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- MODULE StateSpace
 1 1
     The graph representation of n-ary ordered state space and 2D state space used in CJupiter and
    XJupiter, respectively.
    EXTENDS JupiterCtx, GraphsUtil
 7 |
     IsSS(G) \stackrel{\Delta}{=} A state space is a digraph with labeled edges.
            \wedge IsGraph(G) It is a digraph (represented by a record).
 9
           \land G.node \subseteq (SUBSET\ Oid) Each node represents a document state, i.e., a set of Oid.
10
           \land G.edqe \subseteq [from: G.node, to: G.node, cop: Cop] Each edge is labeled with a Cop operation.
11
     EmptySS \stackrel{\triangle}{=} EmptyGraph
13
14
     Locate(cop, ss) \stackrel{\Delta}{=} Locate the (unique) node in state space ss that matches the context ctx of cop.
15
         CHOOSE n \in ss.node : n = cop.ctx
16
    RECURSIVE ExtractCopSeq(\_, \_, \_, \_)
18
     ExtractCopSeq(NextEdge(\_, \_, \_), r, u, ss) \stackrel{\Delta}{=}
19
         If u = ds[r] then \langle \rangle
20
           ELSE LET e \stackrel{\Delta}{=} NextEdge(r, u, ss)
21
                   IN \langle e.cop \rangle \circ ExtractCopSeq(NextEdge, r, e.to, ss)
22
     xFormSS(cop, copprime) \triangleq
                                             Transform cop against copprime on state space.
24
         LET u \triangleq cop.ctx
25
                                             Return the extra state space.
                v \stackrel{\triangle}{=} u \stackrel{\cdot}{\cup} \{cop.oid\}
26
                uprime \stackrel{\triangle}{=} u \cup \{copprime.oid\}
27
                vprime \stackrel{\triangle}{=} u \cup \{cop.oid, copprime.oid\}
28
                cop2copprime \stackrel{\triangle}{=} COT(cop, copprime)
29
                 copprime2cop \triangleq COT(copprime, cop)
30
                [node \mapsto \{u, v, uprime, vprime\},\]
31
                  edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto cop],
32
                              [from \mapsto u, to \mapsto uprime, cop \mapsto copprime],
33
                               [from \mapsto v, to \mapsto vprime, cop \mapsto copprime2cop],
34
                              [from \mapsto uprime, to \mapsto vprime, cop \mapsto cop2copprime]\}]
35
     xFormCopCopsSS(cop, cops) \stackrel{\Delta}{=}
                                                      Transform cop against cops (a sequence of Cop) on state space.
37
         LET RECURSIVE xFormCopCopsSSHelper(\_, \_, \_) Return the extra state space.
38
                 xFormCopCopsSSHelper(coph, copsh, xss) \stackrel{\Delta}{=} xss: the eXtra state space
39
                      Let u \triangleq coph.ctx
40
                            v \triangleq u \cup \{coph.oid\}
41
                       uvSS \stackrel{\Delta}{=} [node \mapsto \{u, v\}, edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto coph]\}]
42
                            IF copsh = \langle \rangle THEN [xcop \mapsto coph, xss \mapsto xss \oplus uvSS, lss \mapsto uvSS]
43
                              ELSE LET copprimeh \stackrel{\triangle}{=} Head(copsh)
44
                                                 uprime \stackrel{\triangle}{=} u \cup \{copprimeh.oid\}
45
                                                 vprime \stackrel{\triangle}{=} u \cup \{coph.oid, copprimeh.oid\}
46
                                             coph2copprimeh \triangleq COT(coph, copprimeh)
47
                                               copprimeh2coph \stackrel{\Delta}{=} COT(copprimeh, coph)
48
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xFormCopCopsSSHelper(coph2copprimeh, Tail(copsh),
49
                                          xss \oplus [node \mapsto \{u, v\},\
50
                                                  edge \mapsto \{[from \mapsto u, \ to \mapsto v, \ cop \mapsto coph], \}
51
                                                            [from \mapsto u, to \mapsto uprime, cop \mapsto copprimeh],
52
                                                            [from \mapsto v, to \mapsto vprime, cop \mapsto copprimeh2coph]\}])
53
              xFormCopCopsSSHelper(cop, cops, EmptySS)
54
55 L
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