```
MODULE StateSpace
1 1
    The graph representation of n-ary ordered state space and 2D state space used in CJupiter and
    XJupiter, respectively.
    EXTENDS JupiterCtx, GraphsUtil
 7 |
    IsSS(G) \stackrel{\triangle}{=} A state space is a digraph with labeled edges.
           \wedge IsGraph(G) It is a digraph (represented by a record).
9
           \land G.node \subseteq (SUBSET\ Oid) Each node represents a document state, i.e., a set of Oid.
10
           \land G.edqe \subseteq [from: G.node, to: G.node, cop: Cop] Each edge is labeled with a Cop operation.
11
    EmptySS \stackrel{\triangle}{=} EmptyGraph
13
14
    Locate(cop, ss) \stackrel{\Delta}{=} Locate the node in state space ss that matches the context of cop.
15
         CHOOSE n \in ss.node : n = cop.ctx
16
    xForm(NextEdge(\_,\_,\_), r, cop, ss) \stackrel{\triangle}{=}
                                                           Transform cop with an operation sequence
18
         LET u \stackrel{\triangle}{=} Locate(cop, ss)
                                                           in state space ss at replica r.
19
               v \triangleq u \cup \{cop.oid\}
20
               RECURSIVE xFormHelper(\_, \_, \_, \_)
21
                xFormHelper(uh, vh, coph, xss) \triangleq
                                                                 xss: eXtra ss created during transformation
22
                     IF uh = ds[r] THEN [xcop \mapsto coph,
23
                                                 xss \mapsto xss,
24
                                                 lss \mapsto [node \mapsto \{vh\},
25
                                                          edge \mapsto \{[from \mapsto uh, to \mapsto vh, cop \mapsto coph]\}]
26
                      ELSE LET e \stackrel{\triangle}{=} NextEdge(r, uh, ss)
27
                                     copprime \triangleq e.cop
28
                                     uprime \triangleq e.to
29
                                     vprime \triangleq vh \cup \{copprime.oid\}
30
                                      coph2copprime \stackrel{\triangle}{=} COT(coph, copprime)
copprime2coph \stackrel{\triangle}{=} COT(copprime, coph)
31
32
                                      xFormHelper(uprime, vprime, coph2copprime,
33
                                          xss \oplus [node \mapsto \{vprime\},\
34
                                                  edge \mapsto \{[from \mapsto vh, to \mapsto vprime,
35
                                                                 cop \mapsto copprime2coph,
36
                                                               [from \mapsto uprime, to \mapsto vprime,
37
                                                                 cop \mapsto coph2copprime[]])
38
39
         IN
                xFormHelper(u, v, cop, [node \mapsto \{v\},
                                                 edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto cop]\}])
40
41
     \ * Modification History
     \* Last modified Sat Jan 12 14:53:19 CST 2019 by hengxin
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