

GVL_XTS.Station[StationId].Cycle()

- Example_1: handshake for a mover with only 1 required stop; only 1 nest (PosStop[1])
- init was already done at machine startup
 - default state after STATION_INIT is STATION_DISABLE
 - check states are not displayed here
 - only the states you have to handshake are displayed
 - error handling, you find in other flow charts in the [doc] folder
 - Ctrl[StationId].nTargetStation must be set by you before releasing the mover!

