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# Benchmarking tree species classification with synthetic data and deep learning

State of the art and plan for Scalable Computing Systems and Applications in  
AI, Big Data and HPC

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# Why is it important to benchmark the training process of neural networks?

Training speed

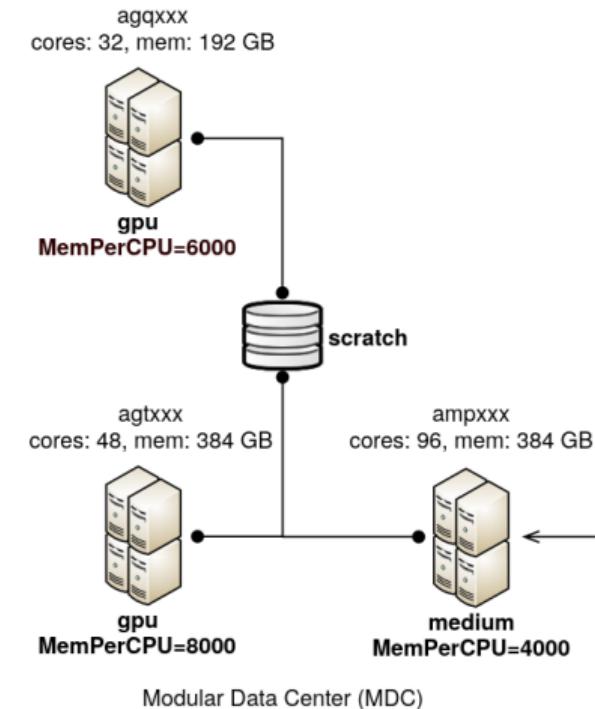


Energy efficiency



# Training speed ⏲

- training of neural networks is computationally intensive
- ↪ workflow needs to be optimized for available hardware
  - ▶ How to make good use of clusters with heterogenous hardware?
  - ▶ How many GPUs are worth requesting?
- ⇒ optimization for available accelerators is critical in ML/DL



Structure and resources of a part of the Scientific Compute Cluster.

# Energy efficiency ⚡

- for different neural networks, the required energy ranges from relatively low demands (finetuning) to very high demands (training of a complex network)
- depends on used hardware and energy source
- ⇒ As deep learning is emerging in several fields, the impact on energy consumption and consequently, our climate is growing

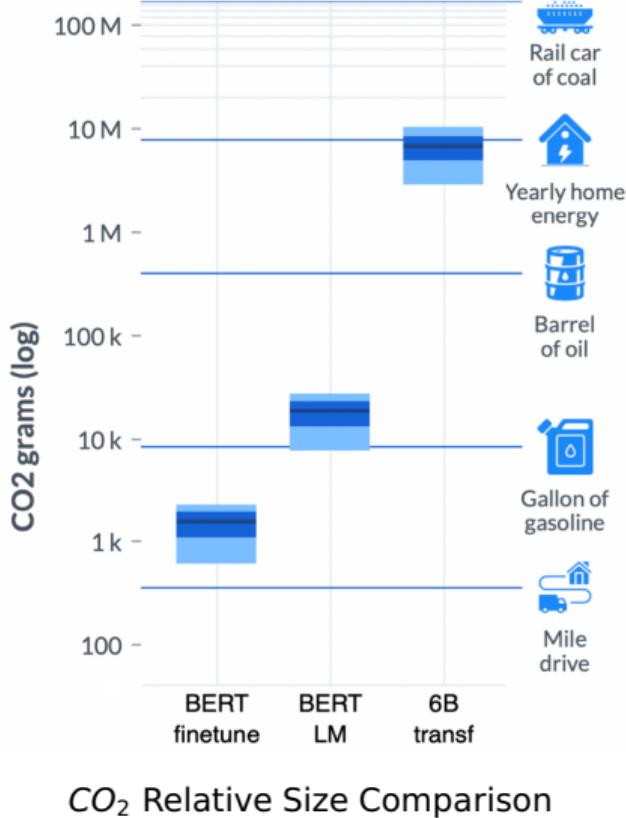


Image source: Adapted from Dodge et al. 2022

# Use case

## Tree species classification from lidar

- monitoring of tree species is essential for forest restructuring towards more resilient forests in changing environments under climate change condition <sup>a</sup>
- lidar is already in use for forest inventories (White et al. 2016)
- Problem: lack of pre-trained models



<sup>a</sup> <https://www.umweltbundesamt.de/angepasster-waldumbau>

Spruce and beech stand close to the national park "Hainich".

Image source: Adapted from Henkel, Hese, and Thiel 2021

# Outline

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# Workflow

## Pre-training with synthetic data

- 1 scene generation with Arbaro<sup>a</sup>
- 2 synthetic lidar data is generated with the lidar operations simulator Helios++ (Esmorís et al. 2022)
- 3 pre-training of PointNet, which is a very popular architecture for point cloud analysis (Qi et al. 2016)

<sup>a</sup><https://github.com/wdiestel/arbaro>

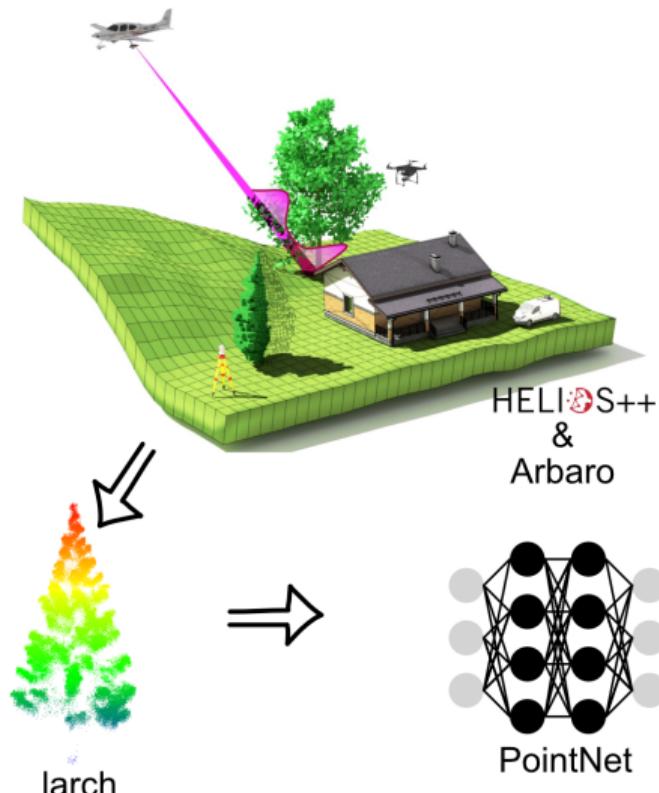


Image source: Adapted from Esmorís et al. 2022

# Metrics

metric	purpose
Execution time	traditionally
FLOPS	
Throughput: $\frac{\text{images}}{\text{sec}}$	with the advent of GPUs
Time to Accuracy (TTA)	
Average Time to	deep learning
Multiple Thresholds (ATTMT)	

Image source: Adapted from [https://snehilverma41.github.io/Metrics\\_ML\\_FastPath19.pdf](https://snehilverma41.github.io/Metrics_ML_FastPath19.pdf)

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# Tools - Overview

tool	metrics	scope
PyTorch Profiler With TensorBoard	performance metrics (e.g. time, memory)	PyTorch
fvcore	FLOPS	
Vtune	general	Intel-only
likwid	performance metrics	general

- ⇒ different tools for different use cases
- ⇒ Vtune and likwid can profile all kind of applications
- ⇒ here I will focus on profiling tools optimized for PyTorch

# PyTorch Profiler With TensorBoard

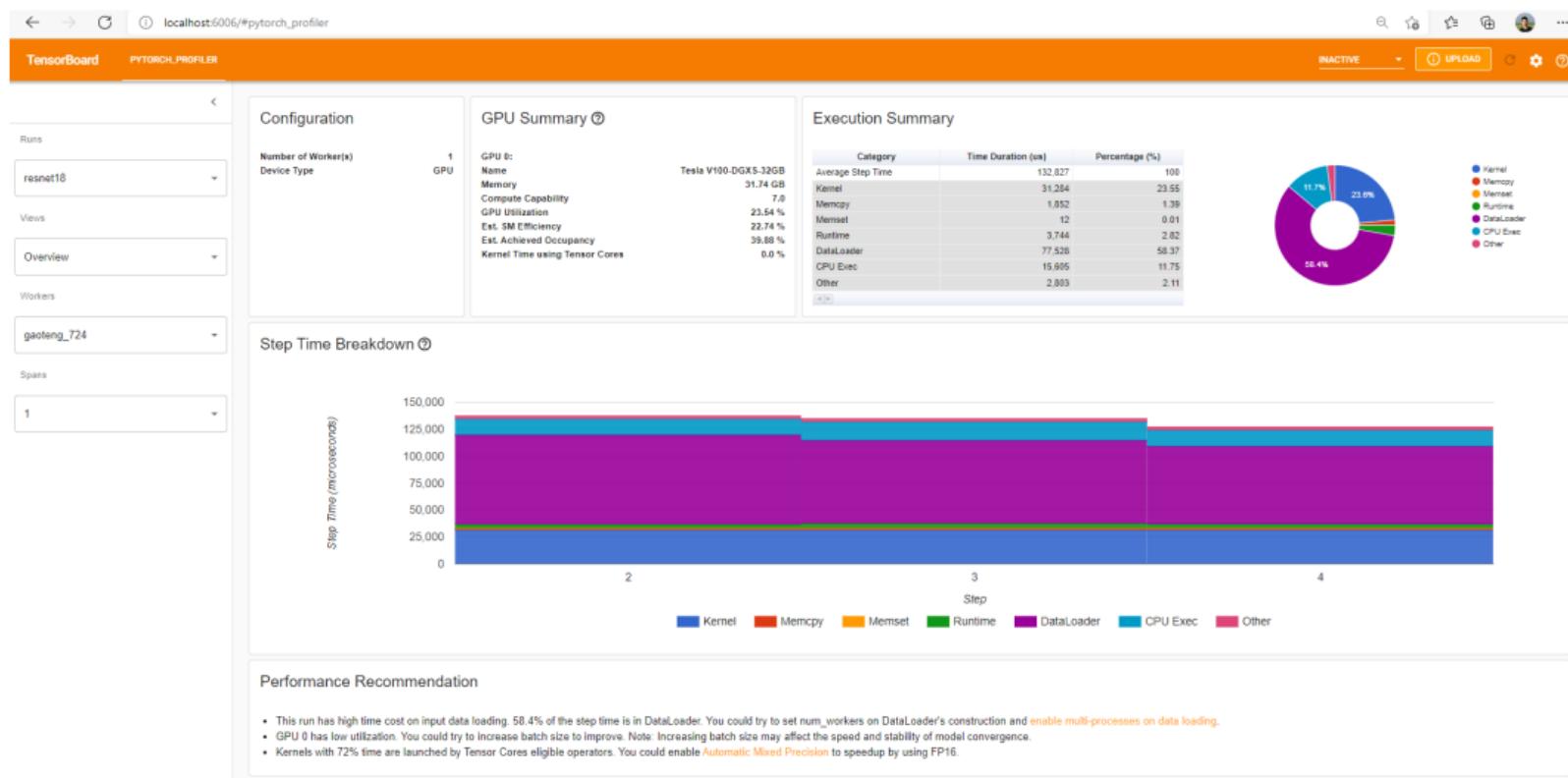


Image source: [https://pytorch.org/tutorials/intermediate/tensorboard\\_profiler\\_tutorial.html](https://pytorch.org/tutorials/intermediate/tensorboard_profiler_tutorial.html), accessed on: 22.11.2022

# PyTorch Profiler With TensorBoard

## GPU Summary ?

**GPU 0:**

Name	Tesla V100-DGXS-32GB
Memory	31.74 GB
Compute Capability	7.0
GPU Utilization	23.54 %
Est. SM Efficiency	22.74 %
Est. Achieved Occupancy	39.88 %
Kernel Time using Tensor Cores	0.0 %

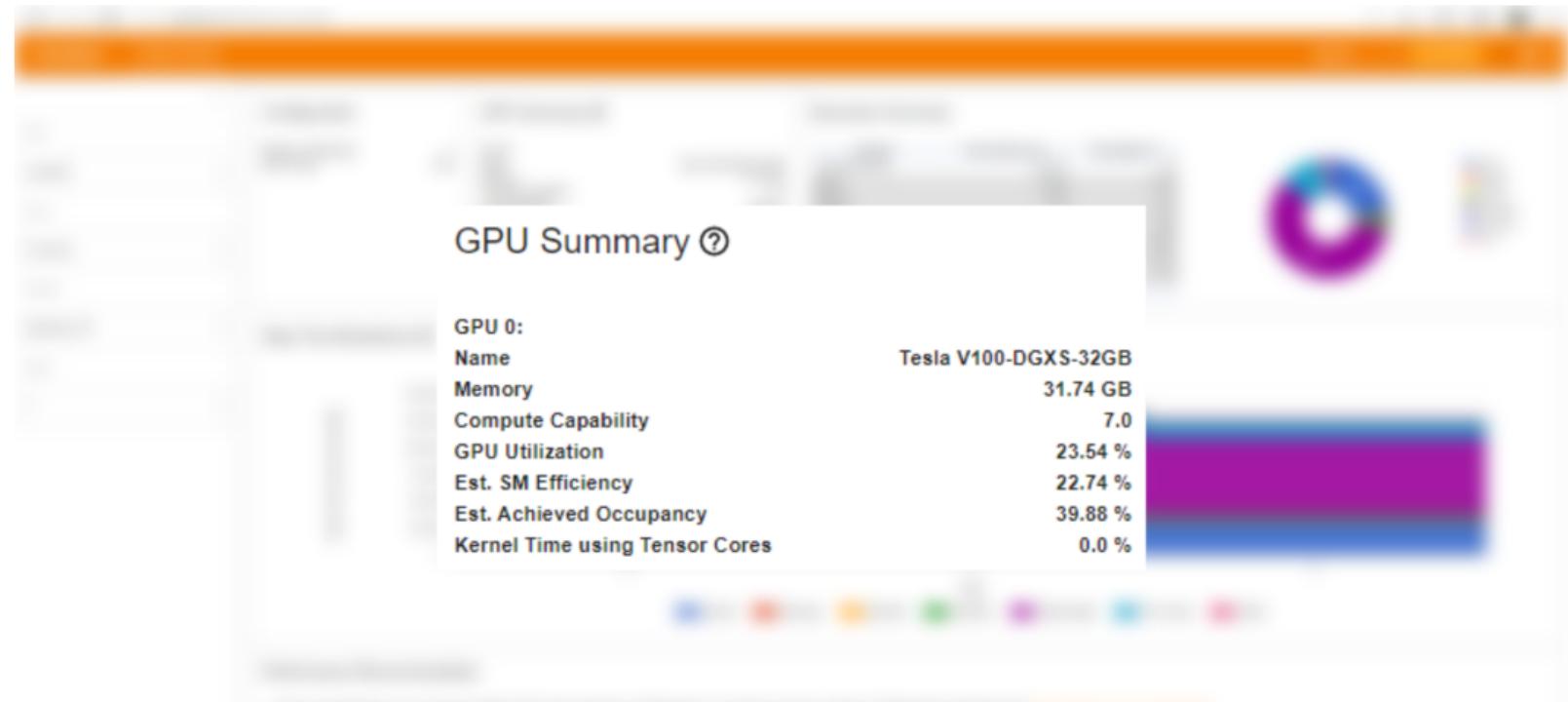
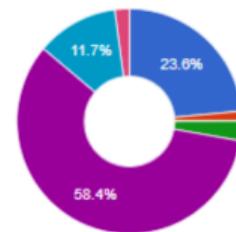


Image source: Adapted from [https://pytorch.org/tutorials/intermediate/tensorboard\\_profiler\\_tutorial.html](https://pytorch.org/tutorials/intermediate/tensorboard_profiler_tutorial.html), accessed on: 22.11.2022

# PyTorch Profiler With TensorBoard

## Execution Summary

Category	Time Duration (us)	Percentage (%)
Average Step Time	132,827	100
Kernel	31,284	23.55
Memcpy	1,852	1.39
Memset	12	0.01
Runtime	3,744	2.82
DataLoader	77,528	58.37
CPU Exec	15,605	11.75
Other	2,803	2.11



- Kernel
- Memcpy
- Memset
- Runtime
- DataLoader
- CPU Exec
- Other

Image source: Adapted from [https://pytorch.org/tutorials/intermediate/tensorboard\\_profiler\\_tutorial.html](https://pytorch.org/tutorials/intermediate/tensorboard_profiler_tutorial.html), accessed on: 22.11.2022

# PyTorch Profiler With TensorBoard

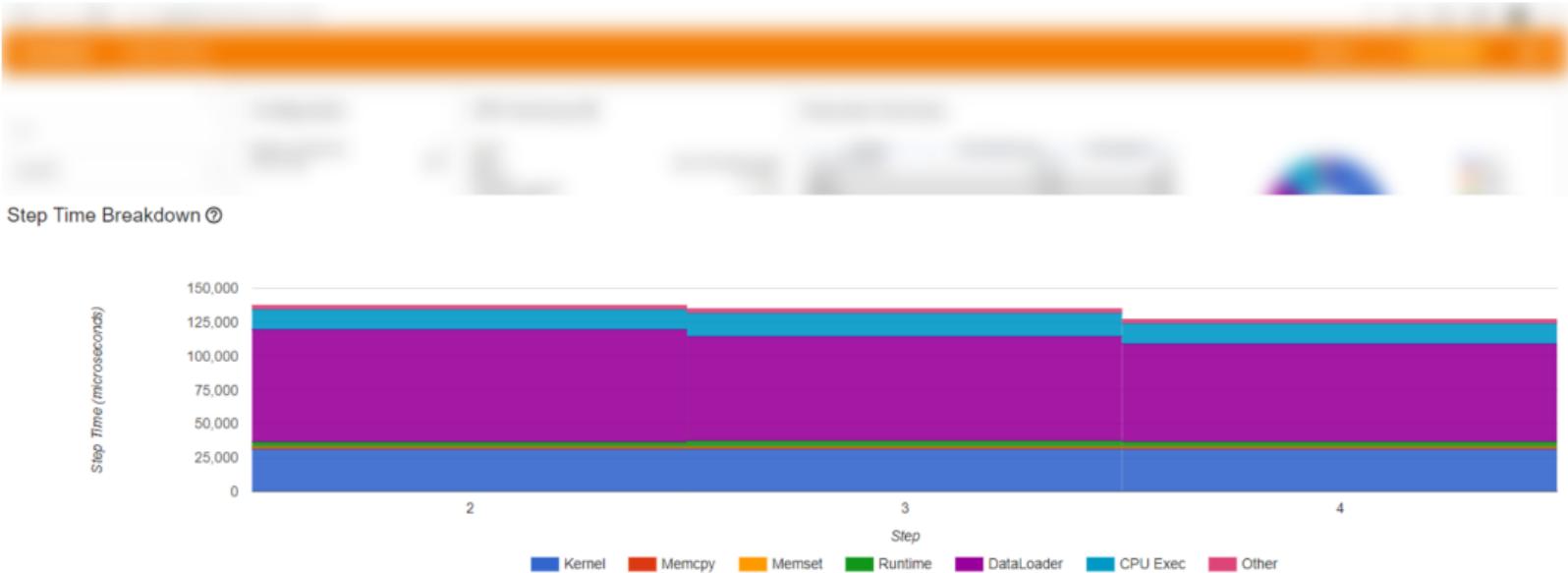


Image source: Adapted from [https://pytorch.org/tutorials/intermediate/tensorboard\\_profiler\\_tutorial.html](https://pytorch.org/tutorials/intermediate/tensorboard_profiler_tutorial.html), accessed on: 22.11.2022

# PyTorch Profiler With TensorBoard

## Performance Recommendation

- This run has high time cost on input data loading. 58.4% of the step time is in DataLoader. You could try to set num\_workers on DataLoader's construction and enable multi-processes on data loading.
- GPU 0 has low utilization. You could try to increase batch size to improve. Note: Increasing batch size may affect the speed and stability of model convergence.
- Kernels with 72% time are launched by Tensor Cores eligible operators. You could enable Automatic Mixed Precision to speedup by using FP16.

Image source: Adapted from [https://pytorch.org/tutorials/intermediate/tensorboard\\_profiler\\_tutorial.html](https://pytorch.org/tutorials/intermediate/tensorboard_profiler_tutorial.html), accessed on: 22.11.2022

# fvcore - Flop Counter for PyTorch Models

```
$ from fvcore.nn import flop_count_table
$ print(flop_count_table(flops))
+-----+-----+-----+
| module | #parameters or shape | #flops |
+-----+-----+-----+
| model  | 81.194K                | 0.275M  |
| conv1   | 60                      | 48.6K   |
| conv1.weight | (6, 1, 3, 3)           |          |
| conv1.bias  | (6,)                   |          |
| conv2    | 0.88K                  | 0.146M  |
| conv2.weight | (16, 6, 3, 3)          |          |
| conv2.bias  | (16,)                  |          |
| fc1      | 69.24K                 | 69.12K  |
| fc1.weight | (120, 576)             |          |
| fc1.bias   | (120,)                 |          |
| fc2      | 10.164K                | 10.08K  |
| fc2.weight | (84, 120)              |          |
| fc2.bias   | (84,)                  |          |
| fc3      | 0.85K                  | 0.84K   |
| fc3.weight | (10, 84)               |          |
| fc3.bias   | (10,)                  |          |
+-----+-----+-----+
```

```
$ from fvcore.nn import flop_count_str
$ print(flop_count_str(flops))
Net(
  #params: 81.19K, #flops: 0.27M
  (conv1): Conv2d(
    1, 6, kernel_size=(3, 3), stride=(1, 1)
    #params: 60, #flops: 48.6K
  )
  (conv2): Conv2d(
    6, 16, kernel_size=(3, 3), stride=(1, 1)
    #params: 0.88K, #flops: 0.15M
  )
  (fc1): Linear(
    in_features=576, out_features=120, bias=True
    #params: 69.24K, #flops: 69.12K
  )
  (fc2): Linear(
    in_features=120, out_features=84, bias=True
    #params: 10.16K, #flops: 10.08K
  )
  (fc3): Linear(
    in_features=84, out_features=10, bias=True
    #params: 0.85K, #flops: 0.84K
  )
)
```

Image source: [https://github.com/facebookresearch/fvcore/blob/main/docs/flop\\_count.md](https://github.com/facebookresearch/fvcore/blob/main/docs/flop_count.md), accessed on: 22.11.2022

# Research Goals

- Identify **profiling tools** that can help to **optimize an existing PyTorch workflow**.
- As this approach should help scientists, the **usability is of high importance**. The simplest tool for doing the job is preferred.
- In contrast to training benchmark suites, such as MLPerf, I do not focus on benchmarking hardware but on optimizing an existing PyTorch workflow (viewpoint of a scientist)

# Benchmarking is the first step of optimizing



Image generated with stable diffusion:

"Sherlock Holmes locates the best graphical processing unit inside the data center for his deep learning workflow"

- "Stable Diffusion v1 version of the model requires 150,000 A100 GPU Hours for a single training session"<sup>a</sup>

⇒ Optimization of deep learning workflows is of growing importance for energy efficiency.

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<sup>a</sup> <https://syncedreview.com/2022/11/09/almost-7x-cheaper-colossal-ais-open-source-solution-accelerates-aigc-at-a-low-cost-diffusion-pretraining-and-hardware-fine-tuning-can-be/>, accessed on: 10.11.2022

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