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- Module StateSpace -
1 1
    The graph representation of n-ary ordered state space and 2D state space used in CJupiter and
    XJupiter, respectively.
    EXTENDS JupiterCtx, GraphsUtil
 7 |
    IsSS(G) \stackrel{\triangle}{=} A state space is a digraph with labeled edges.
           \wedge IsGraph(G) It is a digraph (represented by a record).
9
           \land G.node \subseteq (SUBSET\ Oid) Each node represents a document state, i.e., a set of Oid.
10
           \land G.edqe \subseteq [from: G.node, to: G.node, cop: Cop] Each edge is labeled with a Cop operation.
11
    EmptySS \stackrel{\triangle}{=} EmptyGraph
13
14
    Locate(cop, ss) \stackrel{\Delta}{=} Locate the node in state space ss that matches the context of cop.
15
         CHOOSE n \in ss.node : n = cop.ctx
16
    xForm(NextEdge(\_, \_, \_), r, cop, ss) \stackrel{\Delta}{=}
                                                           Transform cop with an operation sequence
18
         LET u \stackrel{\triangle}{=} Locate(cop, ss)
                                                           in state space ss at replica r.
19
               v \triangleq u \cup \{cop.oid\}
20
               RECURSIVE xFormHelper(\_, \_, \_, \_)
21
                xFormHelper(uh, vh, coph, xss) \triangleq
                                                                 xss: eXtra ss created during transformation
22
                     IF uh = ds[r] THEN [xcop \mapsto coph,
23
                                                 xss \mapsto xss,
24
                                                 lss \mapsto [node \mapsto \{vh\},
25
                                                          edge \mapsto \{[from \mapsto uh, to \mapsto vh, cop \mapsto coph]\}]
26
                      ELSE LET e \stackrel{\triangle}{=} NextEdge(r, uh, ss)
27
                                     copprime \triangleq e.cop
28
                                     uprime \stackrel{\triangle}{=} e.to
29
                                     vprime \triangleq vh \cup \{copprime.oid\}
30
                                      coph2copprime \stackrel{\Delta}{=} COT(coph, copprime)
31
                                      copprime2coph \triangleq COT(copprime, coph)
32
33
                                      xFormHelper(uprime, vprime, coph2copprime,
                                          xss \oplus [node \mapsto \{vprime\},\
34
                                                   edge \mapsto \{[from \mapsto vh, to \mapsto vprime,
35
                                                                 cop \mapsto copprime2coph,
36
                                                               [from \mapsto uprime, to \mapsto vprime,
37
                                                                 cop \mapsto coph2copprime[]])
38
39
                xFormHelper(u, v, cop, [node \mapsto \{v\},
                                                 edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto cop]\}])
40
      RECURSIVE Extract CopSeq(\_, \_, \_) \* Extract a Cop sequence starting with u in ss at replica r.
42
      ExtractCopSeq(NextEdge(\_, \_, \_), r, u, ss) \stackrel{\Delta}{=}
43
        If u = ds[r] then \langle \rangle
44
         ELSE LET e \stackrel{\triangle}{=} NextEdge(r, u, ss)
45
               \langle e.cop \rangle \circ ExtractCopSeg(NextEdge, r, e.to, ss)
46
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48

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LET RECURSIVE xFormCopCopsSSHelper(\_, \_, \_)
49
             xFormCopCopsSSHelper(coph, copsh, xss) \stackrel{\Delta}{=}
50
                 Let u \stackrel{\triangle}{=} coph.ctx
51
                    v \stackrel{\Delta}{=} u \cup \{coph.oid\}
52
                  uvSS \stackrel{\Delta}{=} [node \mapsto \{u, v\}, edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto coph]\}]
53
                 In if copsh = \langle \rangle then [xcop \mapsto coph, xss \mapsto xss \oplus uvSS, lss \mapsto uvSS]
54
                     ELSE LET copprimeh \stackrel{\Delta}{=} Head(copsh)
55
                              uprime \stackrel{\Delta}{=} u \cup \{copprimeh.oid\}
56
                              vprime \stackrel{\triangle}{=} u \cup \{coph.oid, copprimeh.oid\}
57
                            coph2copprimeh \stackrel{\Delta}{=} COT(coph, copprimeh)
58
                            copprimeh2coph \stackrel{\Delta}{=} COT(copprimeh, coph)
59
                         IN xFormCopCopsSSHelper(coph2copprimeh, Tail(copsh),
60
                              xss \oplus [node \mapsto \{u, v\},
61
62
                                      edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto coph],\
                                               [from \mapsto u, to \mapsto uprime, cop \mapsto copprimeh],
63
64
                                              [from \mapsto v, to \mapsto vprime, cop \mapsto copprimeh2coph]\}])
         IN xFormCopCopsSSHelper(cop, cops, EmptySS)
65
66
       67
          Let u \stackrel{\Delta}{=} cop.ctx
                                     \* Return the extra state space.
68
             v \stackrel{\Delta}{=} u \cup \{cop.oid\}
69
             uprime \stackrel{\Delta}{=} u \cup \{copprime.oid\}
70
             vprime \stackrel{\Delta}{=} u \cup \{cop.oid, copprime.oid\}
71
             cop2copprime \stackrel{\Delta}{=} COT(cop, copprime)
72
             copprime2cop \stackrel{\Delta}{=} COT(copprime, cop)
73
               [node \mapsto \{u, v, uprime, vprime\},\]
74
              edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto cop],\
75
76
                      [from \mapsto u, to \mapsto uprime, cop \mapsto copprime],
77
                      [from \mapsto v, to \mapsto vprime, cop \mapsto copprime2cop],
                      [from \mapsto uprime, \ to \mapsto vprime, \ cop \mapsto cop2copprime]\}]
78
79
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- \ * Modification History
- * Last modified Wed Jan 09 16:00:02 CST 2019 by hengxin
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