# The Growth Model in Continuous Time Competitive Equilibrium

Prof. Lutz Hendricks

Econ720

October 8, 2021

### Competitive Equilibrium

- Firms solve the same problem as in the Solow model.
- ► We add a government that imposes lump-sum taxes to finance government spending.
- ▶ The budget constraint is  $\tau_t = G_t$ .

#### Households

$$\max \int_{t=0}^{\infty} e^{-(\rho-n)t} u(c_t) dt \tag{1}$$

subject to:  $k_0$  given, the TVC, and the budget constraint

$$\dot{k}_t = w_t + (r_t - \delta - n)k_t - c_t - \tau_t \tag{2}$$

#### Households

Hamiltonian:

$$H = u(c) + \lambda [w + (r - \delta - n)k - c - \tau]$$
(3)

First-order conditions

$$\partial H/\partial c = 0 \Rightarrow u'(c) = \lambda$$
 (4)

$$\dot{\lambda} = (\rho - n)\lambda - \partial H/\partial k 
= \lambda[\rho - n - (r - \delta - n)] 
= \lambda(\rho - r + \delta)$$

Transversality:

$$\lim_{t\to\infty}e^{-(\rho-n)t}\lambda_tk_t=0$$

(5)

#### Households

Eliminate  $\lambda$ :

$$u''(c)\dot{c} = \dot{\lambda} \tag{6}$$

Substitute into the law of motion for  $\lambda$ :

$$\dot{c} = u'(c)/u''(c) \cdot [\rho + \delta - r]$$

or

$$g_c = (r - \delta - \rho)/\sigma \tag{7}$$

Solution: Functions  $c_t$ ,  $k_t$  that solve the Euler equation, the budget constraint, and the boundary conditions.

## Competitive Equilibrium

Objects: Functions  $c_t, k_t, \tau_t, w_t, r_t$ .

Equilibrium conditions:

- ► Household (2)
- ▶ Firm (2)
- ▶ Government (1)
- ► Market clearing (1)

# **Dynamics**

Simplify to obtain two differential equations:

$$\dot{c} = u'(c)/u''(c) \cdot [\rho + \delta - f'(k)] \tag{8}$$

$$\dot{k} = f(k) - (n+\delta)k - c - G \tag{9}$$

The planning solution and the CE coincide (with G = 0).

# Detrending the Model

# Detrending a model

Consider the Cass Koopmans model with productivity growth:

$$\max \int_0^\infty e^{-(\rho - n)t} u(c_t) dt \tag{10}$$

$$\dot{k}_t = F(k_t, A_t) - (n+\delta)k_t - c_t \tag{11}$$

with

$$A_t = e^{gt} \tag{12}$$

- What does the Planner's solution look like?
- ▶ The problem: the model has no steady state.
- How can we analyze its dynamics?

#### Approach 1: Solve and detrend

Unchanged: the Planner's optimality conditions in terms of original variables:

$$\dot{c}/c = \frac{\frac{\partial F(k,A)}{\partial k} - n - \delta - (\rho - n)}{\sigma(c)}$$
(13)

- But we cannot draw the phase diagram without a steady state.
- Solution: detrend the variables to make them stationary.
  - 1. Find the balanced growth rate for each variable.
  - 2. Divide each variable by a scale factor that grows at its balanced growth rate.

#### Balanced growth rates

▶ The same as in the Solow model with growth:

$$g(c) = g(k) = g \tag{14}$$

Define the detrended variables:

$$\tilde{c}_t = c_t/A_t \tag{15}$$

$$\tilde{k}_t = k_t/A_t \tag{16}$$

$$\tilde{k}_t = k_t/A_t \tag{16}$$

Law of motion:

$$g(\tilde{k}) = g(k) - g$$

$$= \frac{F(\tilde{k}, 1) A - (n + \delta) \tilde{k} A - \tilde{c} A}{k} - g$$

$$d\tilde{k}/dt = f(\tilde{k}) - (n + \delta + g) \tilde{k} - \tilde{c}$$
(17)

#### Detrended first-order conditions

Optimality conditions in terms of detrended variables:

$$\frac{d\tilde{c}/dt}{\tilde{c}} = \frac{\dot{c}}{c} - g$$

$$= \frac{f'(\tilde{k}) - \delta - \rho}{\sigma(c)} - g \tag{18}$$

► This is true because

$$\frac{\partial F(k,A)}{\partial k} = \frac{\partial F(\tilde{k}A,A)}{\partial \tilde{k}} \frac{\partial \tilde{k}}{\partial k} = Af'(\tilde{k}) \frac{1}{A}$$
(19)

#### Detrended first-order conditions

Assume CRRA preferences:

$$u(c) = c^{1-\sigma}/(1-\sigma)$$
 (20)

- ▶ Then  $\sigma(c) = \sigma$  is constant.
- CRRA is required for balanced growth an important result.
  - ▶ Otherwise  $\sigma(c)$  is not constant.

#### Model Solution

Functions of time  $c_t, k_t$  that satisfy:

1. Euler equation

$$g(\tilde{c}) = \frac{f'(\tilde{k}) - \delta - \rho}{\sigma(c)} - g \tag{21}$$

2. Resource constraint

$$d\tilde{k}/dt = f(\tilde{k}) - (n + \delta + g)\tilde{k} - \tilde{c}$$
(22)

- 3. Initial condition:  $\tilde{k}_0$  given
- 4. TVC  $\lim_{t\to\infty} e^{-(\rho-n)t}u'(c_t)k_t = 0$ . With  $u'(c_t) = c_t^{-\sigma} = \tilde{c}_t^{-\sigma}e^{-\sigma gt}$  and  $k_t = \tilde{k}_t e^{gt}$ , this becomes

$$\lim_{t \to \infty} e^{-(\rho - n)t} e^{(1 - \sigma)gt} u'(\tilde{c}_t) \tilde{k}_t = 0$$
 (23)

# Approach 2: Detrend and solve

#### ► Steps:

- 1. Find balanced growth rates as before.
- 2. Write the economy in detrended variables.
- 3. Take the first-order conditions.
- 4. Define the solution.
- 5. Convert back into (undetrended) variables.
- ► This is useful for solution methods that only work on stationary problems (such as DP).
- Exercise: show that this yields the same answer for the growth model.

# Detrending the Model

Summary

In the growth model, optimality conditions change only by adding the 2 occurrences of g:

$$g(\tilde{c}) = \frac{f'(\tilde{k}) - \delta - \rho}{\sigma} - g$$

$$d\tilde{k}/dt = f(\tilde{k}) - (n + \delta + g)\tilde{k} - \tilde{c}$$
(24)

$$d\tilde{k}/dt = f(\tilde{k}) - (n+\delta+g)\tilde{k} - \tilde{c}$$
 (25)

# Detrending the Model

Why do we care?

1. The balanced growth  $\tilde{k}$  now depends on preferences:

$$g(\tilde{c}) = 0 \Rightarrow f(\tilde{k}) = \delta + \rho + \sigma g$$
 (26)

- 2. We see that preferences must be CRRA for a steady state to exist.
- 3. Quantitative differences.

# Reading

- Acemoglu (2009), ch. 8. Ch. 8.6 covers the detrended model. Ch. 7 covers Optimal Control.
- Barro and Sala-i Martin (1995), ch. 2, explains the Cass-Koopmans/Ramsey model in great detail.
- ▶ Blanchard and Fischer (1989), ch. 2
- Romer (2011), ch. 2A
- Phase diagram: Barro and Sala-i Martin (1995), ch. 2.6

#### References I

- Acemoglu, D. (2009): Introduction to modern economic growth, MIT Press.
- Barro, R. and X. Sala-i Martin (1995): "Economic growth," *Boston, MA*.
- Blanchard, O. J. and S. Fischer (1989): Lectures on macroeconomics, MIT press.
- Romer, D. (2011): Advanced macroeconomics, McGraw-Hill/Irwin.