

GVL_XTS.Station[StationId].Cycle()

Example_1: handshake for a mover with only 1 required stop; only 1 nest (PosStop[1])

- init was already done at machine startup
- default state after STATION_INIT is STATION_DISABLE
- check states are not displayed here
- only the states you have to handshake are displayed
- error handling, you find in other flow charts in the [doc] folder
- Ctrl[StationId].nTargetStation must be set by you before releasing the mover!

