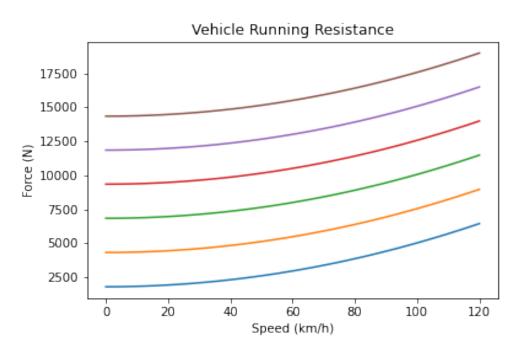


PERFORMANCE REPORT

Design Summary

Motor Power = Motor Nom Torque = Motor Peak Torque = Motor RPM = Gradeability =
Battery Power =
Battery Energy =
Final Gear Ratio =

Grafik Motor Running Resistance



Parameter Kendaraan

Lebar Kendaraan = Tinggi Kendaraan = Ca = Af =

Kode Ban = Jari - jari Ban = Massa Kosong = Massa Isi = Massa Total =

Gear Box = Mech Eff = Axle = Final GR =

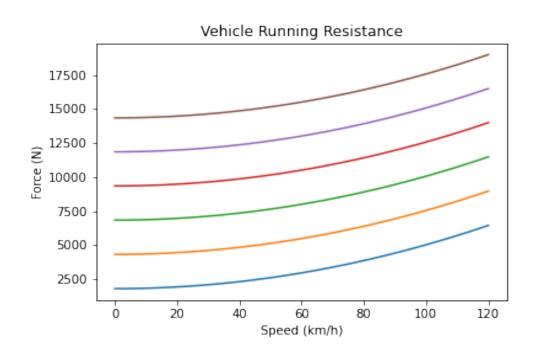
Dinamika Bergerak

Rolling Resistance = Drag Resistance = Massa Jenis Udara =

Kecepatan Angin = Percepatan Gravitasi = Acceleration Margin =

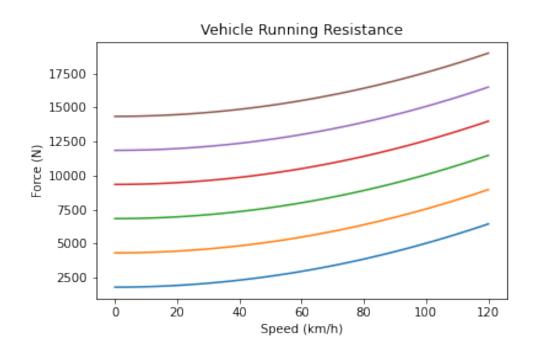
Grafik Vehicle Running Resistance

$$\begin{split} RR(N) &= R_{RR} + R_D + R_G \\ RR(N) &= C_{RR} \cdot m \cdot g \cdot \cos\theta + \frac{\rho}{2} \cdot A_f \cdot C_D \cdot (V_V + V_W)^2 + m \cdot g \cdot \sin\theta \end{split}$$



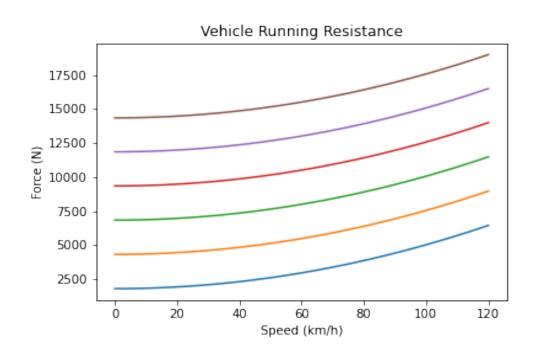
Grafik Wheel Running Resistance

$$\begin{split} RR(Nm) &= RR(N) \times r = (R_{RR} + R_D + R_G) \times r \\ RR(Nm) &= \left(C_{RR} \cdot m \cdot g \cdot \cos\theta + \frac{\rho}{2} \cdot A_f \cdot C_D \cdot (V_V + V_W)^2 + m \cdot g \cdot \sin\theta\right) \times r \end{split}$$



Grafik Motor Side Running Resistance

$$\begin{split} RR(Motor) &= \frac{RR\left(Nm\right)}{GR} = \frac{r}{GR} \times \left(R_{RR} + R_D + R_G\right) \\ RR(Motor) &= \frac{r}{GR} \times \left(C_{RR} \cdot m \cdot g \cdot \cos\theta + \frac{\rho}{2} \cdot A_f \cdot C_D \cdot (V_V + V_W)^2 + m \cdot g \cdot \sin\theta\right) \end{split}$$



Kebutuhan Power

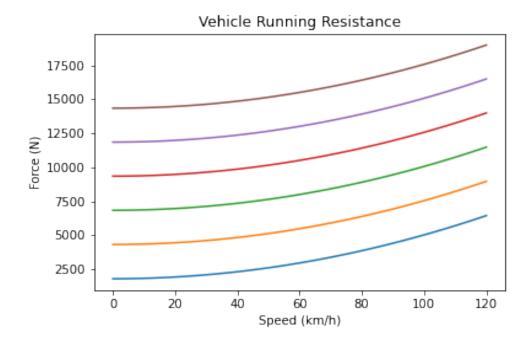
$$\begin{split} F(\theta, V_V) &= C_A .m.a + RR \\ F(\theta, V_V) &= C_A .m.a + C_{RR} .m.g.\cos\theta + \frac{\rho}{2} .A_f .C_D .(V_V + V_W)^2 + m.g.\sin\theta \\ P &= F \times V_{WP} \quad P = \frac{\tau .GR}{r} \times V_{WP} \end{split}$$

Const T = High Acc Const T = Weakening Point = Avg Acc =
P Motor =
High Acc Weakening Point =

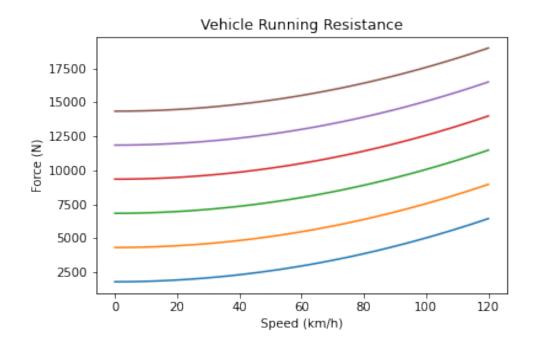
Grafik Vehicle Force Running Resistance



Grafik Vehicle Force Running Resistance



Grafik Motor Force Running Resistance



Kebutuhan Energi

V Cruise =	Pt Cruise =	E Battery =
S Cruise =	P Aux =	P Battery =
t Cruise =	P Cruise =	•
% Cruise -		

Grafik Motor Cruise Running Resistance

