



Agenda | XTS- Assembly

- 1. XTS-StarterKit
- Preparation and Assembly
- 3. First Test
- 4. Rail mounting
- 5. Rerailing of Mover





XTS StarterKit

- AT2000-0500 starter kit small, 500 mm straight length
- AT2000-1000
 starter kit medium, 1000 mm straight length
- AT2000-1500
 starter kit large, 1500 mm straight length



Agenda | XTS- Assembly

- 1. XTS-StarterKit
- 2. Preparation and Assembly
- 3. First Test
- 4. Rail mounting
- 5. Rerailing of Mover



- Insert all pins on the bottom side of the frame
- Insert the pins to the rail
- Insert the pins to the neighbor modules
 - > 4x D5x10 A2 DIN 7
 - > 1x D5x30 A2 DIN 7



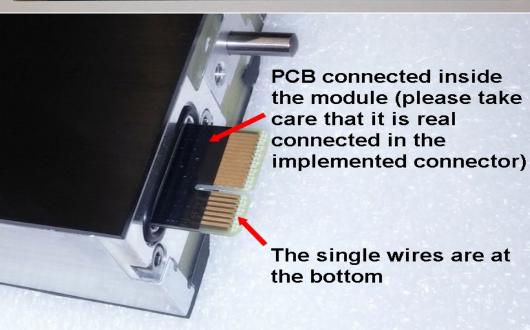




Prepare the XTS Modules

- Insert O-ring (as sealing) on the side of the module
- Insert the connection PCB



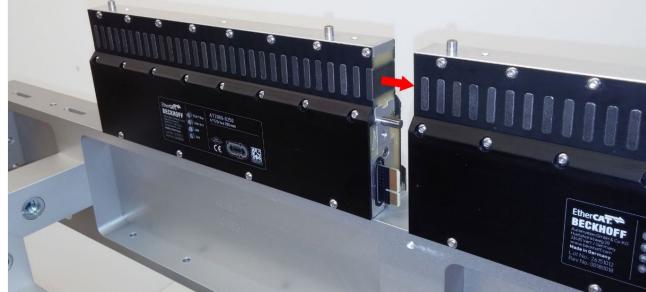




Module frame mounting

- Beginning with the straight infeed module
- Following with all other straights from both sides of the frame
- The electrical connection is done by sliding the connection PCB in the neighbouring module





Fix the modules with

> Screw M5x20 Cyl. A2 DIN 912

➤ Washer M5 A2 DIN 9021

Do not tighten the screws to allow for adjustment of the modules



- Mount the curve modules last
- The curves will meet the straights as you tighten the screws to the frame
 - > 1 x Pin D5x30 A2 DIN 7
 - > 3 (2)x Pin D5x10 A2 DIN 7
 - > (1) x Pin D5x8 A2 DIN 7 \rightarrow lower HW28
 - > 1 x O-ring (as sealing)
 - > 1 x Connection PCB
 - > Screw M5x30 Cyl. A2 DIN 912 &
 - ➤ Washer M5 A2 DIN 9021

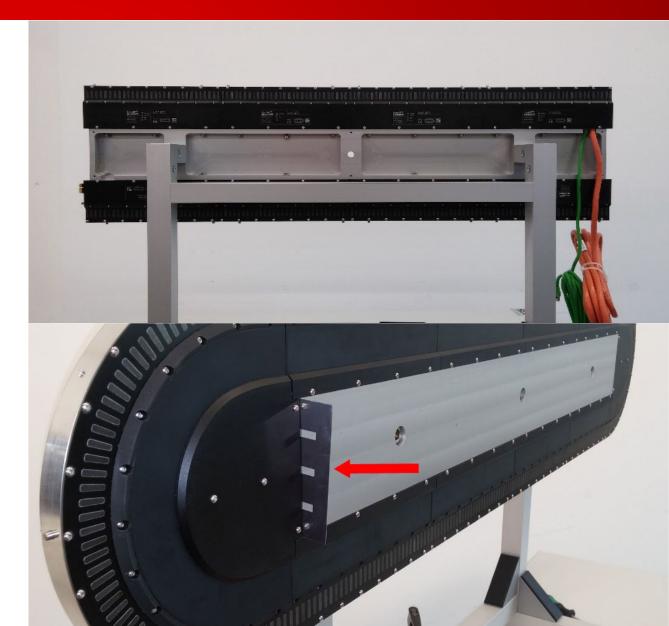


- insert 1mm aluminum sheet at one side
 - Only before HW..

HW03 at 0.5m

HW02 at 1.0m

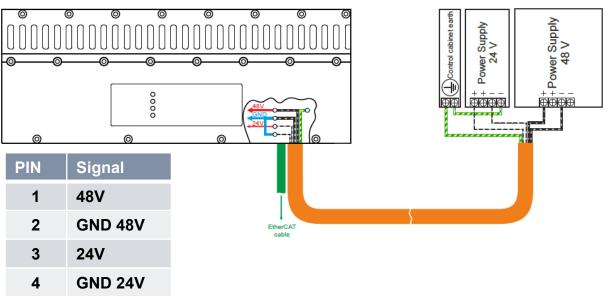
HW02 at 1.5m



 Pin out of the infeed module as labelled on the name plate and cable

Connect EtherCAT to the IPC or CU2508





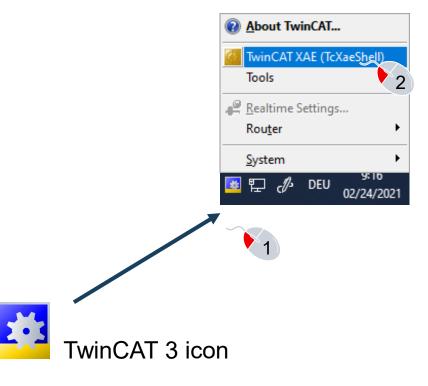
Agenda | XTS- Assembly

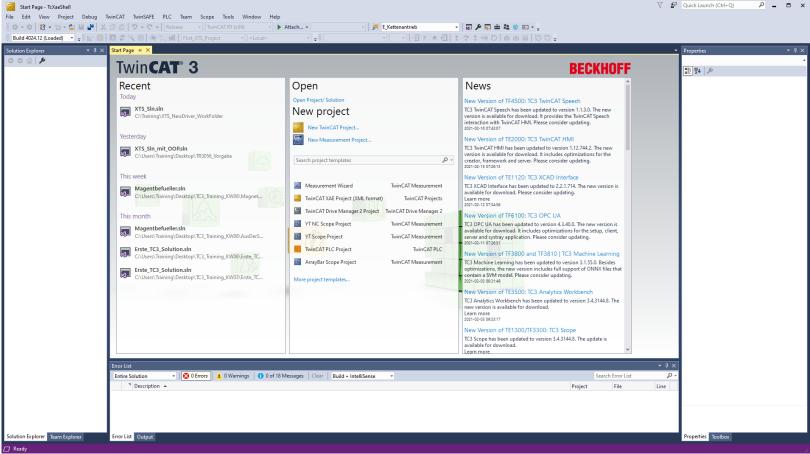
- 1. XTS-StarterKit
- Preparation and Assembly
- 3. First Test
- 4. Rail mounting
- 5. Rerailing of Mover



HardWare Scan | Opening a TC3 solution

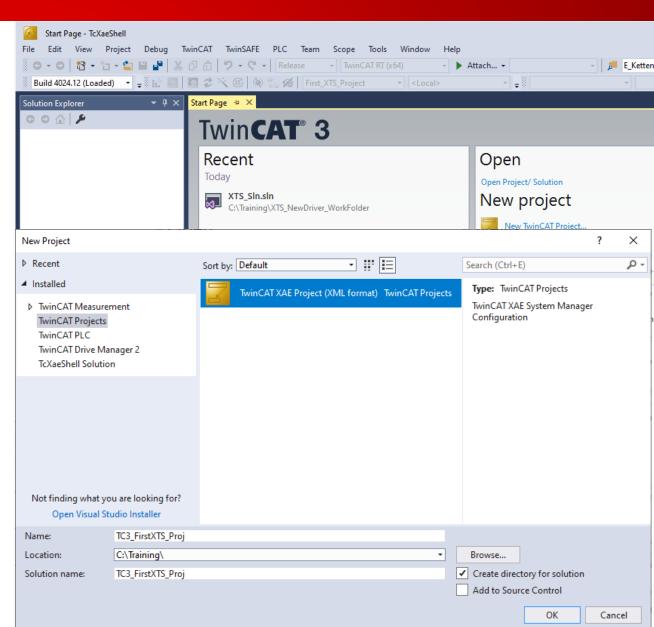
 TwinCAT 3 Engineering (XAE) is started via the TwinCAT icon.





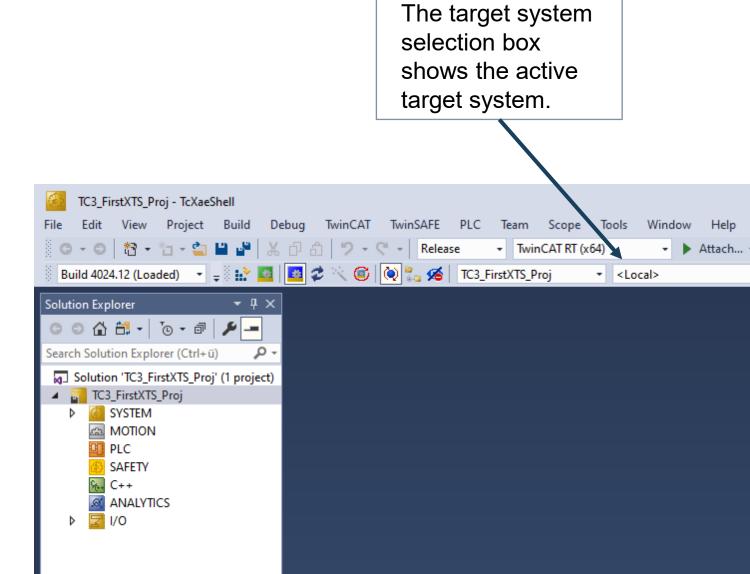
HardWare Scan | Creating a new project

- Create a new project via the start page or the New Project icon.
- Select a project name and storage location and confirm with OK.



HardWare Scan | change to target system

- When a new project is created,
- the local target system "<Local>" is automatically selected.
- Change to your XTS target system



HardWare Scan | Scan HW-devices

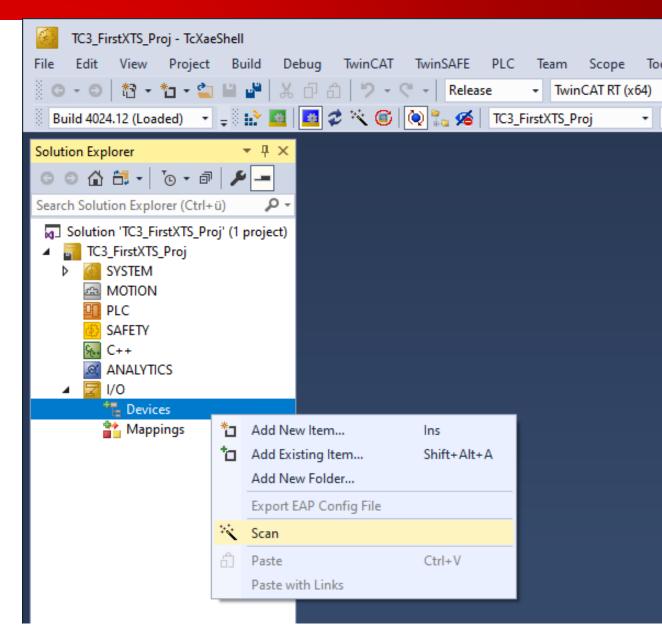
BECKHOFF

- The devices connected to the target system can be scanned.
 i.e. the fieldbus connections or the devicespecific modules such as the Novram in the IPC
- In the Solution Explorer, right-click on "Devices" under I/O and select



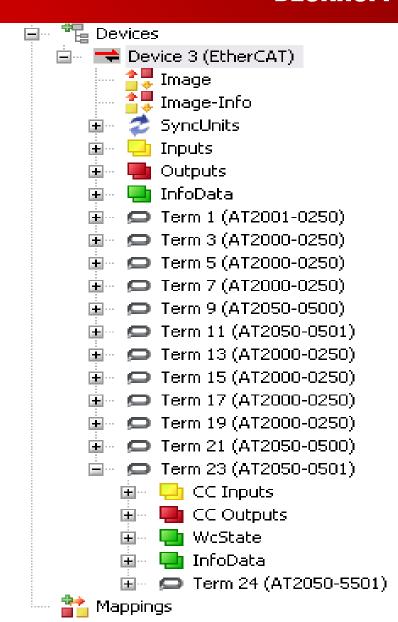


A device scan is only possible from a target system that is in Config mode.



HardWare Scan | found HW-devices

- Once the scan has been completed all the hardware should have been found
- The first module is the straight section infeed module.
 - AT2001-0250
- Each module includes
 - a motor module (AT200X-0250 or AT2050-0500)
 - and a sensor lines(AT200X-5250 or AT2050-5501



Agenda | XTS- Assembly

- 1. XTS-StarterKit
- Preparation and Assembly
- 3. First Test
- 4. Rail mounting
- 5. Rerailing of Mover



Rail module mounting

 Screw the rail onto the system, beginning with the straight and finish with the two curves

> Screw M4x40 Cyl. A2 DIN 912

Do not tighten the screws to allow for adjustment of the rail



Rail module mounting

Important:

If the transition between straight and curve does not fit well it may push out the pin between straight and curve rail.

Important:

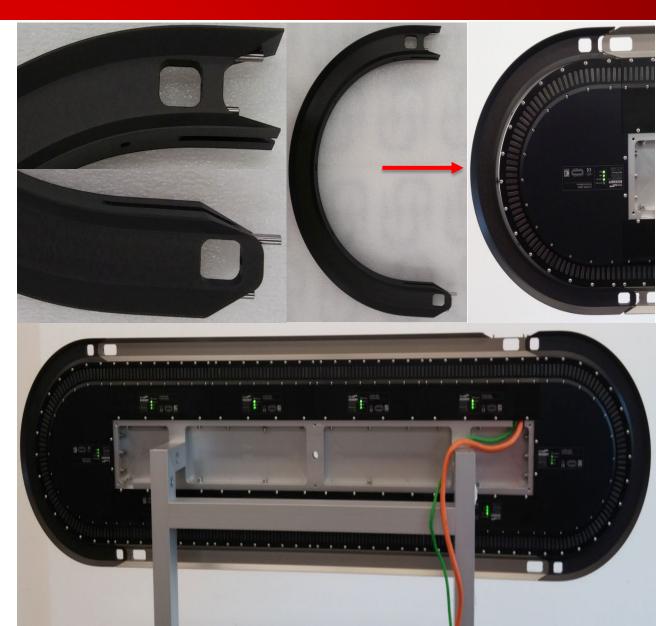
If the pins between curve rail and curve motor module will not fit you may leave them out

Do not tighten the screws to allow for adjustment of the rail



Construction after mounting the straight rails

➢ Pin D4x16 A2 DIN 7

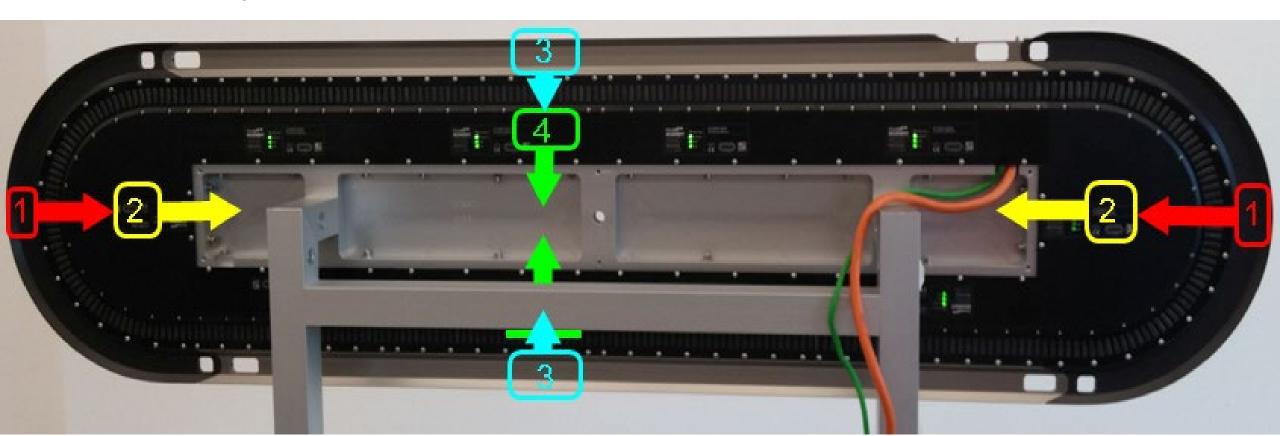


Rail module mounting

Now tighten the screws to the specified torque in this sequence:

▼ 1st - two curved rails with	2x 4 Screw M4x40	4Nm
▼ 2nd - two curved motor modules with	2x 3 Screw M5x30	6Nm

▼ 3rd - the straight rails with 22x Screw M4x40 4Nm



Agenda | XTS- Assembly

- 1. XTS-StarterKit
- Preparation and Assembly
- 3. First Test
- 4. Rail mounting
- 5. Rerailing of Mover



Construction after mounting the curved rails

Close the red auxiliary lock cover

➢ Pin D4x12 A2 DIN 7

> Screw M4x10 Cyl. A2 DIN 91

Important:Don't forget the pins for the gate





Construction after mounting the curved rails

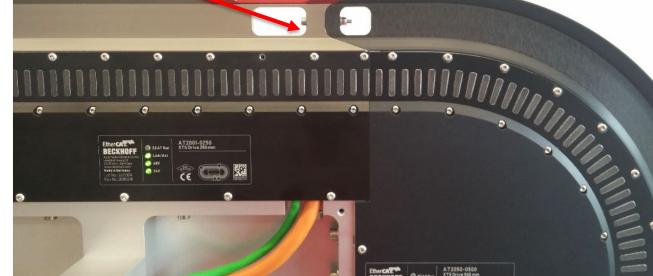
Connect curved and straight rail

> Screw M3x30 A2 DIN 912

➤ Washer M3x30 A2 DIN 125

Important:Don't forget the screws for connecting



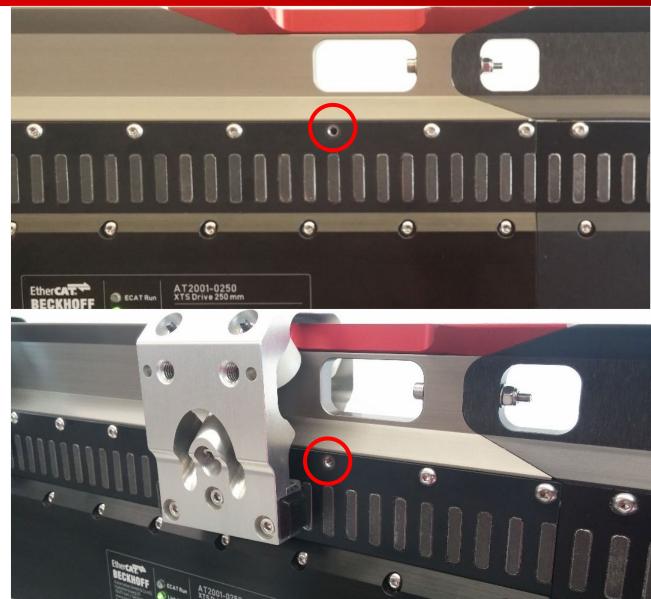


 It may be necessary to remove on motor module screw for easy insertion of the mover (lower HW22)

Insert the Mover

> Attention:

The encoder flag should be on the same side as the XTS sensor (not the side of the name plate and LEDs)



 Remove the red auxiliary lock cover to replace the lock cover again,

➢ Pin D4x12 A2 DIN 7

> Screw M4x10 Cyl. A2 DIN 91

Important:Don't forget the pins for the gate





XTS | New Freedom in Machine Building



This training material is provided to complement the presented training content. Outside the actual training the material may only be used for internal purposes at the company of the course participant. In addition, the material or extracts thereof may be used in end customer training for products containing Beckhoff products, or for presentations, provided the presentation refers to Beckhoff products. Extracts or copies of the training material must contain the following copyright acknowledgement: "© Beckhoff Automation GmbH & Co. KG".

The same applies to extracts from presentation material. The user of the material is solely responsible for the completeness of extracts and copies. It is explicitly not permitted to offer commercial or free training for Beckhoff products. This applies to training with and or without the training material. The training material must not be edited, manipulated or modified.

Passing on of the aforementioned rights to third parties is not permitted.

Beckhoff Automation GmbH & Co. KG

Contact BECKHOFF

Beckhoff Automation GmbH & Co. KG

Headquarters
Huelshorstweg 20
33415 Verl
Germany

Phone: +49 5246 963-0

E-mail: info@beckhoff.com

Web: www.beckhoff.com

© Beckhoff Automation GmbH & Co. KG 02/2021

All images are protected by copyright. The use and transfer to third parties is not permitted.

Beckhoff®, TwinCAT®, EtherCAT G®, EtherCAT G10®, EtherCAT P®, Safety over EtherCAT®, TwinSAFE®, XFC®, XTS® and XPlanar® are registered trademarks of and licensed by Beckhoff Automation GmbH. Other designations used in this publication may be trademarks whose use by third parties for their own purposes could violate the rights of the owners.

The information provided in this presentation contains merely general descriptions or characteristics of performance which in case of actual application do not always apply as described or which may change as a result of further development of the products. An obligation to provide the respective characteristics shall only exist if expressively agreed in the terms of contract.