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- MODULE StateSpace
 1 1
     The graph representation of n-ary ordered state space and 2D state space used in CJupiter and
    XJupiter, respectively.
    EXTENDS JupiterCtx, GraphsUtil
 7 |
     IsSS(G) \stackrel{\Delta}{=} A state space is a digraph with labeled edges.
           \wedge IsGraph(G) It is a digraph (represented by a record).
 9
           \land G.node \subseteq (SUBSET\ Oid) Each node represents a document state, i.e., a set of Oid.
10
           \land G.edqe \subseteq [from: G.node, to: G.node, cop: Cop] Each edge is labeled with a Cop operation.
11
     EmptySS \stackrel{\triangle}{=} EmptyGraph
13
14
     Locate(cop, ss) \stackrel{\triangle}{=} Locate the (unique) node in state space ss that matches the context of cop.
15
         CHOOSE n \in ss.node : n = cop.ctx
16
    RECURSIVE ExtractCopSeq(-, -, -, -) Extract Cop sequences starting with u in ss at replica r.
18
     ExtractCopSeq(NextEdge(\_, \_, \_), r, u, ss) \triangleq
19
         If u = ds[r] then \langle \rangle
20
          ELSE LET e \stackrel{\triangle}{=} NextEdge(r, u, ss)
21
                       \langle e.cop \rangle \circ ExtractCopSeq(NextEdge, r, e.to, ss)
22
    xFormCopCopsSS(cop, cops) \stackrel{\Delta}{=} Transform cop against cops (a sequence of Cop) on state space.
24
         LET RECURSIVE xFormCopCopsSSHelper(\_, \_, \_) Return the extra state space.
25
                 xFormCopCopsSSHelper(coph, copsh, xss) \stackrel{\Delta}{=} xss: the eXtra state space
26
                     LET u \stackrel{\triangle}{=} coph.ctx

v \stackrel{\triangle}{=} u \cup \{coph.oid\}
27
28
                       uvSS \stackrel{\Delta}{=} [node \mapsto \{u, v\}, edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto coph]\}]
29
                           IF copsh = \langle \rangle THEN [xcop \mapsto coph, xss \mapsto xss \oplus uvSS, lss \mapsto uvSS]
30
                              ELSE LET copprimeh \stackrel{\triangle}{=} Head(copsh)
31
                                                uprime \stackrel{\triangle}{=} u \cup \{copprimeh.oid\}
32
                                                vprime \stackrel{\triangle}{=} u \cup \{coph.oid, copprimeh.oid\}
33
                                             coph2copprimeh \stackrel{\triangle}{=} COT(coph, copprimeh)
34
                                              copprimeh2coph \triangleq COT(copprimeh, coph)
35
                                             xFormCopCopsSSHelper(coph2copprimeh, Tail(copsh),
36
                                                 xss \oplus [node \mapsto \{u, v\},
37
                                                          edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto coph],
38
                                                                       [from \mapsto u, to \mapsto uprime, cop \mapsto copprimeh],
39
                                                                       [from \mapsto v, to \mapsto vprime, cop \mapsto copprimeh2coph]\}])
40
                 xFormCopCopsSSHelper(cop, cops, EmptySS)
41
    xFormSS(cop, copprime) \stackrel{\triangle}{=}
                                            Transform cop against copprime on state space.
43
         Let u \triangleq cop.ctx
44
                                            Return the extra state space.
               v \triangleq u \cup \{cop.oid\}
45
                uprime \triangleq u \cup \{copprime.oid\}
46
                vprime \triangleq u \cup \{cop.oid, copprime.oid\}
47
                cop2copprime \stackrel{\triangle}{=} COT(cop, copprime)
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48

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49 copprime2cop \triangleq COT(copprime, cop)

50 IN [node \mapsto \{u, v, uprime, vprime\},

51 edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto cop],

52 [from \mapsto u, to \mapsto uprime, cop \mapsto copprime],

53 [from \mapsto v, to \mapsto vprime, cop \mapsto copprime2cop],

54 [from \mapsto uprime, to \mapsto vprime, cop \mapsto cop2copprime]\}]

55
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