el} = \frac{\pi (1-\nu)}{2\mu} S^2 \alpha \cdot \frac{(2a)^n}{4}$$

$$f_{el} = 2 \gamma_s \quad S_c = \sqrt{\frac{8 \mu \gamma_s}{\pi (1-\nu) (2a)}} \quad \leftarrow \begin{matrix} \text{crack length} \\ \text{fixed} \end{matrix}$$

$$\text{or} \quad 2a_c = \frac{S_c \alpha \gamma_s}{\tau (1-\nu) S^2} \quad \leftarrow \begin{matrix} \text{stress fixed} \end{matrix}$$

Mode-I loading

Energy release rate

$$G = -\frac{\Delta(\Delta H)}{2(\text{Crack length})}$$

$$= \frac{\pi(1-\nu)}{2\mu} S^2 a$$

slit-like

Generalised
expression

$$= \frac{K_I^2}{E'} \quad \left\{ \begin{array}{l} K_I = S\sqrt{\pi a} \\ E' = \frac{E}{1-\nu^2} \text{ (Plane} \\ \text{strain)} \end{array} \right.$$

True loadings.

$$\sigma_{yy}^{(1)}$$

$$\sigma_{yy}^{(2)}$$

$$K_I^{(1)}$$

$$K_I^{(2)}$$

$$G = \frac{(K_I^{(1)} + K_I^{(2)})^2}{E'}$$

can use principles of
superposition due to
linear elasticity.

Multiple modes

$$G = \frac{K_I^2}{E'} + \frac{K_{II}^2}{E'} + \frac{K_{III}^2}{2\mu}$$

J-integral

$$G \geq G_c \rightarrow \text{material property}$$

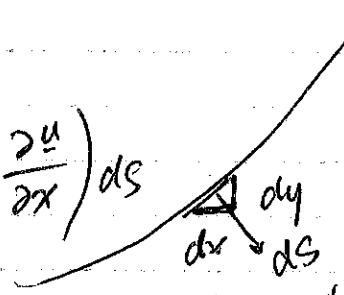
$$\frac{K_I^2}{E'} \geq \frac{K_{Ic}^2}{E'} \rightarrow K_I \geq K_{Ic} \quad \text{Crack growth condition}$$

fracture toughness

$$J_i = \int_S (w n_i - T_j u_{j,i}) dS.$$

x, y, z

In 1D, $J_x = \int_{\Gamma} \left(w dy - T_x \frac{\partial u}{\partial x} \right) dS$

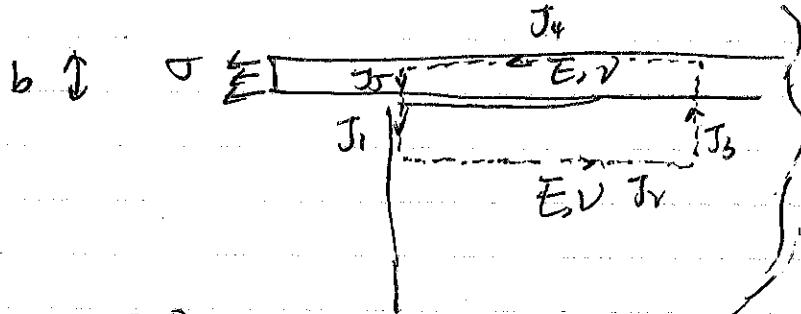


path $\rightarrow dx \hat{i} + dy \hat{j}$
 $dS \rightarrow dy \hat{i} - dx \hat{j}$

$$J_x = \int_{\Gamma} w dy - \left(T_x \frac{\partial u_x}{\partial x} + T_y \frac{\partial u_y}{\partial x} \right) dS.$$

Example

$$J_x = \sum_{i=1}^5 J_i$$



①: ~~w > 0~~ ~~T > 0~~

J_1 by surface

②: ~~dy > 0~~ ~~$\frac{\partial u}{\partial x} > 0$~~

D: E-dx?

③: ~~w > 0~~ ~~T > 0~~ (infinitely faraway)

④: ~~w dy > 0~~ ~~T > 0~~

free

⑤. $\int w dy = \int_b^0 \frac{1}{2} \nabla_j \Sigma_{ij} dy$

$$dS = dx \hat{i} + dy \hat{j}$$

$$w = \frac{1}{2} \sigma \epsilon$$

$$w = \frac{\sigma^2}{2E} \quad \epsilon_{xx} = \frac{\sigma_{xx}}{E}$$

$$\int_0^b w dy = \frac{\sigma^2 b}{2E}$$

$$\int_0^b T_x \frac{\partial u_x}{\partial x} dy$$

$$T_x = \sigma_{xx} = 0$$

$$\frac{\partial u_x}{\partial x} = \epsilon_{xx}$$

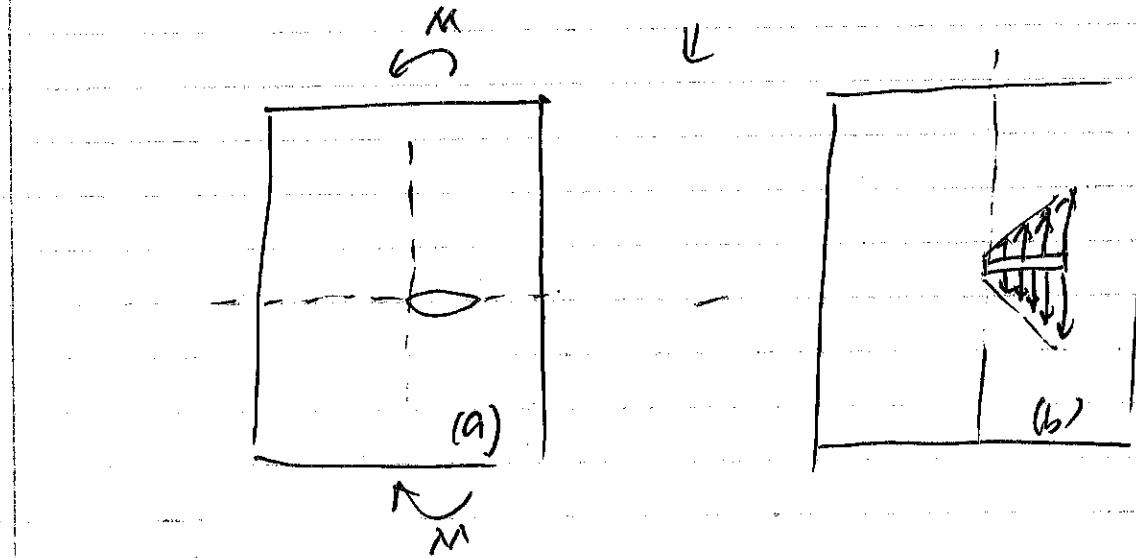
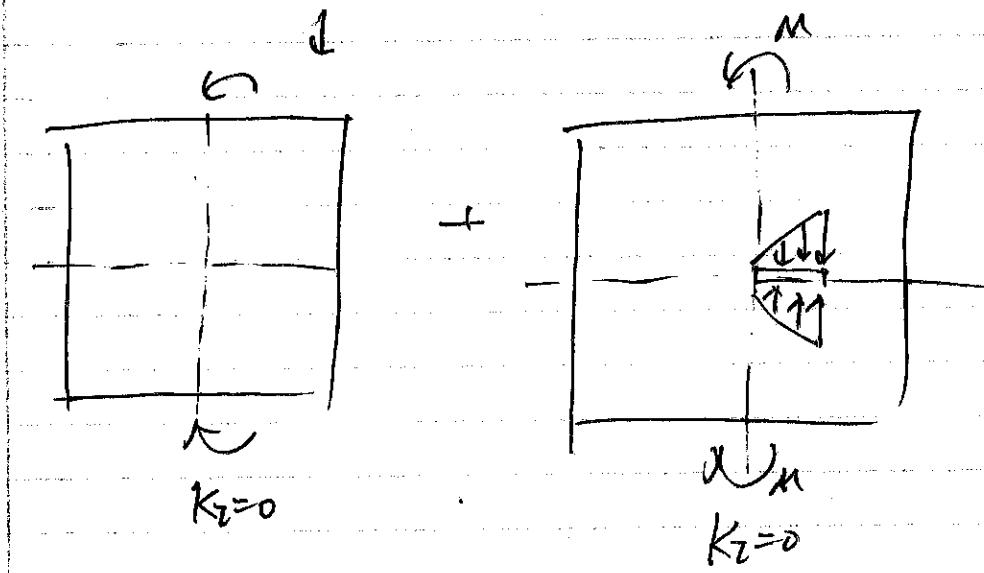
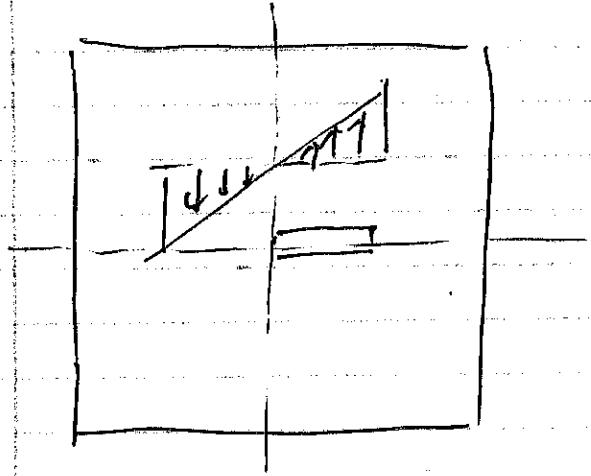
$$= - \int_0^b \sigma_{xx} \epsilon_{xx} dy$$

$$= - \int_0^b \frac{\sigma^2}{E} dy = - \frac{\sigma^2 b}{E}$$

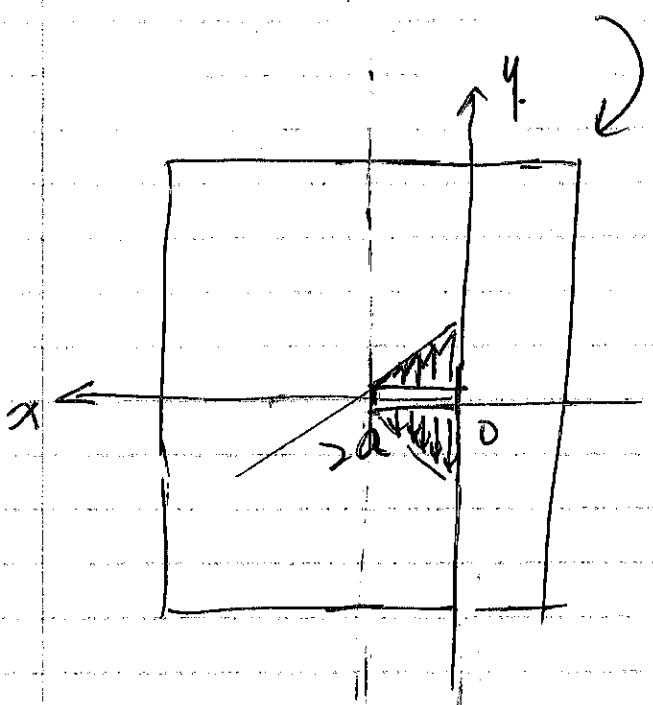
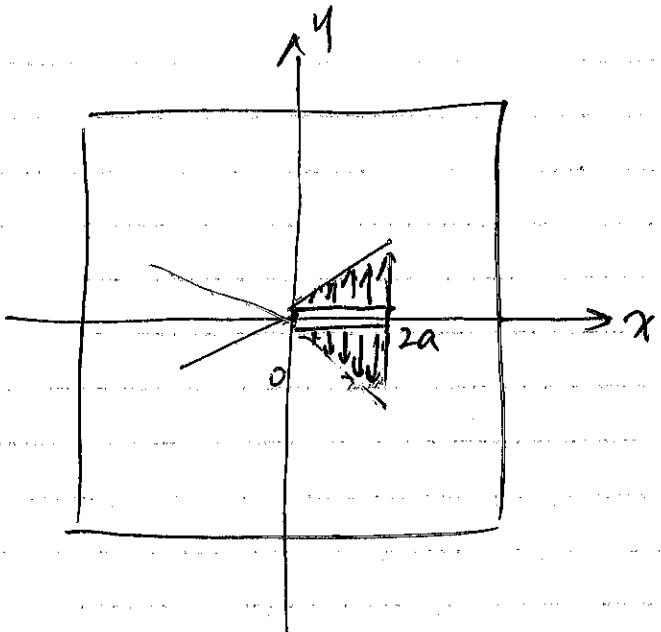
$$J_x = \frac{\sigma^2 b}{2E} - \left(- \frac{\sigma^2 b}{E} \right) = \frac{3 \sigma^2 b}{2E} = \frac{K_D^2}{E}$$

 Plane stress

for plane strain, we replace E with E' .



$$K_I^{(a)} = K_I^{(b)}$$



looking from the back side.

"Shift coordinate to obtain K_I of
the left side \rightarrow integral goes from $0 \rightarrow 2a$ ".

Fracture mechanics review

Contact problem

from the surface Green function we know:

the equation for contact:

$$\frac{dU_0}{da} = \frac{k+1}{4\pi a^2} \int_{-c}^c \frac{P_y(x')}{x-x'} \frac{dM(x')}{dx'} dx'$$

→ integral equation soln:

$$P_y(x) = -\frac{1}{\pi^2 \sqrt{c^2 - x^2}} \int_{-c}^c \frac{\sqrt{c^2 - x'^2} \cdot \frac{dM(x')}{dx'}}{x - x'} \frac{dM(x')}{dx'} dx' + \frac{F}{\pi \sqrt{c^2 - x^2}}$$

From the flat punch contact we know

$$P_y \sim \frac{F}{\pi} (2cr)^{-1/2}$$

$$\rightarrow \sigma_{yy} \propto \frac{1}{\sqrt{r}}$$

Wedge and Notch

Trial soln for wedge:

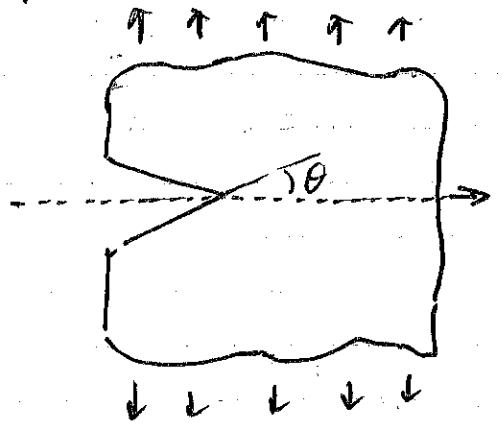
$$\phi = r^2 (A_1 \cos 2\theta + A_2 + A_3 \sin 2\theta + A_4 \theta)$$

$$\sigma_{rr} = -2A_1 \cos 2\theta + 2A_2 - 2A_3 \sin 2\theta + 2A_4 \theta.$$

$$\sigma_{\theta\theta} = 2A_1 \sin 2\theta + 0 - 2A_3 \cos 2\theta - A_4$$

$$\sigma_{r\theta} = 2A_1 \cos 2\theta + 2A_2 + 2A_3 \sin 2\theta + 2A_4 \theta.$$

formulate the notch problem.



William's soln. ($n=2-1$).

$$\phi = r^{2H} \{ A_1 \cos(\gamma+1)\theta + A_2 \cos(\gamma-1)\theta \\ + A_3 \sin(\gamma+1)\theta + A_4 \sin(\gamma-1)\theta \} \\ \rightarrow \sigma_{rr}, \sigma_{\theta\theta}, \sigma_{r\theta}$$

Find the symmetric & anti-symmetric part based on the nature of the loading.

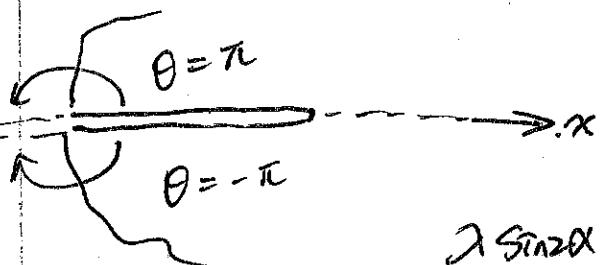
$$\det(M_1) = 0$$

↑
symmetric

$$\det(M_2) = 0$$

↑
anti-symmetric

\rightarrow when the notch turns into a crack



$$\alpha = 2\pi$$

$$\downarrow \\ \sin 2\alpha = 0.$$

$$2 \sin 2\alpha \pm \sin 2\alpha = 0 \rightarrow \sin 2\alpha = 0$$

$$\gamma = 0, \frac{1}{2}, 1, \frac{3}{2}$$

Strain energy is infinite. \uparrow Stress fields non-singular.

$$\sigma \sim \frac{1}{r} \dots \text{crack tip singularity.}$$

Equivalence between crack & flat-punch problems

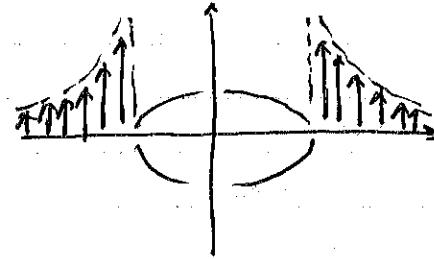
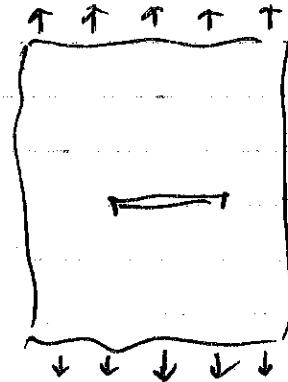
$$P_y(x) = \frac{F}{\pi \sqrt{c^2 - x^2}} = -\sigma_{yy}$$

$$P_y(x) = \frac{F}{\pi N c^2 - x^2} = \sigma_{yy}$$

(... skip plasticity).

Slit-like Crack

Singularity between
Contact & cracks



Recall soln to the singular integral equation:

$$P_y(x) = -\frac{1}{\pi^2} \frac{(x-a)^{1/2}}{(x+a)^{1/2}} \left[\int_{-\infty}^{-a} + \int_a^{+\infty} \right] \frac{(x+a)^{1/2}}{(x'-a)^{1/2}} \frac{g(x')}{x-x'} dx'$$

$$P_y(x) = \frac{A+B/x}{\sqrt{1-(a/x)^2}}$$

$$\dots J_{yy}(x, y=0) = \frac{S \cdot |x|}{\sqrt{x^2 - a^2}}$$

to find the stress singularity at crack tip,

let $x=a+r$, (taking $r \rightarrow 0^+$)

$$\sigma_{yy} \sim \frac{Sa}{\sqrt{2ar}} = S \sqrt{\frac{a}{2}} \frac{1}{\sqrt{r}}$$

recall wedge & notch: $\sigma_{rr} = \frac{K_I}{\sqrt{2\pi r}} \left(\frac{5}{4} \cos \frac{\theta}{2} - \frac{1}{4} \cos \frac{3\theta}{2} \right)$

$$\rightarrow \sigma_{rr} = \frac{K_I}{\sqrt{2\pi r}} \quad \dots \text{ Stress intensity factor: } K_I = S\sqrt{\pi a}$$

for slit-like crack:

$$\tilde{u}_y(x) = -\frac{1-\nu}{\mu} Sa \cdot \sqrt{1-(x/a)^2}$$

$$\rightarrow d(x) = -2\tilde{u}_y(x) = \frac{2(1-\nu)}{\mu} Sa \cdot \sqrt{1-(x/a)^2}$$

D enthalpy of the crack.

$$H = E - \Delta W_{in}$$

linear elastic medium sub. traction force T_j on S_t .

The enthalpy writes:

$$H = \int_S \frac{1}{2} \sigma_{ij} \epsilon_{ij} dV - \int_{S_t} T_j u_j dS.$$

\nearrow
elastic strain energy

For slit-like crack,

$$\{ E = \frac{1}{2} \sigma_{yy}^A \epsilon_{yy} + V$$

works like magic !!!

$$\{ \Delta W_{in} = (\sigma_{yy}^A A) \cdot (\epsilon_{yy} L) = \sigma_{yy}^A \epsilon_{yy} \cdot V. \quad \nearrow$$

$$\{ H = \frac{1}{2} \sigma_{yy}^A \epsilon_{yy} + V - \sigma_{yy}^A \epsilon_{yy} V = -\frac{1}{2} \sigma_{yy}^A \epsilon_{yy} V = -E$$

• Enthalpy: $\Delta H = \Delta W^+ + \Delta W^-$

$$= \frac{1}{2} S \int_{-a}^a 2 \tilde{u}_y(x) dx$$

$$= -\frac{1}{2} S \int_{-a}^a dx) dx$$

crack-opening displacement:

$$d(x) = \frac{2(1-\nu)}{\mu} S a \sqrt{1 - \left(\frac{x}{a}\right)^2}$$

enthalpy change proportional to applied stress S :

$$\Delta H = -\frac{1-\nu}{2\mu} S^2 \pi a^2 \quad (\text{plane strain})$$

• driving force for crack propagation.

$$f_{\text{dr}} = -\frac{\partial \Delta H}{\partial (2a)} = \frac{\pi(1-\nu)}{2\mu} S^2 a = \frac{1-\nu}{2\mu} K_I^2$$

Griffith criteria. free energy:

$$\Delta G = \Delta H + \gamma_S \cdot 2 \cdot 2a \quad \leftarrow \text{slit-like.}$$

$$\text{Plug in: } \Delta G = -\frac{1-\nu}{2\mu} S^2 \pi a^2 + 4\gamma_S a$$

$$f_{\text{tot}} = \frac{\pi(1-\nu)}{2\mu} S^2 a - 2\gamma_S$$

Solving for $f_{\text{tot}} = 0$, one can solve for the critical crack size & critical stress:

$$a_c = \frac{4\mu}{\pi(1-\nu)} \frac{\gamma_S}{S^2} \quad \& \quad S_c = \sqrt{\frac{4\mu \gamma_S}{\pi(1-\nu) a}}$$

(plane strain)

See eqn. (50) for general expression (law), ΔH , f_{dr} , f_{tot} .

Energy release rate

mode - I , mode - II , mode - III .

Solutions for $\begin{cases} \sigma_{xx}^{(I)} \\ \sigma_{yy}^{(I)} \\ \sigma_{xy}^{(I)} \end{cases}$, $\begin{cases} \sigma_{xx}^{(II)} \\ \sigma_{yy}^{(II)} \\ \sigma_{xy}^{(II)} \end{cases}$, $\begin{cases} \sigma_{xz}^{(III)} \\ \sigma_{yz}^{(III)} \end{cases}$

energy release rate G (crack extension force)
elastic contribution.

$$G = - \frac{\partial (aH)}{\partial (2a)} = \frac{\pi(1-\nu)}{2\mu} (\sigma_{yy}^A)^2 a \quad \rightarrow E' = \frac{E}{1-\nu}$$

$$G = \frac{\pi}{E'} (\sigma_{yy}^A)^2 a$$

$$\text{Recall } K_I = \sigma_{yy}^A \sqrt{\pi a} \rightarrow G = \frac{K_I^2}{E'} \dots \text{mode - I}$$

$$\text{general crack case: } G = \frac{K_I^2}{E'} + \frac{K_{II}^2}{E'} + \frac{K_{III}^2}{2\mu}$$

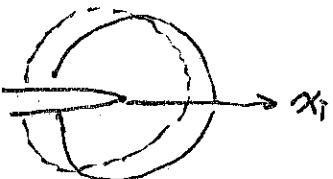
one may also derive the energy release rate based on the variation of H w.r.t. a .

$$\underline{\text{J-Integral (2D)}} \quad J = \int_P w dy - \bar{I} \cdot \frac{\partial u}{\partial x} dS$$

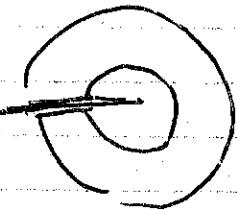
$$J = G = \int_V \frac{\partial w}{\partial x_i} dV - \int_S T_j \frac{\partial u_j}{\partial x_i} dS$$

$$\rightarrow \text{the work done} - T_j \delta x_i = \int_V w dV - \int_V w dV$$

$$+ \int_S T_j u_j dS - \int_S T_j u_j dS \\ = H' - H$$

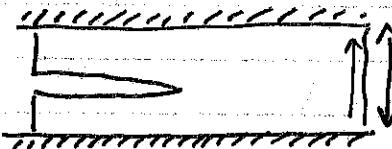


Example 1



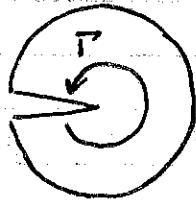
→ no singularity, $J(P) = 0$.

Example 2



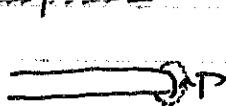
$J = wh$ boundary work.

Example 3

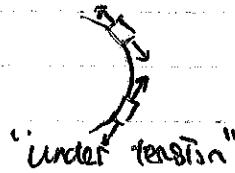


$$J = \int_{\Gamma} w \, dy - I \cdot \frac{\partial u}{\partial x} \, dS = \frac{1-\nu}{2\nu} K_I^2 = \frac{K_I^2}{E'}$$

Example 4



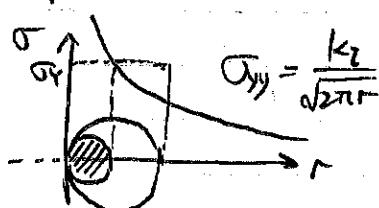
$$J = \int_{\Gamma} w \, dy - I \cdot \frac{\partial u}{\partial x} \, dS$$



"under tension"

Elastic-Plastic Fracture Mechanics

fracture criteria: $J = J_c$



$$\sigma_y = \frac{K_I}{\sqrt{2\pi r}}$$

$$r_y = \frac{1}{2\pi} \left(\frac{K_I}{\sigma_y} \right)^2$$

$$r_p = 2r_y$$

plastic yielding changes K_I .

$$K_I = \frac{P}{B\sqrt{w}} \cdot f\left(\frac{a_{eff}}{w}\right) \quad \text{← estimate: } a_{eff} = a + r_y$$

HRR Solution: $\frac{\sigma}{\sigma_0} = \frac{1}{\sigma_0} + \alpha \left(\frac{\sigma}{\sigma_0} \right)^n$ Strain-hardening exp.

HRR singularity: $\sigma_y \propto \frac{1}{r}$.

► Strip yield model

$$K_{I+0} = \frac{P}{\sqrt{\pi}a} \sqrt{\frac{a+p}{a-p}}, \quad K_{I-a} = \frac{P}{\sqrt{\pi}a} \sqrt{\frac{a-p}{a+p}}$$

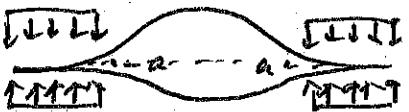
total Stress intensity factor (a) $a+p = 0$

$$K_{tot} = \sigma_y \sqrt{\pi(a+p)} + K_{closure} = 0$$

$$\sigma_y \sqrt{\pi(a+p)} - 2\sigma_y \sqrt{\frac{a+p}{\pi}} \arccos\left(\frac{a}{a+p}\right) = 0$$

... some algebra.

$$p \approx 0.393 \left(\frac{K_I^{dd}}{\sigma_y} \right)^2$$



$$r_p = \frac{1}{\pi} \left(\frac{K_I}{\sigma_y} \right)^2 = 0.318 \left(\frac{K_I}{\sigma_y} \right)^2 \quad \text{... Irwin's approach.}$$

► Crack tip opening displacement

$$\delta = \frac{8\sigma_y a}{\pi E'} \cdot \ln\left(\frac{a+p}{p}\right)$$

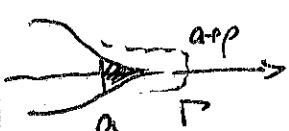
$$\delta = \frac{8\sigma_y a}{\pi E'} \ln \left[\sec \left(\frac{\pi}{2} \cdot \frac{\sigma_y^A}{\sigma_y} \right) \right]$$

$$\text{at small } \sigma_y^A = \delta \approx \frac{K_I^{dd}}{E' \sigma_y} \quad \text{as } \sigma_y^A \rightarrow \sigma_y, \quad \delta \rightarrow \infty$$

► energy release rate of strip yield.

$$G = J = \int_{\Gamma} w dy - I \frac{\partial u}{\partial n} ds$$

$$= -\sigma_y u_y(x=a, y=0^-) + \sigma_y u_y(x=a, y=0^+)$$



$$= \sigma_y \delta$$

$$\dots G = J = \sigma_y \delta \cdot \text{fracture: } \sigma_y \cdot \delta_c \quad \text{fracture CTOD}$$

Plasticity review

• Displacement: $\underline{u} = \underline{x} - \underline{\xi}$

• Strain: $\varepsilon_{ij} = \frac{1}{2}(u_{ij} + u_{ji})$

• Stress: $T_j = \sigma_{ij} n_i$ → same with elasticity

• Equilibrium: $\bar{G}_{ij,i} + \bar{F}_j = 0$

For strain: $\varepsilon_{ij} = \varepsilon_{ij}^{\text{el}} + \varepsilon_{ij}^{\text{pl}}$

Elastic constitutive relationship: $\sigma_{ij} = C_{ijkl} \varepsilon_{kl}^{\text{el}}$

hydrostatic stress: $\bar{\sigma} = \frac{1}{3} \sigma_{ii}$ important

$$\hookrightarrow \bar{\sigma} = 3K \bar{\varepsilon} \quad K = \frac{E}{3(1-2\nu)}$$

deviatoric stress & strain relationship: $\sigma_{ij} = 2\mu \varepsilon_{ij}$

• Yield Condition: $f(\{\sigma_{ij}\}) = 0$

Original stress invariants: I_1, I_2, I_3 (too complicated!)

Solving eigenvalue equation for deviatoric stress.

$$\det(S - \lambda I) = \boxed{\lambda^3 - J_1 \lambda^2 + J_2 \lambda - J_3 = 0} \rightarrow \lambda^3 - J_1 \lambda^2 + J_2 \lambda - J_3 = 0$$

after some algebra, we have $J_2 = \frac{1}{2} S_{ij} S_{ij}$

↑
a measure of deviatoric stress.
Can be think of as the norm.

The new stress invariants:

$$J_1 = 0, \quad J_2 = \frac{1}{2} S_{ij} S_{ij}, \quad J_3 = \det(S_{ij})$$

$$\rightarrow f(\bar{\sigma}, J_2, J_3) = 0 \quad \text{some further simplification:}$$

$$\dots f(J_2) = J_2 - K^2 = 0; \text{ if EPP is assumed:}$$

$$\rightarrow \dot{J}_2 = 0 \rightarrow \dot{J}_2 = \dot{S}_{ij} \dot{S}_{ij} = 0$$

* Q: How to determine \dot{S}_{ij}^{pl} ? ↑ a constraint on the
stress rate.

$$\dot{S}_{ij}^{pl} = \int_0^t \dot{\epsilon}_{ij}^{pl}(t) dt \rightarrow \gamma_n \dot{\epsilon}_{ij}^{pl} = \dot{S}_{ij} \quad (\text{flow rule})$$

$$\dots \text{recall } \gamma_n \dot{\epsilon}_{ij}^{el} = \dot{S}_{ij} \quad \& \quad \gamma_n \dot{\epsilon}_{ij}^{pl} = \dot{S}_{ij}$$

$$\gamma_n \dot{\epsilon}_{ij} = \gamma_n (\dot{\epsilon}_{ij}^{el} + \dot{\epsilon}_{ij}^{pl}) = \dot{S}_{ij} + J S_{ij}$$

(total deviatoric strain rate)

$$\text{define work rate: } \dot{W} = S_{ij} \dot{\epsilon}_{ij} = S_{ij} (\dot{\epsilon}_{ij}^{el} + \dot{\epsilon}_{ij}^{pl})$$

With EPP assumption: $\gamma_{air} = 2\tilde{\sigma}k^2$

$$\rightarrow \tilde{w} = \frac{2u}{2k^2} w \quad \dot{e}_{ij}^{pi} = \frac{w}{2k^2} w$$

Overall summary

$$\begin{aligned} \dot{e}_{ij} & \left\{ \begin{array}{l} \dot{\bar{e}} = \frac{1}{3} \dot{e}_{ii} \rightarrow \bar{\sigma} = 3K\dot{\bar{e}} \\ \dot{e}_{ij} = \dot{e}_{ij} - \dot{\bar{e}} \delta_{ij} \end{array} \right. \quad \dot{\sigma}_{ij} = S_{ij} + \bar{\sigma} \delta_{ij} \end{aligned}$$

$$\begin{aligned} \dot{\sigma}_{ij} & \left\{ \begin{array}{l} \bar{\sigma} = \frac{1}{3} \sigma_{ii} \\ S_{ij} = \sigma_{ij} - \bar{\sigma} \delta_{ij} \end{array} \right. \quad \left. \right\} \bar{w} = S_{ij} \dot{e}_{ij} \rightarrow \dot{S}_{ij} = 2u \left(\dot{e}_{ij} - \frac{w}{2k^2} S_{ij} \right) \end{aligned}$$