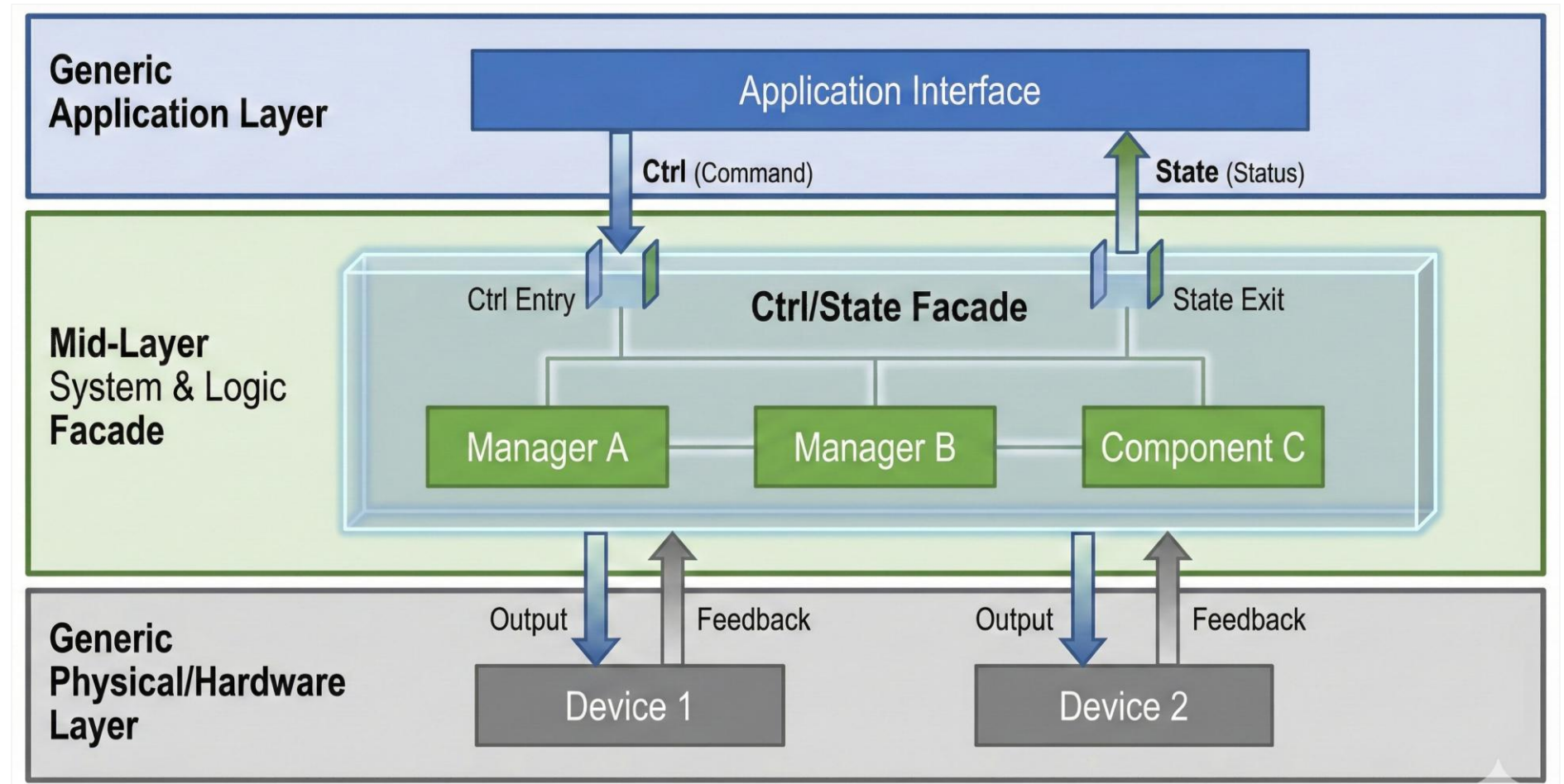


1. Motivation
2. Design



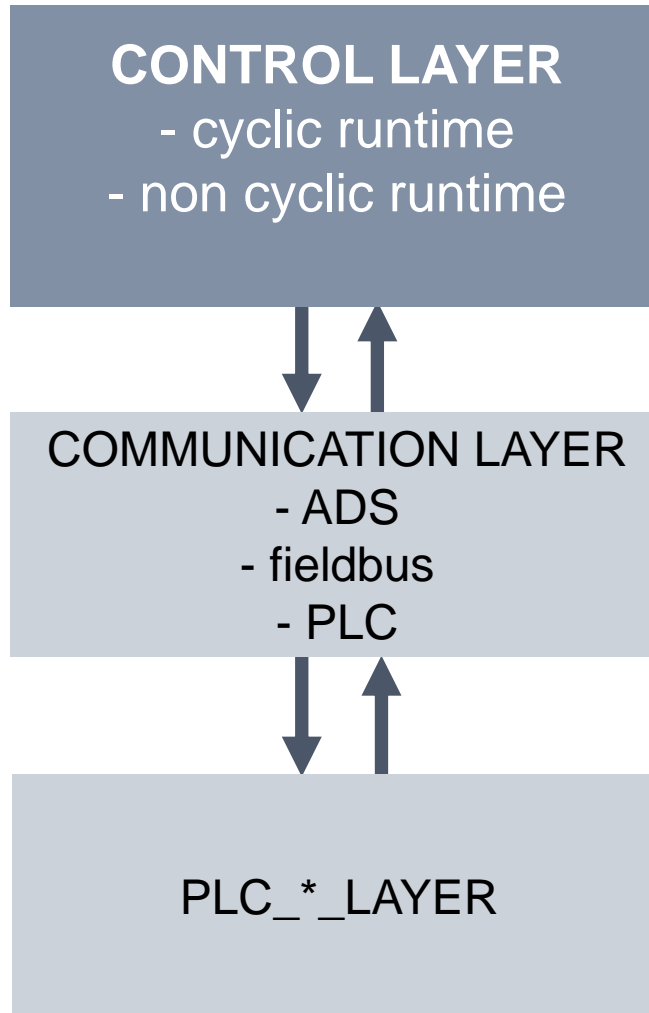
## ■ Motivation

- Unified means of communication between entities
  - Higher level logic is preserved and shielded from lower-level changes
- Agnostic to means of communication
  - Datafields are mappable to any cyclic or non-cyclic information transport
    - Hard real time, TCP/IP, ADS
- Asynchronous, Atomic flow of information
  - Class instances are communicating via LinkedList implementation
- Reducing software latency
  - Sequential case execution enables zero frame latency
  - LinkedList implementation enables atomic information transport
    - Information arrives ahead of state of the physical layer
- Message-System with narrative syntax
  - Use of enumerations enables logs that are instantly readable for the human eye

## ▪ Design

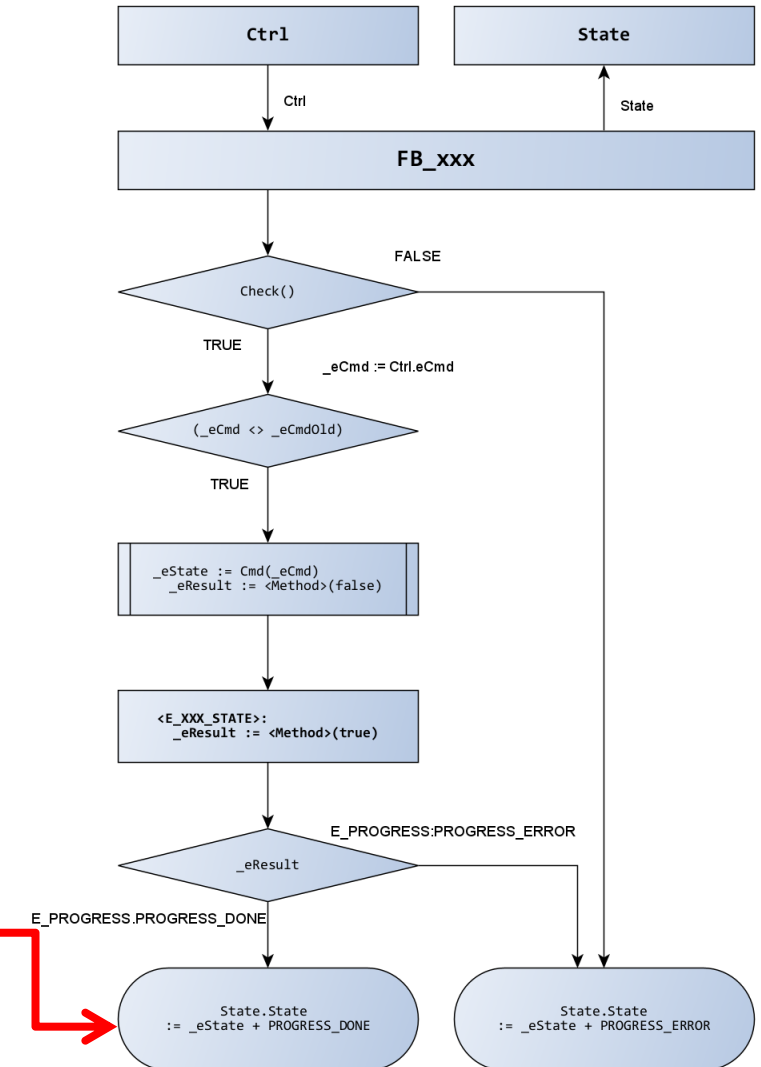
- Compliant to SOLID and ACID principles
  - Built in self similarity of approach enables fractal design choices
  - Due to strong Separation of Concerns the layered approach is suitable for distributed HRT systems
- Encapsulated state machines with generic pattern
  - Generic pattern is applicable to existing code segments
    - Code segments may be reused.
  - Generic pattern enables secure execution
    - State isolation enables to prevent race conditions on a structural level
- Use of base classes with cyclic wrappers (Ctrl/state)
- Cross communication via Interface pointers

- **Design:**
- Transparency of communication layer
- Code base shall remain independent of control layer
- Configurable Options for specific libraries / TC functions
- Balanced load for configurable options in machine layout
- Stable cpu use for XFC applications

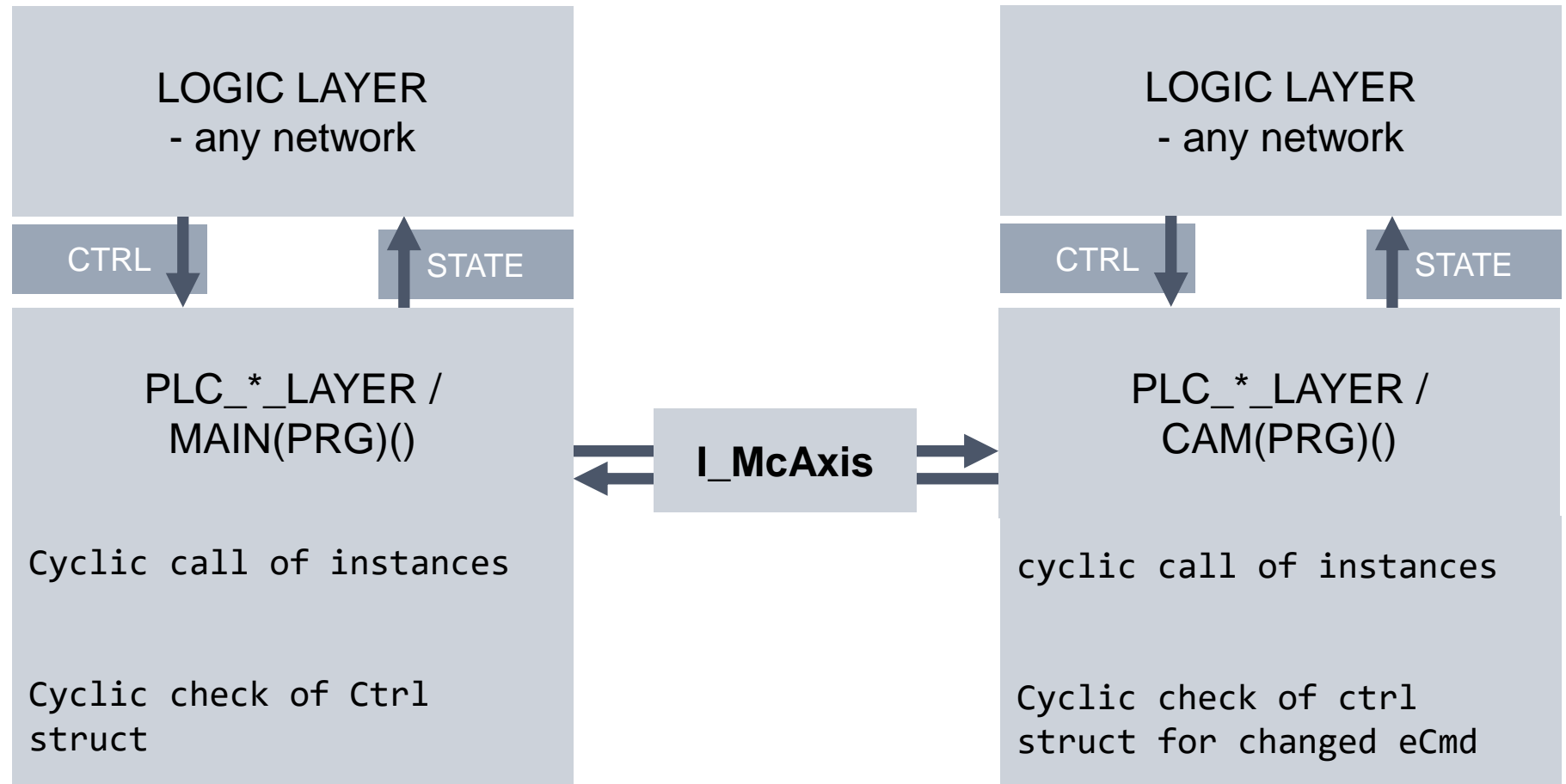


## ■ Design:

- State / Ctrl structures
  - Establishes unified access
  - Commands can simply be 'dropped' into Ctrl datafield
    - Enables asynchronous communication with PLC\_\*\_LAYER (e.g. C# via ADS, C/C++ via ADS, ADS over MQTT, ...)
    - Enables cyclic communication with PLC\_\*\_LAYER since structures can easily be mapped onto any cyclic fieldbus TwinCAT supports (EtherCAT, Profinet, CanOpen, EAP, ...)
  - State is updated by PLC\_\*\_LAYER, so you can move on doing other stuff, come back and check completion/error.
- State feedback for cyclic class wrappers
  - **Always** combined with E\_PROGRESS
    - You can filter your response by a simple modulo division
      - The result may be your entry point for your reaction to State.



## ▪ Software Design Example: Separation of Concerns



## ▪ SOLID DESIGN

- **S — Single Responsibility Principle**
  - a class should have one, and only one, reason to change.
- **O — Open/Closed Principle**
  - software entities should be open for extension but closed for modification.
- **L — Liskov Substitution Principle**
  - Objects of a superclass shall be replaceable with objects of its subclasses without breaking the application.
- **I — Interface Segregation Principle**
  - users should not be forced to depend upon interfaces that they do not use.
    - a software entity only sees the methods it actually needs to the work.
- **D — Dependency Inversion Principle**
  - Depend upon abstractions, not concretions.



## ▪ ACID DESIGN

- **A — Atomicity**
  - A transaction is an "all-or-nothing" unit of work.
- **C — Consistency**
  - A transaction must bring the system from one valid state to another valid state.
- **I — Isolation**
  - Concurrent transactions should not interfere with each other.
- **D — Durability**
  - Once a transaction has been committed, it will remain so, even in the event of power loss, crashes, or errors.