## **Computer Graphics, Lab Assignment 9**

Handed out: May 13, 2020

## Due: 23:59, May 13, 2020 (NO SCORE for late submissions!)

- Only accept answers submitted via git push to this course project for you at <a href="https://hconnect.hanyang.ac.kr">https://hconnect.hanyang.ac.kr</a> (<Year>\_<Course no.>\_<Class code>/<Year>\_<Course no.>\_<Student ID>.git).
- Place your files under the directory structure <Assignment name>/<Problem no.>/<your file> just like the following example.

```
+ 2020_ITE0000_2019000001

+ LabAssignment2/

+ 1/

- 1.py

+ 2/

- 2.py

+ 3/

- 3.py
```

- The submission time is determined not when the commit is made but when the git push is made.
- 1. Write down a Python program to visualize ZXZ Euler angles.
  - A. This is how ZXZ Euler angles works
    - i. Rotate along Z-axis by  $\alpha$
    - ii. Rotate along X-axis of the new frame by  $\boldsymbol{\beta}$
    - iii. Rotate along Z-axis of the new frame by  $\gamma$
  - B. Start from 9-Orientation&Rotation practice code, implement ZXZ Euler angles and add code to change  $\alpha$ ,  $\beta$ ,  $\gamma$  values in the following way.
    - i. If you press or repeat a key, the value of  $\alpha$ ,  $\beta$ ,  $\gamma$  should be changed as shown in the table:

Key	Transformation
Α	Increase $\alpha$ by 10°
Z	Decrease $\alpha$ by 10°
S	Increase β by 10°
Χ	Decrease β by 10°
D	Increase γ by 10°
C	Decrease γ by 10°
V	Initialize orientation

- C. Hint: You do not need to store a composed rotation matrix as a global variable. You can just store  $\alpha$ ,  $\beta$ ,  $\gamma$  as global variables.
- D. Set the window title to **your student ID** and the window size to (480,480).
- E. Expected result: Uploaded LabAssignment9-1.mp4
- F. Files to submit: A Python source file (Name the file whatever you want (in English). Extension should be .py)