

## SUMMARY

**Goal:** Optimise  $f^{\text{target}}$  (target objective) w.r.t  $\theta$ , i.e.

$$\theta_{\text{target}}^* = \operatorname{argmax}_{\theta \in \Theta} f^{\text{target}}(\theta)$$

**Scenario:** There are  $n$  (potentially) related source tasks  $f^i$ ,  $i = 1, \dots, n$ . For each source task, we assume we have  $\{\theta_k^i, f^i(\theta_k^i)\}_{k=1}^{N_i}$  from past runs and  $N_i$  denotes the number of evaluations of  $f^i$  from task  $i$ .

**Method:** Transfer information across tasks using kernel mean embeddings of distributions of training datasets used in those tasks.

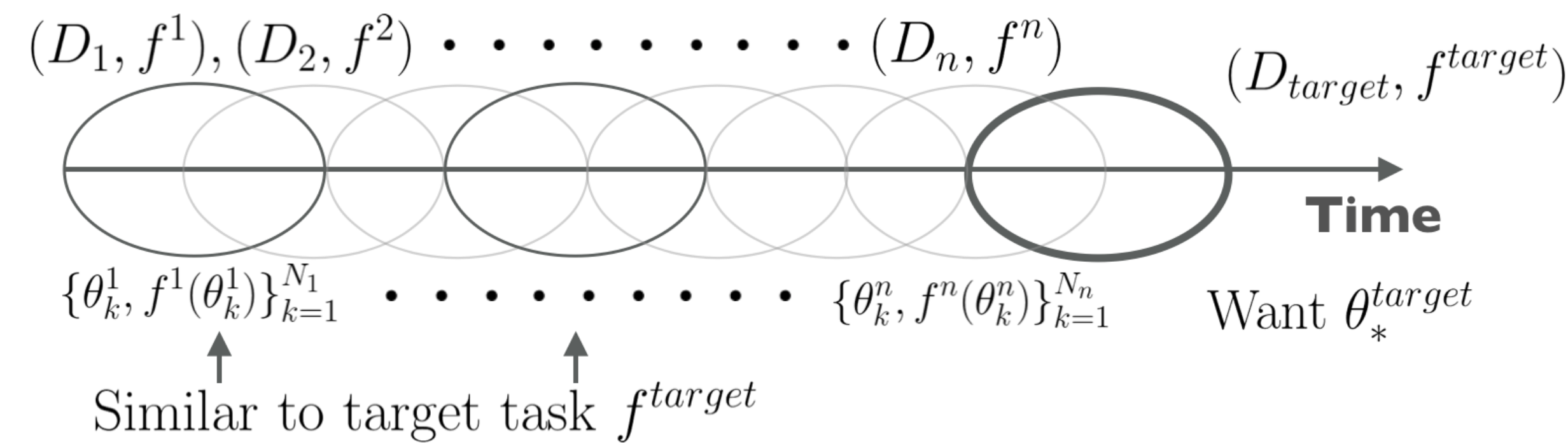
Here  $f^i$  is the accuracy of a trained machine learning model with training data  $D_i = \{\mathbf{x}_\ell^i, y_\ell^i\}_{\ell=1}^{s_i}$ . i.e. we have per source task:

$$(f^i, D_i = \{\mathbf{x}_\ell^i, y_\ell^i\}_{\ell=1}^{s_i}, \{\theta_k^i, f^i(\theta_k^i)\}_{k=1}^{N_i}) \quad i = 1, \dots, n$$

Our strategy now is to measure the similarity between datasets (as a representation of the task itself), in order to find  $\theta_{\text{target}}^*$ .

## MOTIVATION

Consider a scenario, where we have to constantly retrain our model in an online setting. For example, suppose that  $D$  is some traffic data, and that  $f$  is the accuracy of a machine learning model attempting to optimise taxi allocations.



Now as the data distribution changes (e.g. weekend vs weekday), we might expect  $\theta^*$  to also change.

## RELATED WORK

The transfer of information from different tasks has been studied in the context of multi-task BO (multiBO) and meta-learning (manualBO) :

1. Learning task similarities through evaluations of  $f$
2. Hand crafted meta-features for task similarities

**Case 1:** This would imply we need to observe sufficient evaluations from the target task in order to learn these task correlations.

**Case 2:** Using hand crafted meta-features can have an adverse effect on exploration if they are defined poorly.

Our methodology can be seen as a combination of these two frameworks, using learnt embeddings of the joint distribution of the data, while capturing correlation across tasks.

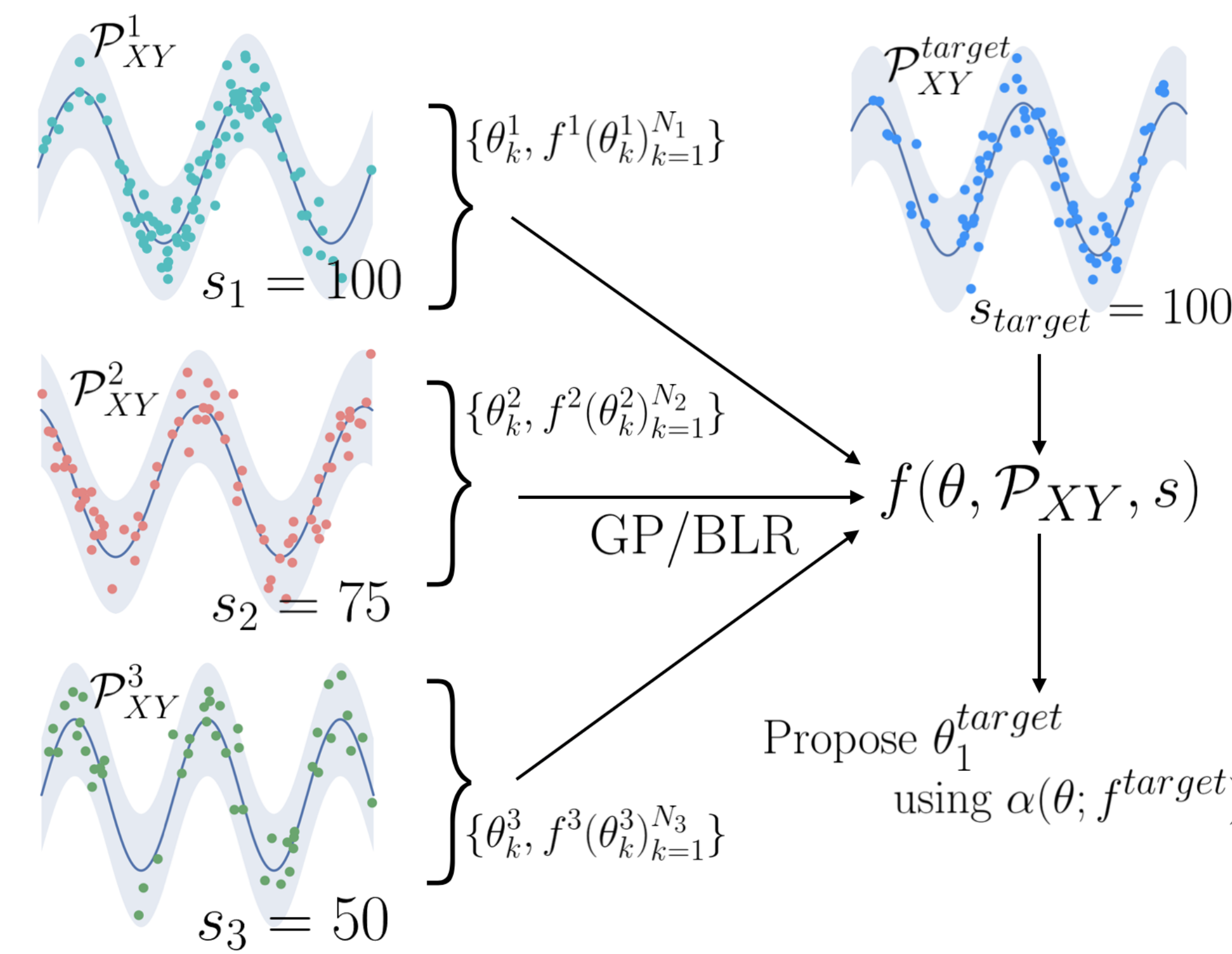
## ASSUMPTIONS

1.  $\mathbf{x}_\ell^i \in \mathcal{X}$  and  $y_\ell^i \in \mathcal{Y}$  for all  $i, \ell$ , supervised learning model  $M$  is the same.
2.  $D_i = \{\mathbf{x}_\ell^i, y_\ell^i\}_{\ell=1}^{s_i} \sim \mathcal{P}_{XY}^i$ , where  $\mathcal{P}_{XY}^i$  is the joint distribution of the data for source task  $i$ .

### Implication

- The source of differences of  $f^i$  across  $i$  and  $f^{\text{target}}$  is due to the distribution  $P_i$  and  $P_{\text{target}}$ .
- Sample size is related to hyperparameter choice, which we also encode.

## MODEL AND EMBEDDING (DistBO)



Under this setting, we will consider  $f(\theta, \mathcal{P}_{XY}, s)$ , where  $f$  is a function of hyperparameters  $\theta$ , joint distribution of the underlying data  $\mathcal{P}_{XY}$  and sample size  $s$ . E.g.  $f$  could be the negative empirical risk, i.e.

$$f(\theta, \mathcal{P}_{XY}, s) = -\frac{1}{s} \sum_{l=1}^s L(h_\theta(\mathbf{x}_l), y_l)$$

where  $L$  is the loss function and  $h_\theta$  is the model's predictor. In particular, we have that:  $f^i(\theta) = f(\theta, \mathcal{P}_{XY}^i, s_i)$  and  $f^{\text{target}}(\theta) = f(\theta, \mathcal{P}_{XY}^{\text{target}}, s_{\text{target}})$ .

Using a Gaussian process for  $f$ , we define a covariance function  $C$ :

$$C(\{\theta_1, \mathcal{P}_{XY}^1, s_1\}, \{\theta_2, \mathcal{P}_{XY}^2, s_2\}) = \nu k_\theta(\theta_1, \theta_2) k_p([\psi(D_1), s_1], [\psi(D_2), s_2])$$

where  $\nu$  is a constant,  $k_\theta$  and  $k_p$  are the standard Matérn-3/2 kernel.

To specify  $\psi(D)$  we consider feature maps  $\phi_x(\mathbf{x}) \in \mathbb{R}^p$  and  $\phi_y(y) \in \mathbb{R}^q$ . To embed a joint distribution  $\mathcal{P}_{XY}^i$ , we use the cross covariance operator  $\mathcal{C}_{XY}^i$  [1], estimated by  $D_i$  with:

$$\hat{\mathcal{C}}_{XY}^i = \frac{1}{s_i} \sum_{\ell=1}^{s_i} \phi_x(\mathbf{x}_\ell^i) \otimes \phi_y(y_\ell^i) = \frac{1}{s_i} \Phi_x^i(\mathbf{x}) \Phi_y^i(y)^\top \in \mathbb{R}^{p \times q}$$

where  $\Phi_x^i(\mathbf{x}) = [\phi_x(\mathbf{x}_1^i), \dots, \phi_x(\mathbf{x}_{s_i}^i)] \in \mathbb{R}^{p \times s_i}$ ,  $\Phi_y^i(y) = [\phi_y(y_1^i), \dots, \phi_y(y_{s_i}^i)] \in \mathbb{R}^{q \times s_i}$ . Flattening  $\hat{\mathcal{C}}_{XY}^i$ , we obtain  $\psi(D_i) \in \mathbb{R}^{pq}$ .

## IMPLEMENTATION

For  $\phi_x, \phi_y$ , we will consider a flexible representation, specifically in the form of neural networks (1 hidden and 1 output layer in this case).

**Explanation:** Suppose we have two task  $i, j$  and that  $\mathcal{P}_{XY}^i \approx \mathcal{P}_{XY}^j$ , this will imply that  $f^i \approx f^j$ , and hence  $\theta_i^* \approx \theta_j^*$ . However, the converse does not hold in general, i.e.  $f^i \approx f^j$  does not imply  $\mathcal{P}_{XY}^i \approx \mathcal{P}_{XY}^j$ !

**Example:** Ridge regression with regularisation  $\lambda$  are likely to be robust to rotations of the covariates, which leads to a different  $\mathcal{P}_X$ .

**Optimisation:** Maximise the marginal likelihood to optimise neural network and model parameters in an end-to-end fashion.

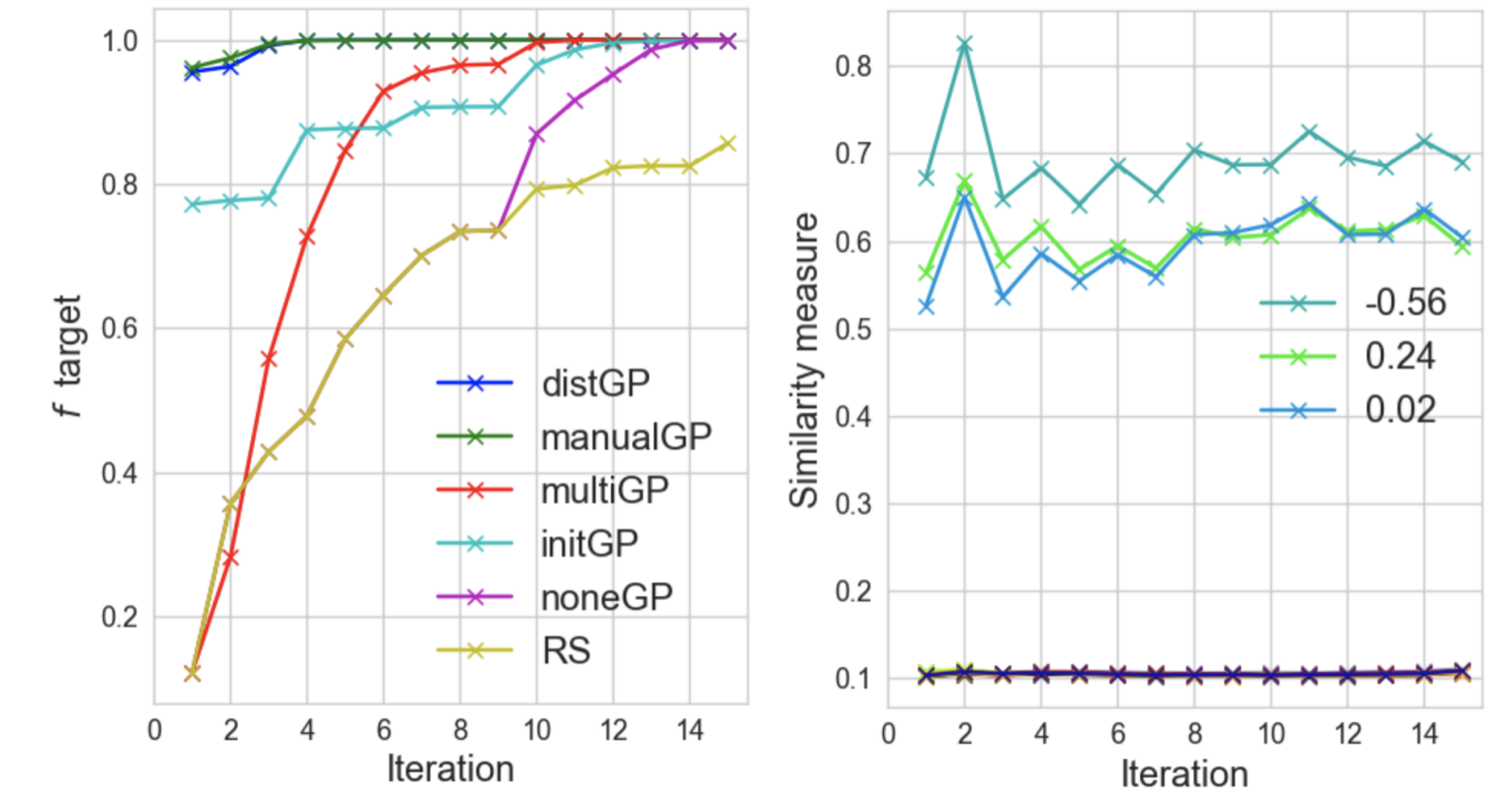
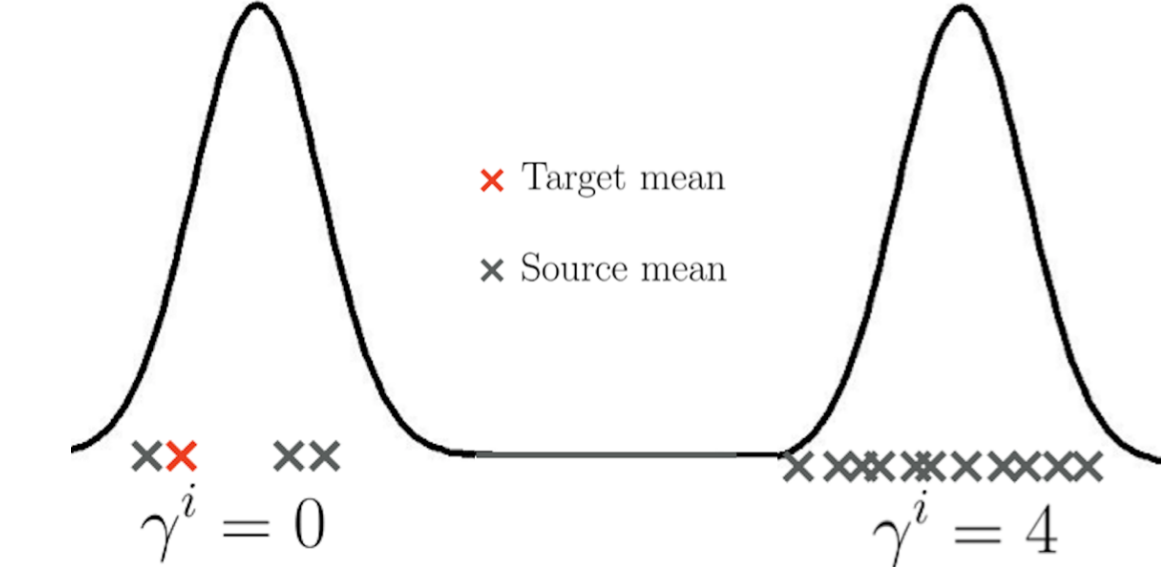
**Scalability:** Replace GP by Bayesian linear regression [2], which scales linearly with the number of observations  $N = \sum_{i=1}^N s_i$  (distBLR). As  $S = \sum_{i=1}^N s_i$  is likely to be large, we can employ different random sub-sample of batch-size  $b$  for each step of optimisation.

## EXPERIMENTS

### Toy example.

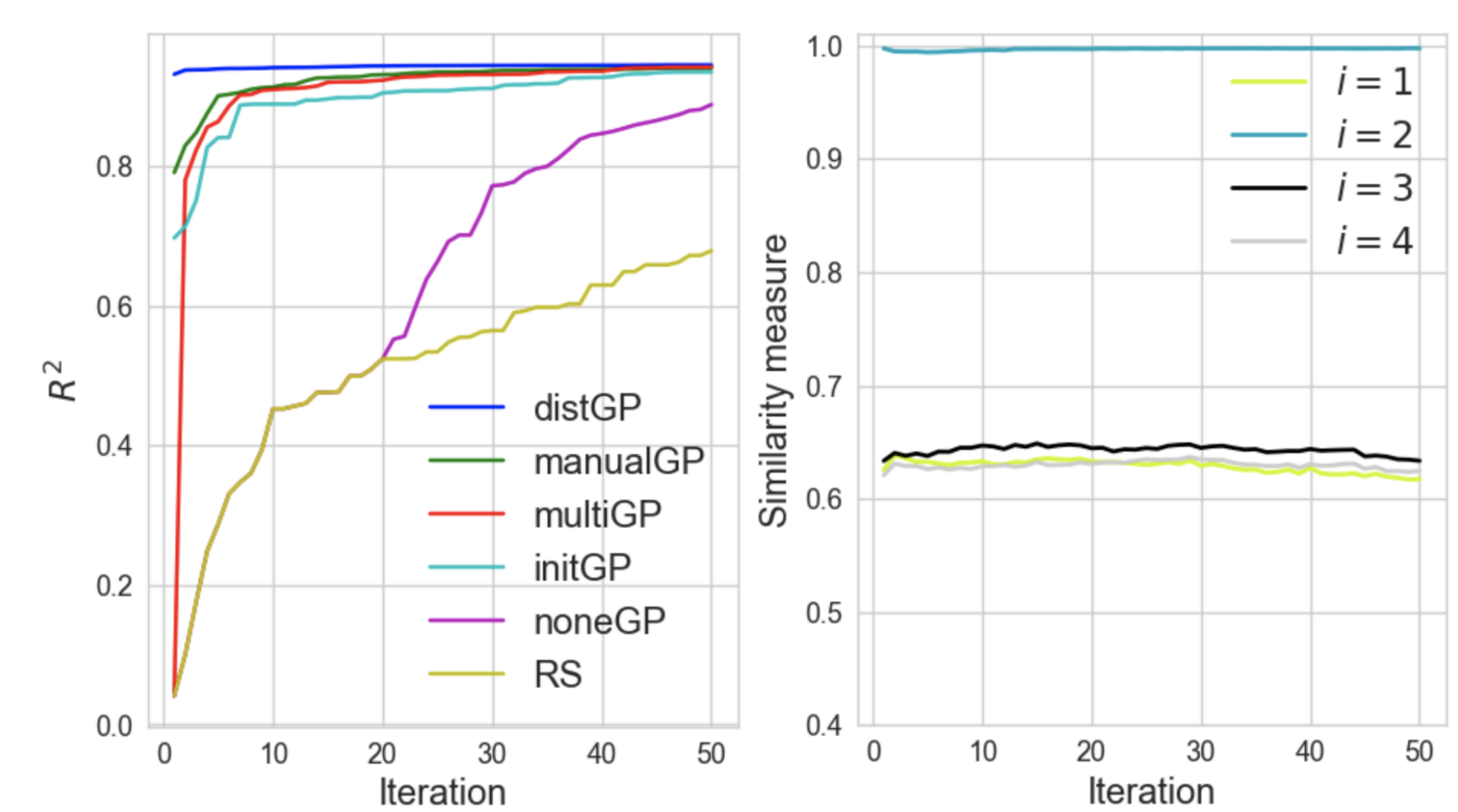
$$X^i | \mu^i \sim \mathcal{N}(\mu^i, 1)$$

$$f(\theta; \mu^i) = \exp\left(-\left(\theta - \frac{1}{s_i} \sum x_\ell^i\right)^2 / 2\right)$$



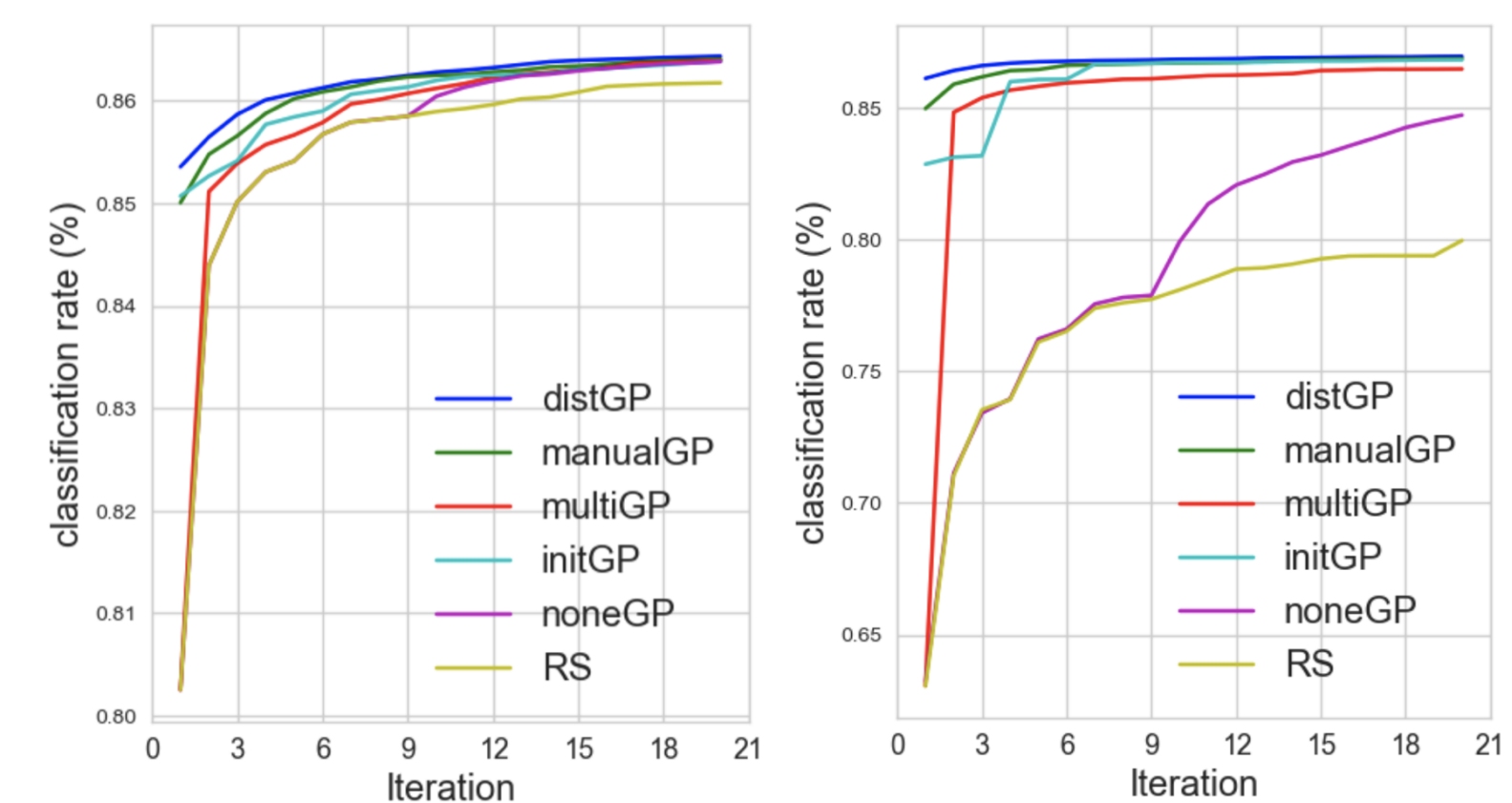
### Handcrafted features.

- Regression process invariant to manual meta-features
- 4 source tasks (1 similar)
- Ridge regression (ARD)
- 6 hyperparameters



### Protein dataset.

- Protein-ligand binding classification problem in the area of drug design
- 7 different proteins
- Jaccard kernel C-SVM (left)
- Random forest (right)



## REFERENCES

- [1] Muandet, et al. 'Kernel Mean Embedding of Distributions: A Review and Beyond', 2017
- [2] Perrone, et al. 'Scalable hyperparameter transfer learning', NeurIPS, 2018