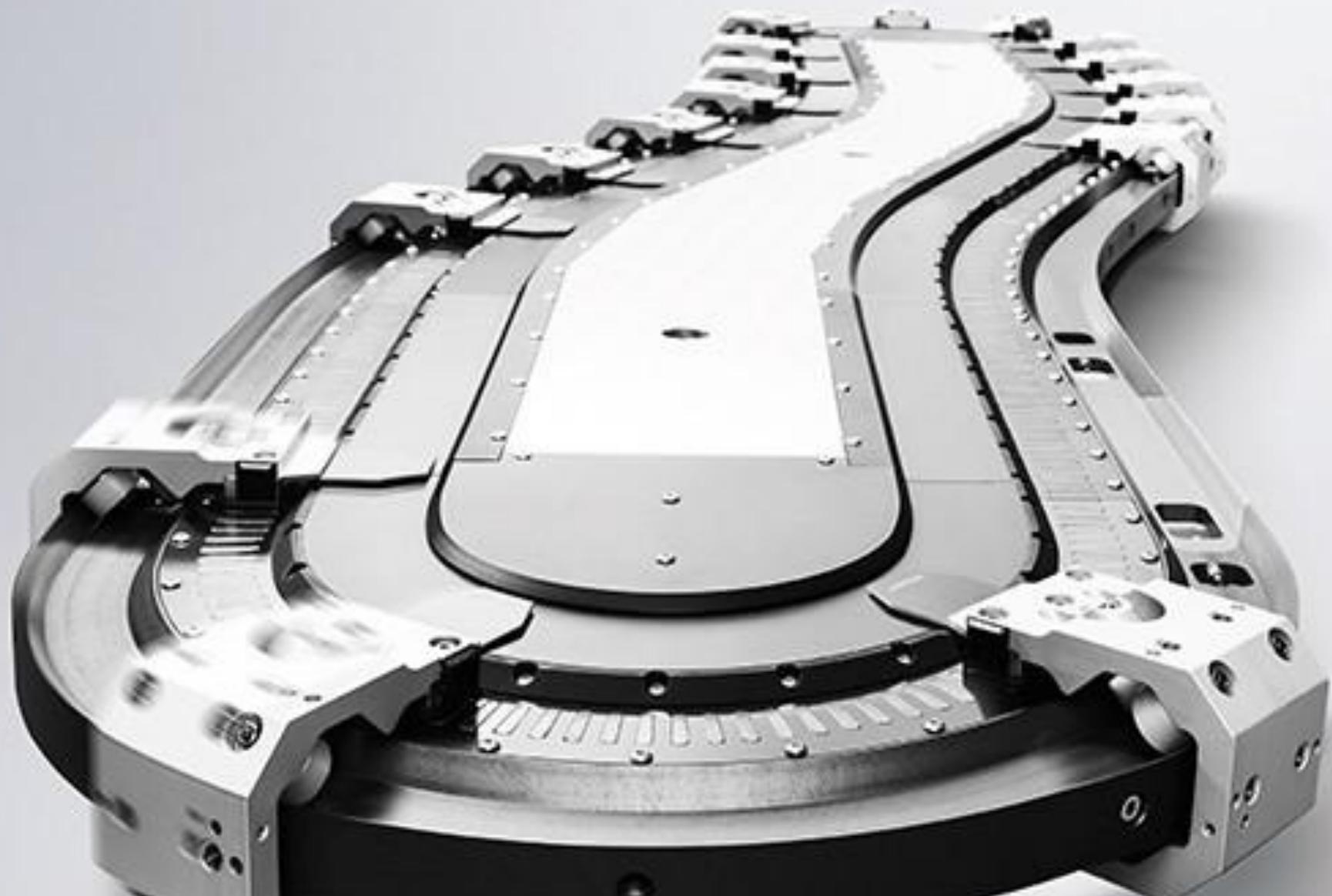
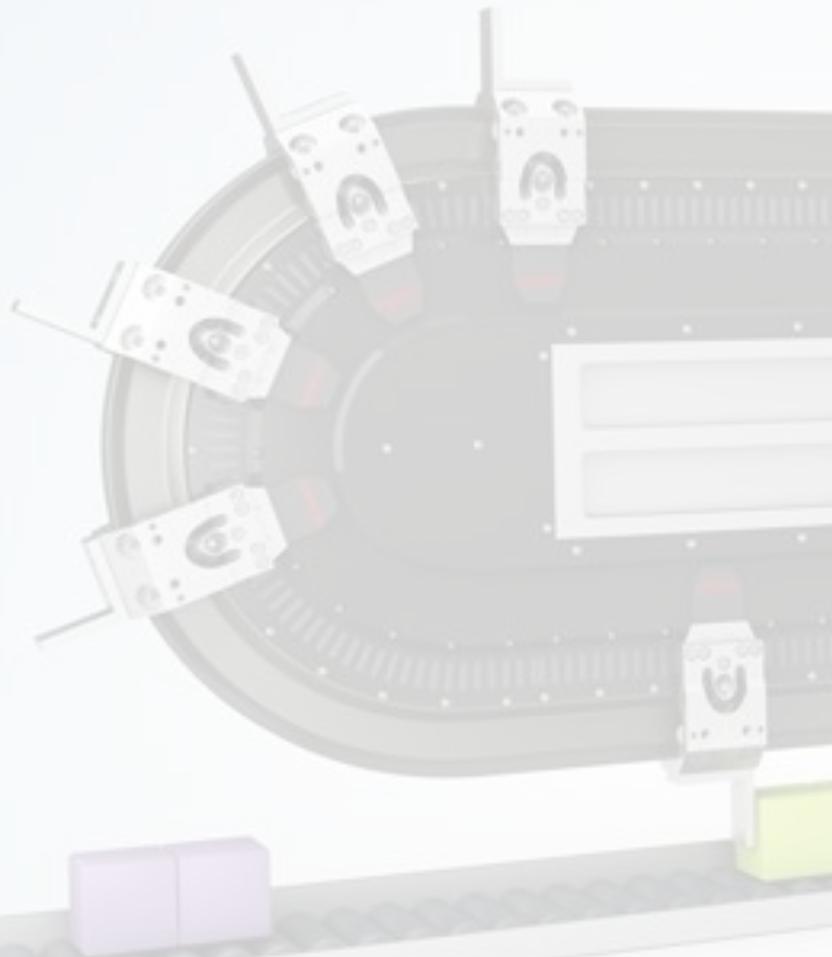


XTS TRANSPORT LAYER – Mover Class

BECKHOFF

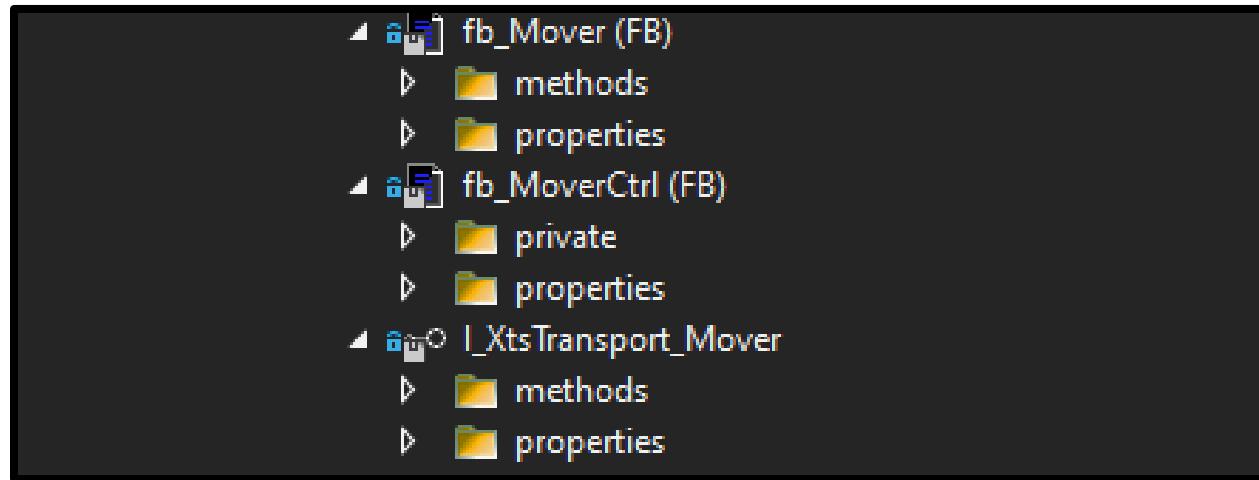


1. Design



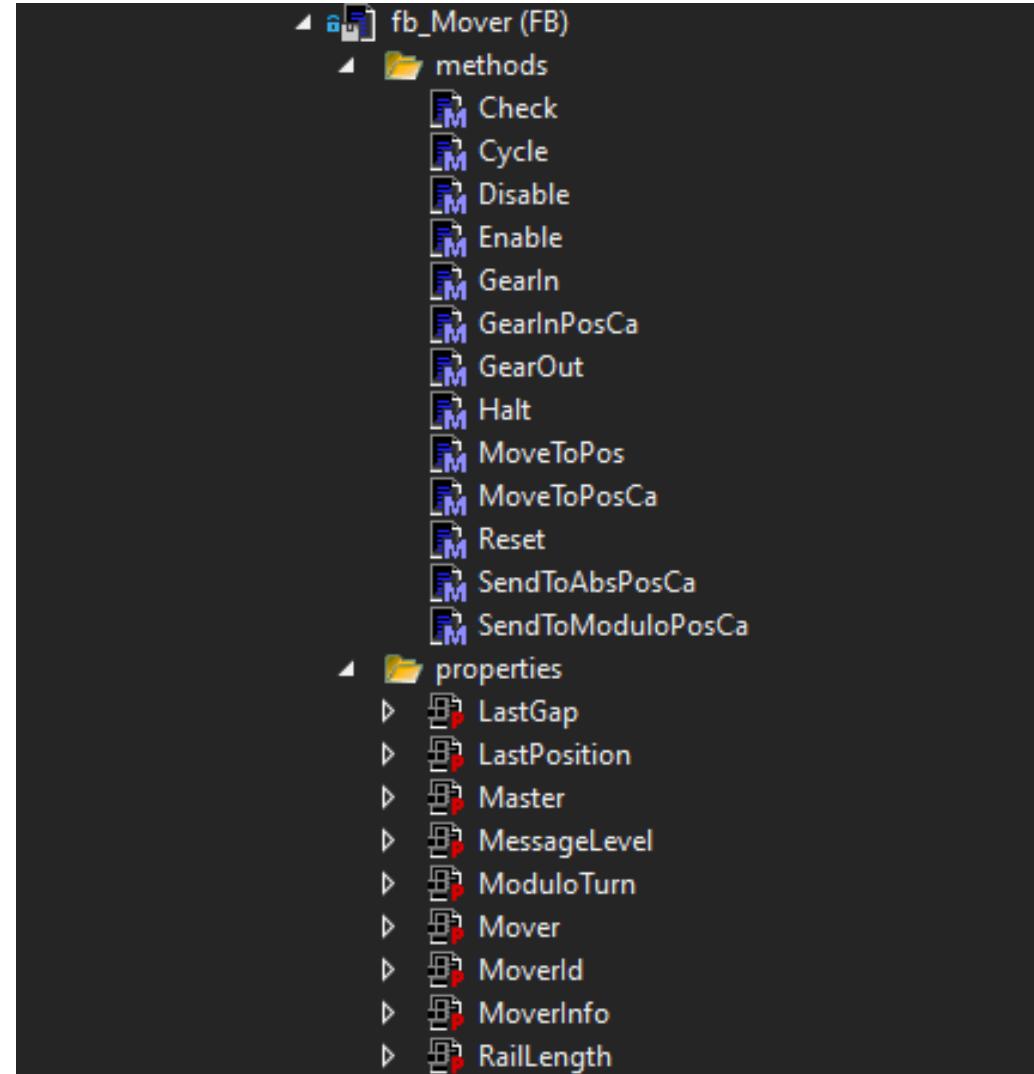
- **GVL_XTS.Mover (fb_MoverCtrl)**

- fb_Mover
 - Encapsulates Motion Control and Collision Avoidance function blocks
 - Message handling
 - Base class of fb_MoverCtrl
- fb_MoverCtrl
 - Cyclic execution wrapper
 - OnChange check of commands
 - State feedback
- I_XtsTransport_Mover
 - Interface for use in fb_CaGroup, fb_Station, fb_TransportUnit



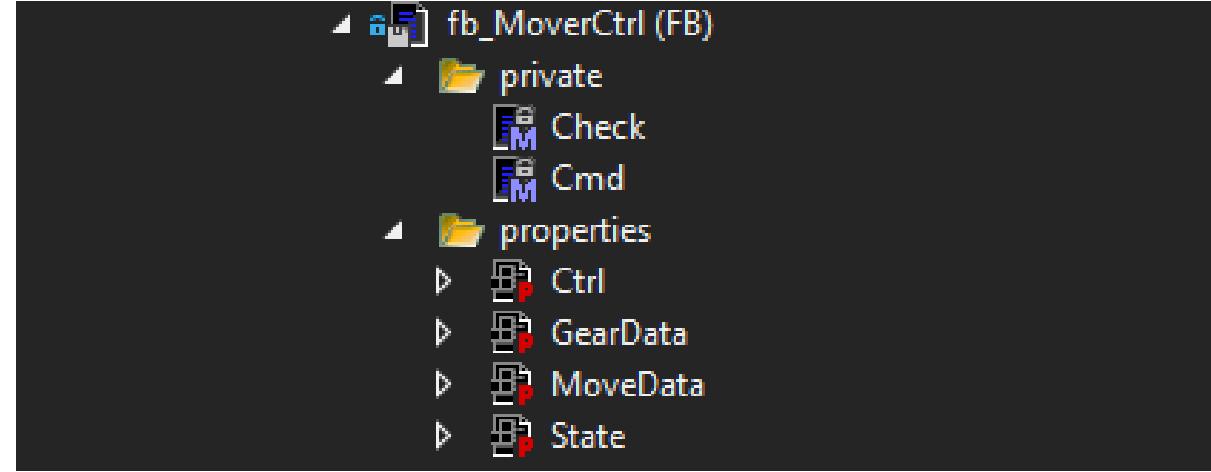
- **fb_Mover:**

- **Cycle()** method must be called by extending class
 - **Check()** must be used in extending class (pointer checks)
 - Method flow charts, see doc folder
 - Execute behaviour:
→ initialize call with ‘Execute:=FALSE’
 - Methods feedback: E_PROGRESS



- **fb_MoverCtrl():**

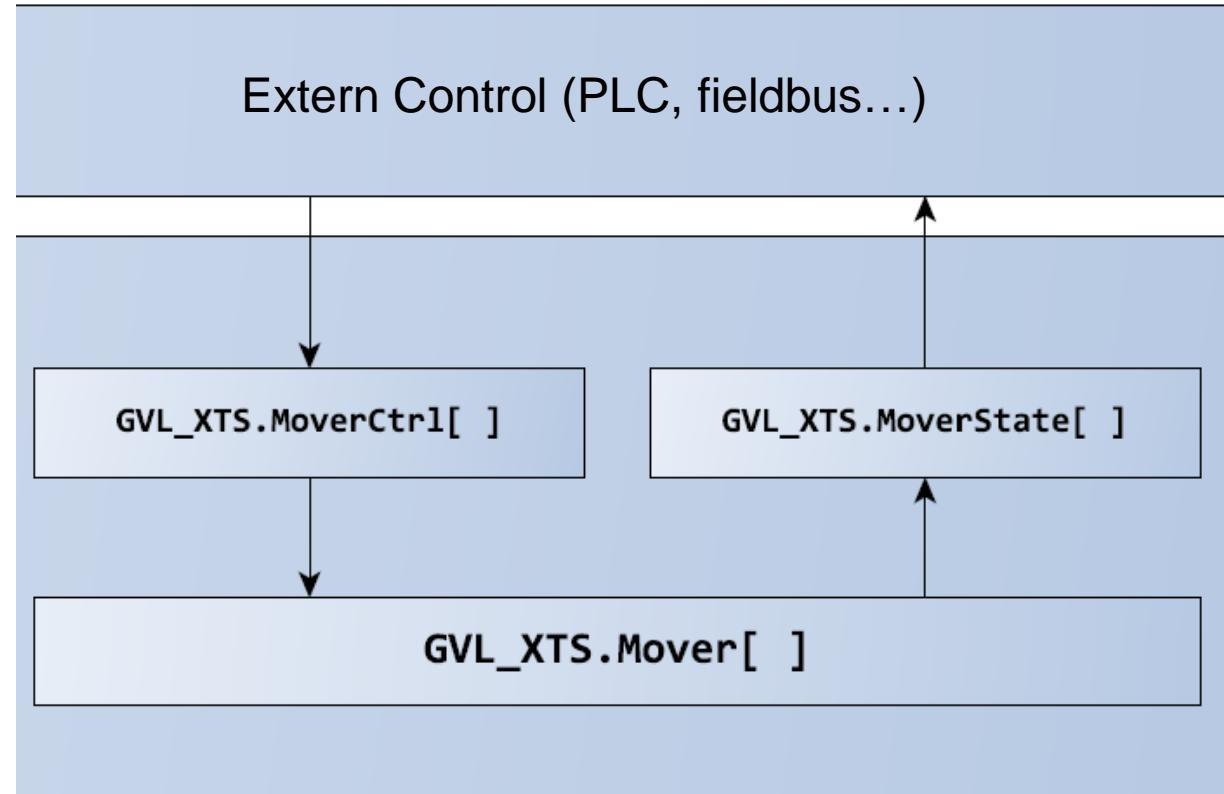
- Requires cyclic call of instance
 - See calls in MAIN() as example
 - OnChange check of Ctrl.Cmd
 - References to Ctrl/State structs
 - References to Mover motion parameter structs
 - State.State feedback:
 - Command enum equivalent + E_PROGRESS



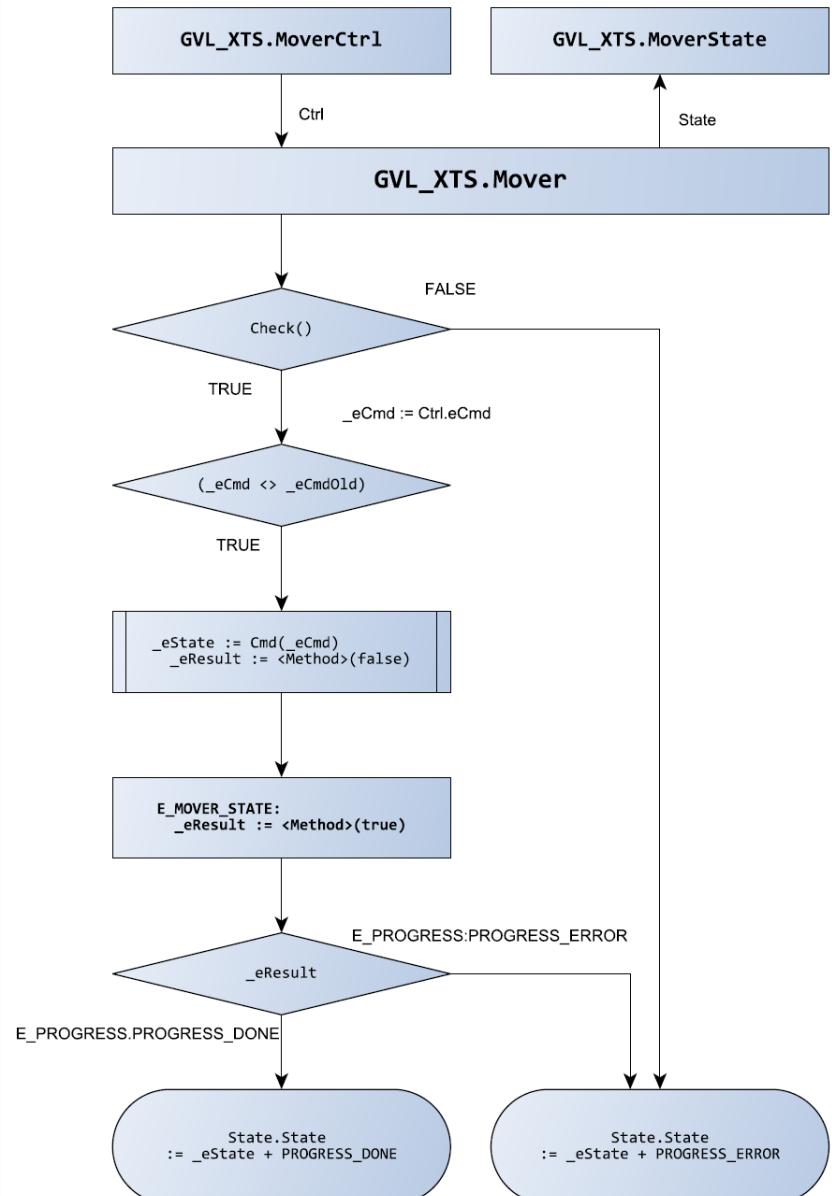
- **fb_MoverCtrl():**
 - Cyclic execution of movement commands
 - OnChange check of Ctrl.Cmd
 - References to Ctrl/State structs
 - References to Mover motion parameter structs

```
21 FUNCTION_BLOCK fb_MoverCtrl EXTENDS fb_Mover
22 VAR
23   // Ctrl and State for executing commands
24   _stCtrl      : REFERENCE TO ARRAY[1..MAX_MOVER] OF ST_MOVER_CTRL;
25   _stState     : REFERENCE TO ARRAY[1..MAX_MOVER] OF ST_MOVER_STATE;
26
27   // data structures to use with commands
28   _stMoveData  : REFERENCE TO ARRAY[1..MAX_MOVER] OF ST_MOVE_DATA;
29   _stGearData  : REFERENCE TO ARRAY[1..MAX_MOVER] OF ST_GEAR_DATA;
30
31   _eCmd,
32   _eCmdOld     : E_MOVER_CTRL;
33
34   _eState       : E_MOVER_STATE;
35
36   _eResult      : E_PROGRESS;
37 END_VAR
38
39
40 IF NOT Check() THEN RETURN; END_IF
41
42 _stMsg.eDevice          := e_Device.Mover + _nMoverId;
43
44 // copy to local for debug
45 _eCmd                   := _stCtrl[_nMoverId].Cmd;
46
47 // cyclic check for command change
48 // get state for cmd
49 IF (_eCmd <> _eCmdOld)
50 THEN
51   // get matching sstate for Ctrl.Cmd
52   _eState                := Cmd(_eCmd);
53   _eCmdOld                := _eCmd;
54 END_IF
```

- **fb_MoverCtrl():**
 - Control structure
 - ST_MOVER_CTRL
 - State structure
 - ST_MOVER_STATE
 - Ctrl/State structs are used to address mover
 - Parameter structures are to be used according to the job you want to give to the mover
 - ST_MOVE_DATA
 - ST_GEAR_DATA
 - Mover information:
 - ST_MOVER_INFO



- **fb_MoverCtrl():**
 - **ST_MOVER_CTRL / ST_MOVER_STATE**
 - Command
 - State + Progress
 - See doc folder for flow chart



- **fb_MoverCtrl():**
 - **ST_MOVE_DATA**
 - Parameter struct for motion commands

```
XTS_TRANSPORT ♦ ST_MOVE_DATA ♦ X TC_XTS_BASE
1 {attribute 'pack_mode' := '2'}
2 TYPE ST_MOVE_DATA :
3 STRUCT
4 // HAUD 2024 03 14
5 // some init data added for example
6 rPos          : LREAL := 2275.0;
7 rVelo         : LREAL := 500.0;
8 rAcc          : LREAL := 5000.0;
9 rJerk         : LREAL := 500000.0;
10 rGap          : LREAL := 100.0;
11 rOverride    : LREAL := 100.0;
12 rDelta        : LREAL := 0.05;
13 rDistance    : LREAL := 25.0;
14 END_STRUCT
15 END_TYPE
16
```

- **fb_MoverCtrl():**
 - **ST_GEAR_DATA**
 - Parameter struct for motion commands
 - E_MOVER_CTRL.MOVER_GEAR_IN
 - E_MOVER_CTRL.MOVER_GEAR_OUT
 - E_MOVER_CTRL.MOVER_GEAR_IN_POS_CA

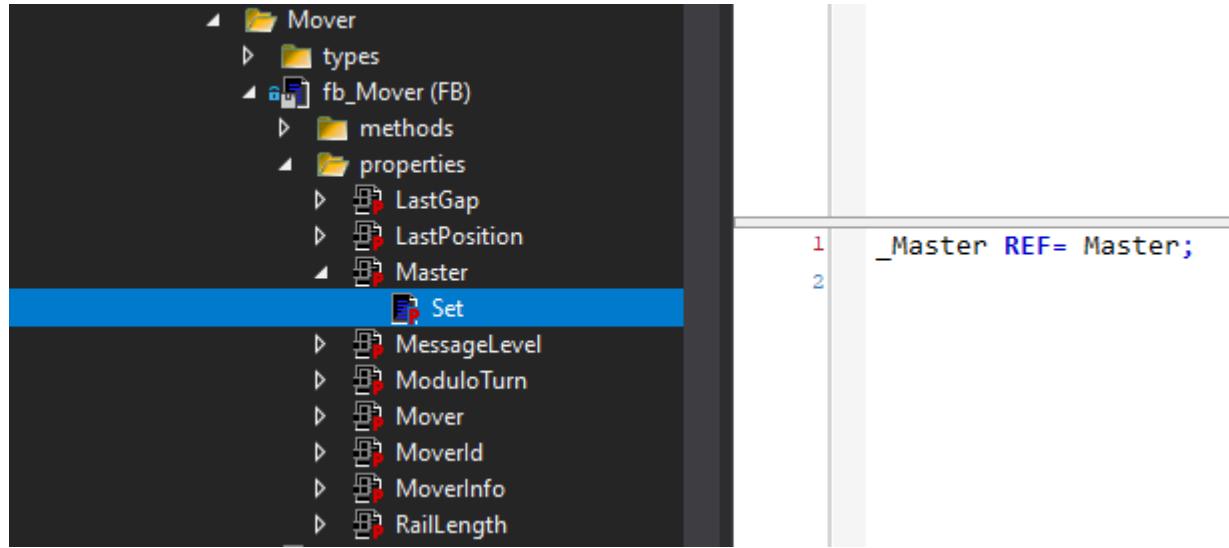
```
XTS_TRANSPORT # ST_GEAR_DATA # X E_MOVER_CTRL
1 {attribute 'pack_mode' := '2'}
2 TYPE ST_GEAR_DATA :
3 STRUCT
4     rDeltaToMasterPos      : LREAL;
5     rModuloSyncPosSlave   : LREAL;
6     rMasterStartDistance  : LREAL;
7     rGearNumerator        : LREAL;
8     iGearDenumerator      : USINT
9 END_STRUCT
10 END_TYPE
11
```

- **fb_MoverCtrl():**
 - **ST_GEAR_DATA**
 - Reference to MasterAxis
 - local var ‘_Master’ must be valid reference
 - Base class contains property to link AXIS_REF of master axis to fb_Mover

```
XTS_TRANSPORT # fb_Mover # X fb_Mover.Master ST_GEAR_DATA E_MOVER_CTRL ST_MOVE_DATA
20 //-----
21 FUNCTION_BLOCK fb_Mover IMPLEMENTS I_XtsTransport_Mover
22 VAR
23     _nMoverId      : UINT;
24
25     _sState        : STRING;
26
27     _Master,
28     _Mover         : REFERENCE TO AXIS_REF;
29     _rLastPosition : REFERENCE TO LREAL;
30     _rLastGap      : REFERENCE TO LREAL;
31
32     _RailLength    : LREAL;
33     _nSyncStrategy : Tc3_Mc3Definitions.MC_SYNC_STRATEGY := Tc3_Mc3Definitions.MC
34
35     // mover compact axis information
36     _stInfo        : REFERENCE TO ST_MOVER_INFO; // ActPos, Enable, ...
37
38     _bError        : BOOL;    // used in Cycle()
```

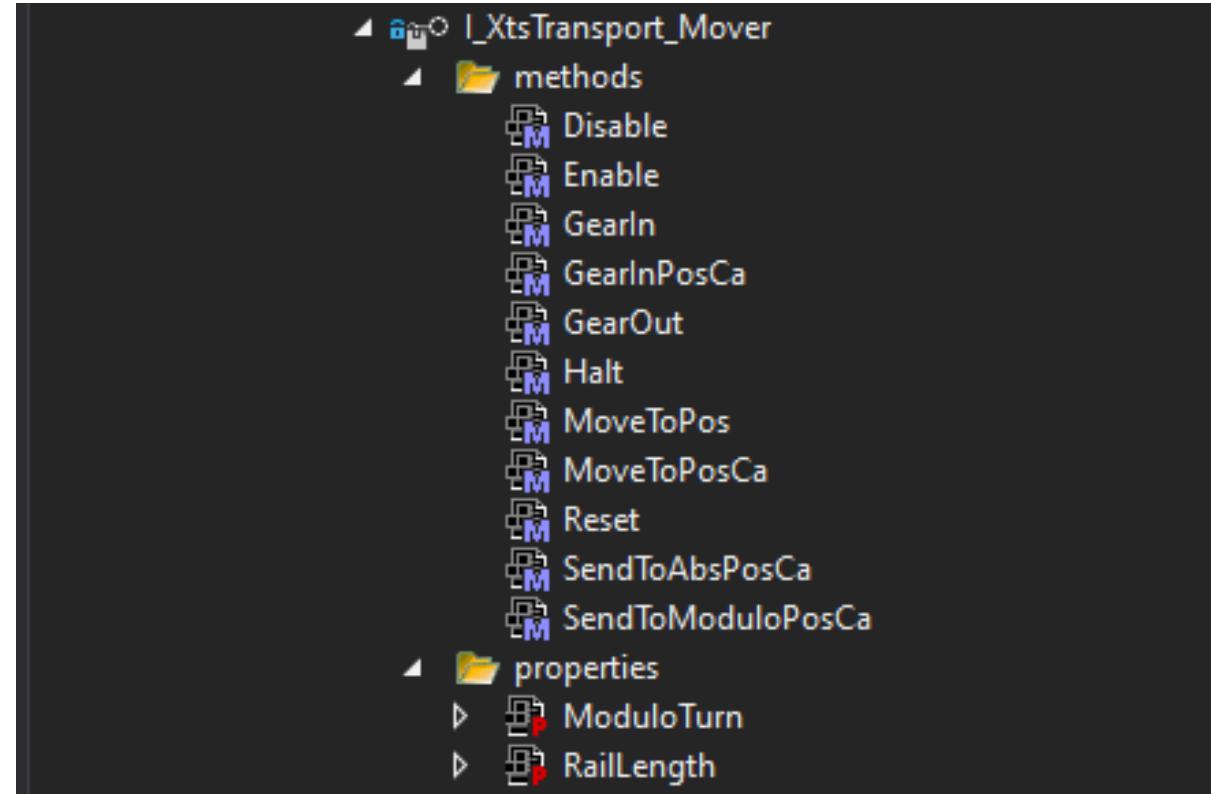
- **fb_MoverCtrl():**

- **ST_GEAR_DATA**
 - Reference to MasterAxis
 - local var '_Master' must be valid reference
 - Base class contains property to link AXIS_REF of master axis to Mover
 - Property you have to set before / on use of gearing motion function



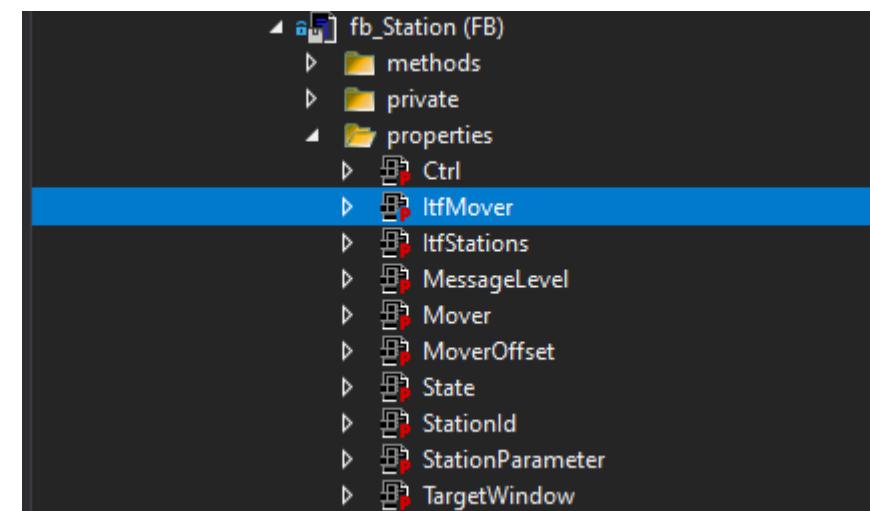
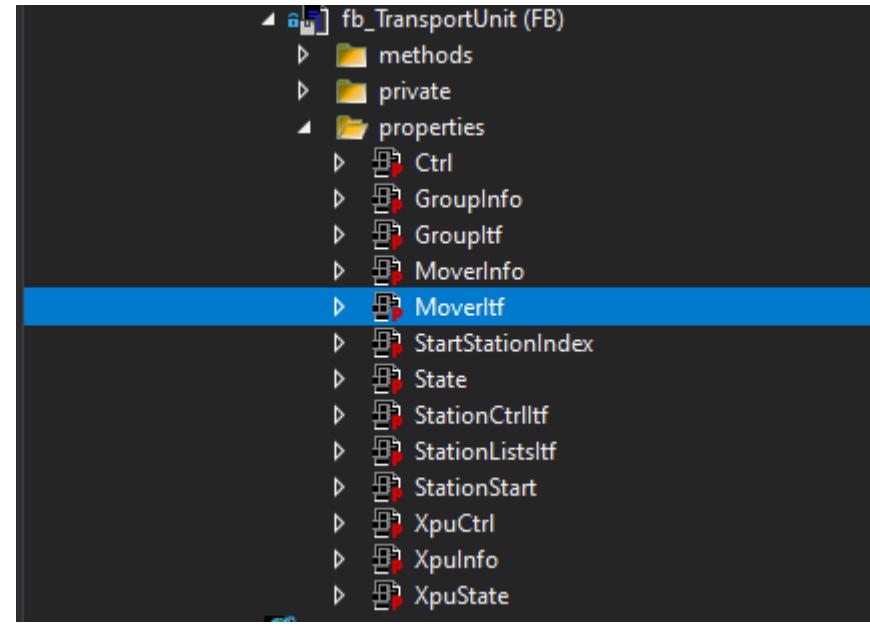
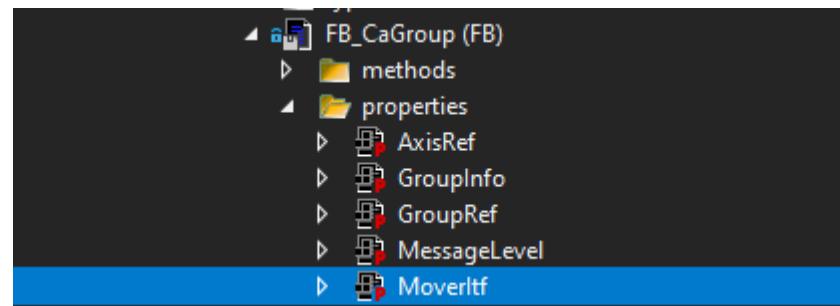
- **I_Transport_Mover:**

- Interface for use in other classes
 - Fb_TransportUnit
 - Fb_CaGroup
 - Fb_Station
 - Interface is implemented by fb_Mover



- **I_Transport_Mover:**

- Used in Property by other classes



XTS_TRANSPORT_LAYER project

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